

Chapter

**8-1**

***Binary  
Search Trees***

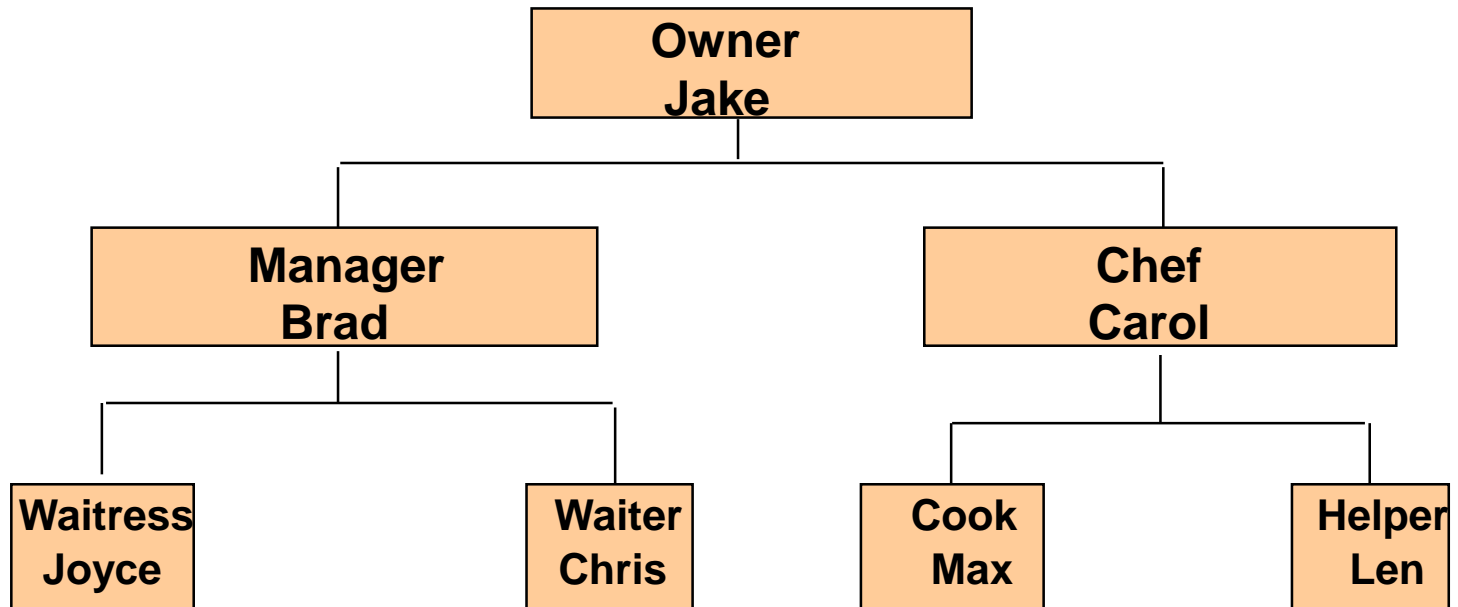
*Third Edition*

**C<sup>++</sup>** *Plus* **Data  
Structures**

*Nell Dale*

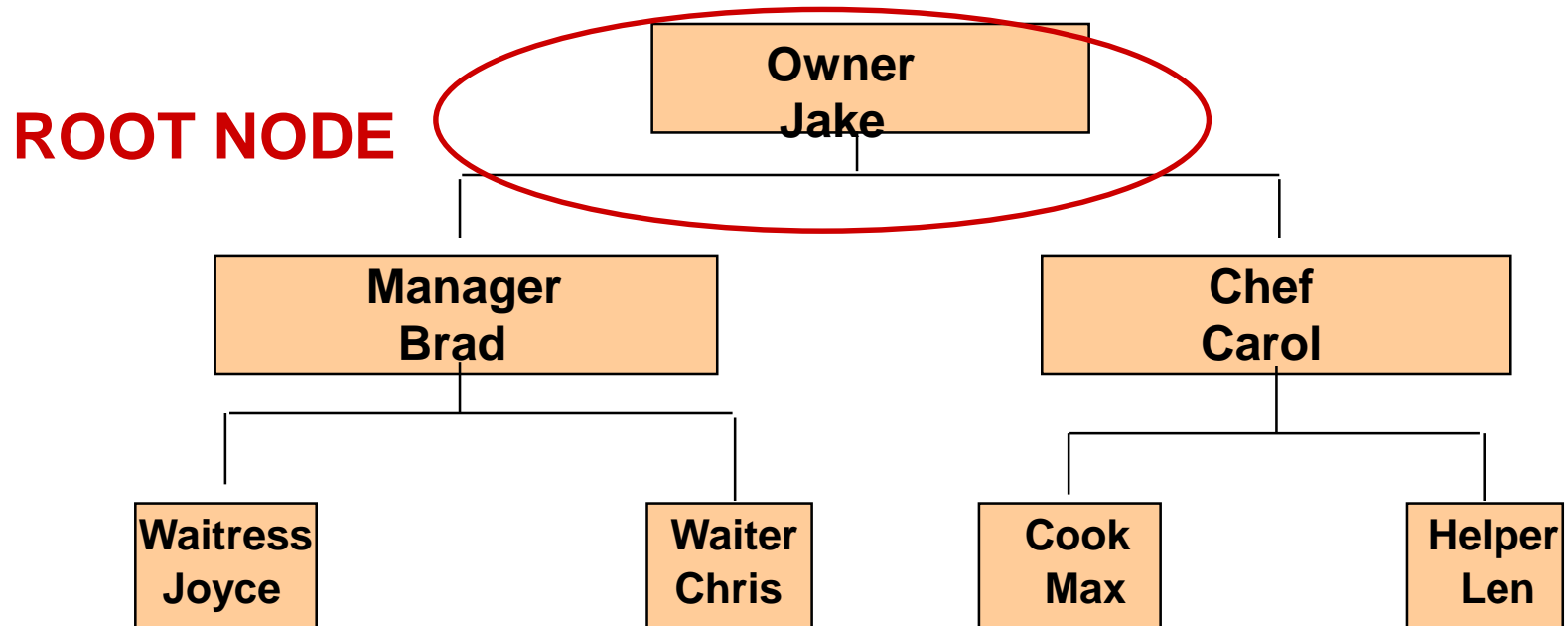


# Jake's Pizza Shop



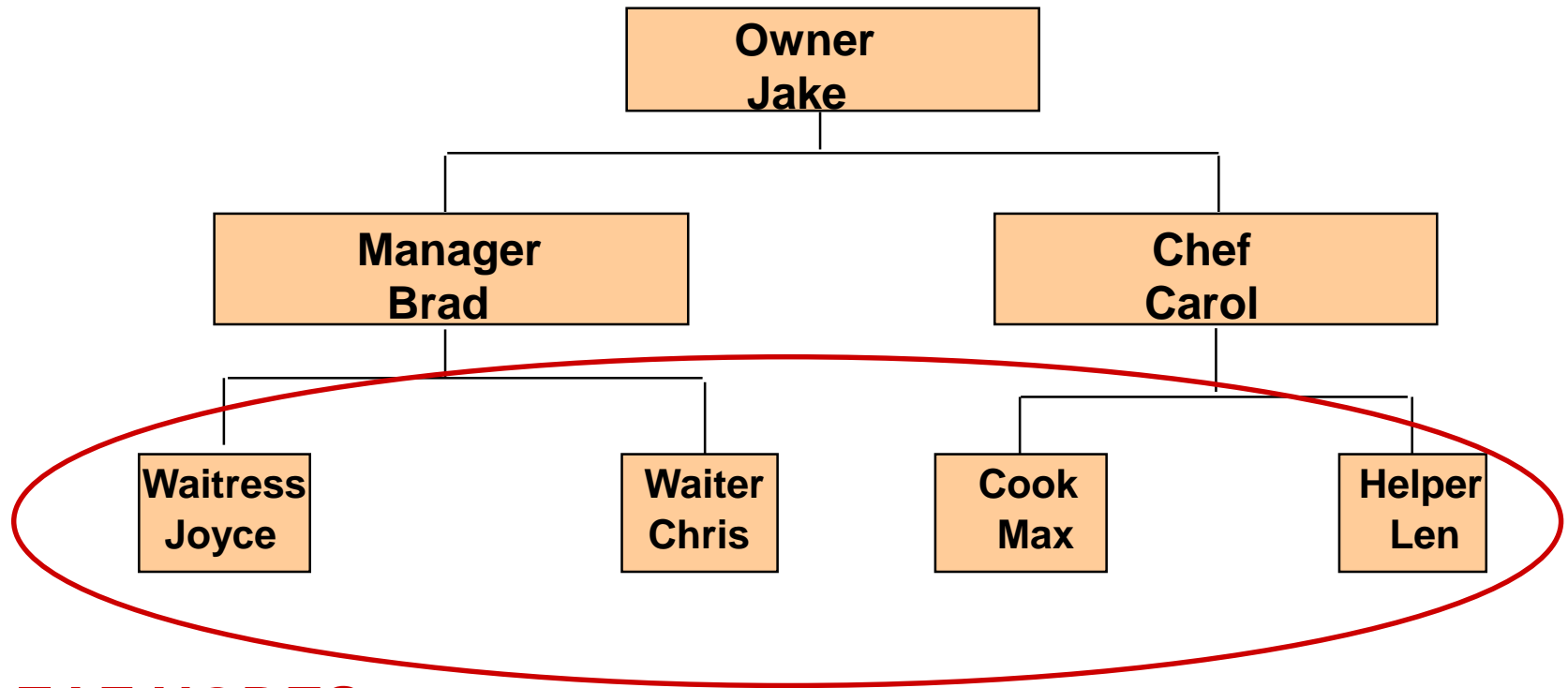


# A Tree Has a Root Node





# Leaf Nodes have No Children

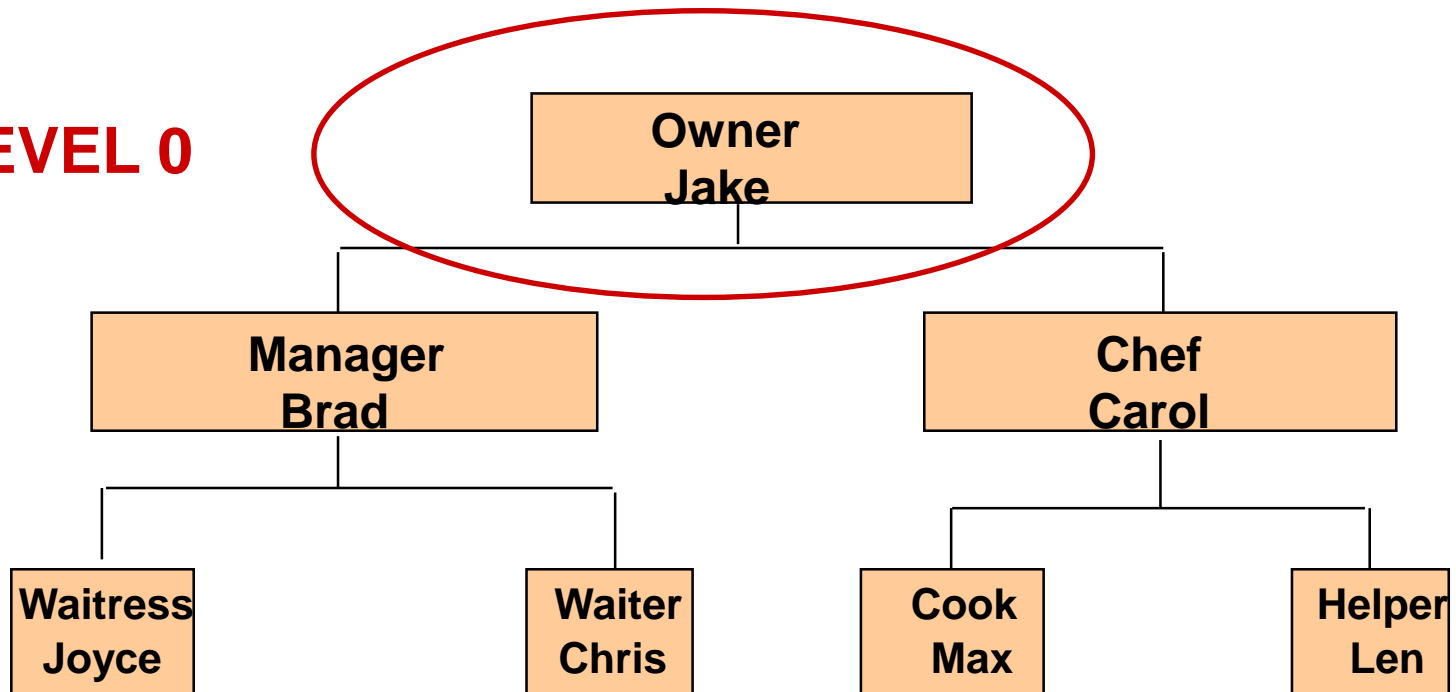


**LEAF NODES**



# A Tree Has Leaves

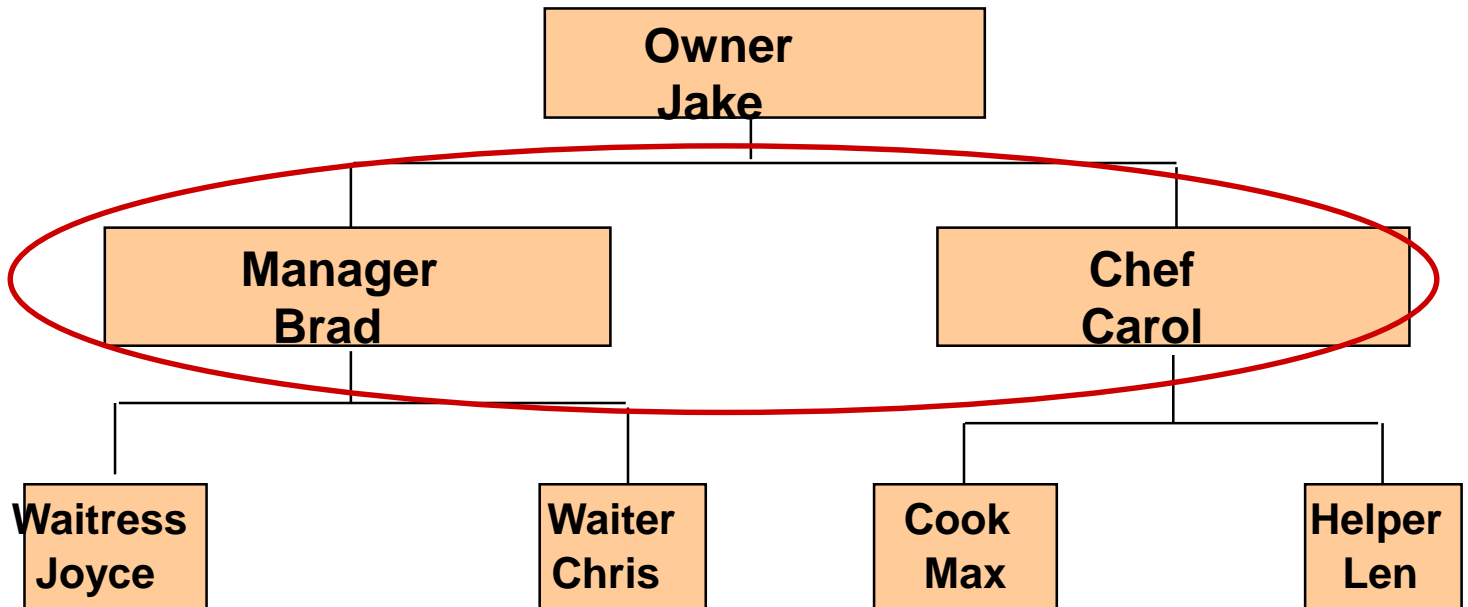
