A NOTE ON FINDING THE BRIDGES OF A GRAPH*

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Recently, algorithms have been developed which use depth-first search to test various connectivity properties of graphs efficiently. Examples include algorithms to find the connected, biconnected, and triconnected components of an undirected graph [1-3], and the strongly connected components [2] and dominators [4] of a directed graph. Depth-first search is not always necessary for testing connectivity properties like these efficiently, however. This note presents an efficient algorithm which uses any search method to find all the bridges of a graph.

A graph $G = (\mathcal{V}, \mathcal{E})$ is a set of vertices \mathcal{V} and a set of edges \mathcal{E} . The edges are either unordered pairs (v, w)or distinct vertices (the graph is undirected) or ordered pairs (v, w) of distinct vertices (the graph is directed). We denote the number of vertices by V and the number of edges by E. Graph $G_1 = (\mathcal{V}_1, \mathcal{E}_1)$ is a subgraph of G if $\mathcal{Y}_1 \subseteq \mathcal{Y}$ and $\mathcal{E}_1 \subseteq \mathcal{E}$. A sequence of edges $(v_1, v_2), (v_2, v_3), \dots, (v_{n-1}, v_n)$ is a path from v_1 to v_n. A path is simple if all its vertices are distinct. There is a path of no edges from any vertex to itself. An undirected graph is connected if there is a path between every pair of vertices. If there is a path from a vertex v to a vertex w in G but every path from v to w contains edge e, then e is said to be a bridge of G. An undirected graph is bridge-connected if it is connected and has no bridges. The connected (bridge-connected) components of a graph are its maximal connected (bridge-connected) subgraphs.

A tree is an undirected graph with exactly one simple path between every pair of distinct vertices. A spanning tree of a graph is a subgraph which is a tree and which contains every vertex of the graph. A directed rooted tree is a directed graph with a specified vertex called the root, such that there is a unique path from the root to any other vertex in the tree. We denote the existence of an edge (v, w) in a directed, rooted tree by $v \rightarrow w$ and the existence of a path from v to w in a directed, rooted tree by $v \stackrel{*}{\rightarrow} w$. If $v \rightarrow w$, v is the father of w and w is a son of v. If $v \stackrel{*}{\rightarrow} w$, v is an ancestor of w and w is a descendant of v. Note that v is, by this convention, an ancestor of itself.

We wish to find all the bridges of an undirected graph G. Without loss of generality we may assume that G is connected; otherwise we can apply the procedure below to each connected component of G. Let T be any spanning tree of G. We can convert T into a directed, rooted tree T by choosing an arbitrary vertex r of T as root and, for every path from r to a vertex v in T, directing the edges on this path so that it is a directed path from r to v. We denote the existence of a non-tree edge (v, w) in G by v - w. Number the vertices of T from 1 to V in postorder [5]. This ordering corresponds to applying the following algorithm to tree T:

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begin
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procedure POSTORDER(\nu); begin
for w such that \nu \to w do POSTORDER(w);
NUMBER (\nu) := i := i + 1;
end;
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i := 0;POSTORDER(r); comment r is the root of \overrightarrow{T} ; end;

Hencefoth we shall refer to vertices by their number, so that $\nu = \text{NUMBER}(\nu)$. For any vertex ν , let $\text{ND}(\nu)$ be the number of its descendants (including ν itself). Furthermore let

$$S(v) = \{w \mid v \rightarrow w\} \cup \{w \mid \exists u(v \rightarrow u \text{ and } u - - w)\},$$

let $L(\nu)$ = minimum $(S(\nu))$, and let $H(\nu)$ = maximum $(S(\nu))$. The following lemmas are easy to prove:

Lemnia 1:
$$v \to w \text{ iff } v - ND(v) < w \le v$$
.

Lemma 2:
$$ND(v) = 1 + \sum_{v \to w} ND(w)$$
.

Lemma 3:
$$L(v) = \min \left(\{v - ND(v) + 1\} \cup \{L(w)|v \rightarrow w\} \cup \{w|v - w\} \right).$$

Lemma 4:
$$H(v) = \text{maximum } (\{v\})$$

 $\bigcup \{H(w)|v \rightarrow w\} \bigcup \{w|v - w\}.$

Our main result is:

Theorem: Edge (v, w) is a bridge of G if and only if $v \to w$ in $T, H(w) \le w$, and L(w) > w - ND(w).

Proof: Obviously, no non-tree edge is a bridge. Consider any tree edge $v \to w$. This edge is a bridge if and only if no descendant of w is joined by an edge to a non-descendant of w. This condition is equivalent to that stated in the theorem, by Lemma 1 and the definitions of L(w) and H(w). Q.E.D.

To find all the bridges of G, we calculate $ND(\nu)$, $L(\nu)$, and $H(\nu)$ for all vertices ν using Lemmas 2, 3, and 4 and test the condition in the theorem for each tree edge. The entire algorithm is:

for each connected component G_1 of G do begin let G_1 have V_1 vertices;

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a: find a spanning tree T of G₁;
b: convert T to a directed, rooted tree T;
c: number the vertices of T in postorder;
d: for v := 1 until V₁ do begin
ND(v) := 1 + ∑ ND(w);
L(v) := minimum ({v - ND(v) · 1}
∪ {L(w)|v → w} ∪ {w|v - w});
H(v) := maximum ({v}) ∪ {H(w)|v → w}
∪ {w|v - w});
for w such that v → w do if H(w) ≤ w and L(w) > w - ND(w)
then denote (v, w) a bridge;
end;
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Finding the connected components of G and carrying out steps a, b, and c an each component requires O(V+E) time using any search method, if graph G is represented by a list structure [1,2]. The computations of ND, L, and H are well defined since $v \to w$ implies v > w by the postorder numbering. These computations take O(V+E) time. Thus, finding all the bridges of G requires O(V+E) time with this algorithm. Knowing the bridges of G, it is an easy matter to find the bridge-connected components of G in O(V+E) additional time.

References

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