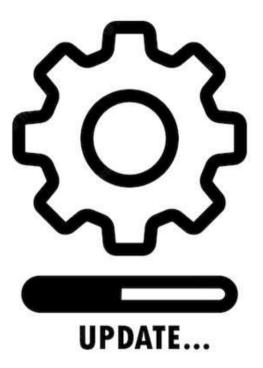


### Updates

- Choice of materials
- Modification of the structure
- First part of the assembly
- Planning of the electric part
- Creation of the website





https://qrco.de/bctadL



# Components

- 2 x Stepper motor NEMA 17
- 1x Pump
- 4x Slide
- 4x Guide supports
- 2x Timing pulley+ timing belt
- 1x Dispenser
- 2x Chrome bar



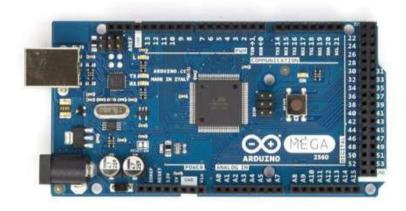


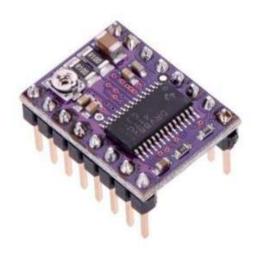




# Components

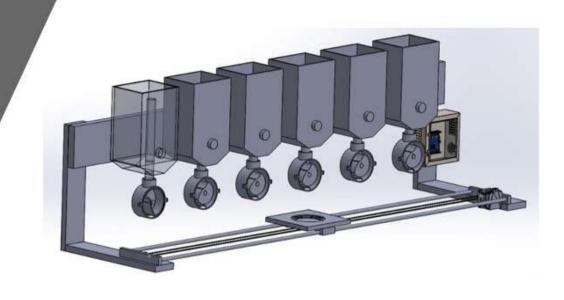
- 2x Driver DRV8825
- 1x ESP32
- 2x DC-DC converter
- 1x Arduino MEGA
- 1x Power supply 12V 5A
- 1x Protoboard

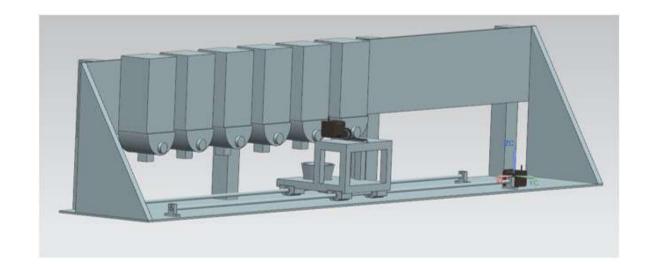


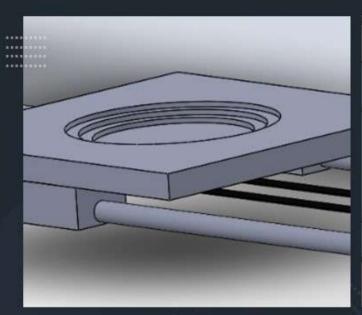


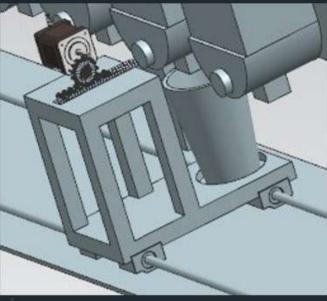


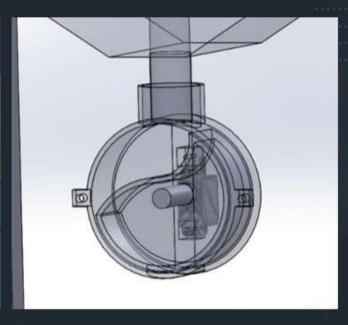
# Mechanical Changes







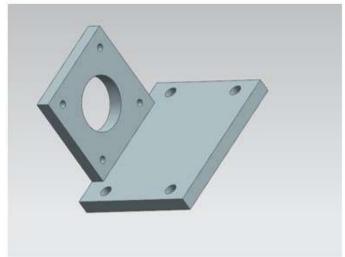


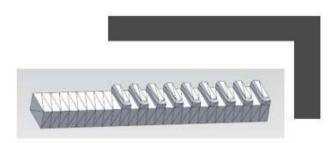


### Changes

- Modifications of the structure for regulation the toppings.
- Utilization of 2 stepper motors instead of 6 servos.
- Changes in the platform.