**LEVEL 0**





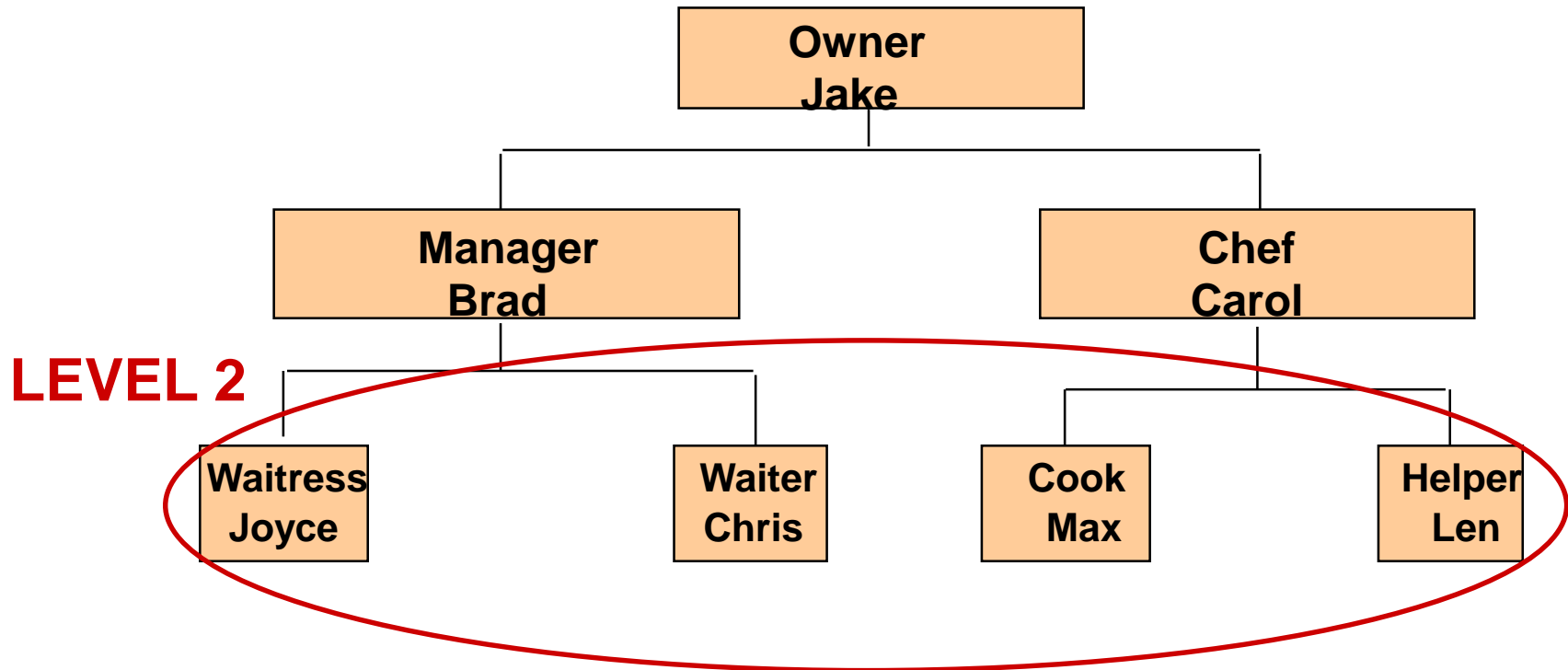
# Level One

**LEVEL 1**



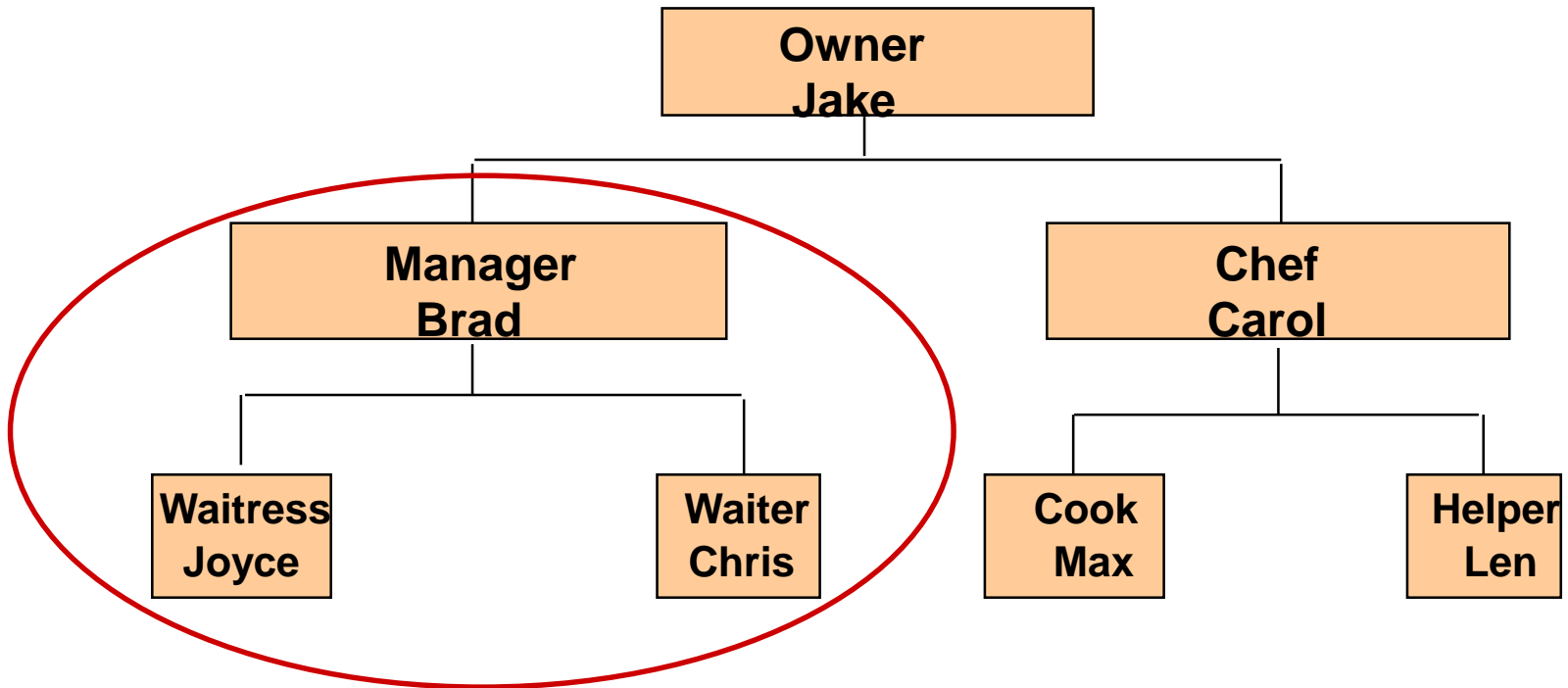


# Level Two





# A Subtree

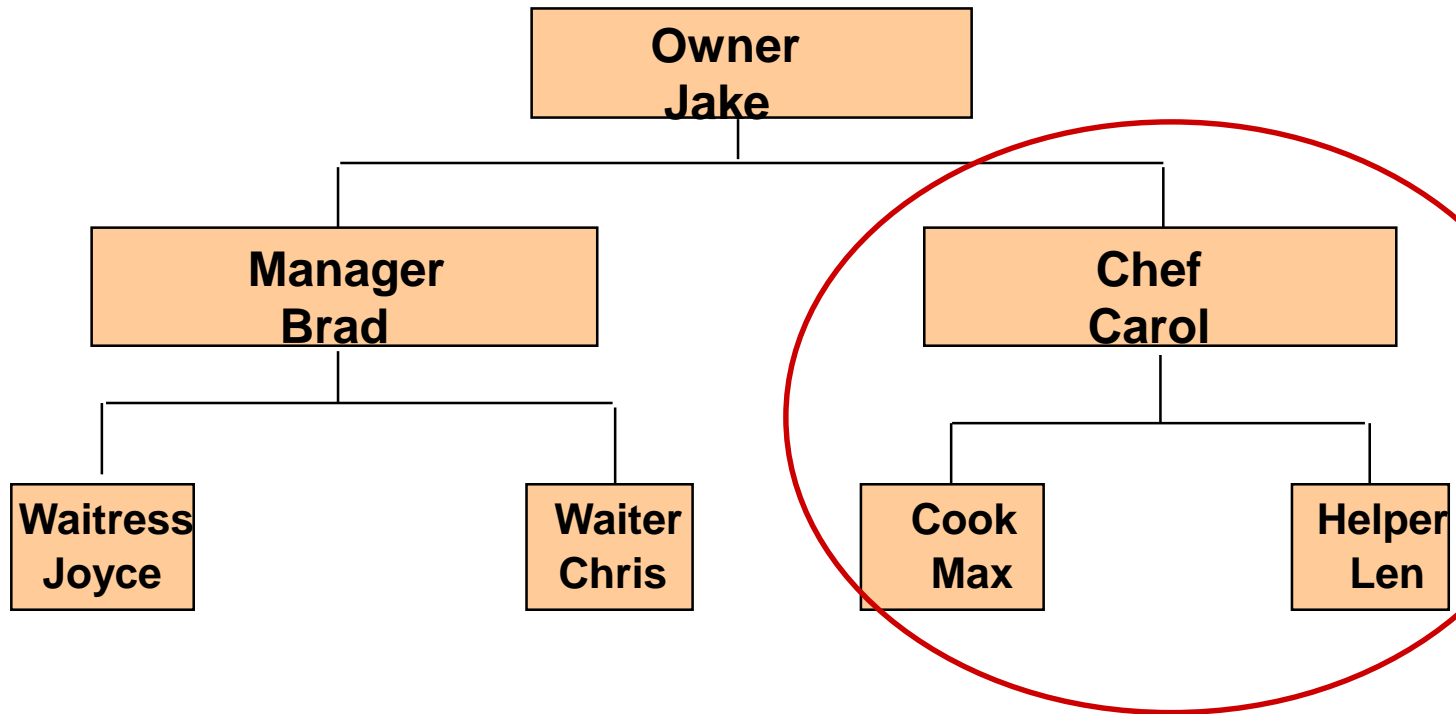


**LEFT SUBTREE OF ROOT NODE**





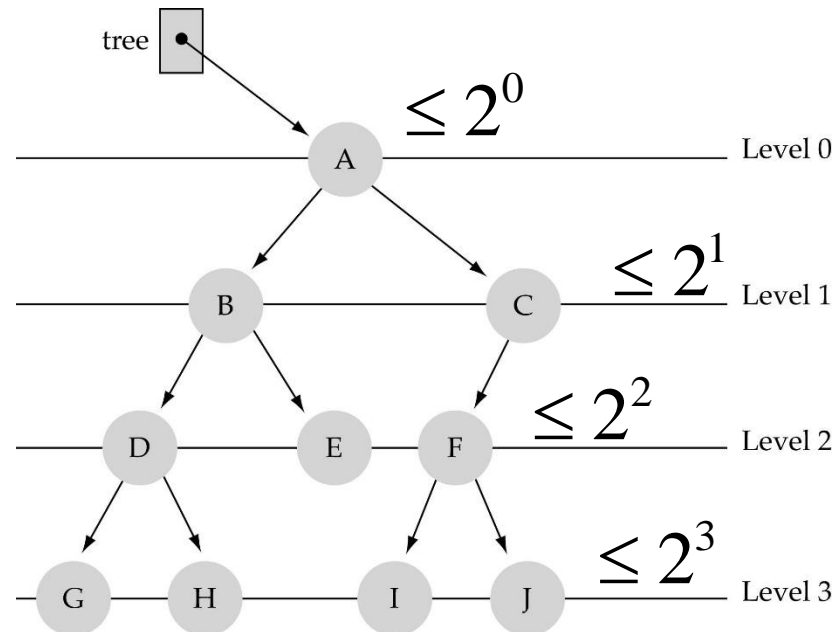
# Another Subtree



**RIGHT SUBTREE  
OF ROOT NODE**

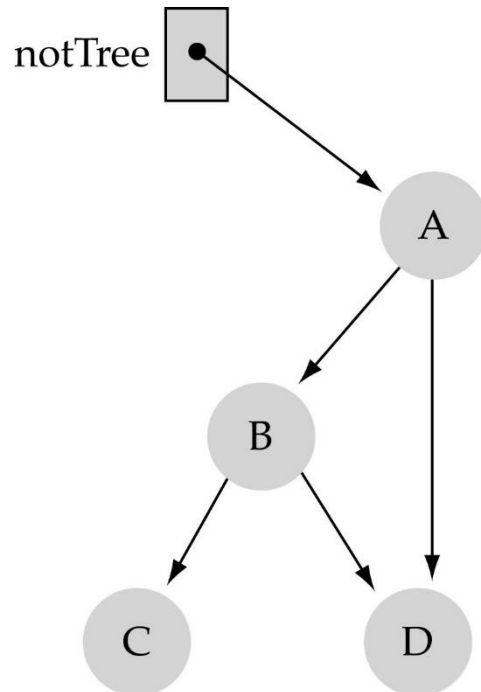
# What is a binary tree?

