

# Logic programming

Introducing GOLOG and FLUX

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# Outline

- Situation Calculus
- GOLOG
- FLUX
- Conclusion

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# Situation calculus

- McCarthy and Hayes (1969), Reiter (1991)
- First-order logic
- Dynamic world encoded with second-order logic

# Situation calculus

## Elements

- **Fluents**

- Model properties of the world

- **Actions**

- Execution of actions may change the world

- **Situations**

- Are a history of action executions
  - There exists one initial situation  $s_0$

# Situation calculus

## Fluents

- **Relational fluents**

- When evaluated can be true or false
- e.g.  $\text{hasCoffee}(p, s)$   
with  $p$  being a person and  $s$  a situation

- **Functional fluents**

- May return a value
- e.g.  $\text{location}(p, s)$  returns coordinates  $(x, y)$

# Situation calculus

## Actions (1/2)

- **Action precondition axioms**

- Describe when an action is executable with the predicate  $\text{Poss}(a, s)$
- For example:

$$\text{Poss}(\text{pourCoffee}(p), s) \Leftrightarrow \neg \text{hasCoffee}(p, s)$$

- Executing an action alters the situation:

$$\text{do}(a, s) \rightarrow s'$$

# Situation calculus

## Actions (2/2)

- **Action effect axioms**

- Describe the effects of actions on the world
- For example:

$\text{Poss}(\text{pourCoffee}(p), s)$

$\rightarrow \text{hasCoffee}(p, \text{do}(\text{pourCoffee}(p), s))$

- **Frame problem:** What are the non-effects of actions? Has  $\text{location}(p, s)$  changed?



# Situation calculus

## Successor state axiom (1/2)

- Defining for every fluent how every action may or may not affect it:  $\mathcal{O}(A * F)$
- Instead define all effects of every action once (Reiter (1991)):  $\mathcal{O}(A * E)$

# Situation calculus

## Successor state axiom (2/2)

$$\text{Poss}(a, s) \rightarrow [F(\text{do}(a, s)) \\ \Leftrightarrow \gamma_F^+(a, s) \vee F(s) \wedge \neg \gamma_F^-(a, s)]$$

$F(\text{do}(a, s))$  = fluent is true after action

$\gamma_F^+(a, s)$  = action made fluent true

$F(s) \wedge \neg \gamma_F^-(a, s)$  = fluent was true beforehand  
and is unaffected by action

# Situation calculus

## Example

$$\text{Poss}(\text{pourCoffee}(p), s) \Leftrightarrow \neg \text{hasCoffee}(p, s)$$

$$\text{Poss}(\text{sing}) \Leftrightarrow \top$$

$$\text{Poss}(a, s) \rightarrow [\text{hasCoffee}(p, \text{do}(a, s))$$

$$\Leftrightarrow [a = \text{pourCoffee}(p)]$$

$$\vee [\text{hasCoffee}(p, s) \wedge a \neq \text{pourCoffee}(p)]]$$

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# GOLOG

- Builds on situation calculus
- Adds complex actions like
  - Loops
  - Conditions and tests
  - Non-deterministic procedures
- **Regression-based**: deciding whether an action is executable is only possible after looking at all previous actions

# GOLOG

## Example (1/2)

- Extend the situation calculus fluents, action preconditions and successor state axiom with GOLOG procedures:

```
proc pourS0Coffee ( $\pi p$ ) [ $\neg$ hasCoffee( $p$ )?;  
                        pourCoffee( $p$ )] endProc
```

```
proc control [while ( $\exists p$ ) $\neg$ hasCoffee( $p$ )  
                  do pourS0Coffee( $p$ ) endWhile];  
sing endProc
```

# GOLOG

## Example (2/2)

- Initial configuration:

$$\neg \text{hasCoffee}(p, s_0) \Leftrightarrow p = \text{Miriam} \vee p = \text{Sergey}$$

- Two possible results:

$$s = \text{do}\left(\text{sing}, \text{do}\left(\text{pourCoffee}(\text{Miriam}), \text{do}(\text{pourCoffee}(\text{Sergey}), s_0)\right)\right)$$

$$s = \text{do}\left(\text{sing}, \text{do}\left(\text{pourCoffee}(\text{Sergey}), \text{do}(\text{pourCoffee}(\text{Miriam}), s_0)\right)\right)$$

# GOLOG

## Problems

- Complete knowledge in initial situation assumed
- Internal reactions on sensed action and acting on it is missing
- Exogenous events not handled
- Reasoning takes exponentially longer over time due to being regression-based



