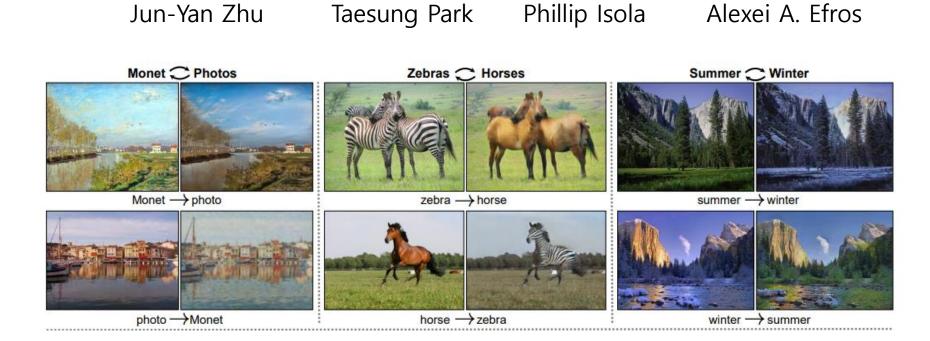
# Cycle GAN

Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks

(https://arxiv.org/abs/1703.10593)

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## 목차

- Abstract
- GAN and pix2pix
- Cycle Consistency
- CycleGAN Architecture and Loss
- CycleGAN Implementation detail

#### **Abstract**

- 연구 배경
  - Image-to-Image translation 에서 aligned image pairs data를 이용하여 학습한다.
  - 대부분의 연구에서, Paired training data를 사용할 수 없다.
  - Paired image 없이, source domain X에서 target domain Y로 translate하게 학습

#### 목표

- Adversarial loss를 이용하여 mapping G: X->Y를 학습.
- Inverse mapping F: Y->X 를 이용한 cycle consistency loss를 추가하여 Unpaired image 를 학습.

#### **Abstract**

Paired & Unpaired training datasets

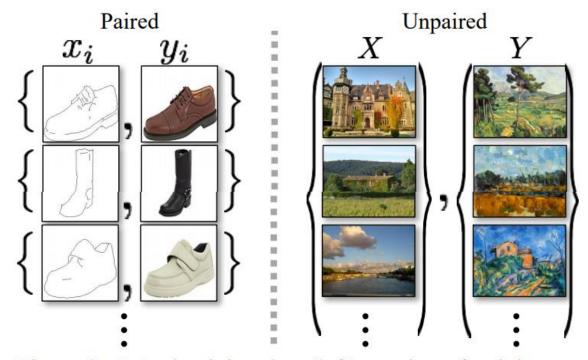
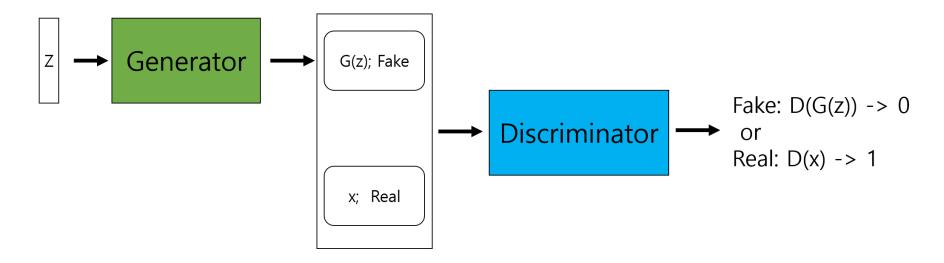


Figure 2: Paired training data (left) consists of training examples  $\{x_i, y_i\}_{i=1}^N$ , where the correspondence between  $x_i$  and  $y_i$  exists [22]. We instead consider unpaired training data (right), consisting of a source set  $\{x_i\}_{i=1}^N$  ( $x_i \in X$ ) and a target set  $\{y_j\}_{j=1}$  ( $y_j \in Y$ ), with no information provided as to which  $x_i$  matches which  $y_j$ .

#### **GAN**

#### **GAN** architecture and loss function

- Generative Adversarial Net(GAN)
  - 실제 데이터(x)인지, G로부터 만들어졌는지 구분하는 network D와, D를 속이도록 학습하는 network G의 적대적 (adversarial)관계를 이용한 생성모델 G를 만드는 프레임워크.
  - G(z)의 distribution은 x의 distribution과 같아지고, D는 둘을 구분하지 못하는 상태 D(x) = 0.5가 될 것이다.