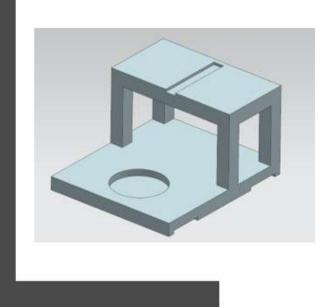




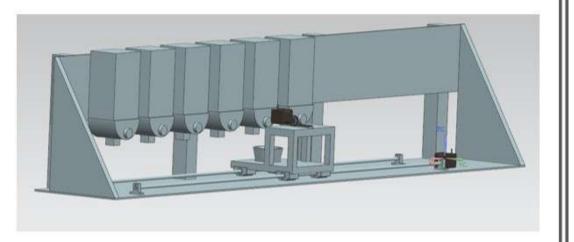
#### Our pieces

- Support of dispenser
- Support of motor
- Gear rack
- Transport structure

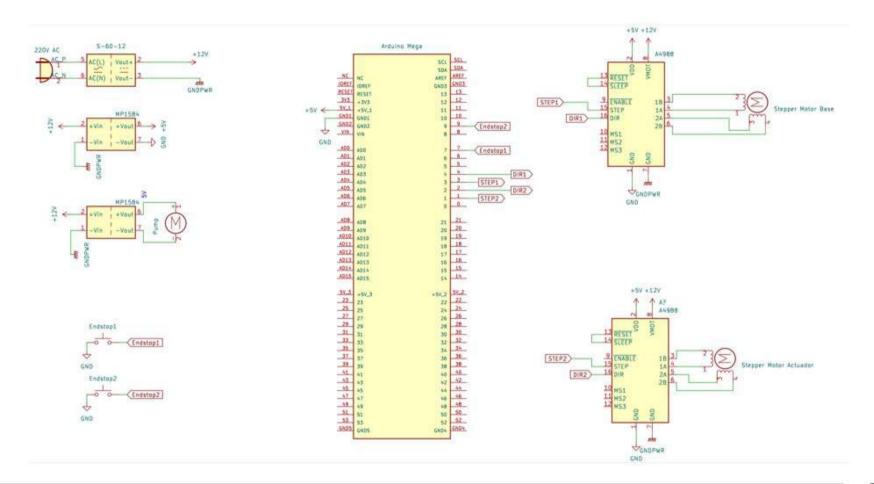




# 3D vs Real prototipe





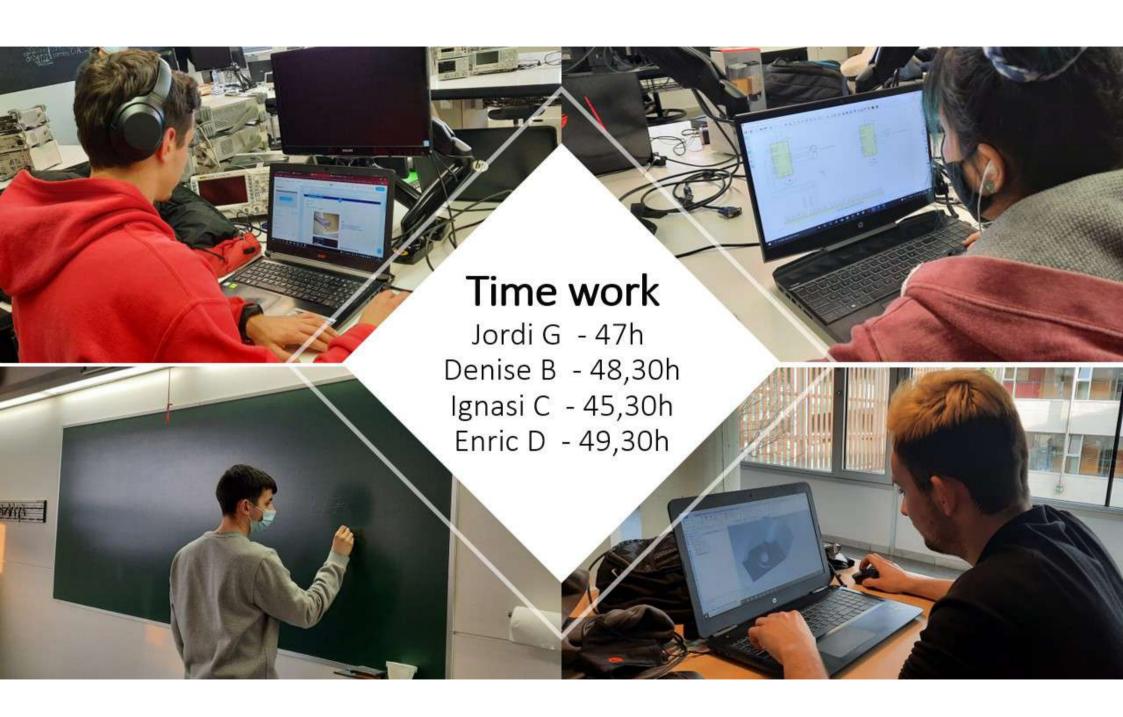




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#### Electronic part





#### Github

