Dimensionality Reduction for Signal Analysis

Roman Isachenko

Skoltech advisor: Maxim Fedorov MIPT advisor: Vadim Strijov

June 18, 2018.





Signal decoding problem

Goal

Investigate dependencies in both input and target spaces and build a stable model for signal decoding in the case of multicorrelated object description.

Challenge

- Measurements of spatial-temporal data are interacted since sensors are close to each other.
- Target variable is a vector whose elements are dependent.

Solution

Propose dimensionality reduction and feature selection algorithms which take into account dependencies in both input and target spaces.

Related works

- Katrutsa A., Strijov V. Comprehensive study of feature selection methods to solve multicollinearity problem according to evaluation criteria // Expert Systems with Applications 76, 2017.
- Li J. et al. Feature selection: A data perspective //ACM Computing Surveys (CSUR) 50(6), 2017.
- Eliseyev A. et al. Iterative N-way partial least squares for a binary self-paced brain-computer interface in freely moving animals // Journal of neural engineering 4(8), 2011.
- Rodriguez-Lujan I. et al. Quadratic programming feature selection // Journal of Machine Learning Research 11(Apr), 2010.
- Motrenko A., Strijov V. Multi-way Feature Selection for ECoG-based Brain-Computer Interface // Expert Systems with Applications Submitted to the journal.

Multivariate regression

Given

Dataset (\mathbf{X},\mathbf{Y}) , design matrix $\mathbf{X} \in \mathbb{R}^{m \times n}$, target matrix $\mathbf{Y} \in \mathbb{R}^{m \times r}$,

$$\mathbf{X} = [\boldsymbol{\chi}_1, \dots, \boldsymbol{\chi}_n]; \quad \mathbf{Y} = [\boldsymbol{\nu}_1, \dots, \boldsymbol{\nu}_r].$$

Model

Forecast a dependent variable $\mathbf{y} \in \mathbb{R}^r$ from an independent input object $\mathbf{x} \in \mathbb{R}^n$

$$\mathbf{y} = \mathbf{\Theta}\mathbf{x} + \boldsymbol{\varepsilon}, \quad \mathbf{\Theta} \in \mathbb{R}^{r \times n}.$$

Loss function

$$\begin{split} \mathcal{L}(\boldsymbol{\Theta}|\mathbf{X},\mathbf{Y}) &= \left\| \mathbf{Y} - \mathbf{X} \cdot \mathbf{\Theta}^{\mathsf{T}}_{r \times n} \right\|_{2}^{2} \rightarrow \min_{\boldsymbol{\Theta}}. \\ \boldsymbol{\Theta}^{\mathsf{T}} &= (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{Y}. \end{split}$$

The linear dependent columns of the matrix \mathbf{X} leads to an instable solution. To avoid the strong linear dependence, dimensionality reduction and feature selection techniques are used.

Dimensionality reduction

Goal

- project the matrices **X** and **Y** into joint latent space;
- · maximize covariance between the projections;
- · save variance of the initial matrices.

Partial Least Squares (PLS) regression

$$\begin{split} & \mathbf{X}_{m \times n} = \mathbf{T}_{m \times l} \cdot \mathbf{P}_{l \times n}^{\mathsf{T}} + \mathbf{F}_{m \times n} = \sum_{k=1}^{l} \mathbf{t}_{k} \cdot \mathbf{p}_{k}^{\mathsf{T}} + \mathbf{F}_{m \times n}, \\ & \mathbf{Y}_{m \times r} = \mathbf{U}_{m \times l} \cdot \mathbf{Q}_{l \times r}^{\mathsf{T}} + \mathbf{E}_{m \times r} = \sum_{k=1}^{l} \mathbf{u}_{k} \cdot \mathbf{q}_{k}^{\mathsf{T}} + \mathbf{E}_{m \times r}. \\ & \mathbf{U} \approx \mathsf{TB}, \quad \mathbf{B} = \mathsf{diag}(\beta_{k}), \quad \beta_{k} = \mathbf{u}_{k}^{\mathsf{T}} \mathbf{t}_{k} / (\mathbf{t}_{k}^{\mathsf{T}} \mathbf{t}_{k}). \end{split}$$