- *Property 1*: each node can have up to two successor nodes (*children*)
  - The predecessor node of a node is called its *parent*
  - The "beginning" node is called the *root* (no parent)
  - A node without *children* is called a *leaf*



# What is a binary tree? (cont.)

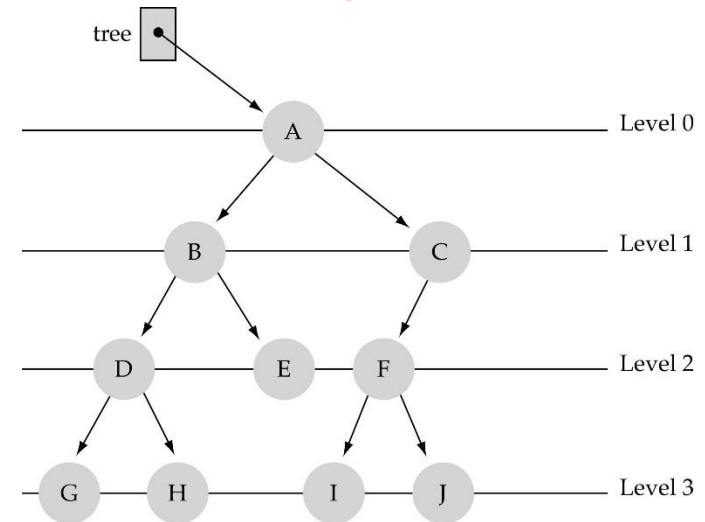
- *Property2*: a unique path exists from the root to every other node





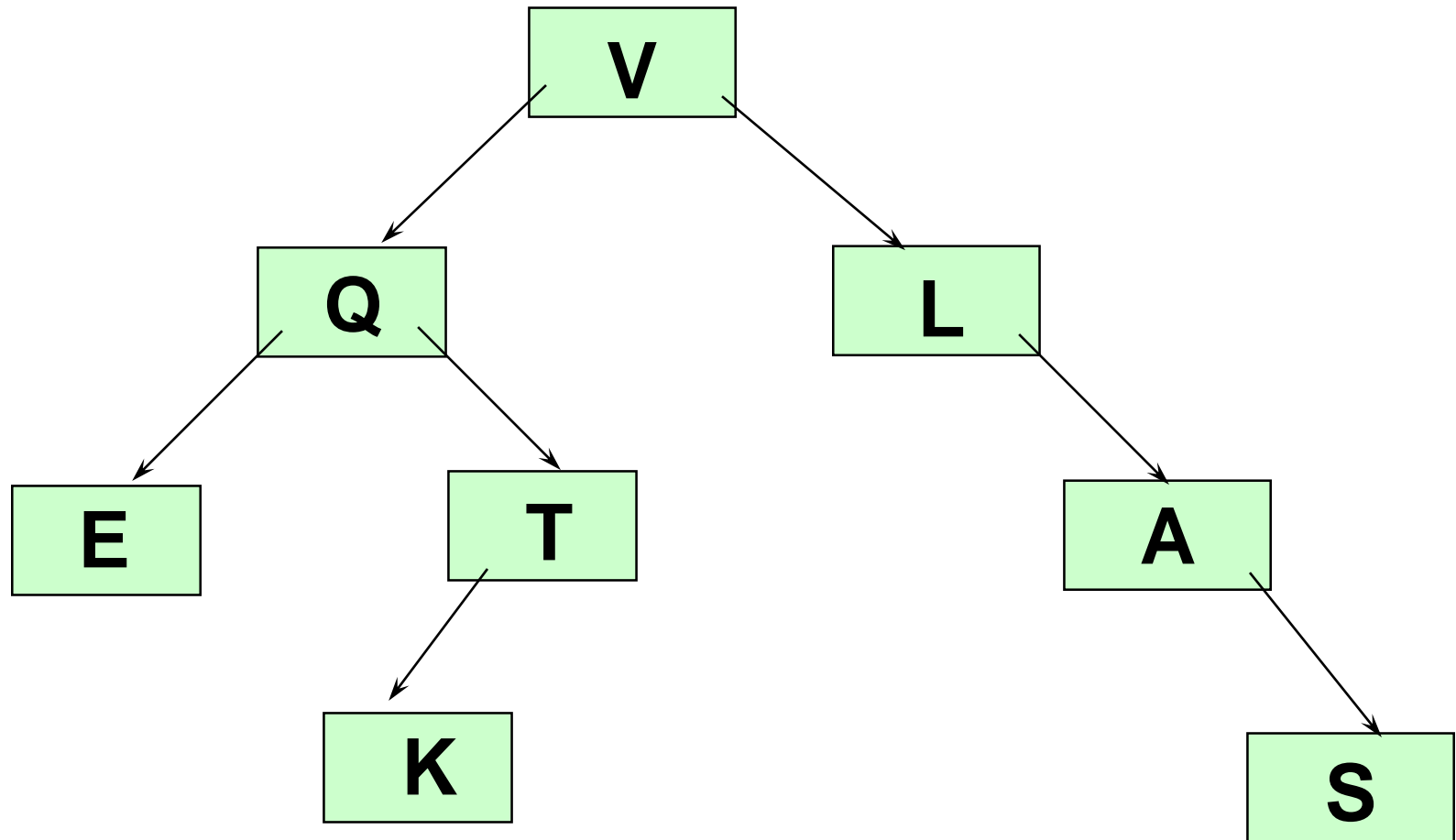
# Some terminology

- Ancestor of a node: any node on the path from the root to that node (parent, grandparent, ...)
- Descendant of a node: any node on a path from the node to the last node in the path (child, grandchild, ...)
- Level (depth) of a node: number of edges in the path from the root to that node
- Height of a tree: number of levels (**warning**: some books define it as  $\#levels - 1$ )