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# FLUX

- Uses fluent calculus
- Supports incomplete descriptions of the world
- Offers a solution to knowledge reasoning and sensing
- Reasoning is linear in the size of a state representation

# FLUX

## States

- A state  $z$  is a set of fluents  $f_1, \dots, f_n$  denoted as:  $z = f_1 \circ \dots \circ f_n$
- There is only one state in a situation
- The world can be in the same state in multiple situations
- Agents have their own state representing their knowledge  $KState(s, z)$ 
  - The agent knows that  $z$  holds in  $s$

# FLUX

## State update axiom

- Solves frame problem
- Defines effects of an action as the difference between the state before and after the action
- Uses negative and positive effects of actions  $\vartheta^-$  and  $\vartheta^+$  respectively
  - Both are macros for finite states

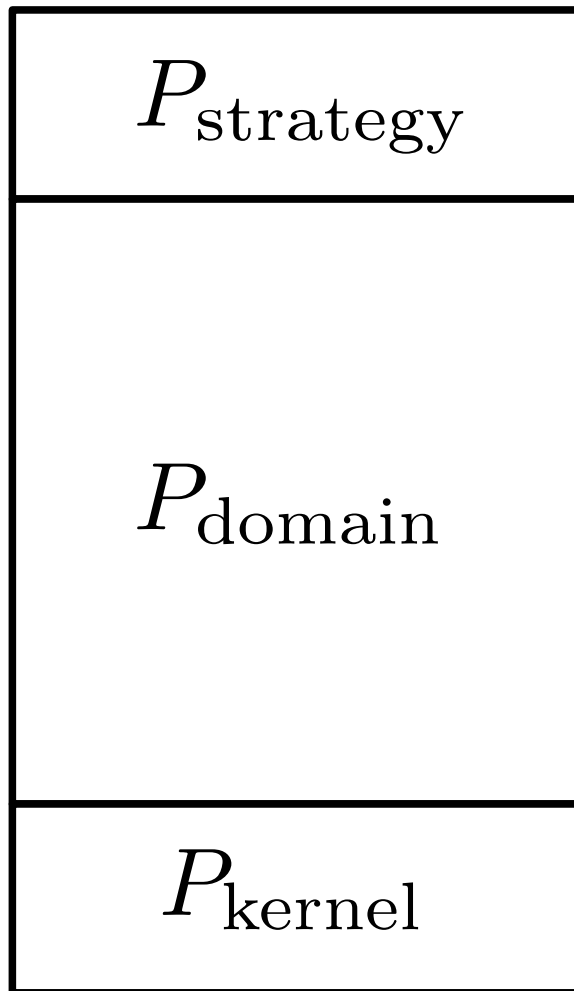
# FLUX

## Constraint solver

- Constraints model negative and disjunctive state knowledge
- Constraint solver uses **constraint handling rules** to rewrite constraints into simpler ones until they are solved
- $H_1, \dots, H_m \Leftrightarrow G_1, \dots, G_k \mid B_1, \dots, B_n$ 
  - When the guard can be derived
  - The head gets replaced by the body

# FLUX

## Program structure



- Programmer defined intended agent behaviour
- Domain encodings
  - Initial knowledge state & domain constraints
  - Action precondition axioms & state update axioms
- Constraint system and constraint solver

# FLUX

## Example (1/3)

```
perform(sing, []).  
poss(sing, Z) :- all_holds(hasCoffee(_), Z).  
state_update(Z, sing, Z, []).
```

```
perform(pourCoffee(P), []).  
poss(pourCoffee(P), Z) :-  
    member(P, [miriam, sergey]),  
    not_holds(hasCoffee(P), Z).  
state_update(Z1, pourCoffee(P), Z2, []) :-  
    update(Z1, [hasCoffee(P)], [], Z2).
```

# FLUX

## Example (2/3)

```
main_loop(Z) :-  
    poss(sing, Z)  
        -> execute(sing, Z, Z);  
    poss(pourCoffee(P), Z)  
        -> execute(pourCoffee(P), Z, Z1),  
            main_loop(Z1);  
false.
```



# FLUX

## Example (3/3)

```
init(Z0) :-  
    not_holds(hasCoffee(miriam), Z0),  
    not_holds(hasCoffee(sergey), Z0).
```

The final state will be:

```
Z = [hasCoffee(sergey), hasCoffee(miriam)]
```

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# Conclusion

- GOLOG does not satisfy our demands without modifications and extensions
- FLUX is applicable to a multi-agent scenario as shown e.g. by Schiffel and Thielscher (2007)

Questions?

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