

# Dimensionality reduction for time series decoding and forecasting

Roman Isachenko

Moscow Institute of Physics and Technology  
Skolkovo Institute of Science and Technology

December 25, 2017.

# Timeline

- September** quadratic programming approach were investigated, the problem was not formulated properly
- October** MMRO-2017 conference, Taganrog, "Feature Generation for Physical Activity Classification" The paper was prepared and submitted to the journal
- November** The research about time series decoding were begun. The new method was proposed.
- December** The research was narrowed down, the experiments were conducted, the paper was prepared

## Problem Statement

Given a dataset  $\mathcal{D} = (\mathbf{X}, \mathbf{Y})$

- $\mathbf{X} \in \mathbb{R}^{m \times n}$  is a design matrix,
- $\mathbf{Y} \in \mathbb{R}^{m \times r}$  is a target matrix.

We assume that there is a linear dependence between the objects  $\mathbf{x} \in \mathbb{R}^n$  and the responses  $\mathbf{y} \in \mathbb{R}^r$

$$\underset{1 \times r}{\mathbf{y}} = \underset{1 \times n}{\mathbf{x}} \cdot \underset{n \times r}{\boldsymbol{\Theta}} + \underset{1 \times r}{\boldsymbol{\varepsilon}}.$$

### Error function

$$S(\boldsymbol{\Theta}|\mathcal{D}) = \left\| \underset{m \times n}{\mathbf{X}} \cdot \underset{n \times r}{\boldsymbol{\Theta}} - \underset{m \times r}{\mathbf{Y}} \right\|_2^2 = \sum_{i=1}^m \left\| \underset{1 \times n}{\mathbf{x}_i} \cdot \underset{n \times r}{\boldsymbol{\Theta}} - \underset{1 \times r}{\mathbf{y}_i} \right\|_2^2 \rightarrow \min_{\boldsymbol{\Theta}}.$$

# Partial Least Squares Regression

PLS algorithm finds the matrix  $\mathbf{T}$  in the low-dimensional latent space. The  $\mathbf{T}$  jointly describes the input matrix  $\mathbf{X}$  and the target matrix  $\mathbf{Y}$ .

$$\begin{aligned}\mathbf{X}_{m \times n} &= \mathbf{T}_{m \times l} \cdot \mathbf{P}_{l \times n}^T + \mathbf{F}_{m \times n} = \sum_{k=1}^l \mathbf{t}_k_{m \times 1} \cdot \mathbf{p}_k^T_{1 \times n} + \mathbf{F}_{m \times n}, \\ \mathbf{Y}_{m \times r} &= \mathbf{T}_{m \times l} \cdot \mathbf{Q}_{l \times r}^T + \mathbf{E}_{m \times r} = \sum_{k=1}^l \mathbf{t}_k_{m \times 1} \cdot \mathbf{q}_k^T_{1 \times r} + \mathbf{E}_{m \times r},\end{aligned}$$

# PLS pseudocode

**Require:**  $\mathbf{X}, \mathbf{Y}, l$ ;

**Ensure:**  $\mathbf{T}, \mathbf{P}, \mathbf{Q}$ ;

- 1: normalize matrices  $\mathbf{X}$  и  $\mathbf{Y}$  by columns
- 2: initialize  $\mathbf{u}_0$  (the first column of  $\mathbf{Y}$ )
- 3:  $\mathbf{X}_1 = \mathbf{X}; \mathbf{Y}_1 = \mathbf{Y}$
- 4: **for**  $k = 1, \dots, l$  **do**
- 5:   **repeat**
- 6:      $\mathbf{w}_k := \mathbf{X}_k^\top \mathbf{u}_{k-1} / (\mathbf{u}_{k-1}^\top \mathbf{u}_{k-1}); \quad \mathbf{w}_k := \frac{\mathbf{w}_k}{\|\mathbf{w}_k\|}$
- 7:      $\mathbf{t}_k := \mathbf{X}_k \mathbf{w}_k$
- 8:      $\mathbf{c}_k := \mathbf{Y}_k^\top \mathbf{t}_k / (\mathbf{t}_k^\top \mathbf{t}_k); \quad \mathbf{c}_k := \frac{\mathbf{c}_k}{\|\mathbf{c}_k\|}$
- 9:      $\mathbf{u}_k := \mathbf{Y}_k \mathbf{c}_k$
- 10:   **until**  $\mathbf{t}_k$  stabilizes
- 11:    $\mathbf{p}_k := \mathbf{X}_k^\top \mathbf{t}_k / (\mathbf{t}_k^\top \mathbf{t}_k), \quad \mathbf{q}_k := \mathbf{Y}_k^\top \mathbf{t}_k / (\mathbf{t}_k^\top \mathbf{t}_k)$
- 12:    $\mathbf{X}_{k+1} := \mathbf{X}_k - \mathbf{t}_k \mathbf{p}_k^\top$
- 13:    $\mathbf{Y}_{k+1} := \mathbf{Y}_k - \mathbf{t}_k \mathbf{q}_k^\top$