PLS pseudocode

```
Require: X, Y, l;
Ensure: T, P, Q;
   1: normalize matrices X u Y by columns
   2: initialize \mathbf{u}_0 (the first column of \mathbf{Y})
   3: X_1 = X; Y_1 = Y
   4: for k = 1, ..., l do
   5:
              repeat
                   \mathbf{w}_k := \mathbf{X}_k^{\mathsf{T}} \mathbf{u}_{k-1} / (\mathbf{u}_{k-1}^{\mathsf{T}} \mathbf{u}_{k-1}); \quad \mathbf{w}_k := \frac{\mathbf{w}_k}{\|\mathbf{w}_k\|}
  6:
                   \mathbf{t}_{k} := \mathbf{X}_{k} \mathbf{w}_{k}
   7:
  8: \mathbf{c}_k := \mathbf{Y}_k^{\mathsf{T}} \mathbf{t}_k / (\mathbf{t}_k^{\mathsf{T}} \mathbf{t}_k); \quad \mathbf{c}_k := \frac{\mathbf{c}_k}{\|\mathbf{c}_k\|}
            \mathbf{u}_{\iota} := \mathbf{Y}_{\iota} \mathbf{c}_{\iota}
  9.
              until \mathbf{t}_k stabilizes
10:
            \mathbf{p}_k := \mathbf{X}_k^\mathsf{T} \mathbf{t}_k / (\mathbf{t}_k^\mathsf{T} \mathbf{t}_k), \ \mathbf{q}_k := \mathbf{Y}_k^\mathsf{T} \mathbf{t}_k / (\mathbf{t}_k^\mathsf{T} \mathbf{t}_k)
11:
12: \mathbf{X}_{k+1} := \mathbf{X}_k - \mathbf{t}_k \mathbf{p}_k^\mathsf{T}
13: \mathbf{Y}_{k+1} := \mathbf{Y}_k - \mathbf{t}_k \mathbf{q}_k^\mathsf{T}
```

PLS regression

Statement (Isachenko, 2017)

The best description of the matrices X and Y taking into account their interrelation is achieved by maximization of the covariance between the vectors \mathbf{t}_k and \mathbf{u}_k .

Statement (Isachenko, 2017)

The vector \mathbf{w}_k and \mathbf{c}_k are eigenvectors of the matrices $\mathbf{X}_k^{\mathsf{T}} \mathbf{Y}_k \mathbf{Y}_k^{\mathsf{T}} \mathbf{X}_k$ and $\mathbf{Y}_k^{\mathsf{T}} \mathbf{X}_k \mathbf{X}_k^{\mathsf{T}} \mathbf{Y}_k$, corresponding to the maximum eigenvalues.

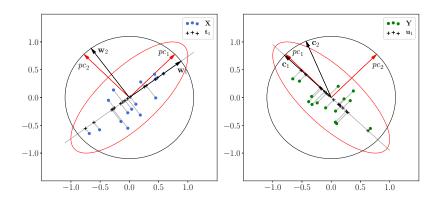
Statement (Isachenko, 2017)

The update rule for the vectors in steps (6)–(9) corresponds to the maximization of the covariance between the vectors \mathbf{t}_k and \mathbf{u}_k .

PLS regression model

$$\begin{split} \mathbf{Y} &= \mathbf{U} \mathbf{Q}^\mathsf{T} + \mathbf{E} \approx \mathbf{T} \mathbf{B} \mathbf{Q}^\mathsf{T} + \mathbf{E} = \mathbf{X} \mathbf{W}^* \mathbf{B} \mathbf{Q}^\mathsf{T} + \mathbf{E} = \mathbf{X} \mathbf{\Theta} + \mathbf{E}. \\ \mathbf{\Theta} &= \mathbf{W} (\mathbf{P}^\mathsf{T} \mathbf{W})^{-1} \mathbf{B} \mathbf{Q}^\mathsf{T}, \quad \mathbf{T} = \mathbf{X} \mathbf{W}^*, \quad \text{where } \mathbf{W}^* = \mathbf{W} (\mathbf{P}^\mathsf{T} \mathbf{W})^{-1}. \end{split}$$

PLS example for two-dimensional case



Feature selection problem

Goal

Find a boolean vector $\mathbf{a} = \{0,1\}^n$ of indicators for selected features.