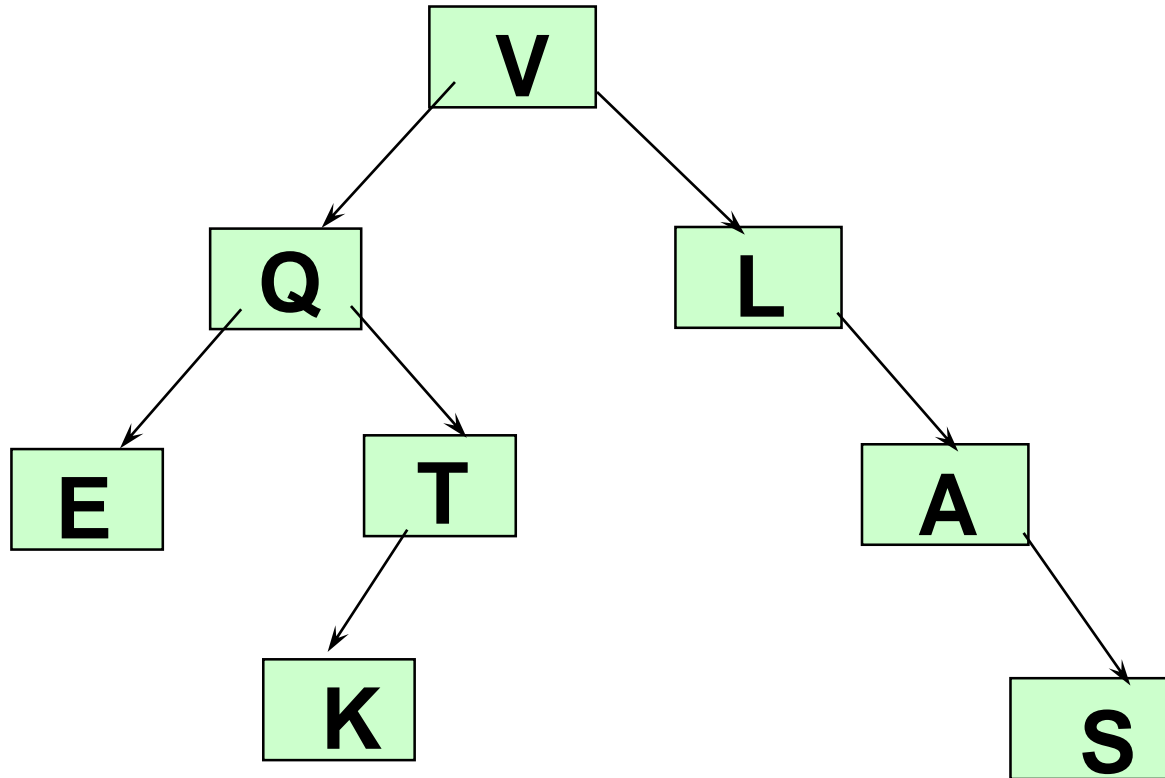


# A Binary Tree



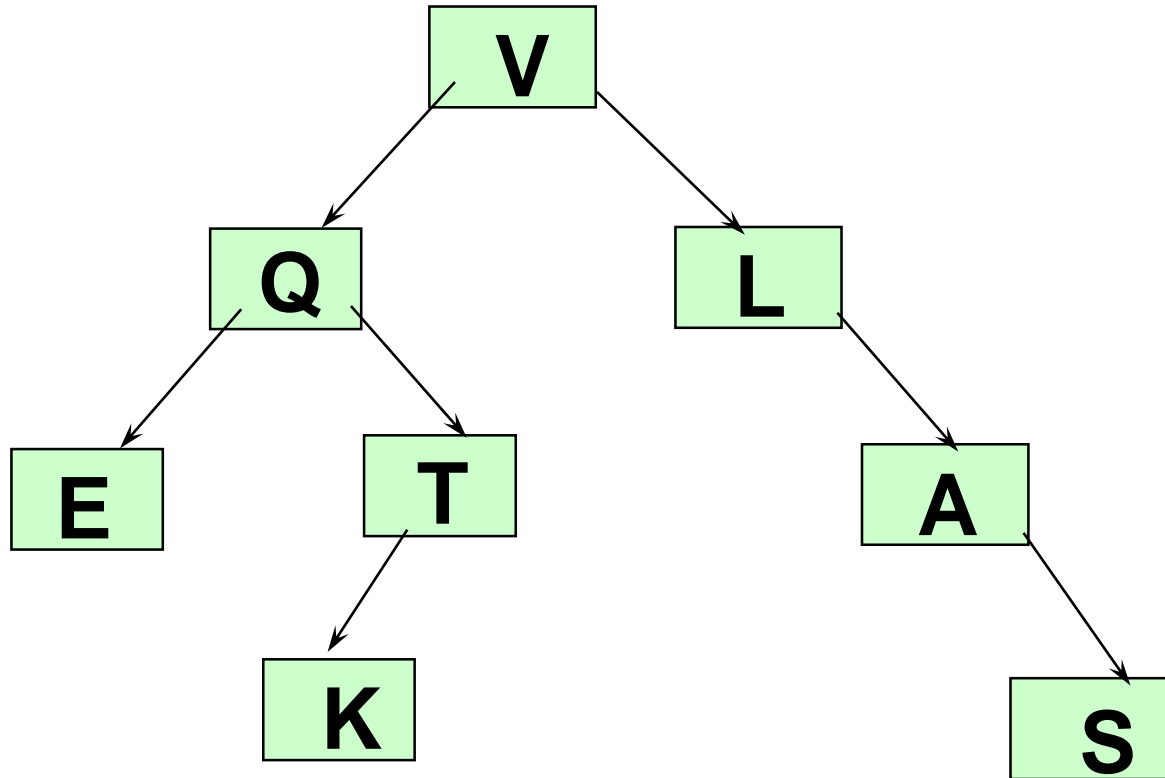


# How many leaf nodes?



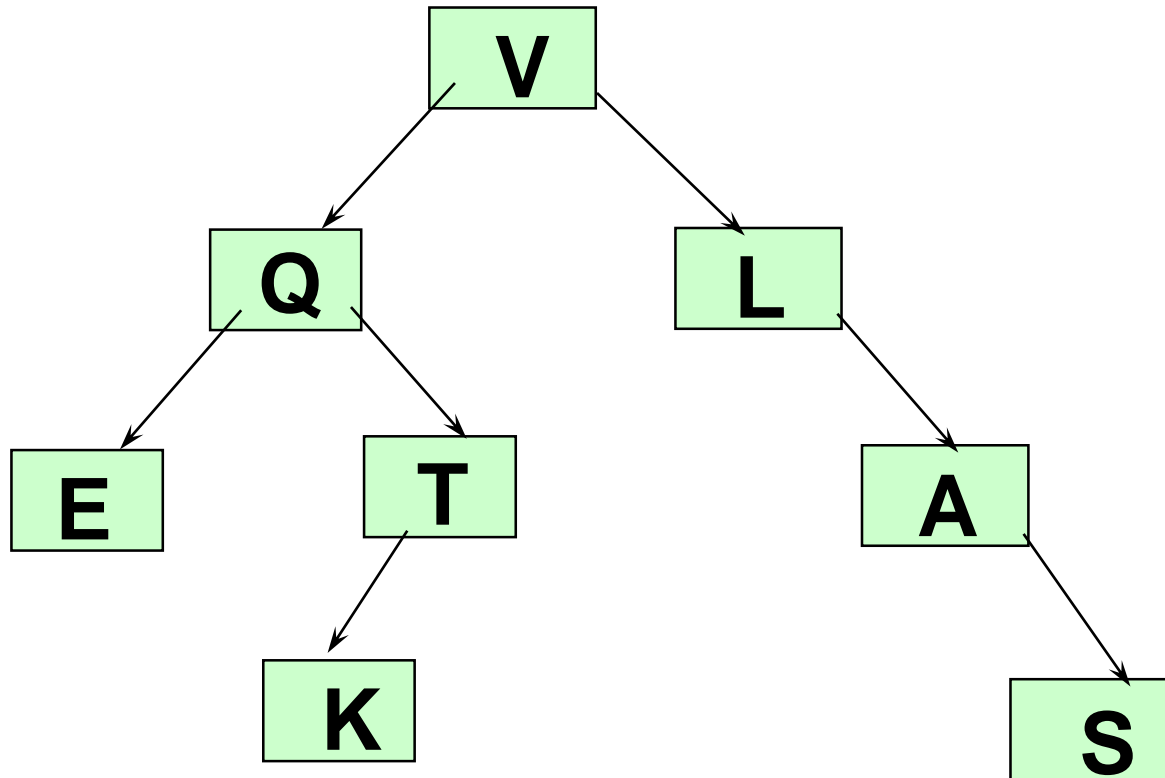


# How many descendants of Q?






# How many ancestors of K?







# What is the # of nodes $N$ of a full tree with height $h$ ?

full tree: a tree in which all of the leaves are on the same level and every nonleaf node has two children

The max #nodes at level  $l$  is  $2^l$

$$N = 2^0 + 2^1 + \dots + 2^{h-1} = 2^h - 1$$

$l=0$                    $l=1$                    $l=h-1$

using the geometric  
series:

$$x^0 + x^1 + \dots + x^{n-1} = \sum_{i=0}^{n-1} x^i = \frac{x^n - 1}{x - 1}$$



# What is the height $h$ of a full tree with $N$ nodes?

$$2^h - 1 = N$$

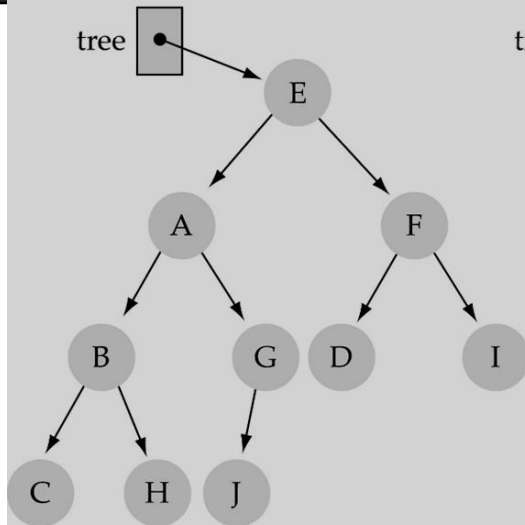
$$\Rightarrow 2^h = N + 1$$

$$\Rightarrow h = \log(N + 1) \rightarrow O(\log N)$$

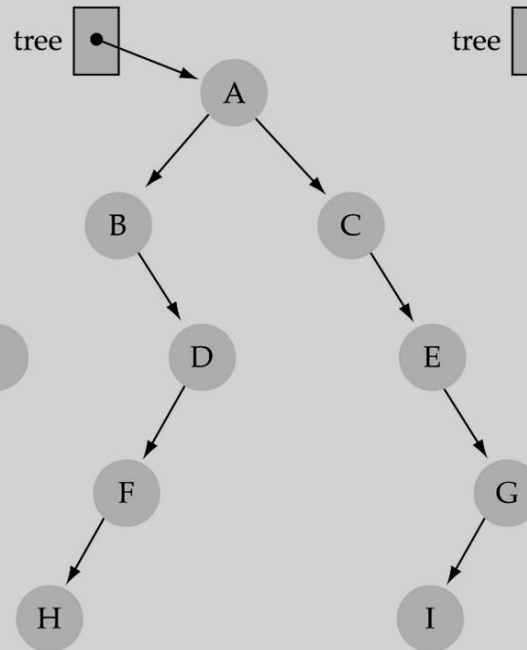
- The max height of a tree with  $N$  nodes is  $N$  (same as a linked list)
- The min height of a tree with  $N$  nodes is  $\log(N+1)$



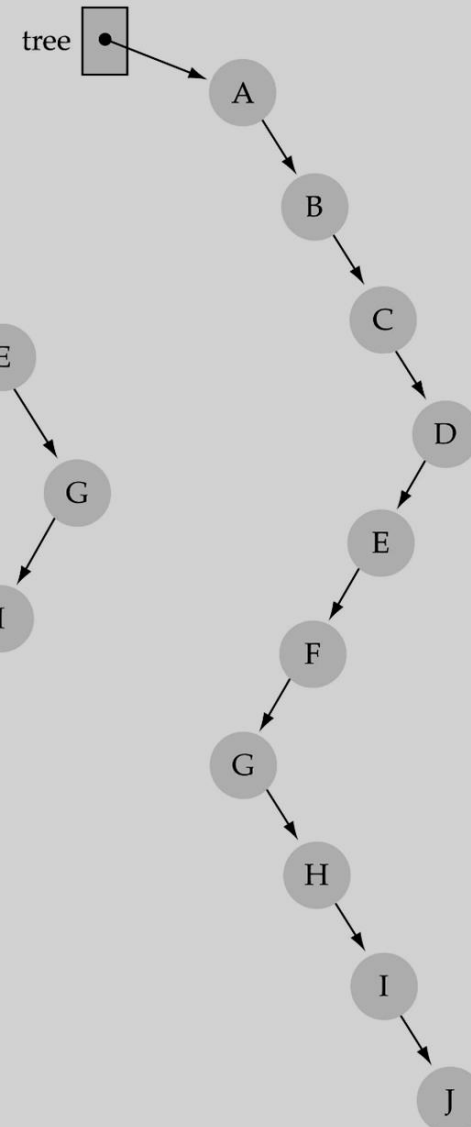
(a) A 4-level tree



(b) A 5-level tree



(c) A 10-level tree





# Searching a binary tree

- (1) Start at the root
- (2) Search the tree level by level, until you find the element you are searching for ( $O(N)$  time in worst case)

Is this better than searching a linked list?

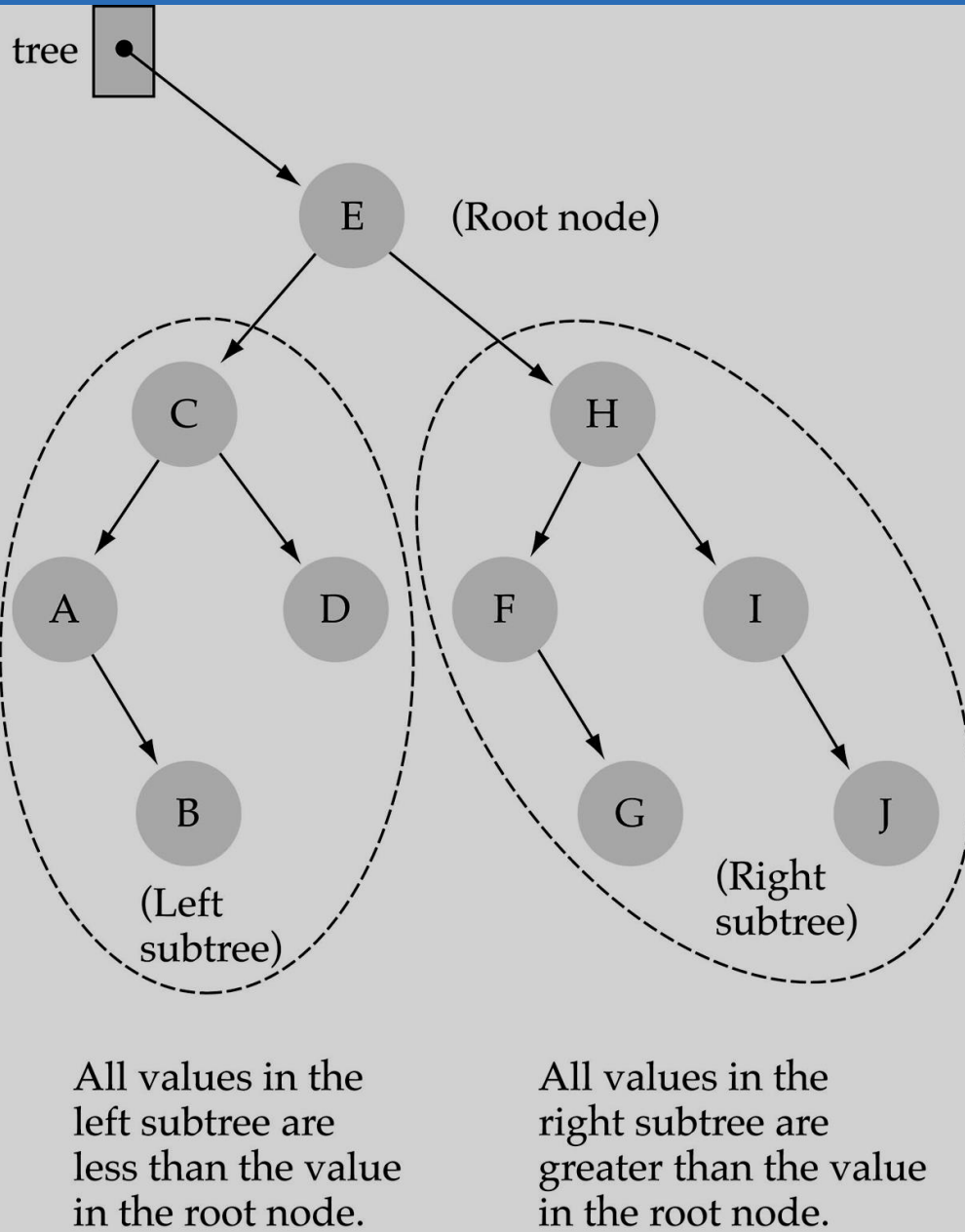
No --->  $O(N)$



# A Binary Search Tree (BST) is . . .

**A special kind of binary tree in which:**

- 1. Each node contains a distinct data value,**
- 2. The key values in the tree can be compared using “greater than” and “less than”, and**
- 3. The key value of each node in the tree is**  
**less than every key value in its right subtree, and**  
**greater than every key value in its left subtree.**





# Shape of a binary search tree . . .

**Depends on its key values and their order of insertion.**

**Insert the elements 'J' 'E' 'F' 'T' 'A' in that order.**

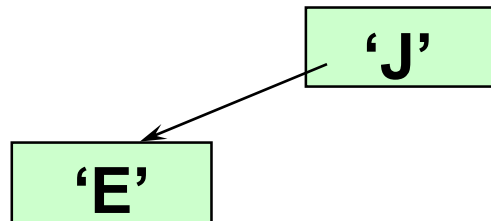
**The first value to be inserted is put into the root node.**

**'J'**



# Inserting 'E' into the BST

Thereafter, each value to be inserted begins by comparing itself to the value in the root node, moving left if it is less, or moving right if it is greater. This continues at each level until it can be inserted as a new leaf.