# PLS Example

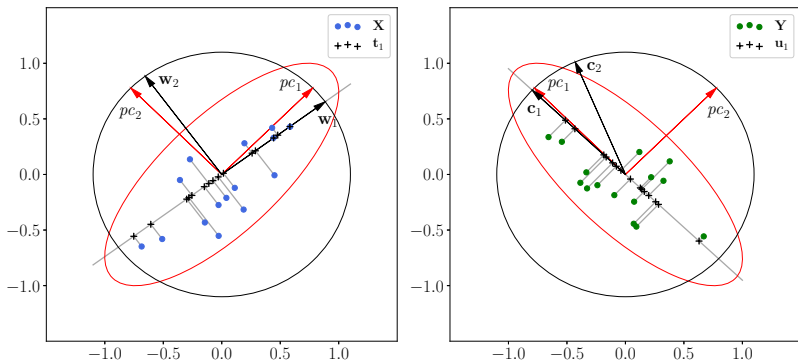


Figure: The result of the PLS algorithm for the case  $n = r = l = 2$ .

## Statement

*The best description of the matrices  $\mathbf{X}$  and  $\mathbf{Y}$  taking into account their interrelation is achieved by maximization the covariance between the vectors  $\mathbf{t}_k$  and  $\mathbf{u}_k$ .*

## Statement

*The vector  $\mathbf{w}_k$  and  $\mathbf{c}_k$  are eigenvectors of the matrices  $\mathbf{X}_k^T \mathbf{Y}_k \mathbf{Y}_k^T \mathbf{X}_k$  and  $\mathbf{Y}_k^T \mathbf{X}_k \mathbf{X}_k^T \mathbf{Y}_k$ , corresponding to the maximum eigenvalues.*

## Statement

*The update rule for the vectors in steps (6)–(9) of the PLS algorithm corresponds to the maximization of the covariance between the vectors  $\mathbf{t}_k$  and  $\mathbf{u}_k$ .*

## PLS solution

The linear transformation between objects in the input and latent spaces has the form

$$\mathbf{T} = \mathbf{XW}^*,$$

where  $\mathbf{W}^* = \mathbf{W}(\mathbf{P}^T \mathbf{W})^{-1}$ .

$$\mathbf{Y} = \mathbf{TQ}^T + \mathbf{E} = \mathbf{XW}^* \mathbf{Q}^T + \mathbf{E} = \mathbf{X}\boldsymbol{\Theta} + \mathbf{E}.$$

The model parameters (3) are equal to

$$\boldsymbol{\Theta} = \mathbf{W}(\mathbf{P}^T \mathbf{W})^{-1} \mathbf{Q}^T.$$



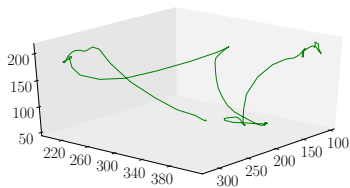
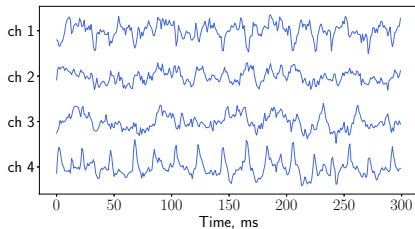
# Computational experiment

## Datasets

- energy consumption
- electrocorticogram signals

## Autoregressive approach

$$\mathbf{X} = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_2 & x_3 & \dots & x_{n+1} \\ \dots & \dots & \dots & \dots \\ x_{T-n+1} & x_{T-n+2} & \dots & x_T \end{pmatrix}.$$



# Computational experiment