Feature selection error function

$$\mathbf{a} = \mathop{\text{arg min}}_{\mathbf{a}' \in \{0,1\}^n} S(\mathbf{a}'|\mathbf{X},\mathbf{Y}).$$

Relaxed problem

From discrete domain $\{0,1\}^n$ to continuous relaxation $[0,1]^n$:

$$\mathbf{z} = \underset{\mathbf{z}' \in [0,1]^n}{\min} S(\mathbf{z}'|\mathbf{X},\mathbf{Y}), \quad a_j = [z_j > \tau].$$

Once the solution a is known:

$$\mathcal{L}(\boldsymbol{\Theta}_{a}|\boldsymbol{X}_{a},\boldsymbol{Y}) = \left\|\boldsymbol{Y} - \boldsymbol{X}_{a}\boldsymbol{\Theta}_{a}^{\mathsf{T}}\right\|_{2}^{2} \rightarrow \min_{\boldsymbol{\Theta}_{a}},$$

where the subscript a indicates the submatrix with the columns for which $a_i=1$.

Quadratic Programming Feature Selection

$$\|oldsymbol{
u} - oldsymbol{\mathsf{X}}oldsymbol{ heta}\|_2^2
ightarrow \min_{oldsymbol{ heta} \in \mathbb{R}^n}.$$

Quadratic programming problem

$$S(\mathbf{z}|\mathbf{X}, \boldsymbol{\nu}) = (1-\alpha) \cdot \underbrace{\mathbf{z}^\mathsf{T} \mathbf{Q} \mathbf{z}}_{\mathsf{Sim}(\mathbf{X})} - \alpha \cdot \underbrace{\mathbf{b}^\mathsf{T} \mathbf{z}}_{\mathsf{Rel}(\mathbf{X}, \boldsymbol{\nu})} \to \min_{\substack{\mathbf{z} \geq \mathbf{0}_n \\ \mathbf{1}_n^\mathsf{T} \mathbf{z} = 1}}.$$

- $z \in [0,1]^n$ feature importances;
- $\mathbf{Q} \in \mathbb{R}^{n \times n}$ pairwise feature similarities;
- $\mathbf{b} \in \mathbb{R}^n$ feature relevances to the target vector.

$$\mathbf{Q} = \left[\left| \mathsf{corr}(\boldsymbol{\chi}_i, \boldsymbol{\chi}_j) \right| \right]_{i,j=1}^n, \quad \mathbf{b} = \left[\left| \mathsf{corr}(\boldsymbol{\chi}_i, \boldsymbol{\nu}) \right| \right]_{i=1}^n.$$

Statement

In the case of semidefinite matrix \mathbf{Q} the QPFS problem is convex. Shift spectrum for semidefinite relaxation:

$$\mathbf{Q} o \mathbf{Q} - \lambda_{\mathsf{min}} \mathbf{I}$$
.



Multivariate QPFS

Relevance Aggregation (RelAgg)

$$\mathbf{b} = [|\mathsf{corr}(\boldsymbol{\chi}_i, \boldsymbol{\nu})|]_{i=1}^n \to \mathbf{b} = \left[\sum_{k=1}^r |\mathsf{corr}(\boldsymbol{\chi}_i, \boldsymbol{\nu}_k)|\right]_{i=1}^n.$$

Drawback: the approach does not use the dependencies in the columns of Y.

Symmetric Importances (SymImp)

Penalize correlated targets by Sim(Y)

$$\alpha_1 \cdot \underbrace{\mathbf{z}_{\mathbf{x}}^\mathsf{T} \mathbf{Q}_{\mathbf{x}} \mathbf{z}_{\mathbf{x}}}_{\mathsf{Sim}(\mathbf{X})} - \alpha_2 \cdot \underbrace{\mathbf{z}_{\mathbf{x}}^\mathsf{T} \mathbf{B} \mathbf{z}_{\mathbf{y}}}_{\mathsf{Rel}(\mathbf{X},\mathbf{Y})} + \alpha_3 \cdot \underbrace{\mathbf{z}_{\mathbf{y}}^\mathsf{T} \mathbf{Q}_{\mathbf{y}} \mathbf{z}_{\mathbf{y}}}_{\mathsf{Sim}(\mathbf{Y})} \to \min_{\substack{\mathbf{z}_{\mathbf{x}} \geq \mathbf{0}_n, \, \mathbf{1}_n^\mathsf{T} \mathbf{z}_{\mathbf{x}} = 1 \\ \mathbf{z}_{\mathbf{y}} \geq \mathbf{0}_r, \, \mathbf{1}_r^\mathsf{T} \mathbf{z}_{\mathbf{y}} = 1}}.$$

