



Clustering

GU 4241/GR 5241

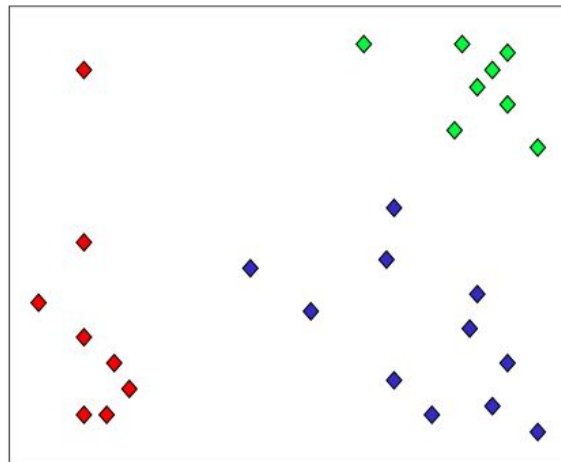
Statistical Machine Learning

Xiaofei Shi

Clustering

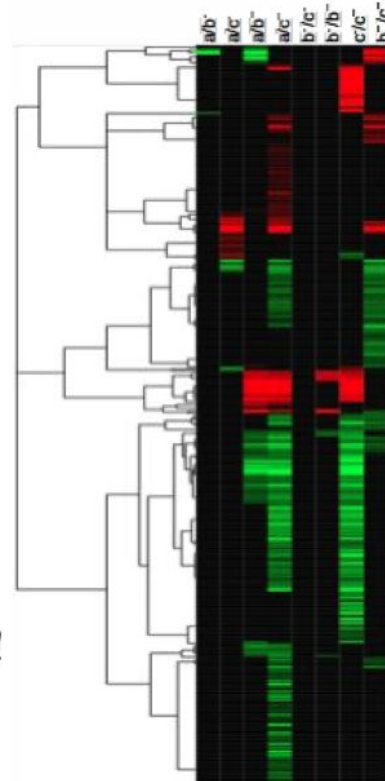
- Organizing data into groups.
- Unlike classification, there is no label provided!
- Informally, finding natural groups in data.
- Why do we want to do that?
- Any real application?

Unsupervised learning



Clustering

- Microarrays measures the activities of all genes in different conditions
- Clustering genes can help determine new functions for unknown genes
- An early “killer application” in this area
 - The most cited (11,591) paper in PNAS!

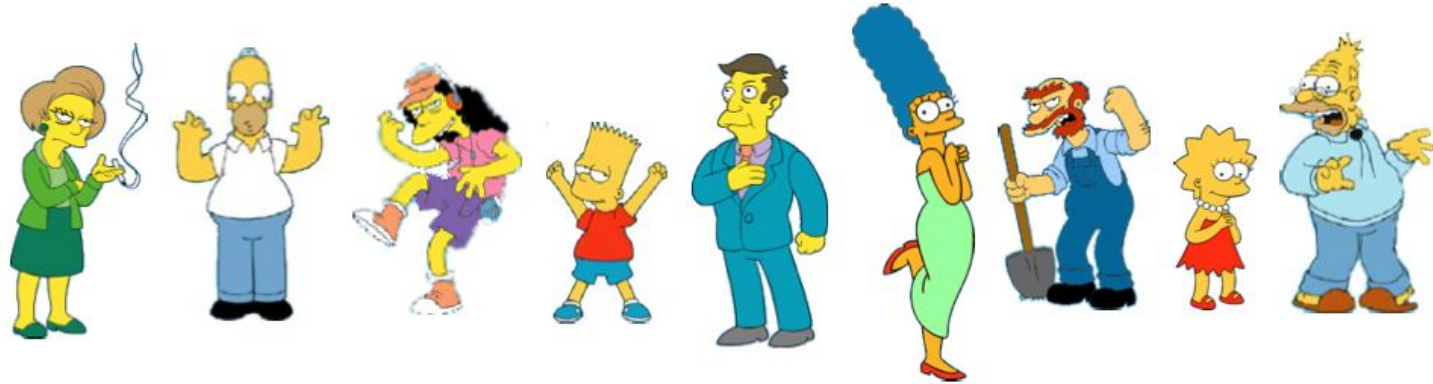


Clustering



- Organizing data into clusters provides information about the internal structure of the data
 - Ex. Clusty and clustering genes above
- Sometimes the partitioning is the goal – Ex. Image segmentation
- Knowledge discovery in data
 - Ex. Underlying rules, recurring patterns, topics, etc.

Clustering is subjective!

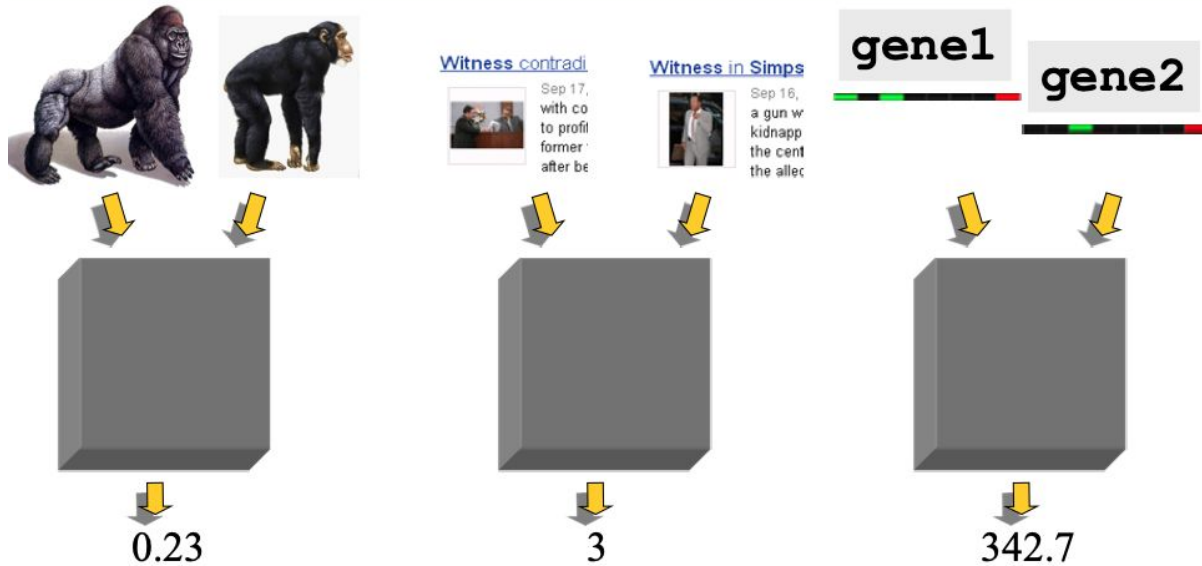


Similarity



Similarity: distance matrix

Definition: Let O_1 and O_2 be two objects from the universe of possible objects. The distance (dissimilarity) between O_1 and O_2 is a real number denoted by $D(O_1, O_2)$



