

Logic programming

Introducing GOLOG and FLUX

Michael Ruster

Research lab – Summer term 2014

University Koblenz-Landau

Outline

- Situation Calculus
- GOLOG
- FLUX
- Conclusion

Outline

- Situation Calculus
- GOLOG
- FLUX
- Conclusion

Situation calculus

- McCarthy and Hayes (1969), Reiter (1991)
- First-order logic
- Dynamic world encoded with second-order logic

Situation calculus

Elements

- **Fluents**

- Model properties of the world

- **Actions**

- Execution of actions may change the world

- **Situations**

- Are a history of action executions
 - There exists one initial situation s_0

Situation calculus

Fluents

- **Relational fluents**
 - When evaluated can be true or false
 - e.g. $\text{hasCoffee}(p, s)$
with p being a person and s a situation
- **Functional fluents**
 - May return a value
 - e.g. $\text{location}(p, s)$ returns coordinates (x, y)

Situation calculus

Actions (1/2)

- **Action precondition axioms**

- Describe when an action is executable with the predicate $\text{Poss}(a, s)$
- For example:

$$\text{Poss}(\text{pourCoffee}(p), s) \Leftrightarrow \neg \text{hasCoffee}(p, s)$$

- Executing an action alters the situation:

$$\text{do}(a, s) \rightarrow s'$$

Situation calculus

Actions (2/2)

- **Action effect axioms**

- Describe the effects of actions on the world
- For example:

$\text{Poss}(\text{pourCoffee}(p), s)$

$\rightarrow \text{hasCoffee}(p, \text{do}(\text{pourCoffee}(p), s))$

- **Frame problem:** What are the non-effects of actions? Has $\text{location}(p, s)$ changed?

Situation calculus

Successor state axiom (1/2)

- Defining for every fluent how every action may or may not affect it: $\mathcal{O}(A * F)$
- Instead define for every action all effects it can have (Reiter (1991)): $\mathcal{O}(A * E)$

Situation calculus

Successor state axiom (2/2)

$$\text{Poss}(a, s) \rightarrow [F(\text{do}(a, s)) \\ \Leftrightarrow \gamma_F^+(a, s) \vee F(s) \wedge \neg \gamma_F^-(a, s)]$$

$F(\text{do}(a, s))$ = fluent is true after action

$\gamma_F^+(a, s)$ = action made fluent true

$F(s) \wedge \neg \gamma_F^-(a, s)$ = fluent was true beforehand
and is unaffected by action

Situation calculus

Example

$$\text{Poss}(\text{pourCoffee}(p), s) \Leftrightarrow \neg \text{hasCoffee}(p, s)$$

$$\text{Poss}(\text{sing}) \Leftrightarrow \top$$

$$\text{Poss}(a, s) \rightarrow [\text{hasCoffee}(p, \text{do}(a, s))$$

$$\Leftrightarrow [a = \text{pourCoffee}(p)]$$

$$\vee [\text{hasCoffee}(p, s) \wedge a \neq \text{pourCoffee}(p)]]$$

Outline

- Situation Calculus
- **GOLOG**
- FLUX
- Conclusion

GOLOG

- Builds on situation calculus
- Adds complex actions like
 - Loops
 - Conditions and tests
 - Non-deterministic procedures
- **Regression-based**: deciding whether an action is executable is only possible after looking at all previous actions

GOLOG

Example (1/2)

- Extend the situation calculus fluents, action preconditions and successor state axiom with GOLOG procedures:

```
proc pourS0Coffee ( $\pi p$ ) [ $\neg$ hasCoffee( $p$ )?;  
                        pourCoffee( $p$ )] endProc
```

```
proc control [while ( $\exists p$ ) $\neg$ hasCoffee( $p$ )  
                  do pourS0Coffee( $p$ ) endWhile];  
sing endProc.
```

GOLOG

Example (2/2)

- Initial configuration:

$$\neg \text{hasCoffee}(p, s_0) \Leftrightarrow p = \text{Miriam} \vee p = \text{Sergey}.$$

- Two possible results:

$$s = \text{do}\left(\text{sing}, \text{do}\left(\text{pourCoffee}(\text{Miriam}), \text{do}(\text{pourCoffee}(\text{Sergey}), s_0)\right)\right)$$

$$s = \text{do}\left(\text{sing}, \text{do}\left(\text{pourCoffee}(\text{Sergey}), \text{do}(\text{pourCoffee}(\text{Miriam}), s_0)\right)\right)$$

GOLOG

Problems

- Complete knowledge in initial situation assumed
- Internal reactions on sensed action and acting on it is missing
- Exogenous events not handled
- Reasoning takes exponentially longer over time due to being regression-based

Outline

- Situation Calculus
- GOLOG
- **FLUX**
- Conclusion

FLUX

- Uses fluent calculus
- Supports incomplete descriptions of the world
- Offers a solution to knowledge reasoning and sensing
- Reasoning is linear in the size of a state representation

FLUX

States

- A state z is a set of fluents f_1, \dots, f_n denoted as: $z = f_1 \circ \dots \circ f_n$
- There is only one state in a situation
- The world can be in the same state in multiple situations
- Agents have their own state representing their knowledge $KState(s, z)$
 - The agent knows that z holds in s

FLUX

State update axiom

- Solves frame problem
- Defines effects of an action as the difference between the state before and after the action
- Uses negative and positive effects of actions ϑ^- and ϑ^+ respectively
 - Both are macros for finite states