$$\begin{aligned} \mathbf{Q}_{\mathbf{x}} &= \left[\left|\mathsf{corr}(\boldsymbol{\chi}_i, \boldsymbol{\chi}_j)\right|\right]_{i,j=1}^n, \, \mathbf{Q}_{\mathbf{y}} = \left[\left|\mathsf{corr}(\boldsymbol{\nu}_i, \boldsymbol{\nu}_j)\right|\right]_{i,j=1}^r, \, \mathbf{B} = \left[\left|\mathsf{corr}(\boldsymbol{\chi}_i, \boldsymbol{\nu}_j)\right|\right]_{\substack{i=1,\ldots,n\\j=1,\ldots,r}}^n. \\ &\alpha_1 + \alpha_2 + \alpha_3 = 1, \quad \alpha_i \geq 0. \end{aligned}$$

Multivariate QPFS

SymImp penalizes targets that are correlated and are explained by features to a lesser extent.

$$\alpha_1 \cdot \underbrace{\mathbf{z}_{\mathbf{x}}^\mathsf{T} \mathbf{Q}_{\mathbf{x}} \mathbf{z}_{\mathbf{x}}}_{\mathsf{Sim}(\mathbf{X})} - \alpha_2 \cdot \underbrace{\mathbf{z}_{\mathbf{x}}^\mathsf{T} \mathbf{B} \mathbf{z}_{\mathbf{y}}}_{\mathsf{Rel}(\mathbf{X}, \mathbf{Y})} \to \min_{\substack{\mathbf{z}_{\mathbf{x}} \geq \mathbf{0}_n \\ \mathbf{1}_n^\mathsf{T} \mathbf{z}_{\mathbf{x}} = 1}}; \quad \alpha_3 \cdot \underbrace{\mathbf{z}_{\mathbf{y}}^\mathsf{T} \mathbf{Q}_{\mathbf{y}} \mathbf{z}_{\mathbf{y}}}_{\mathsf{Sim}(\mathbf{Y})} + \alpha_2 \cdot \underbrace{\mathbf{z}_{\mathbf{x}}^\mathsf{T} \mathbf{B} \mathbf{z}_{\mathbf{y}}}_{\mathsf{Rel}(\mathbf{X}, \mathbf{Y})} \to \min_{\substack{\mathbf{z}_{\mathbf{y}} \geq \mathbf{0}_r \\ \mathbf{1}_r^\mathsf{T} \mathbf{z}_{\mathbf{y}} = 1}};$$

Minimax approach (MinMax)

$$\min_{\substack{\mathbf{z}_x \geq \mathbf{0}_n \\ \mathbf{1}_n^\mathsf{T} \mathbf{z}_x = 1}} \max_{\substack{\mathbf{1}_r^\mathsf{T} \mathbf{z}_y = 1 \\ \mathbf{1}_r^\mathsf{T} \mathbf{z}_y = 1}} \left(\text{or} \max_{\substack{\mathbf{z}_y \geq \mathbf{0}_r \\ \mathbf{1}_r^\mathsf{T} \mathbf{z}_x = 1}} \min_{\substack{\mathbf{z}_x \geq \mathbf{0}_n \\ \mathbf{1}_r^\mathsf{T} \mathbf{z}_x = 1}} \left(\alpha_1 \cdot \underbrace{\mathbf{z}_x^\mathsf{T} \mathbf{Q}_x \mathbf{z}_x}_{\mathsf{Sim}(\mathbf{X})} - \alpha_2 \cdot \underbrace{\mathbf{z}_x^\mathsf{T} \mathbf{B} \mathbf{z}_y}_{\mathsf{Rel}(\mathbf{X}, \mathbf{Y})} - \alpha_3 \cdot \underbrace{\mathbf{z}_y^\mathsf{T} \mathbf{Q}_y \mathbf{z}_y}_{\mathsf{Sim}(\mathbf{Y})} \right].$$

Theorem (Isachenko, 2018)

For positive definite matrices \mathbf{Q}_x and \mathbf{Q}_y the maxmin and minmax problems have the same optimal value.