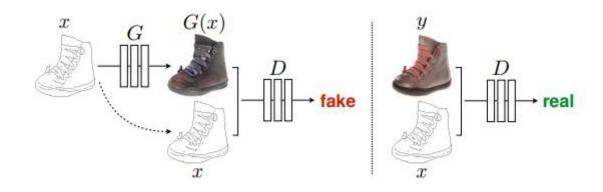
 $\bullet \quad \text{Adversarial loss:} \quad \min_{G} \max_{D} V(D,G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})}[\log D(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})}[\log(1 - D(G(\boldsymbol{z})))].$ 

### Pix2Pix

Image-to-Image Translation with Conditional Adversarial Networks (<a href="https://arxiv.org/abs/1611.07004">https://arxiv.org/abs/1611.07004</a>)

#### pix2pix

- Image-to-Image translation 모델.
- Input image를 D의 condition으로 사용하여 학습.
- G는 U-Net model, D는 Markovian discriminator (PatchGAN)을 사용.
- Paired image dataset을 사용.



$$G^* = \arg\min_{G} \max_{D} \mathcal{L}_{cGAN}(G, D) + \lambda \mathcal{L}_{L1}(G).$$



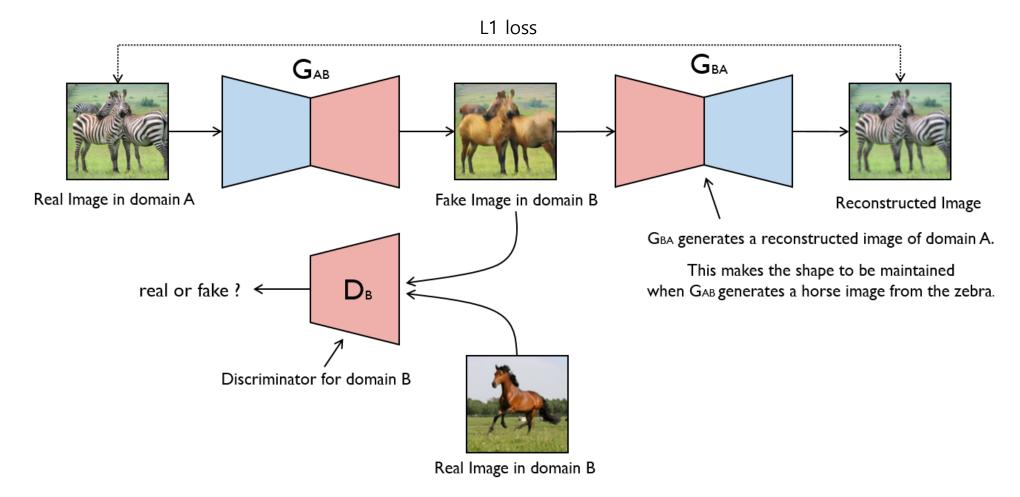
 $Figure~17:~Example~results~of~our~method~on~automatically~detected~edges \rightarrow shoes,~compared~to~ground~truth.$ 

## **Cycle Consistency**

- Unpaired image를 GAN에 학습시키면?
  - 각각의 input x에 대해, y가 의미 있는 pair가 될 보장이 없음.
  - Mode collapse(all input images map to the same output image.) 가 종종 발생.
- 위의 이유로, Objective에 cycle consistent 특성을 추가.
  - If we translate, eg., a sentence from English to French, and then translate it back from French to English, we should arrive back at the original sentence
  - 두 translator  $G: X \to Y$ ,  $F: Y \to X$ 에 대해,  $F(G(x)) \approx x$ ,  $G(F(y)) \approx y$ 에서 비롯된 cycle consistency loss를 adversarial loss와 결합하여 학습을 진행.

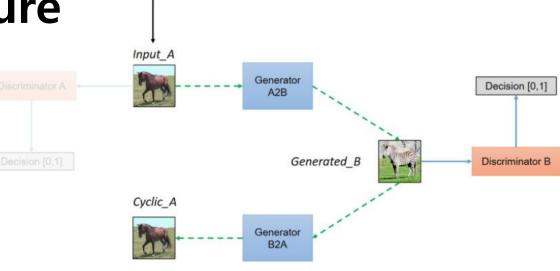
### CycleGAN architecture

• A -> B로의 Translate 입장에서 본 architecture

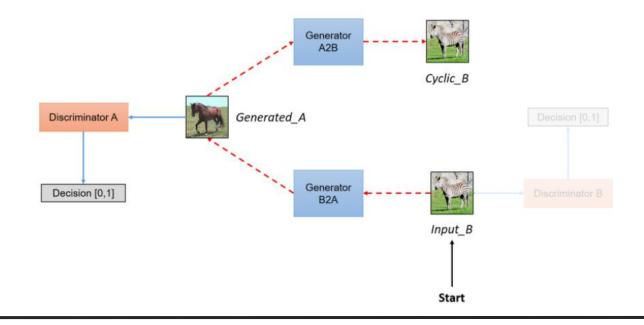


CycleGAN architecture image from <a href="https://modelzoo.co/model/mnist-svhn-transfer">https://modelzoo.co/model/mnist-svhn-transfer</a>

