

Dual Representations and Hom

WDRP - Representation Theory

1 Dual Representation

In the reading we saw that given a representation of G , (ρ, V) we can put a representation on the dual space V^* by

$$\rho(g) \cdot f = f \circ \rho(g^{-1})$$

for all $g \in G$ and $f \in V^*$. The inversion of g is necessary since we require associativity for the product. That is $(\rho(g)\rho(h)) \cdot f = \rho(g)(\rho(h) \cdot f)$. Otherwise we would get the following

$$(gh) \cdot f = f \circ (gh) = (f \circ g)h = h \cdot (f \circ g) = h(g \cdot f)$$

which would imply that any G is abelian. So instead having the inversion gives

$$(gh) \cdot f = f \circ (gh)^{-1} = (f \circ h^{-1})g^{-1} = g \cdot (f \circ h^{-1}) = g(h \cdot f).$$

We also saw in the reading that the induced matrix representation for g on V^* will be $\rho(g^{-1})^T$. There is another way to view the dual representation which shows that the transpose appears without checking coordinates directly. Recall that we can write the evaluation of f on v using the Euclidean inner product defined by $\langle v, w \rangle = v \cdot w = v^T \cdot w$ where the multiplication in the last expression is the usual matrix multiplication. Then for a matrix $A : V \rightarrow V$ we have

$$\langle f, Av \rangle = f^T \cdot (Av) = f^T (A^T)^T \cdot v = (A^T f)^T \cdot v = \langle A^T f, v \rangle.$$

This means we can phrase this representation of G on V^* as follows,

Definition 1.1. Let (ρ, V) be a representation of G and V^* the linear dual of V . Then the *dual representation* is the unique representation on V^* such that $\langle \rho^*(g)f, \rho(g)v \rangle = \langle f, v \rangle$.

2 Hom Spaces

The dual space of a vector space V is defined as $V^* = \text{Hom}(V, \mathbb{F})$. We can generalize this notion to maps from V to any other vector space W by $\text{Hom}(V, W)$. In particular, these are all linear maps (Vector space homomorphisms) from $V \rightarrow W$. In fact we can define a representation on this "Hom" space as follows.

Definition 2.1. Let (ρ_V, V) and (ρ_W, W) be representations of G . Then there is a representation ρ_{Hom} of G on $\text{Hom}(V, W)$ given by $\rho_{\text{Hom}}(g) \cdot f = \rho_W(g) \circ f \circ \rho_V(g^{-1})$.

You can remember this by the diagram below. So tracing from the bottom left V to the bottom right W we get a new map from $V \rightarrow W$.

$$\begin{array}{ccc} V & \xrightarrow{f} & W \\ \rho_V(g^{-1}) \uparrow & & \downarrow \rho_W(g) \\ V & \dashrightarrow & W \end{array}$$

There are some other facts about this hom space as well.

1. Hom depends on what type of map you are considering. For example, $\text{Hom}_{\mathbb{F}}(V, W)$ are the \mathbb{F} -linear maps between V and W . It is entirely possible to only consider the set maps between them which would be denoted $\text{Hom}_{\mathbf{Set}}(V, W)$. We have a containment $\text{Hom}_{\mathbb{F}}(V, W) \subseteq \text{Hom}_{\mathbf{Set}}(V, W)$ since any \mathbb{F} -linear map is also a map between sets. the reverse is not true since some set maps may not map $0_V \mapsto 0_W$.

Another example is in the case of rings. The collection $\text{Hom}_{\mathbf{Ring}}(R, S)$ is all ring homomorphisms between R and S . Recall that any ring homomorphism is also an abelian group homomorphism between $(R, +)$ and $(S, +)$ if we think of only the additive group structure on R and S . Then we have the containment $\text{Hom}_{\mathbf{Ring}}(R, S) \subseteq \text{Hom}_{\mathbf{Ab}}(R, S)$. Recall that not every group homomorphism between rings extends to a ring homomorphism.

This means whenever we wrote Hom before, we technically should have been writing $\text{Hom}_{\mathbb{F}}$. Although many sources will just write Hom if the context is clear. So I guess its okay that we wrote just Hom before.

2. Given two representations of a group G , (ρ_V, V) and (ρ_W, W) , we will use the notation $\text{Hom}_G(V, W)$ to mean the collection of intertwining operators between V and W . More specifically

$$\text{Hom}_G(V, W) = \{T \in \text{Hom}_{\mathbb{F}}(V, W) : \rho_W(g) \circ T = T \circ \rho_V(g^{-1})\}.$$

Additionally, we will write $\text{Hom}_{\mathbb{F}}(V, W)^G$ to be all \mathbb{F} -linear maps from $V \rightarrow W$ which are invariant (fixed) by the Hom representation of G . That is

$$\text{Hom}_{\mathbb{F}}(V, W)^G = \{T \in \text{Hom}_{\mathbb{F}}(V, W) : \rho_{\text{Hom}} \cdot T = T\}.$$

Both of these are subsets of the usual $\text{Hom}_{\mathbb{F}}(V, W)$, and infact they are equivalent (Exercise).

3. We have a relationship between Hom and the tensor product. In particular

$$\text{Hom}_{\mathbb{F}}(V, W) \cong V^* \otimes W.$$

Essentially, we may write a map $T \in \text{Hom}_{\mathbb{F}}(V, W)$ as $T(v) = f(v)w$ for some $f \in V^*$ and $w \in W$. Notice that $f(v)$ will be a scalar. So any linear transformation between vector spaces is just a scalar given by evaluation by a linear form and a vector from the codomain.