Theorem (Isachenko, 2018)

Minimax problem is equivalent to the quadratic problem with n + r + 1 variables.

Shift spectrum to obtain the convex semidefinite relaxation.



Multivariate QPFS

Maximum Relevances (MaxRel)

$$\min_{\substack{\mathbf{z}_{x} \geq \mathbf{0}_{n} \\ \mathbf{1}_{n}^{\mathsf{T}}\mathbf{z}_{x} = 1}} \max_{\substack{\mathbf{r}_{y} \geq \mathbf{0}_{r} \\ \mathbf{1}_{n}^{\mathsf{T}}\mathbf{z}_{y} = 1}} \left[\left(1 - \alpha \right) \cdot \mathbf{z}_{x}^{\mathsf{T}} \mathbf{Q}_{x} \mathbf{z}_{x} - \alpha \cdot \mathbf{z}_{x}^{\mathsf{T}} \mathbf{B} \mathbf{z}_{y} \right].$$

Theorem (Isachenko, 2018)

For positive definite matrices \mathbf{Q}_x the max-min and min-max problems have the same optimal value and the final quadratic problem is convex.

Assymmetric importances (AsymImp)

$$\alpha_1 \cdot \underbrace{\mathbf{z}_{\mathbf{x}}^\mathsf{T} \mathbf{Q}_{\mathbf{x}} \mathbf{z}_{\mathbf{x}}}_{\mathsf{Sim}(\mathbf{X})} - \alpha_2 \cdot \underbrace{\left(\mathbf{z}_{\mathbf{x}}^\mathsf{T} \mathbf{B} \mathbf{z}_{\mathbf{y}} - \mathbf{b}^\mathsf{T} \mathbf{z}_{\mathbf{y}}\right)}_{\mathsf{Rel}(\mathbf{X}, \mathbf{Y})} + \alpha_3 \cdot \underbrace{\mathbf{z}_{\mathbf{y}}^\mathsf{T} \mathbf{Q}_{\mathbf{y}} \mathbf{z}_{\mathbf{y}}}_{\mathsf{Sim}(\mathbf{Y})} \rightarrow \min_{\substack{\mathbf{z}_{\mathbf{x}} \geq \mathbf{0}_n, \mathbf{1}_n^\mathsf{T} \mathbf{z}_{\mathbf{x}} = 1 \\ \mathbf{z}_{\mathbf{y}} \geq \mathbf{0}_r, \mathbf{1}_r^\mathsf{T} \mathbf{z}_{\mathbf{y}} = 1}}.$$

For $b_j = \max_{i=1,...n} [\mathbf{B}]_{i,j}$ coefficients of \mathbf{z}_y in $\mathsf{Rel}(\mathbf{X},\mathbf{Y})$ are non-negative.

Statement

For the univariate case r=1 the proposed strategies SymImp, MinMax, MaxRel, AsymImp coincide with the original QPFS algorithm.