# **CycleGAN** architecture



Start



### CycleGAN Loss

Adversarial Loss

$$\mathcal{L}_{\text{GAN}}(G, D_Y, X, Y) = \mathbb{E}_{y \sim p_{\text{data}}(y)}[\log D_Y(y)] + \mathbb{E}_{x \sim p_{\text{data}}(x)}[\log(1 - D_Y(G(x)))]$$

Cycle Loss

$$\mathcal{L}_{\text{cyc}}(G, F) = \mathbb{E}_{x \sim p_{\text{data}}(x)}[\|F(G(x)) - x\|_1] + \mathbb{E}_{y \sim p_{\text{data}}(y)}[\|G(F(y)) - y\|_1].$$

Full Objective

$$\mathcal{L}(G, F, D_X, D_Y) = \mathcal{L}_{GAN}(G, D_Y, X, Y) + \mathcal{L}_{GAN}(F, D_X, Y, X) + \lambda \mathcal{L}_{cyc}(G, F)$$

$$G^*, F^* = \arg\min_{G, F} \max_{D_x, D_Y} \mathcal{L}(G, F, D_X, D_Y).$$

## CycleGAN Implementataion detail

#### Network Architecture

- G: ResNet구조 (3conv 9resnetblock 3conv)
- D: Markovian Discriminator(PatchGAN) (70x70 patch)

#### Adversarial loss

- LSGAN : Least-squares loss 사용.

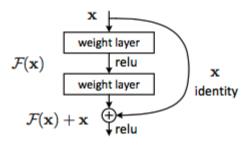
G to minimize 
$$\mathbb{E}_{x \sim p_{\text{data}}(x)}[(D(G(x)) - 1)^2]$$

$$D$$
 to minimize  $\mathbb{E}_{y \sim p_{\text{data}}(y)}[(D(y)-1)^2] + \mathbb{E}_{x \sim p_{\text{data}}(x)}[D(G(x))^2].$ 

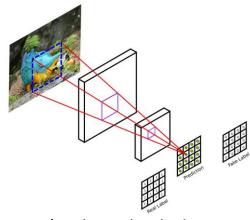
#### Identity loss

- Color composition을 보존하는데 도움을 주는 loss

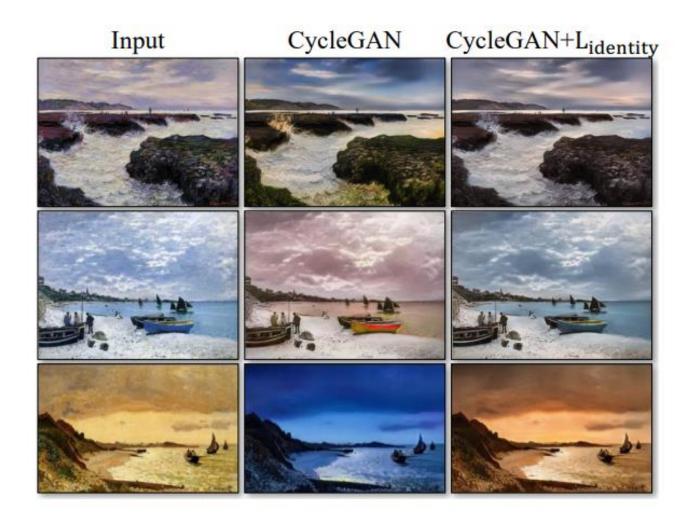
$$\mathcal{L}_{\text{identity}}(G, F) = \mathbb{E}_{y \sim p_{\text{data}}(y)}[\|G(y) - y\|_1] + \mathbb{E}_{x \sim p_{\text{data}}(x)}[\|F(x) - x\|_1].$$

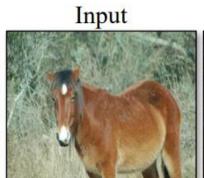


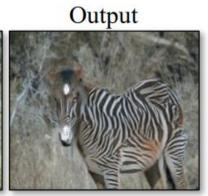
Residual block

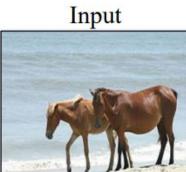


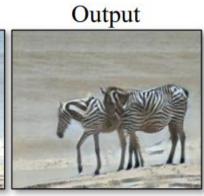
Markovian Discriminator

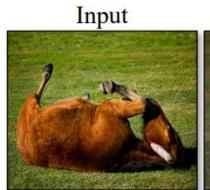


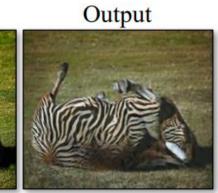












horse → zebra













zebra → horse









winter Yosemite → summer Yosemite









summer Yosemite → winter Yosemite