Similarity: distance matrix

A few examples:

- Euclidian distance

$$d(x, y) = \sqrt{\sum_i (x_i - y_i)^2}$$

- Correlation coefficient

$$s(x, y) = \frac{\sum_i (x_i - \mu_x)(y_i - \mu_y)}{\sigma_x \sigma_y}$$

- Similarity rather than distance
- Can determine similar trends



Desirable properties of a clustering algorithm



- Scalability (in terms of both time and space)
- Ability to deal with different data types
- Minimal requirements for domain knowledge to determine input parameters
- Interpretability and usability
- Incorporation of user-specified constraints

Similarity: distance matrix

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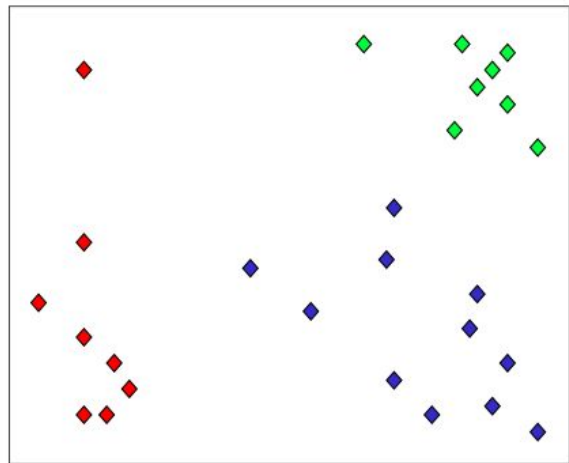
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- Can determine similar trends



Clustering algorithm

- Clustering algorithms:
 - k-means
 - mixture methods
 - density based clustering: level sets, trees; modes
 - hierarchical clustering
 - spectral clustering

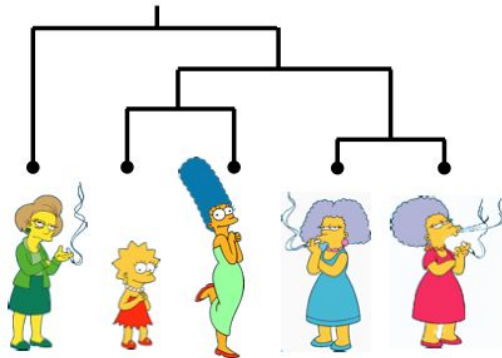


Clustering algorithm

- **Partitional algorithms:** Construct various partitions and then evaluate them by some criterion
- **Hierarchical algorithms:** Create a hierarchical decomposition of the set of objects using some criterion (focus of this class)

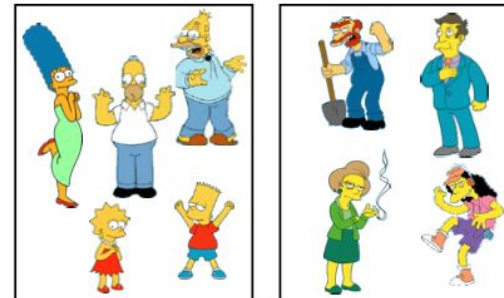
Bottom up or top down

Hierarchical



Top down

Partitional

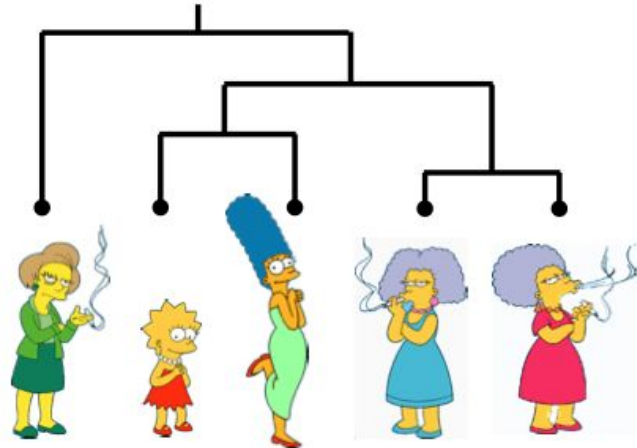


Hierarchical clustering

- Bottom-Up (agglomerative):
 - Starting with each item in its own cluster, find the best pair to merge into a new cluster. - Repeat until all clusters are fused together.

The number of dendrograms with n leafs = $(2n-3)! / [(2^{n-2})(n-2)!]$

| Number of Leafs | Number of Possible Dendrograms |
|-----------------|--------------------------------|
| 2 | 1 |
| 3 | 3 |
| 4 | 15 |
| 5 | 105 |
| ... | ... |
| 10 | 34,459,425 |

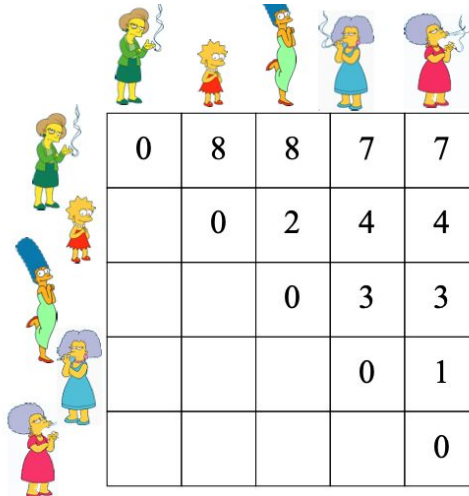












Hierarchical clustering

- Bottom-Up (agglomerative):
 - Starting with each item in its own cluster, find the best pair to merge into a new cluster.
 - Repeat until all clusters are fused together.

$$D(\text{Marge}, \text{Lisa}) = 8$$

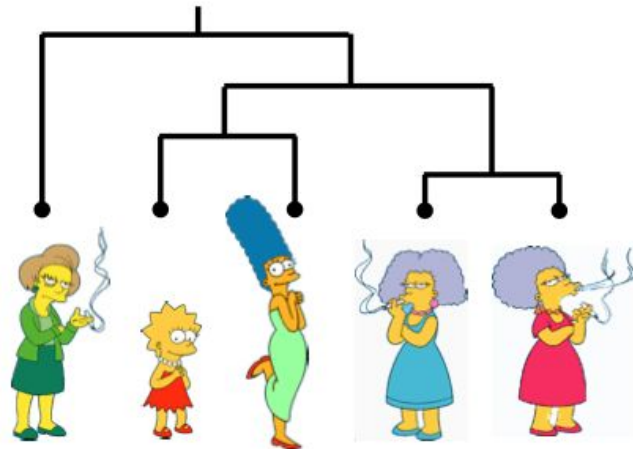
$$D(\text{Bart}, \text{Homer}) = 1$$



| | | | | | |
|--|---|---|---|---|---|
| |  |  |  |  |  |
|  | 0 | 8 | 8 | 7 | 7 |
|  | | 0 | 2 | 4 | 4 |
|  | | | 0 | 3 | 3 |
|  | | | | 0 | 1 |
|  | | | | | 0 |