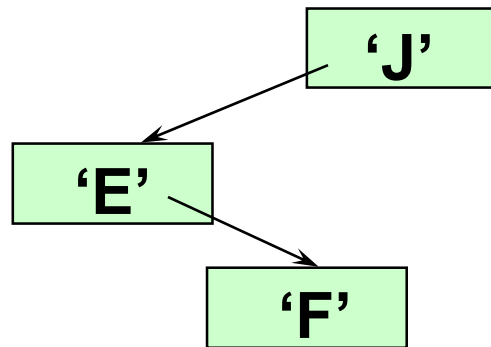






# Inserting 'F' into the BST

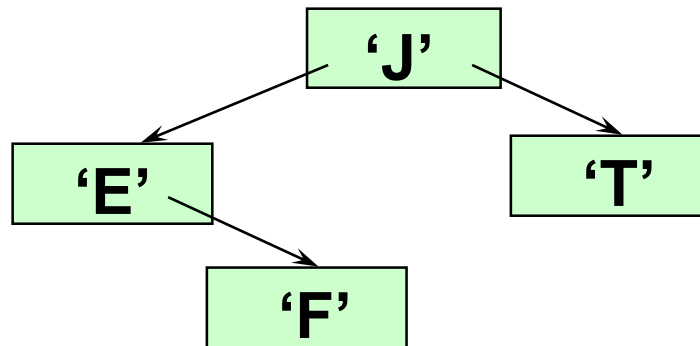
**Begin by comparing 'F' to the value in the root node, moving left if it is less, or moving right if it is greater. This continues until it can be inserted as a leaf.**





# Inserting 'T' into the BST

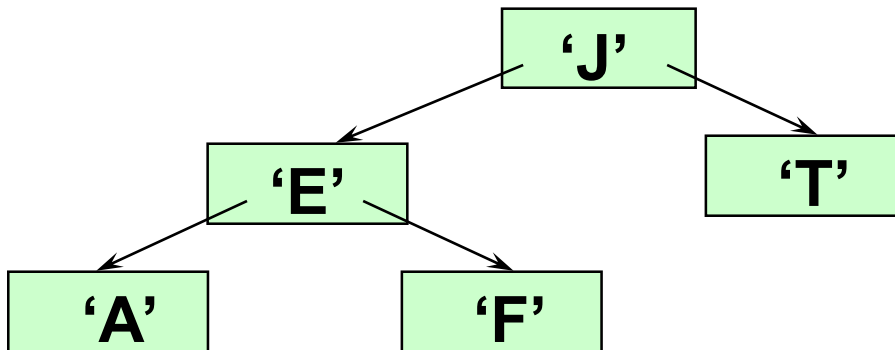
**Begin by comparing 'T' to the value in the root node, moving left if it is less, or moving right if it is greater. This continues until it can be inserted as a leaf.**





# Inserting 'A' into the BST

**Begin by comparing 'A' to the value in the root node, moving left if it is less, or moving right if it is greater. This continues until it can be inserted as a leaf.**





# What binary search tree . . .

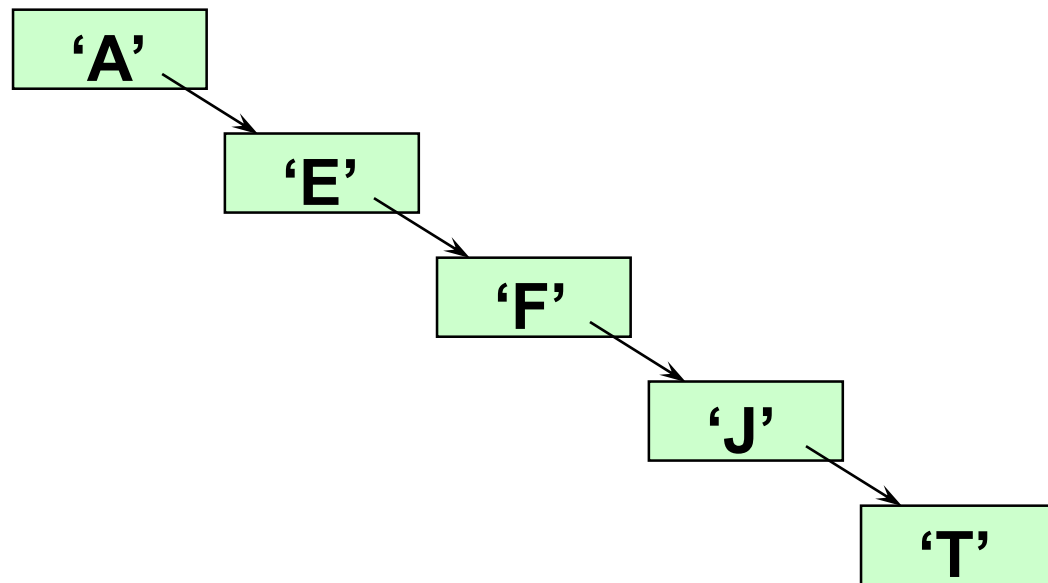
is obtained by inserting  
the elements 'A' 'E' 'F' 'J' 'T' in that order?

'A'



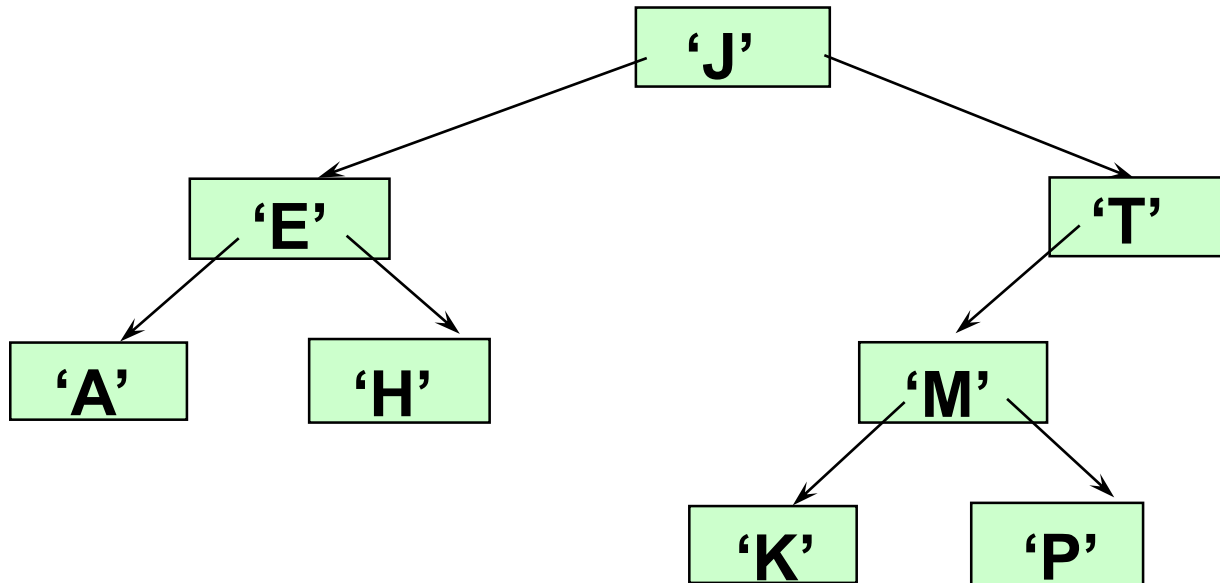
# Binary search tree . . .

obtained by inserting  
the elements 'A' 'E' 'F' 'J' 'T' in that order.





# Another binary search tree

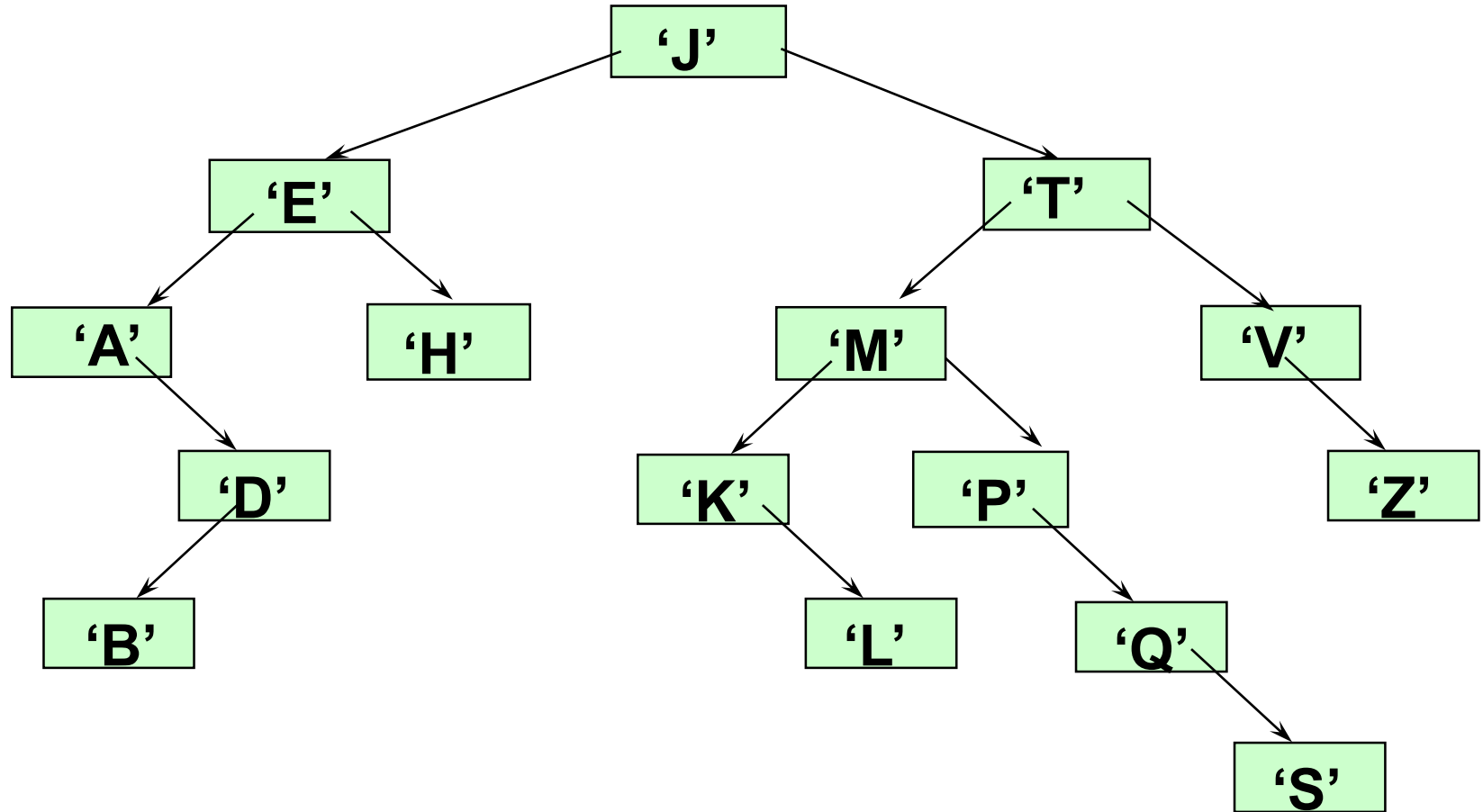


**Add nodes containing these values in this order:**

**'D'   'B'   'L'   'Q'   'S'   'V'   'Z'**



# Is 'F' in the binary search tree?





# Searching a binary search tree

- (1) Start at the root
- (2) Compare the value of the item you are searching for with the value stored at the root
- (3) If the values are equal, then *item found*; otherwise, if it is a leaf node, then *not found*





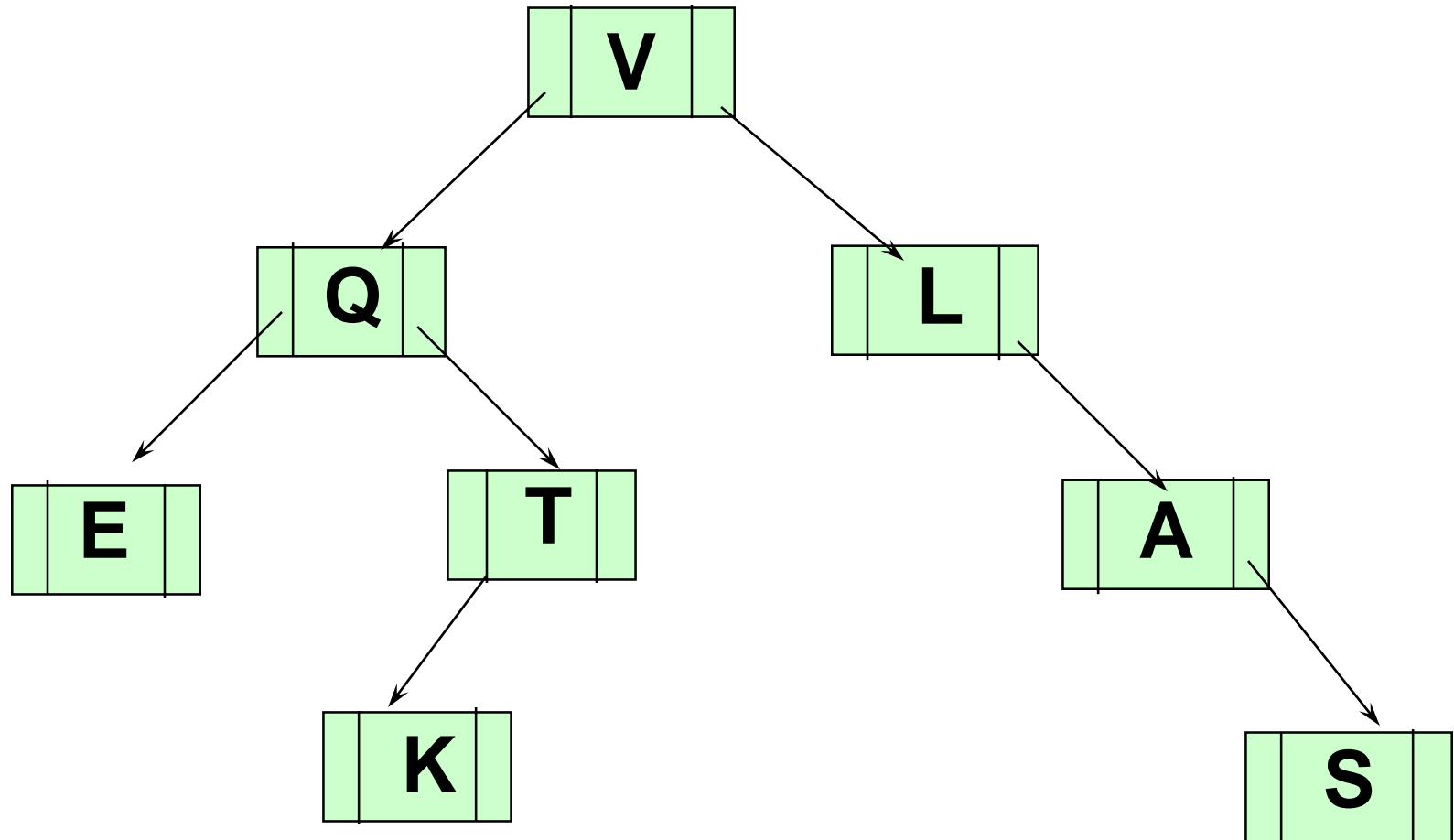
# Searching a binary search tree (cont.)

