

Q1.

$$E_{avg} = \frac{1}{M} \sum_{i=1}^M E(\epsilon_i(x)^2) \quad \text{--- (1)}$$

where $E(\epsilon_i(x)^2) = E[(f(x) - h_i(x))^2]$

$$E_{agg}(x) = E\left[\left\{\frac{1}{M} \sum_{i=1}^M \epsilon_i(x)\right\}^2\right]$$

where, $\epsilon_i(x) = f(x) - h_i(x)$

$$E_{agg}(x) = \frac{1}{M^2} \cdot E\left[\left\{\sum_{i=1}^M \epsilon_i(x)\right\}^2\right]$$

[As we know that $E(ax) = a E(x)$]

$$= \frac{1}{M^2} E\left[(\epsilon_1(x) + \epsilon_2(x) + \epsilon_3(x) + \dots + \epsilon_M(x))^2\right]$$

$$= \frac{1}{M^2} E\left[(\epsilon_1(x))^2 + (\epsilon_2(x))^2 + \dots + (\epsilon_M(x))^2 + 2 \cdot \epsilon_1(x) \epsilon_2(x) + \dots\right]$$

$$= \frac{1}{M^2} \left[E\left[\sum_{i=1}^M \epsilon_i(x)^2\right] + 2 E\left[\sum_{i=1}^M \sum_{j=1}^M (\epsilon_i(x) \cdot \epsilon_j(x))\right] \right]$$

$$= \frac{1}{M^2} \cdot \left[E \cdot \sum_{i=1}^M (\epsilon_i(x)^2) \right] \quad \begin{matrix} \parallel \\ 0 \end{matrix}$$

[As all ~~are~~ errors are uncorrelated and $E(\epsilon_i(x) \epsilon_j(x)) = 0$ for all $i \neq j$]

$$= \frac{1}{M} \cdot \left[\frac{1}{M} \cdot E \sum_{i=1}^M (\epsilon_i(x)^2) \right] = \frac{1}{M} \cdot E_{avg} \quad \text{[from (1)]} \quad \text{--- (2)}$$

Hence,

$$\boxed{E_{agg}(x) = \frac{1}{M} \cdot E_{avg}} \quad [\text{from ① and ②}]$$

Hence Proved.

Q2.

Jensen's inequality states that for any convex function f :

$$f\left(\sum_{i=1}^M \lambda_i x_i\right) \leq \sum_{i=1}^M \lambda_i f(x_i)$$

[assuming that each of the errors are not uncorrelated.]

To prove: $E_{agg} \leq E_{avg}$

Ans.

→

Now, as the errors are not uncorrelated
i.e.

$$E(\epsilon_i(x) \cdot \epsilon_j(x)) \neq 0 \quad \text{for all } i \neq j$$

$$E_{agg}(x) = E\left[\left\{\frac{1}{M} \sum_{i=1}^M \epsilon_i(x)\right\}^2\right]$$

and

$$E_{avg} = \frac{1}{M} E\left[\sum_{i=1}^M \epsilon_i(x)^2\right]$$

comparing with E_{avg} with RHS of Jensen's inequality, according to the given equation

$$\lambda_i = \frac{1}{M}, \quad f(x) = \sum_{i=1}^M E[E_i(x)^2]$$

$$f(x_i) = E[E_i(x)^2]$$

and we have,

$$f\left(\sum_{i=1}^M \lambda_i x_i\right) = E\left[\sum_{i=1}^M \frac{1}{M} E_i(x)^2\right]$$

i.e. we get ^{from} Jensen's inequality as:

$$E\left[\sum_{i=1}^M \frac{1}{M} E_i(x)^2\right] \leq \sum_{i=1}^M \frac{1}{M} E(E_i(x)^2) = E_{avg} \quad \text{--- (1)}$$

we need to prove that,

$$E_{agg} \leq E\left(\sum_{i=1}^M \frac{1}{M} E_i(x)^2\right)$$

Because we have already proved from result (1) that

$$E\left(\sum_{i=1}^M \frac{1}{M} E_i(x)^2\right) \leq E_{avg}$$

We know that

$$\frac{(a+b)^2}{2} \leq a^2 + b^2$$

(from Cauchy-Schwarz inequality)

$$\frac{(\epsilon_1(x) + \epsilon_2(x) + \dots + \epsilon_M(x))^2}{M} \leq \epsilon_1(x)^2 + \epsilon_2(x)^2 + \dots + \epsilon_M(x)^2$$

$$E \left[\frac{1}{M} \left(\sum_{i=1}^M \epsilon_i(x) \right)^2 \right] \leq E \left[\epsilon_1(x)^2 + \epsilon_2(x)^2 + \dots + \epsilon_M(x)^2 \right]$$

dividing each side by M ,

$$E \left[\frac{1}{M^2} \left(\sum_{i=1}^M \epsilon_i(x) \right)^2 \right] \leq \frac{1}{M} E \left[\sum_{i=1}^M \epsilon_i(x)^2 \right]$$

$$E \left[\left(\frac{1}{M} \sum_{i=1}^M \epsilon_i(x) \right)^2 \right] \leq \frac{1}{M} E \left[\sum_{i=1}^M \epsilon_i(x)^2 \right]$$

————— (2)

We know that, from the question 1,

$$E_{agg}(x) = E \left[\left\{ \frac{1}{M} \sum_{i=1}^M \epsilon_i(x) \right\}^2 \right] \text{ ————— (3)}$$

and

$$E_{avg} = \frac{1}{M} \cdot \sum_{i=1}^M E(\epsilon_i(x)^2) \text{ ————— (4)}$$

from (2), (3) and (4), we get

$$E_{agg}(x) \leq E_{avg}$$

Hence proved.