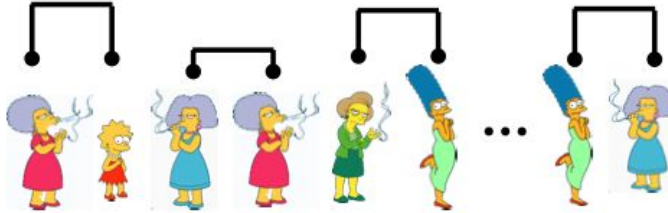
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Hierarchical clustering

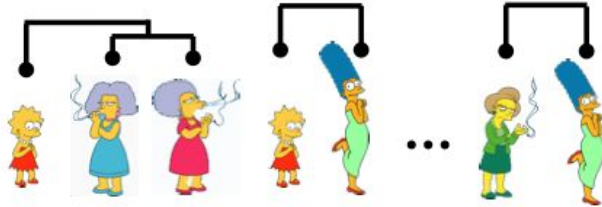
Consider all possible merges...



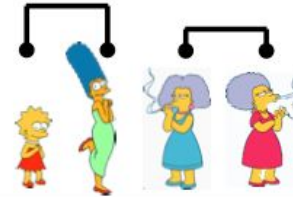
Choose the best



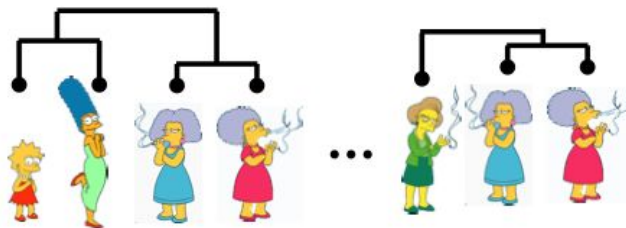
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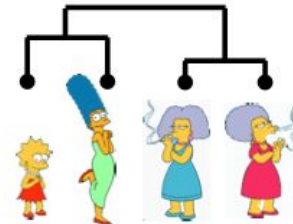
Choose the best



Consider all possible merges...

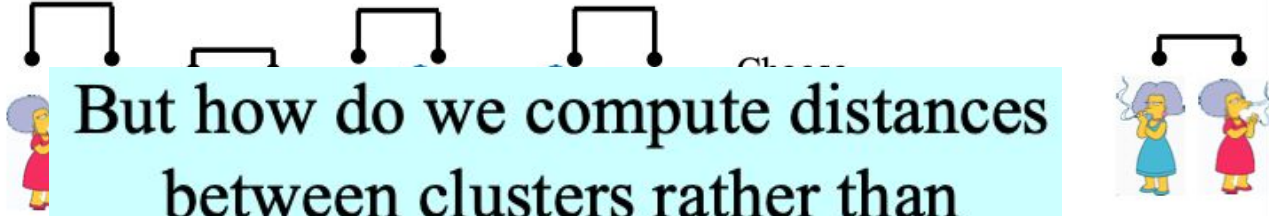


Choose the best



Hierarchical clustering

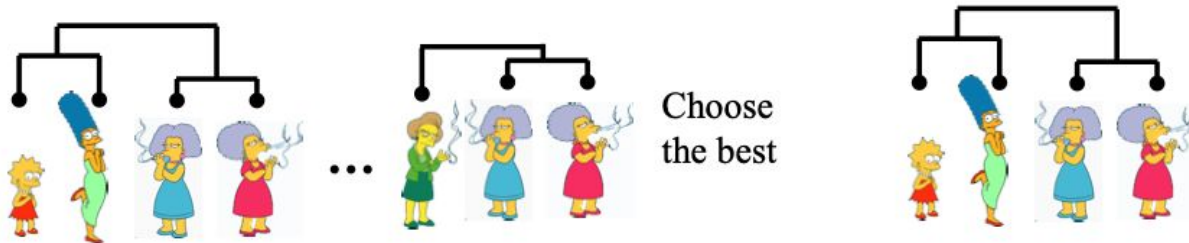
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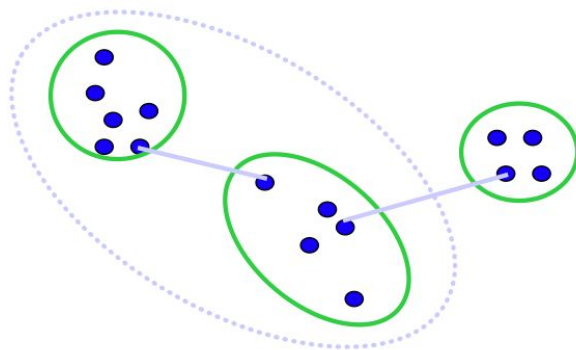


Consider all possible merges...



Simple link

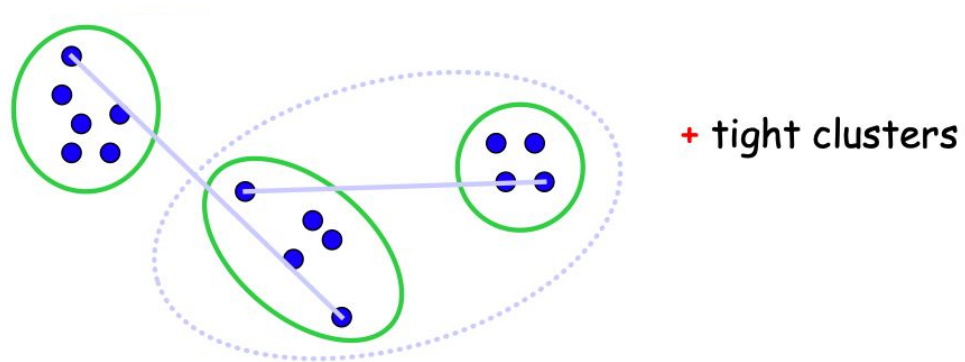
- Cluster distance = distance of two **closest** members in each class