- (4) If it is less than the value stored at the root, then search the left subtree
- (5) If it is greater than the value stored at the root, then search the right subtree
- (6) Repeat steps 2-6 for the root of the subtree chosen in the previous step 4 or 5

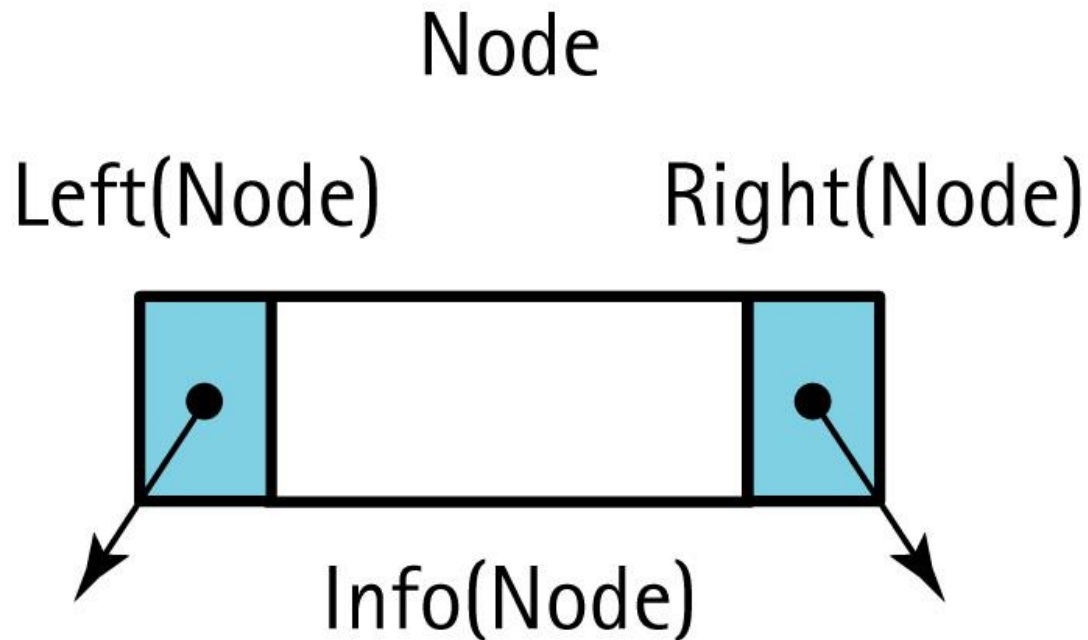
Is this better than searching a linked list?

Yes !! --->  $O(\log N)$

# Implementing a Binary Tree with Pointers and Dynamic Data



# Node Terminology for a Tree Node



```
template<class ItemType>
struct TreeNode {
    ItemType info;
    TreeNode* left;
    TreeNode* right; };

```



# Binary Search Tree Specification

```
#include <fstream.h>

template<class ItemType>
struct TreeNode;

enum OrderType {PRE_ORDER, IN_ORDER, POST_ORDER};

template<class ItemType>
class TreeType {
public:
    TreeType();
    ~TreeType();
    TreeType(const TreeType<ItemType>&);
    void operator=(const TreeType<ItemType>&);
```

(continues)



# Binary Search Tree Specification

(cont.)

```
void MakeEmpty();
bool IsEmpty() const;
bool IsFull() const;
int LengthIs() const;
void RetrieveItem(ItemType&, bool& found);
void InsertItem(ItemType);
void DeleteItem(ItemType);
void ResetTree(OrderType);
void GetNextItem(ItemType&, OrderType, bool&);
void PrintTree(ofstream&) const;
private:
    TreeNode<ItemType>* root;
};
```



# Functions IsFull( ) & IsEmpty( )

```
bool TreeType::IsFull() const
{
    NodeType* location;
    try
    {
        location = new NodeType;
        delete location;
        return false;
    }
    catch(std::bad_alloc exception)
    {
        return true;
    }
}

bool TreeType::IsEmpty() const
{
    return root == NULL;
}
```



# Function CountNodes

- Recursive implementation
  - #nodes in a tree =  
#nodes in left subtree + #nodes in right subtree + 1
- What is the size factor?
  - Number of nodes in the tree we are examining
- What is the base case?
  - The tree is empty
- What is the general case?
  - $\text{CountNodes}(\text{Left}(\text{tree})) + \text{CountNodes}(\text{Right}(\text{tree})) + 1$



# CountNodes Version 1

```
if (Left(tree) is NULL) AND (Right(tree) is NULL)
```

```
    return 1
```

```
else
```

```
    return CountNodes(Left(tree)) +  
           CountNodes(Right(tree)) + 1
```

**What happens when Left(tree) is NULL?**





## CountNodes Version 2

```
if (Left(tree) is NULL) AND (Right(tree) is NULL)
    return 1
else if Left(tree) is NULL
    return CountNodes(Right(tree)) + 1
else if Right(tree) is NULL
    return CountNodes(Left(tree)) + 1
else return CountNodes(Left(tree)) +
    CountNodes(Right(tree)) + 1
```

**What happens when the initial tree is NULL?**



# CountNodes Version 3

**if tree is NULL**

**return 0**

**else if (Left(tree) is NULL) AND (Right(tree) is NULL)**

**return 1**

**else if Left(tree) is NULL**

**return CountNodes(Right(tree)) + 1**

**else if Right(tree) is NULL**

**return CountNodes(Left(tree)) + 1**

**else return CountNodes(Left(tree)) +**

**CountNodes(Right(tree)) + 1**

**Can we simplify this algorithm?**



# CountNodes Version 4

if tree is NULL

    return 0

else

    return CountNodes(Left(tree)) +  
        CountNodes(Right(tree)) + 1

Is that all there is?



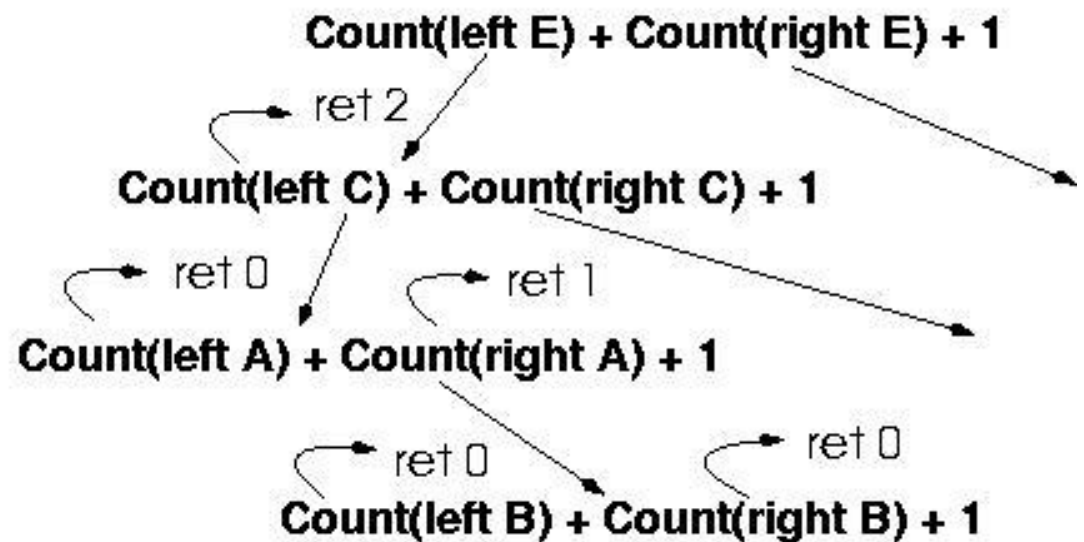
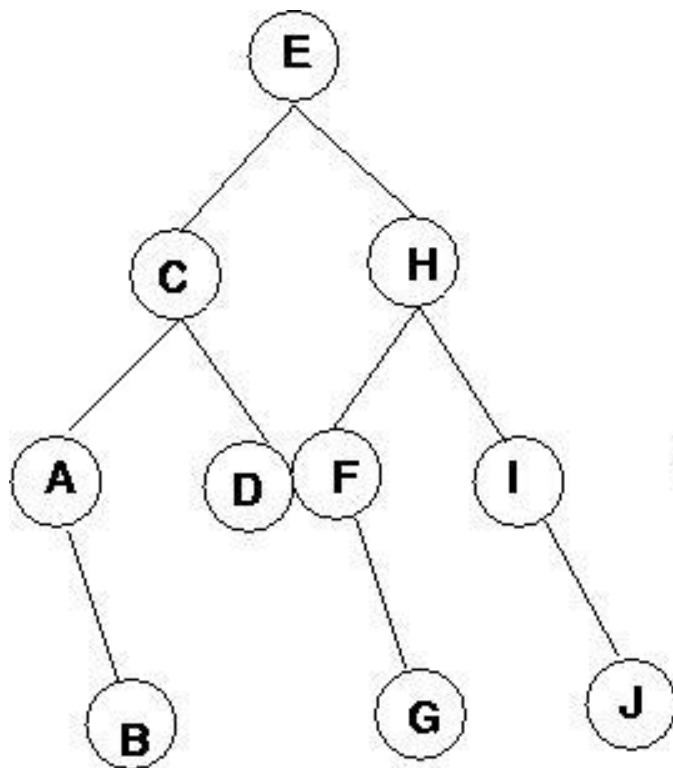
# Function Lengths()

```
// Implementation of Final Version
int CountNodes(TreeNode* tree); // Pototype
int TreeType::LengthIs() const
// Class member function
{
    return CountNodes(root);
}

int CountNodes(TreeNode* tree)
// Recursive function that counts the nodes
{
    if (tree == NULL)
        return 0;
    else
        return CountNodes(tree->left) +
               CountNodes(tree->right) + 1;
}
```



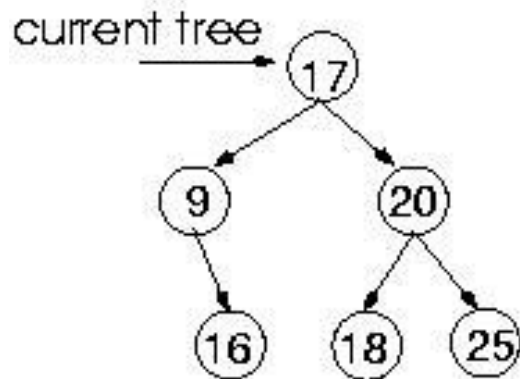
Let's consider the first few steps:



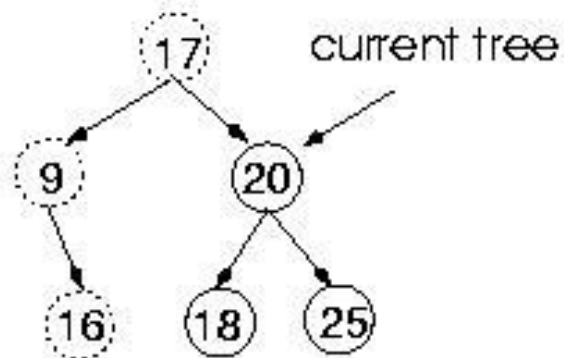
# Function RetrievalItem

**Retrieve: 18**

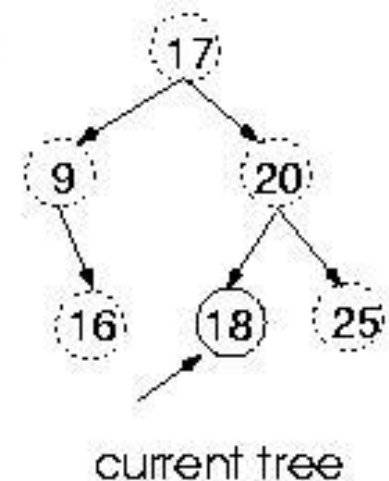
**Compare 18 with 17:  
Choose right subtree**



**Compare 18 with 20:  
Choose left subtree**



**Compare 18 with 18:  
Found !!**





# Function Retrieval Item

- What is the size of the problem?  
Number of nodes in the tree we are examining
- What is the base case(s)?
  - 1) When the key is found
  - 2) The tree is empty (key was not found)
- What is the general case?  
Search in the left or right subtrees



# Retrieval Operation

```
void TreeType::RetrieveItem(ItemType& item, bool& found)
{
    Retrieve(root, item, found);
}
```

```
void Retrieve(TreeNode* tree,
    ItemType& item, bool& found)
{
    if (tree == NULL)    // base case 2
        found = false;
    else if (item < tree->info)
        Retrieve(tree->left, item, found);
}
```





## Retrieval Operation, cont.

```
else if (item > tree->info)
    Retrieve(tree->right, item, found);
else // base case 1
{
    item = tree->info;
    found = true;
}
}
```



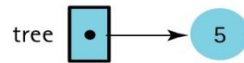
# The Insert Operation

- A new node is always inserted into its appropriate position in the tree as a leaf.