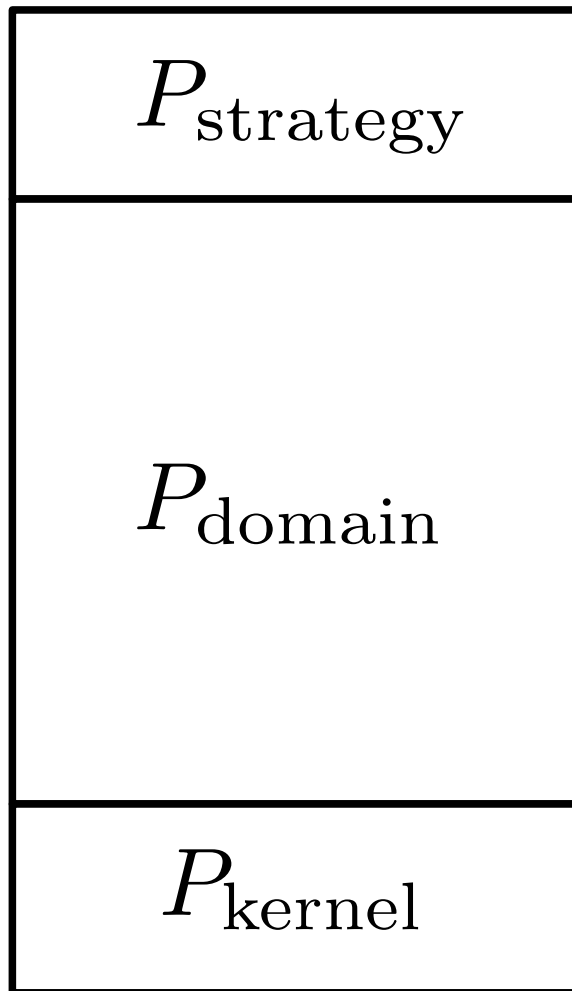
FLUX

Constraint solver

- Constraints model negative and disjunctive state knowledge
- Constraint solver uses **constraint handling rules** to rewrite constraints into simpler ones until they are solved
- $H_1, \dots, H_m \Leftrightarrow G_1, \dots, G_k \mid B_1, \dots, B_n$
 - When the guard can be derived
 - The head gets replaced by the body

FLUX

Program structure



- Programmer defined intended agent behaviour
- Domain encodings
 - Initial knowledge state & domain constraints
 - Action precondition axioms & state update axioms
- Constraint system and constraint solver

FLUX

Example (1/3)

```
perform(sing, []).  
poss(sing, Z) :- all_holds(hasCoffee(_), Z).  
state_update(Z, sing, Z, []).
```

```
perform(pourCoffee(P), []).  
poss(pourCoffee(P), Z) :-  
    member(P, [miriam, sergey]),  
    not_holds(hasCoffee(P), Z).  
state_update(Z1, pourCoffee(P), Z2, []) :-  
    update(Z1, [hasCoffee(P)], [], Z2).
```

FLUX

Example (2/3)

```
main_loop(Z) :-  
    poss(sing, Z)  
        -> execute(sing, Z, Z);  
    poss(pourCoffee(P), Z)  
        -> execute(pourCoffee(P), Z, Z1),  
                main_loop(Z1);  
false.
```


FLUX

Example (3/3)

```
init(Z0) :-  
    not_holds(hasCoffee(miriam), Z0),  
    not_holds(hasCoffee(sergey), Z0).
```

The final state will be:

```
Z = [hasCoffee(sergey), hasCoffee(miriam)]
```

Outline

- Situation Calculus
- GOLOG
- FLUX
- Conclusion

Conclusion

- GOLOG does not satisfy our demands without modifications and extensions
- FLUX is applicable to a multi-agent scenario as shown e.g. by Schiffel and Thielscher (2007)

Questions?

References

- Reiter, R., 1991. The frame problem in the situation calculus: A simple solution (sometimes) and a completeness result for goal regression. Artificial intelligence and mathematical theory of computation: papers in honor of John McCarthy 27, 359–380.
- McCarthy, J., Hayes, P., 1968. Some philosophical problems from the standpoint of artificial intelligence. Stanford University USA.
- Levesque, H.J., Reiter, R., Lesperance, Y., Lin, F., Scherl, R.B., 1997. GOLOG: A logic programming language for dynamic domains. The Journal of Logic Programming 31, 59–83.

References

- Papataxiarhis, V., 2006. Situation Calculus.
- Thielscher, M., 2005. FLUX: A logic programming method for reasoning agents. *Theory and Practice of Logic Programming* 5, 533–565.
- Levesque, H.J., Reiter, R., Lesperance, Y., Lin, F., Scherl, R.B., 1997. GOLOG: A logic programming language for dynamic domains. *The Journal of Logic Programming* 31, 59–83.
- Thielscher, M., 1999. From situation calculus to fluent calculus: State update axioms as a solution to the inferential frame problem. *Artificial intelligence* 111, 277–299.

References

- Schiffel, S., Thielscher, M., 2006. Reconciling situation calculus and fluent calculus, in: AAAI. pp. 287–292.
- Frühwirth, T., 1998. Theory and practice of constraint handling rules. The Journal of Logic Programming 37, 95–138.
- Schiffel, S., Thielscher, M., 2007. Multi-agent FLUX for the gold mining domain (system description), in: Computational Logic in Multi-Agent Systems. Springer, pp. 294–303.