- Potentially
long and skinny
clusters

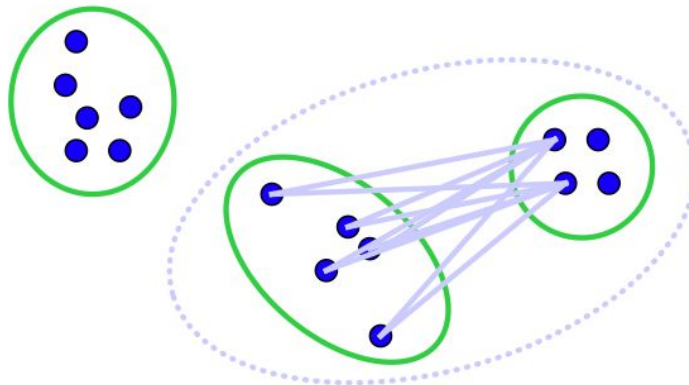
Complete link

- Cluster distance = distance of two **farthest** members in each class

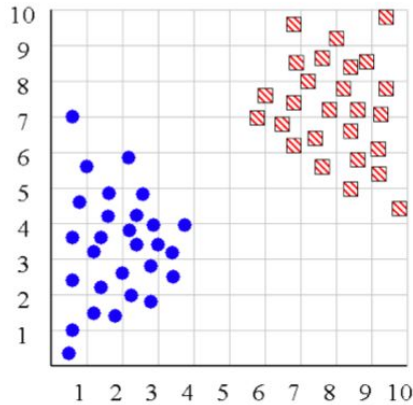


Average link

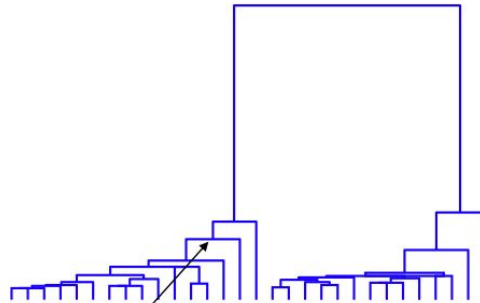
- Cluster distance = **average distance** of all pairs
- The most widely used measure
- Robust against noise



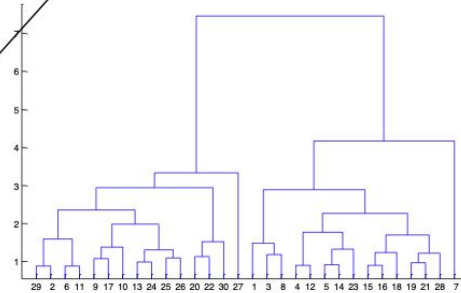
Hierarchical clustering: comparison



Height represents
distance between objects
/ clusters



Single linkage



Average linkage

Hierarchical clustering: summary

- No need to specify the number of clusters in advance.
- Hierarchical structure maps nicely onto human intuition for some domains
- They do not scale well: time complexity of at least $O(n^2)$, where n is the number of total objects.
- Like any heuristic search algorithms, local optima are a problem.
- Interpretation of results is (very) subjective.



Partitional clustering

- Nonhierarchical, each instance is placed in exactly one of K non-overlapping clusters.
- Since the output is only one set of clusters the user has to specify the desired number of clusters K .



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- K-means: **hard assignment**:
each object belongs to only one cluster

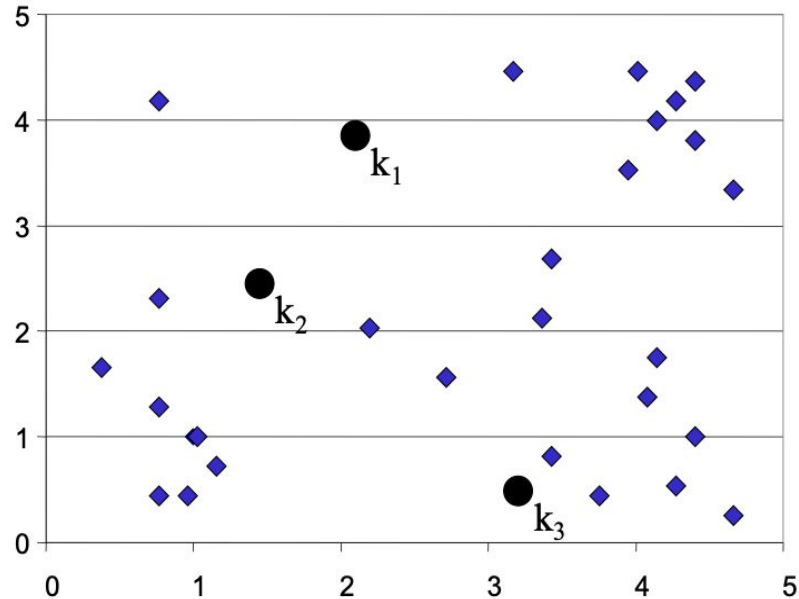
- Mixture modeling: **soft assignment**
probability that an object belongs to a cluster

Generative approach: think of each cluster as a component distribution, and any data point is drawn from a “mixture” of multiple component distributions



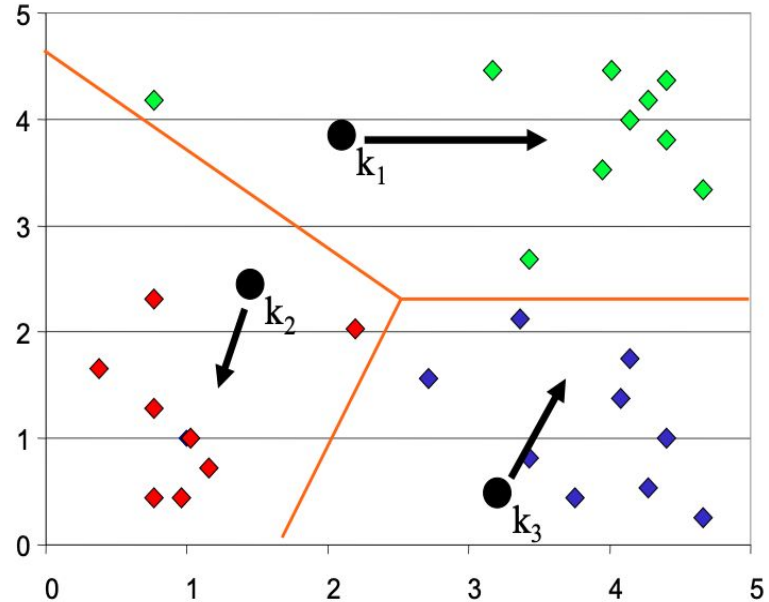
K-means clustering (Lloyd's method)

- Decide K and initialize K centers (randomly).
- Assign all objects to the nearest center.
- Move a center to the mean of its members.