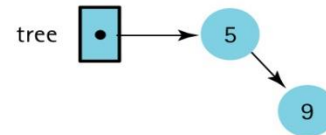
# Insertions into a Binary Search Tree

(a) tree 

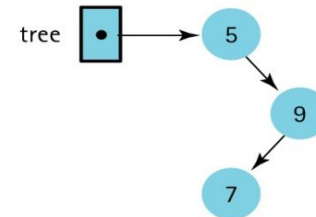
(b) Insert 5



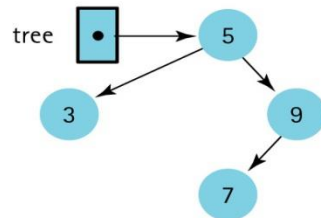
(c) Insert 9



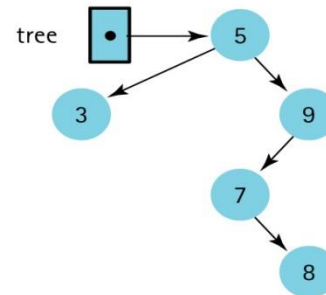
(d) Insert 7



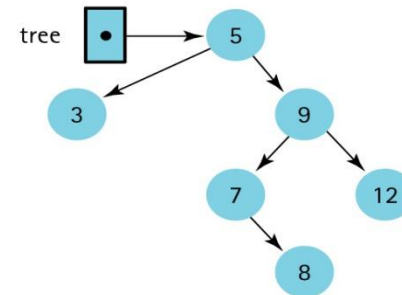
(e) Insert 3



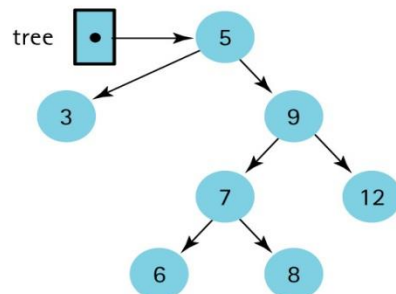
(f) Insert 8



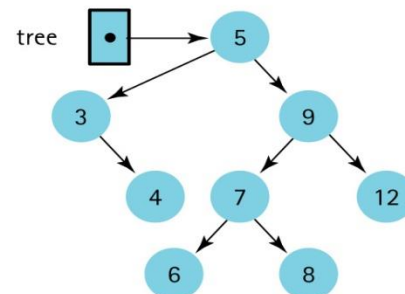
(g) Insert 12



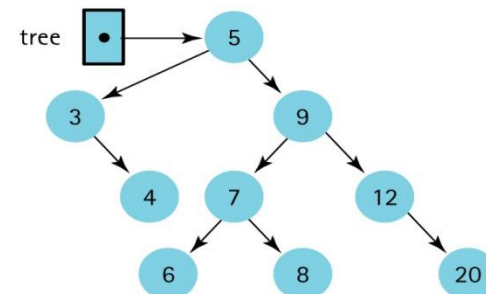
(h) Insert 6



(i) Insert 4



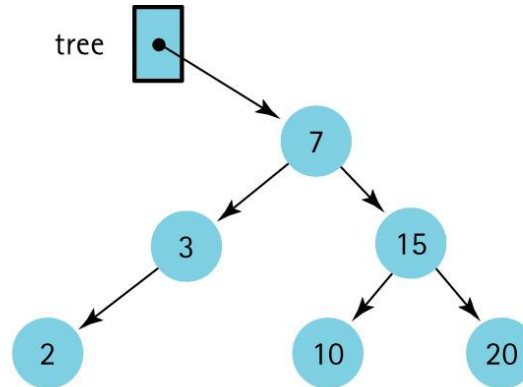
(j) Insert 20



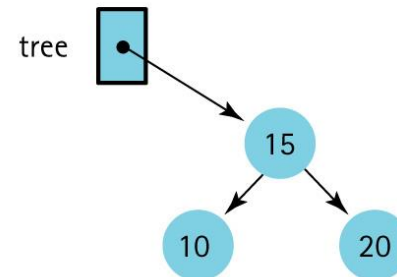
# The recursive InsertItem operation

insert 11

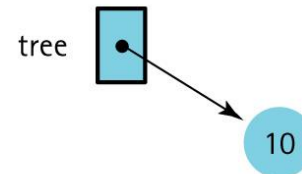
(a) The initial call



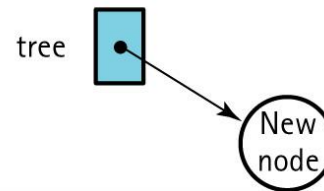
(b) The first recursive call



(c) The second recursive call

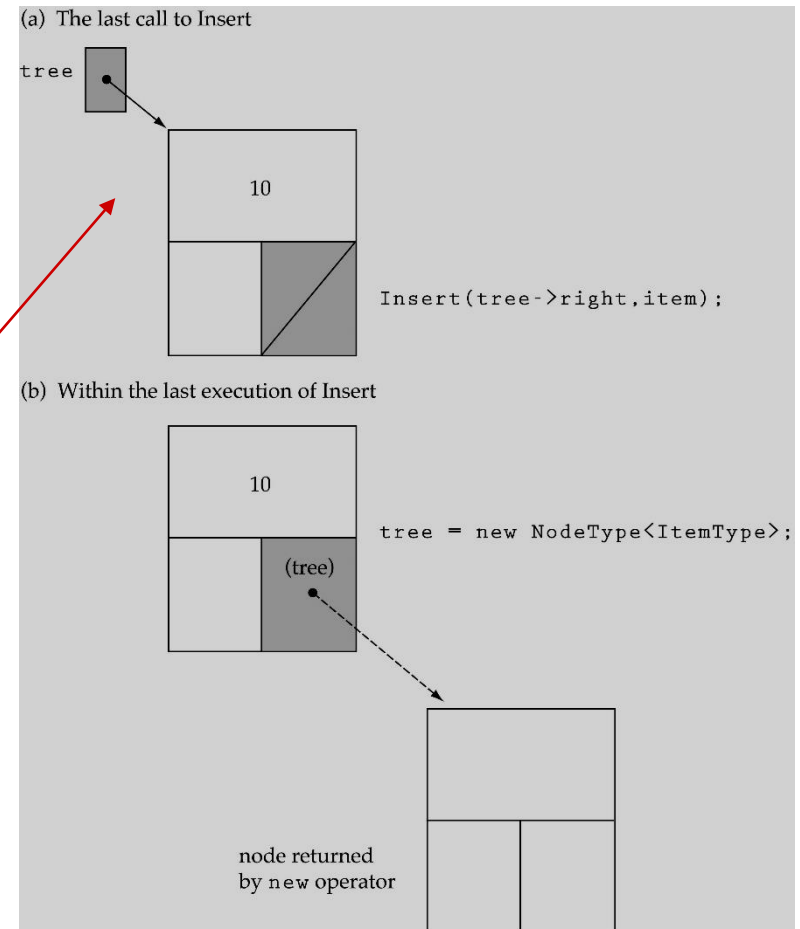
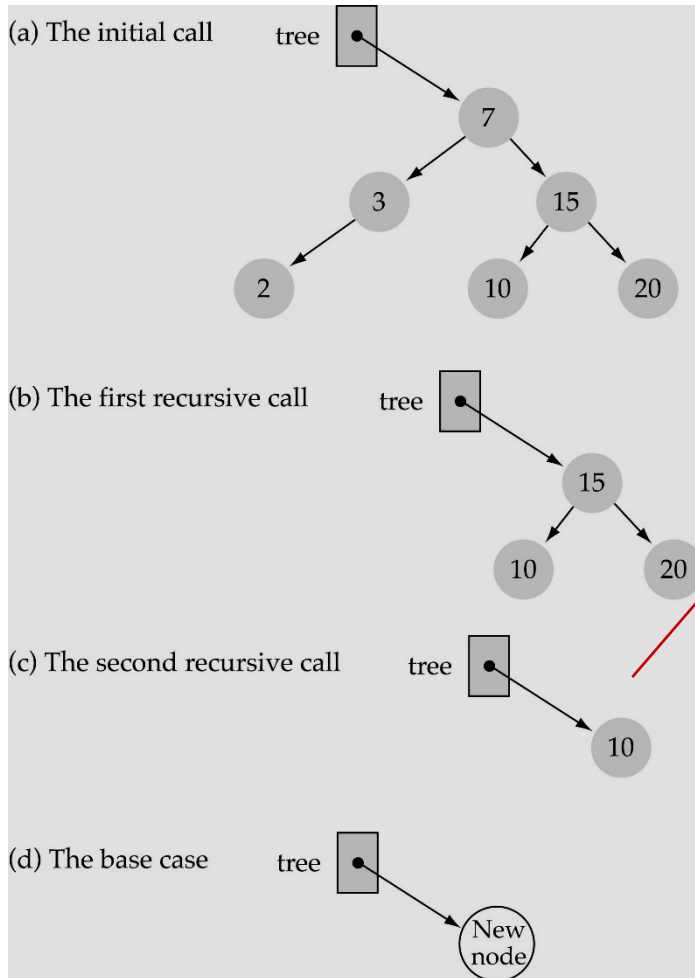


(d) The base case



# The tree parameter is a pointer within the tree

## Insert 11





# Recursive Insert

```
void Insert(TreeNode*& tree, ItemType item)
{
    if (tree == NULL)
    { // Insertion place found.
        tree = new TreeNode;
        tree->right = NULL;
        tree->left = NULL;
        tree->info = item;
    }
    else if (item < tree->info)
        Insert(tree->left, item);
    else
        Insert(tree->right, item);
}
```

referenc  
e type



# Does the order of inserting elements into a tree matter?

- Yes, certain orders produce very unbalanced trees!!
- Unbalanced trees are not desirable because search time increases!!
- There are advanced tree structures (e.g., "**red-black trees**") which guarantee balanced trees

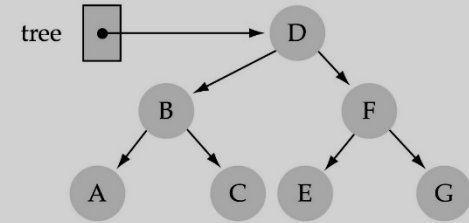


Does the order of  
inserting  
elements into a  
tree matter?

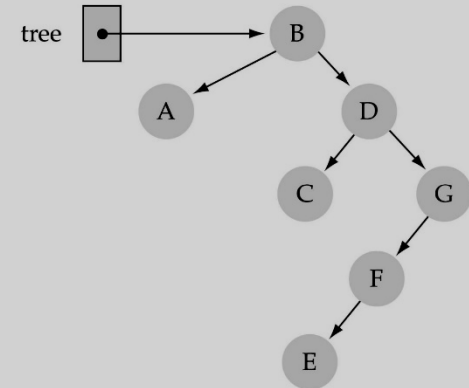
Yes!!!