Q3.

Final Hypothesis for a Boolean classification problem at the end of T iterations is given as:

$$H(x) = \text{sign} \left(\sum_{t=1}^T a_t h_t(x) \right) \quad \text{--- (1)}$$

i.e. Final hypothesis is the weighted hypothesis generated at the end of each individual step.

The weight for the point i at step $t+1$ is given by:

$$D_{t+1}(i) = \frac{D_t(i)}{Z_t} \times e^{-\alpha_t h_t(x_i) y(i)} \quad \text{--- (2)}$$

at step 1, the points have equal weight

$$D_1 = \frac{1}{N} \quad \text{--- (3)}$$

total error at each step is:

$$E_t = \frac{1}{2} - \frac{1}{2} \quad \text{--- (4)}$$

We have,

$$\begin{aligned} D_{t+1}(i) &= \frac{D_t(i) \exp(-\alpha_t y_i h_t(x_i))}{Z_t} \\ &= \frac{D_t(i)}{Z_t} \cdot e^{-\alpha_t \cdot y_i \cdot h_t(x_i)} \quad \text{from (2)} \end{aligned}$$

Since, $y(i)$ and $h_t(x_i)$ are both in $\{-1, +1\}$ unwrapping this recurrence,

$$\begin{aligned} D_{T+1}(i) &= D_1(i) \cdot \frac{e^{-\alpha_1 y_i h_1(x_i)}}{Z_1} \dots \frac{e^{-\alpha_T y_i h_T(x_i)}}{Z_T} \\ &= \frac{1}{N} \cdot \frac{e^{-(y_i) \sum_t \alpha_t h_t(x_i)}}{\prod_t Z_t} \end{aligned}$$

$$= \frac{1}{N} \cdot \frac{\exp(-y_i f(x_i))}{\prod_t z_t} \quad \text{--- (5)}$$

Now,

$$\text{training error } (H) = \frac{1}{N} \sum_i \begin{cases} 1 & \text{if } y_i \neq H(x_i) \\ 0 & \text{else} \end{cases}$$

$$= \frac{1}{N} \sum_i \begin{cases} 1 & \text{if } y_i f(x_i) \leq 0 \\ 0 & \text{else} \end{cases} \quad \left| \begin{array}{l} \text{(By the definition of training error)} \\ \text{since } H(x) = \text{sign}(f(x)) \text{ \& } y_i \in \{-1, +1\} \end{array} \right.$$

$$\leq \frac{1}{N} \sum_i \exp(-y_i f(x_i)) \quad \left| \text{as } e^{-z} \geq 1 \text{ if } z \leq 0 \right.$$

$$= \sum_i D_{T+1}(i) \cdot \prod_t z_t \quad \left| \text{from step (5)} \right.$$

$$= \prod_t z_t \quad \left| \text{since} \right. \quad \text{--- (6)}$$

~~So~~

$$z_t = \sum_i D_t(i) \times \begin{cases} e^{-\lambda t} & \text{if } h_t(x_i) = y_i \\ e^{\lambda t} & \text{if } h_t(x_i) \neq y_i \end{cases}$$

$$= \sum_{i: h_t(x_i) = y_i} D_t(i) \cdot e^{-\lambda t} + \sum_{i: h_t(x_i) \neq y_i} D_t(i) \cdot e^{\lambda t}$$

$$= e^{-\lambda t} \sum_{i: h_t(x_i) = y_i} D_t(i) + e^{\lambda t} \sum_{i: h_t(x_i) \neq y_i} D_t(i)$$

$$= e^{-\lambda t} (1 - \epsilon_t) + e^{\lambda t} \cdot \epsilon_t \quad \left(\text{by the definition of } \epsilon_t \right)$$

$$= 2 \sqrt{\epsilon_t(1-\epsilon_t)} \quad (\text{as } \alpha_t \text{ was chosen to minimize the expression})$$

$$= \sqrt{1-4\gamma_t^2}$$

$$\text{plugging in } \epsilon_t = \frac{1}{2} - \gamma_t$$

$$\leq e^{-2\gamma_t^2}$$

using $1+x \leq e^x$ for all real x .

from (6) and (7),

(7)

$$\text{training error} = \prod_t Z_t$$

$$\& \quad Z_t \leq e^{-2\gamma_t^2}$$

Hence, this gives the claimed upper bound on the training error of H .

Hence, at the end of T steps, overall training error will be less than or equal to the i.e. it will be bounded by:

$$\boxed{\exp\left(-2 \cdot \sum_{t=1}^T \gamma_t^2\right)} \quad \left[\text{taking } t=1 \text{ to } t=T \right]$$

Hence proved.