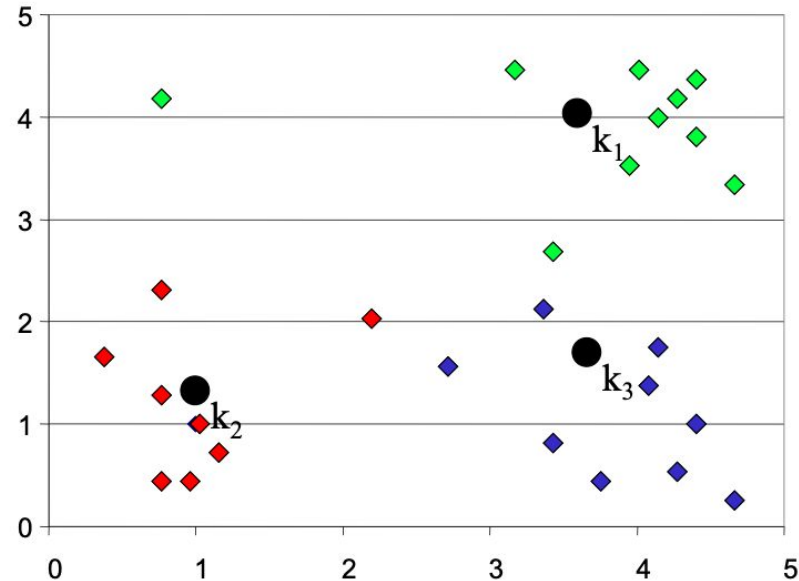
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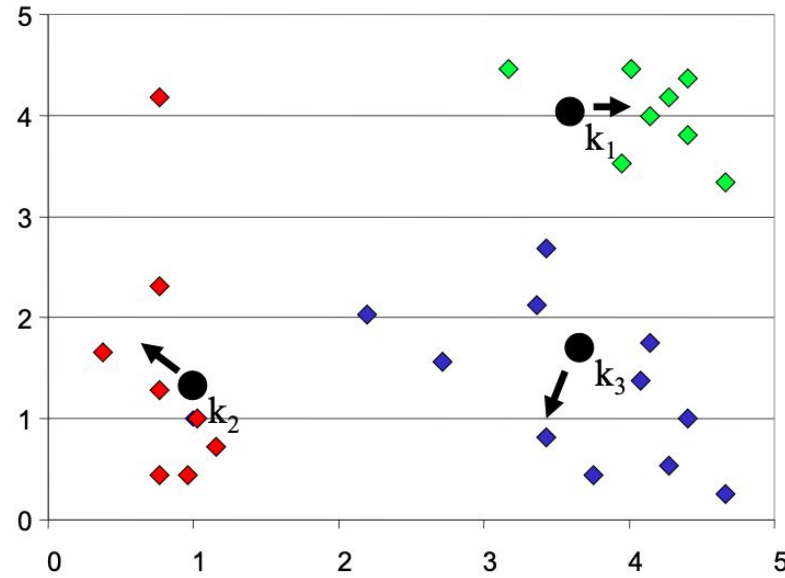
K-means clustering

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- Move a center to the mean of its members.
- After moving centers, re-assign the objects...



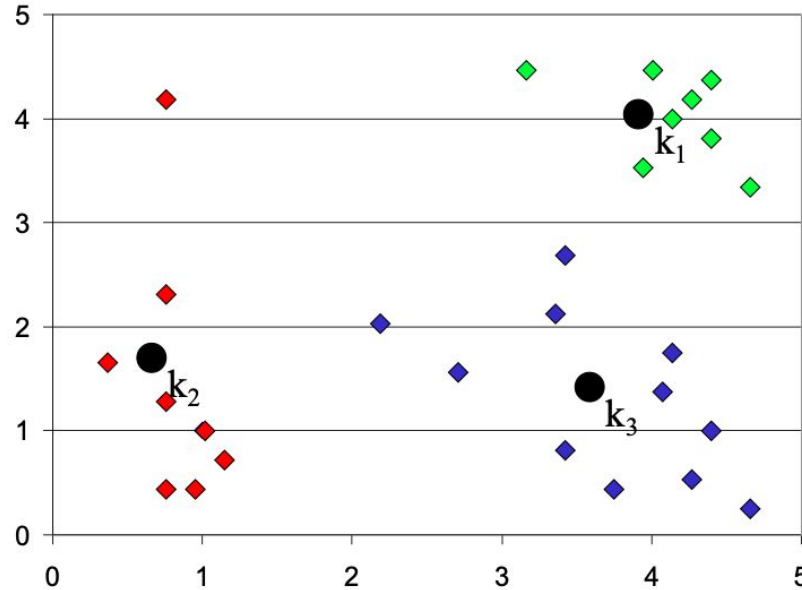
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- Move a center to the mean of its new members.
- Re-assign and move centers, until ... no objects changed membership.



K-means algorithm



1. Decide on a value for K , the number of clusters.
2. Initialize the K cluster centers (randomly, if necessary).
3. Decide the class memberships of the N objects by assigning them to the nearest cluster center.
4. Re-estimate the K cluster centers, by assuming the memberships found above are correct.
5. Repeat 3 and 4 until none of the N objects changed membership in the last iteration.

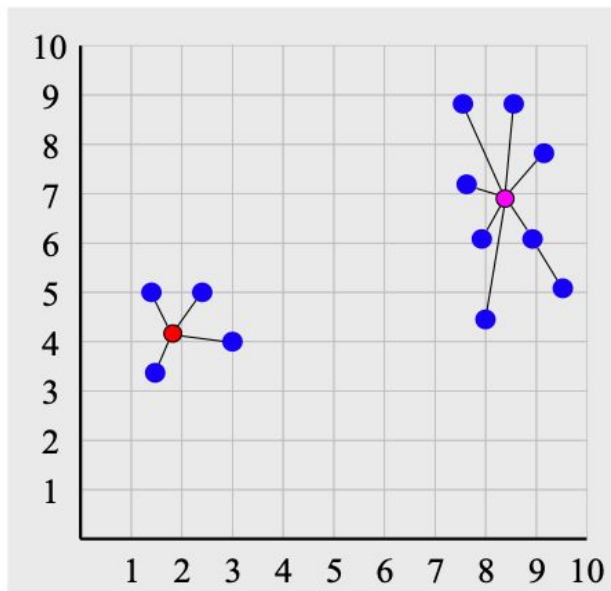
Why K-means works

- What is a good partition?
- High intra-cluster similarity
- K-means optimizes
 - the average distance to members of the same cluster