A random mix of  
the elements  
produces a  
shorter, “bushy”  
tree

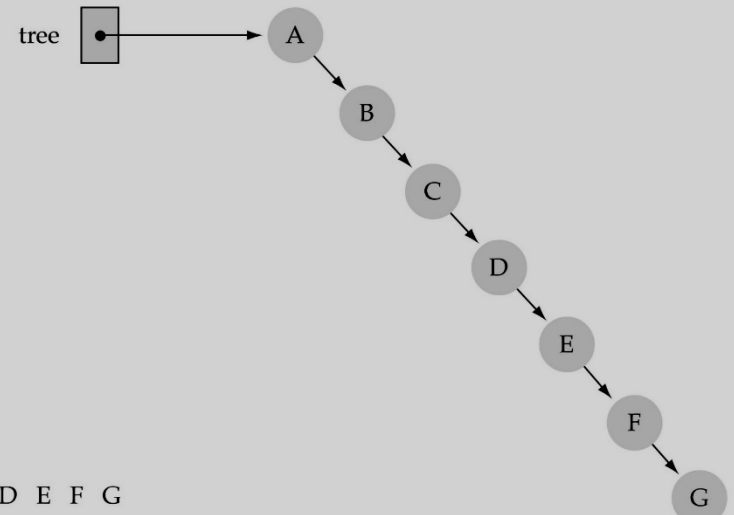
(a) Input: D B F A C E G



(b) Input: B A D C G F E



(c) Input: A B C D E F G



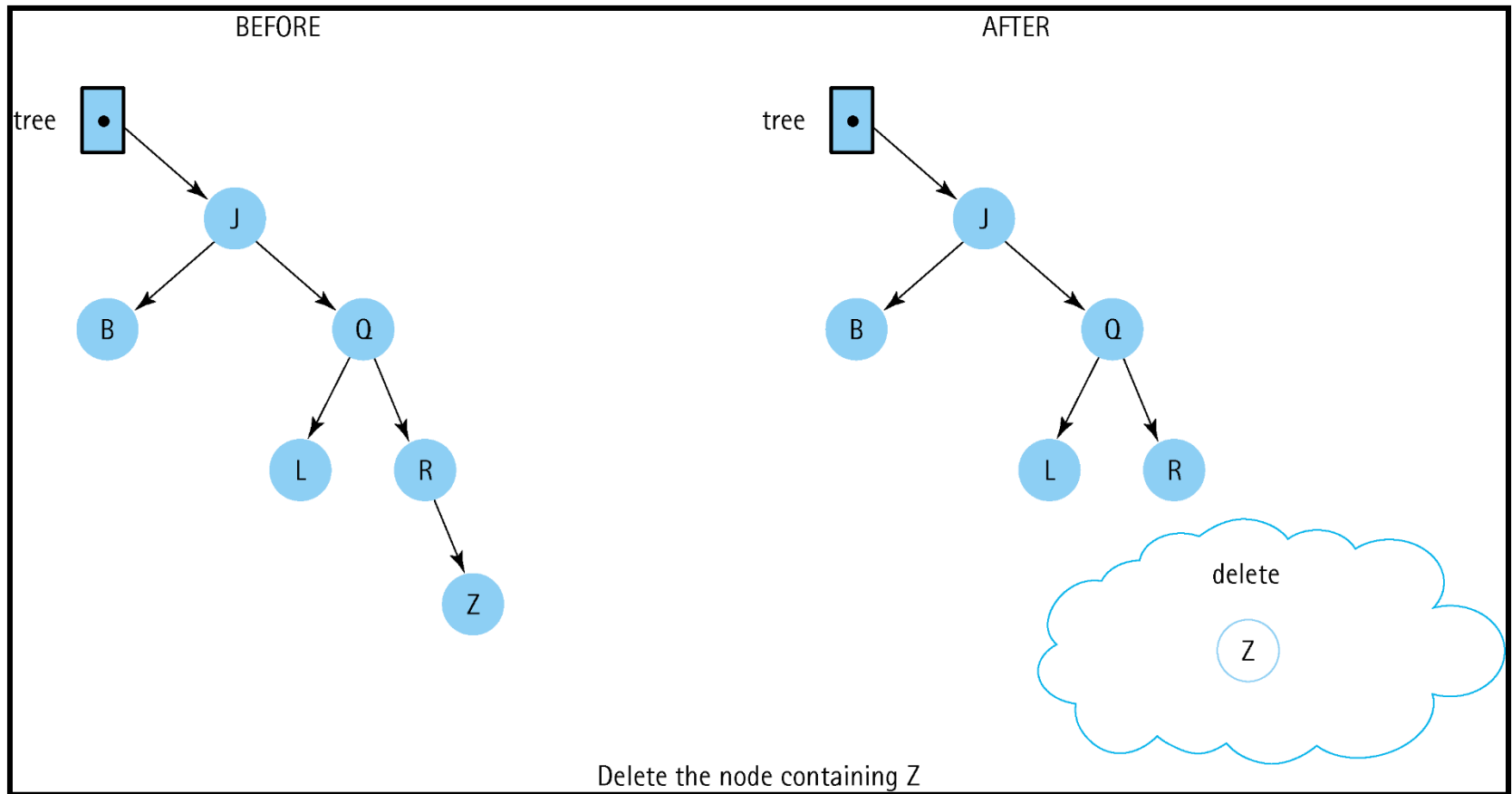




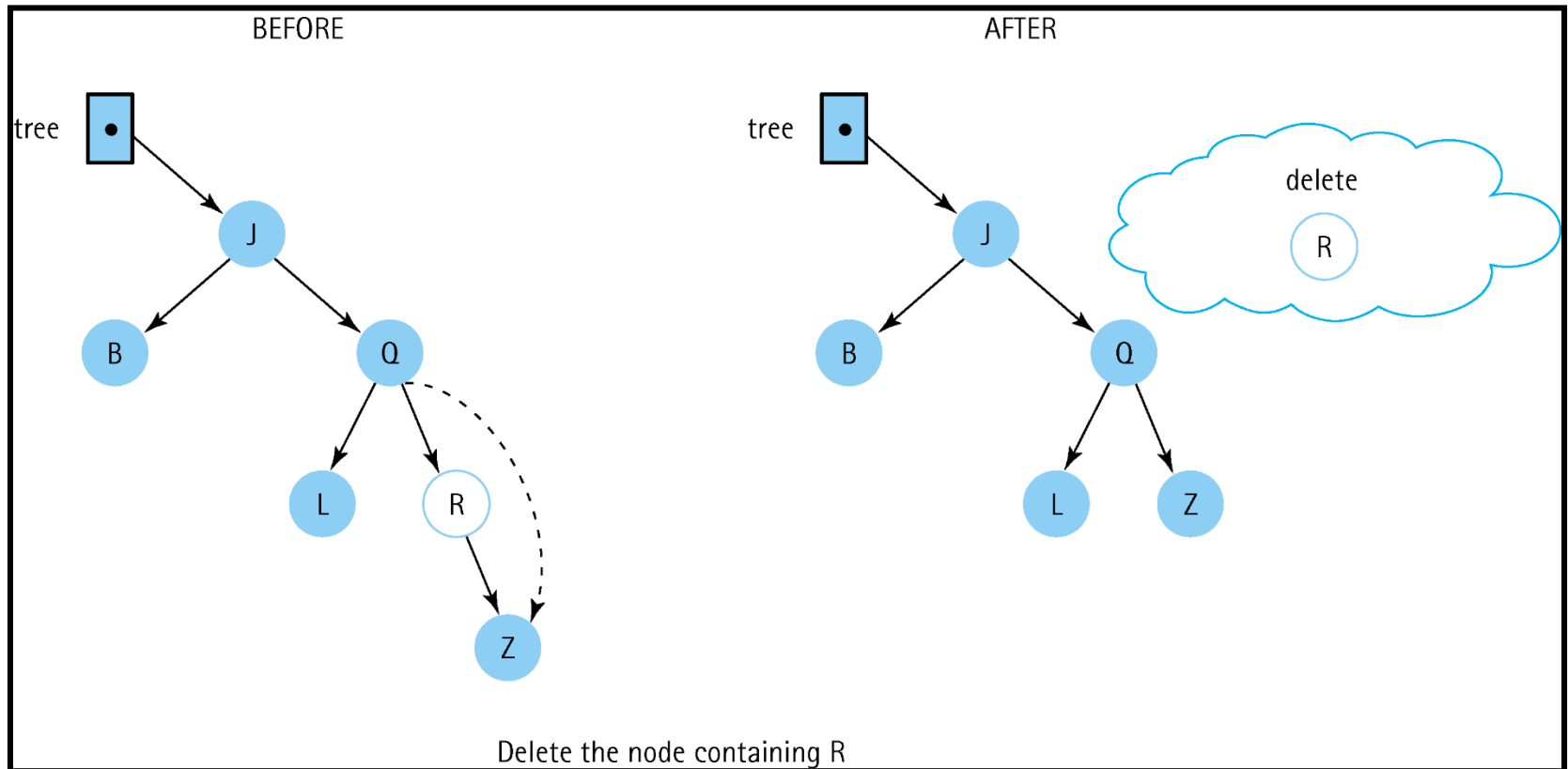
# Function DeleteItem

- First, find the item; then, delete it
- Important: binary search tree property must be preserved!!
- We need to consider three different cases:
  - (1) Deleting a leaf
  - (2) Deleting a node with only one child
  - (3) Deleting a node with two children

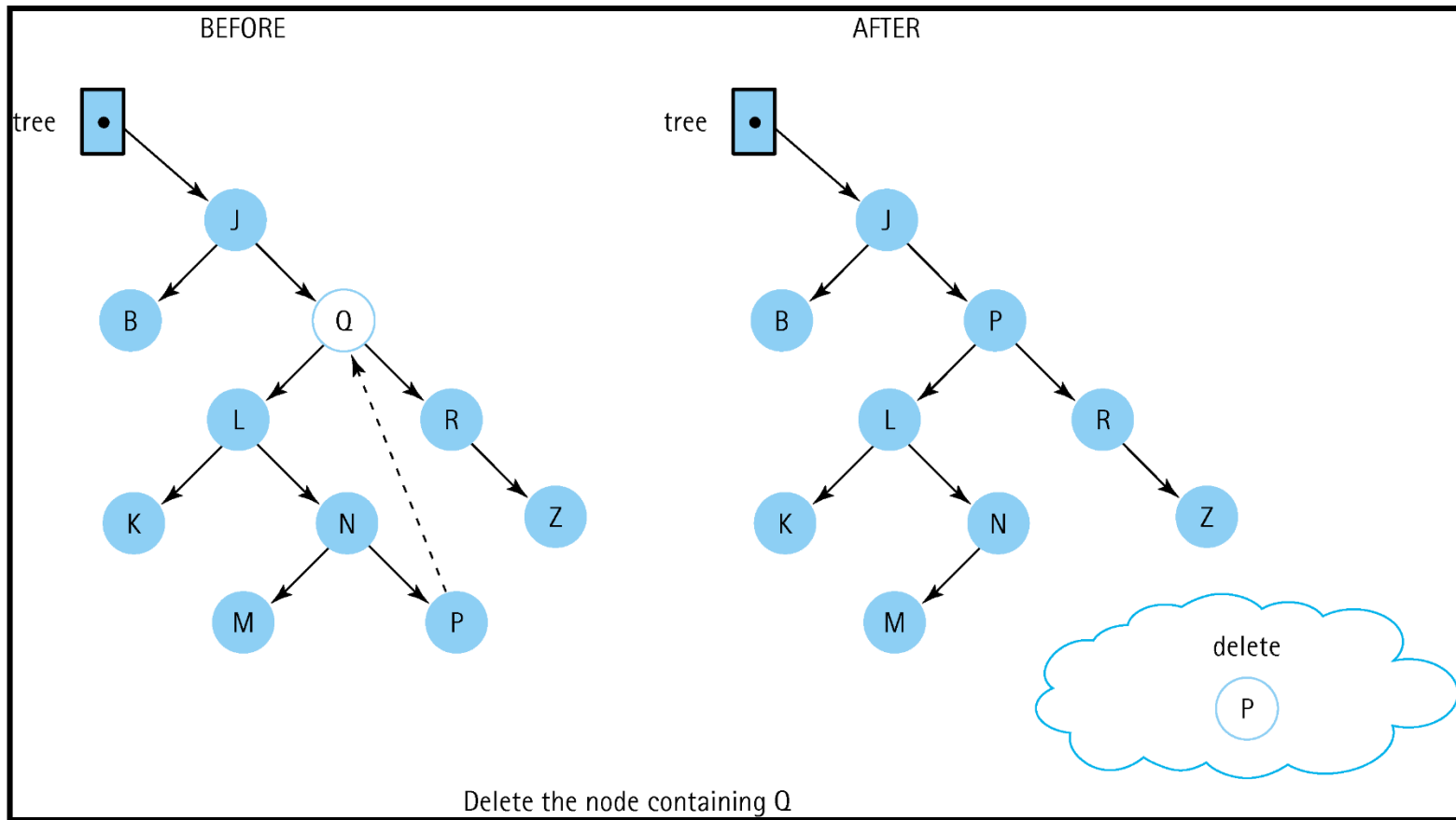
# Deleting a Leaf Node



# Deleting a Node with One Child



# Deleting a Node with Two Children





## Deleting a Node with Two Children (cont'd)

- Find predecessor (it is the rightmost node in the left subtree)
- Replace the data of the node to be deleted with predecessor's data
- Delete predecessor node



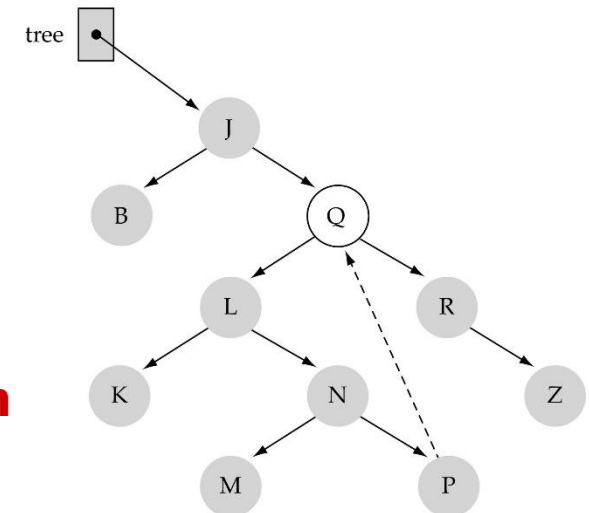
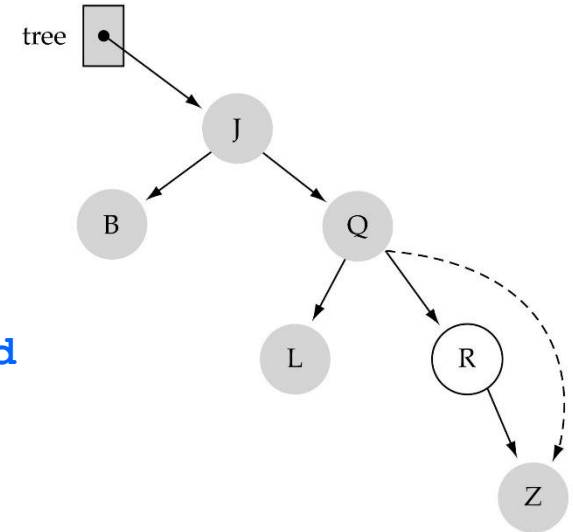
# DeleteNode Algorithm

```
if (Left(tree) is NULL) AND (Right(tree) is NULL)
    Set tree to NULL
else if Left(tree) is NULL
    Set tree to Right(tree)
else if Right(tree) is NULL
    Set tree to Left(tree)
else
    Find predecessor
    Set Info(tree) to Info(predecessor)
    Delete predecessor
```



# Code for DeleteNode

```
void DeleteNode(TreeNode*& tree)
{
    ItemType data;
    TreeNode* tempPtr;
    tempPtr = tree;
    if (tree->left == NULL) { //right child
        tree = tree->right;
        delete tempPtr; }      0 or 1 child
    else if (tree->right == NULL) { //left child
        tree = tree->left;
        delete tempPtr; }      0 or 1 child
    else{
        GetPredecessor(tree->left, data);
        tree->info = data;
        Delete(tree->left, data); } 2 children
}
```





# Definition of Recursive Delete

**Definition:** Removes item from tree

**Size:** The number of nodes in the path from the root to the node to be deleted.

**Base Case:** If item's key matches key in Info(tree), delete node pointed to by tree.

**General Case:** If item < Info(tree),  
Delete(Left(tree), item);  
else  
Delete(Right(tree), item).





# Code for Recursive Delete

```
void Delete(TreeNode*& tree, ItemType
    item)
{
    if (item < tree->info)
        Delete(tree->left, item);
    else if (item > tree->info)
        Delete(tree->right, item);
    else
        DeleteNode(tree); // Node found
}
```



# Code for GetPredecessor

```
void GetPredecessor(TreeNode* tree,
    ItemType& data)
{
    while (tree->right != NULL)
        tree = tree->right;
    data = tree->info;
}
```

*Why is the code not recursive?*