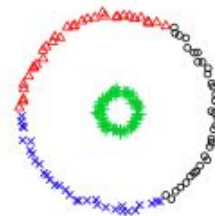
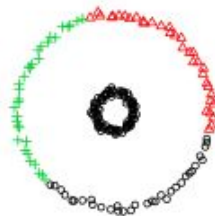
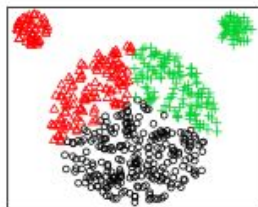
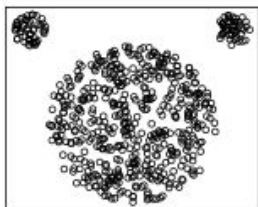
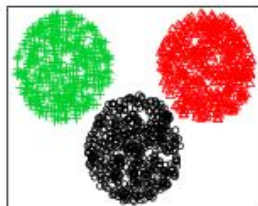
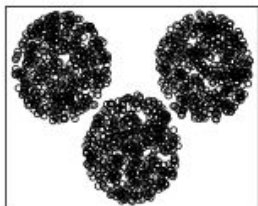
$$\sum_{k=1}^K \frac{1}{n_k} \sum_{i=1}^{n_k} \sum_{j=1}^{n_k} \|x_{ki} - x_{kj}\|^2$$

- which is twice the total distance to centers, also called squared error

$$se = \sum_{k=1}^K \sum_{i=1}^{n_k} \|x_{ki} - \mu_k\|^2$$



But sometimes...



K-means: summary

- Pros:
 - simple to implement (and debug)
 - intuitive objective function: optimizes intra-cluster similarity
 - relatively efficient: $O(tkn)$, where normally, $k, t \ll n$
- Cons:
 - Often terminates at a local optimum. Initialization is important
 - K is a hyperparameter, needs to be specified
 - Unable to handle noisy data and outliers
 - Not suitable to discover clusters with non-convex shapes
- Summary:
 - Assign members based on current centers
 - Re-estimate centers based on current assignment

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- K-means: **hard assignment**:
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- Mixture modeling: **soft assignment**
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Generative approach: think of each cluster as a component distribution, and any data point is drawn from a “mixture” of multiple component distributions



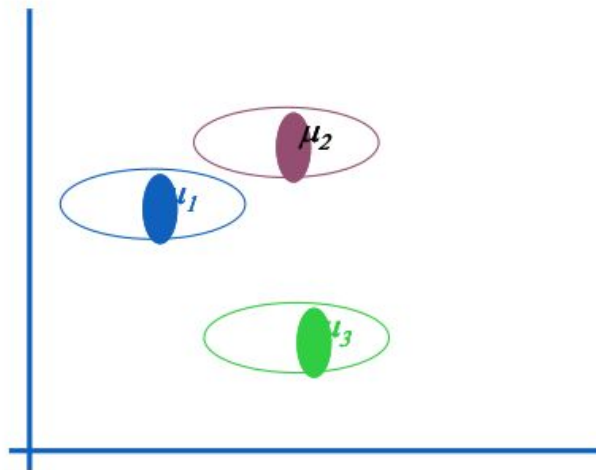
Gaussian mixture modeling

Mixture of K Gaussian distributions: (Multi-modal distribution)

$$p(x|y=i) \sim N(\mu_i, \sigma^2 I)$$

$$p(x) = \sum_i p(x|y=i) P(y=i)$$

↓ ↓
Mixture **Mixture**
component **proportion**



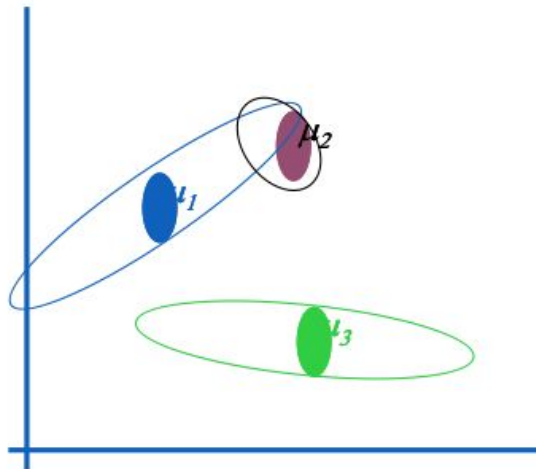
Gaussian mixture modeling

GMM – Gaussian Mixture Model (Multi-modal distribution)

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$$p(x) = \sum_i p(x|y=i) P(y=i)$$

↓ ↓
Mixture Mixture
component proportion



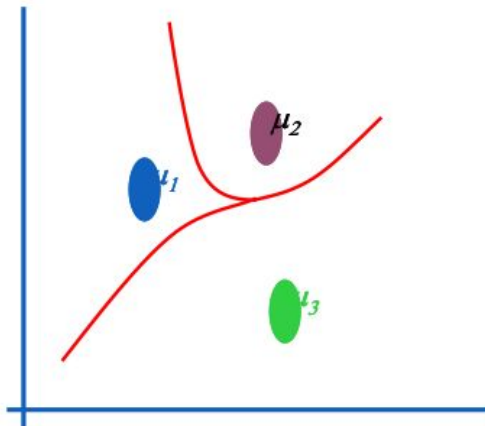
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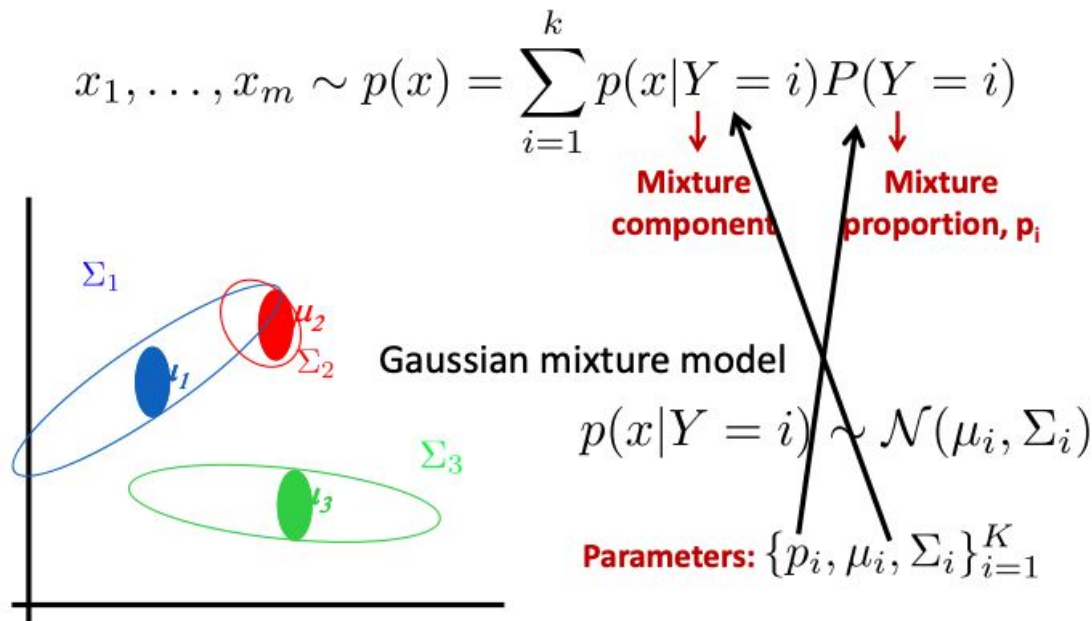
$$p(x|y=i) \sim N(\mu_i, \Sigma_i)$$

Gaussian Bayes Classifier:

$$\begin{aligned} \log \frac{P(y=i|x)}{P(y=j|x)} \\ = \log \frac{p(x|y=i)P(y=i)}{p(x|y=j)P(y=j)} \end{aligned}$$



Learning General GMM



- How to estimate parameters? Maximum Likelihood
But don't know labels Y (recall Gaussian Bayes classifier)

Learning General GMM

Maximize marginal likelihood:

$$\begin{aligned}\operatorname{argmax} \prod_j P(x_j) &= \operatorname{argmax} \prod_j \sum_{i=1}^K P(y_j=i, x_j) \quad \dots \text{marginalizing } y_j \\ &= \operatorname{argmax} \prod_j \sum_{i=1}^K P(y_j=i) p(x_j | y_j=i)\end{aligned}$$

$P(y_j=i) = P(y=i)$ Mixture component i is chosen with prob $P(y = i)$

$$= \operatorname{argmax} \prod_{j=1}^m \sum_{i=1}^k P(y=i) \frac{1}{\sqrt{\det(\Sigma_i)}} \exp\left[-\frac{1}{2} (x_j - \mu_i)^T \Sigma_i (x_j - \mu_i)\right]$$

How do we find the μ_i 's and $P(y=i)$ s which give max. marginal likelihood?

* Set $\frac{\partial}{\partial \mu_i} \log \text{Prob}(\dots) = 0$ and solve for μ_i 's. **Non-linear non-analytically solvable**

* Use gradient descent: **Doable, but often slow**

Connection to K-means

Maximize marginal likelihood:

$$\begin{aligned}\operatorname{argmax} \prod_j P(x_j) &= \operatorname{argmax} \prod_j \sum_{i=1}^K P(y_j=i, x_j) \\ &= \operatorname{argmax} \prod_j \sum_{i=1}^K P(y_j=i) p(x_j | y_j=i)\end{aligned}$$

- What happens if we assume **Hard assignment**?

$$\begin{aligned}P(y_j = i) &= 1 \text{ if } i = C(j) \\ &= 0 \text{ otherwise}\end{aligned}$$

Same as k-means (if we assume equal covariance matrix)!

$$\begin{aligned}\operatorname{argmax} \prod_j P(x_j) &= \operatorname{argmax} \prod_j p(x_j | y_j=C(j)) \\ &= \operatorname{argmax} \prod_{j=1}^n \exp\left(\frac{-1}{2\sigma^2} \|x_j - \mu_{C(j)}\|^2\right) \\ &= \operatorname{argmin} \sum_{j=1}^n \|x_j - \mu_{C(j)}\|^2 = \operatorname{argmin}_{\mu, C} F(\mu, C)\end{aligned}$$

Expectation-Maximization (EM Algorithm)

A general algorithm to deal with hidden data, but we will study it in the context of unsupervised learning (hidden labels) first

- No need to choose step size as in Gradient methods.
- EM is an Iterative algorithm with two linked steps:
 - E-step: fill-in hidden data (Y) using inference
 - M-step: apply standard MLE/MAP method to estimate parameters $\{p_i, \mu_i, \Sigma_i\}_{i=1}^k$
- We will see that this procedure monotonically improves the likelihood (or leaves it unchanged). Thus it always converges to a local optimum of the likelihood.



EM Algorithm with known variance

E-step

Compute “expected” classes of all datapoints for each class

$$P(y = i | x_j, \mu_1, \dots, \mu_k) \propto \exp\left(-\frac{1}{2\sigma^2} \|x_j - \mu_i\|^2\right) P(y = i)$$

In K-means “E-step”
we do hard assignment

EM does soft assignment

M-step

Compute MLE for μ , Σ and p given our data’s class membership distributions (weights)

Similar to K-means, but with
weighted data

Iterate.

General EM Algorithm

Marginal likelihood – \mathbf{x} is observed, \mathbf{z} is missing:

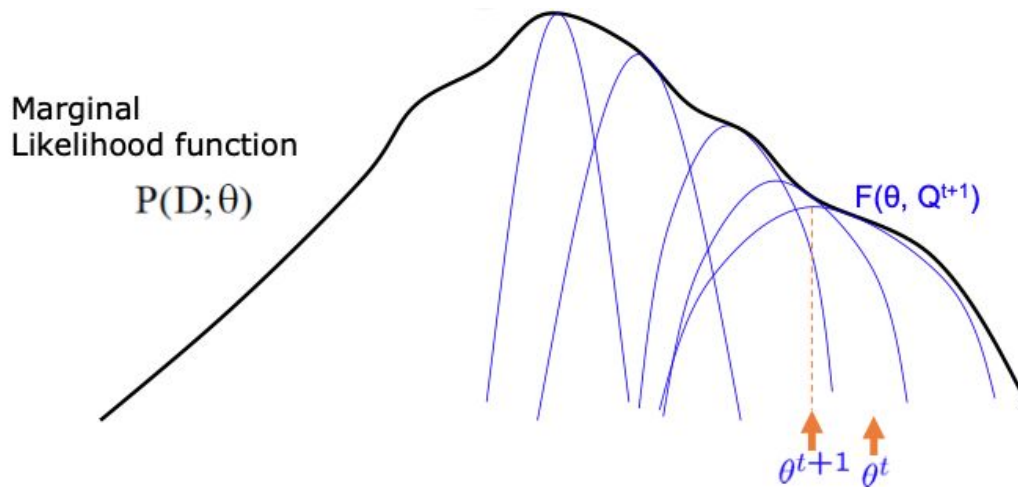
$$\begin{aligned}\log P(D; \theta) &= \log \prod_{j=1}^m P(\mathbf{x}_j | \theta) \\ &= \sum_{j=1}^m \log P(\mathbf{x}_j | \theta) \\ &= \sum_{j=1}^m \log \sum_{\mathbf{z}} P(\mathbf{x}_j, \mathbf{z} | \theta)\end{aligned}$$

$$D = \{\mathbf{x}_j\}_{j=1}^m$$

θ - model parameter(s)



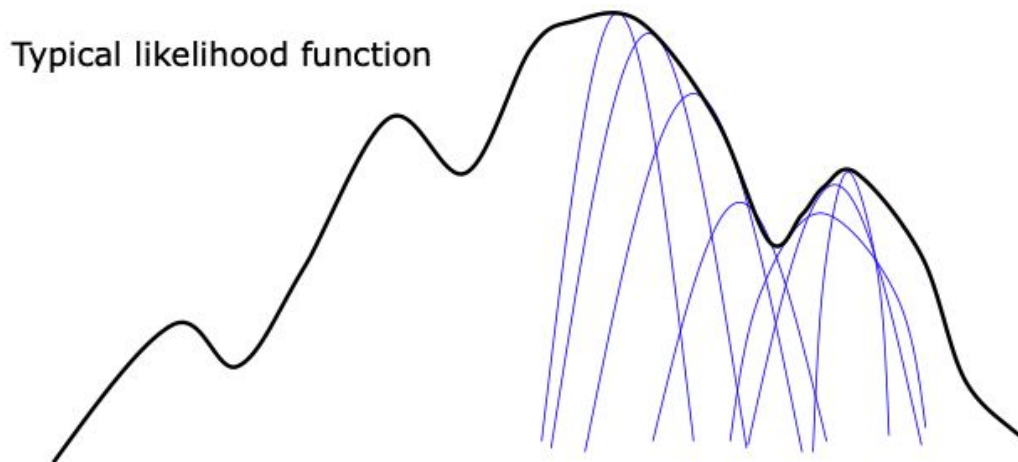
General EM Algorithm



Sequence of EM lower bound F-functions

EM monotonically converges to a local maximum of likelihood !

General EM Algorithm



Different sequence of EM lower bound
F-functions depending on initialization

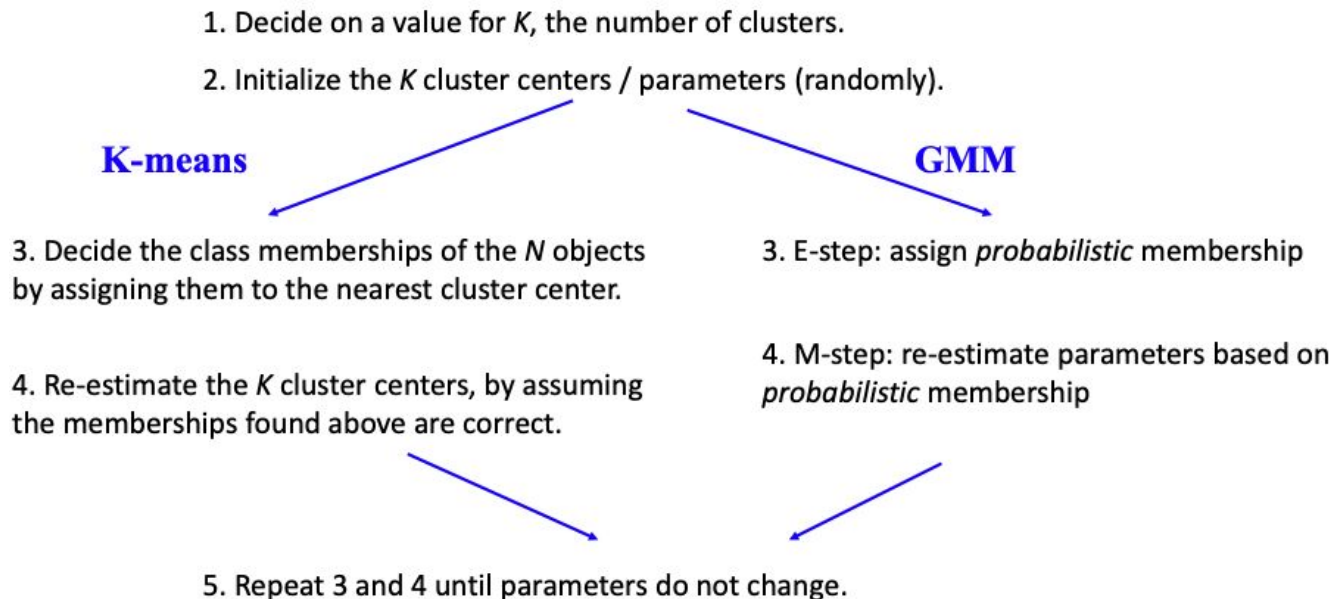
Use multiple, randomized initializations in practice

EM Algorithm

- A way of maximizing likelihood function for hidden variable models. Finds MLE of parameters when the original (hard) problem can be broken up into two (easy) pieces:
 1. Estimate some “missing” or “unobserved” data from observed data and current parameters.
 2. Using this “complete” data, find the maximum likelihood parameter estimates.
- Alternate between filling in the latent variables using the best guess (posterior) and updating the parameters based on this guess:
 1. E-step: $Q^{t+1} = \arg \max_Q F(\theta^t, Q)$
 2. M-step: $\theta^{t+1} = \arg \max_{\theta} F(\theta, Q^{t+1})$
- In the M-step we optimize a lower bound on the likelihood. In the E-step we close the gap, making bound=likelihood.
- EM performs coordinate ascent on F , but can get stuck in local minima.
- Extremely popular and useful in practice.



K-means vs GMM



Comparison

| | Hierarchical | K-means | GMM |
|-------------------------|--|------------------------------------|---------------------------------|
| Running time | naively, $O(N^3)$ | fastest (each iteration is linear) | fast (each iteration is linear) |
| Assumptions | requires a similarity / distance measure | strong assumptions | strongest assumptions |
| Input parameters | none | K (number of clusters) | K (number of clusters) |
| Clusters | subjective (only a tree is returned) | exactly K clusters | exactly K clusters |



References

- Christopher Bishop: Pattern Recognition and Machine Learning, Chapter 9
- Trevor Hastie, Robert Tibshirani, Jerome Friedman: The Elements of Statistical Learning: Data Mining, Inference and Prediction, Chapter 14
- Ziv Bar-Joseph, Tom Mitchell, Pradeep Ravikumar and Aarti Singh: CMU 10-701