Summary of the proposed algorithms

Algorithm	Problem	Error function $S(\mathbf{z} \mathbf{X},\mathbf{Y})$	
RelAgg	$min\big[Sim(\mathbf{X}) - Rel(\mathbf{X},\mathbf{Y})\big]$	$\min_{\mathbf{z}_{_{X}}} \left[(1 - \alpha) \cdot \mathbf{z}_{_{X}}^{T} \mathbf{Q}_{_{X}} \mathbf{z}_{_{X}} - \alpha \cdot \mathbf{z}_{_{X}}^{T} \mathbf{B} 1_{_{f}} \right]$	
SymImp	$\begin{aligned} \min \left[Sim(\mathbf{X}) - Rel(\mathbf{X}, \mathbf{Y}) \\ + Sim(\mathbf{Y}) \right] \end{aligned}$	$\min_{\mathbf{z}_{x},\mathbf{z}_{y}} \left[\alpha_{1} \cdot \mathbf{z}_{x}^{T} \mathbf{Q}_{x} \mathbf{z}_{x} - \alpha_{2} \cdot \mathbf{z}_{x}^{T} \mathbf{B} \mathbf{z}_{y} + \alpha_{3} \cdot \mathbf{z}_{y}^{T} \mathbf{Q}_{y} \mathbf{z}_{y} \right]$	
MinMax	$\begin{aligned} & \min \left[Sim(\mathbf{X}) - Rel(\mathbf{X}, \mathbf{Y}) \right] \\ & \max \left[Rel(\mathbf{X}, \mathbf{Y}) + Sim(\mathbf{Y}) \right] \end{aligned}$	$\min_{\mathbf{z}_x} \max_{\mathbf{z}_y} \left[\alpha_1 \cdot \mathbf{z}_x^T \mathbf{Q}_x \mathbf{z}_x - \alpha_2 \cdot \mathbf{z}_x^T \mathbf{B} \mathbf{z}_y - \alpha_3 \cdot \mathbf{z}_y^T \mathbf{Q}_y \mathbf{z}_y \right]$	
MaxRel	$\begin{aligned} & \min \left[Sim(\mathbf{X}) - Rel(\mathbf{X}, \mathbf{Y}) \right] \\ & \max \left[Rel(\mathbf{X}, \mathbf{Y}) \right] \end{aligned}$	$\min_{\mathbf{z}_{x}} \max_{\mathbf{z}_{y}} \left[(1 - \alpha) \cdot \mathbf{z}_{x}^{T} \mathbf{Q}_{x} \mathbf{z}_{x} - \alpha \cdot \mathbf{z}_{x}^{T} \mathbf{B} \mathbf{z}_{y} \right]$	
AsymImp	$\begin{aligned} & \min \left[Sim(\mathbf{X}) - Rel(\mathbf{X}, \mathbf{Y}) \right] \\ & \max \left[Rel(\mathbf{X}, \mathbf{Y}) + Sim(\mathbf{Y}) \right] \end{aligned}$	$\left \min_{\mathbf{z}_{x}, \mathbf{z}_{y}} \left[\alpha_{1} \mathbf{z}_{x}^{T} \mathbf{Q}_{x} \mathbf{z}_{x} - \alpha_{2} \left(\mathbf{z}_{x}^{T} \mathbf{B} \mathbf{z}_{y} - \mathbf{b}^{T} \mathbf{z}_{y} \right) + \alpha_{3} \mathbf{z}_{y}^{T} \mathbf{Q}_{y} \mathbf{z}_{y} \right] \right $	

Quality criteria

Scaled RMSE

Prediction quality:

$$\mathsf{sRMSE}(\boldsymbol{Y},\widehat{\boldsymbol{Y}}_a) = \sqrt{\frac{\mathsf{MSE}(\boldsymbol{Y},\widehat{\boldsymbol{Y}}_a)}{\mathsf{MSE}(\boldsymbol{Y},\overline{\boldsymbol{Y}})}} = \frac{\|\boldsymbol{Y}-\widehat{\boldsymbol{Y}}_a\|_2}{\|\boldsymbol{Y}-\overline{\boldsymbol{Y}}\|_2}, \quad \text{where} \quad \widehat{\boldsymbol{Y}}_a = \boldsymbol{X}_a\boldsymbol{\Theta}_a^\mathsf{T}.$$

 $\overline{\mathbf{Y}}$ is a constant prediction.

Multicorrelation

Mean value of miltiple correlation coefficient:

$$\boldsymbol{R}^2 = \frac{1}{r} \mathrm{tr} \left(\mathbf{C}^\mathsf{T} \mathbf{R}^{-1} \mathbf{C} \right); \quad \mathbf{C} = [\mathrm{corr}(\boldsymbol{\chi}_i, \boldsymbol{\nu}_j)]_{\substack{i=1,\ldots,n\\j=1,\ldots,r}}, \ \mathbf{R} = [\mathrm{corr}(\boldsymbol{\chi}_i, \boldsymbol{\chi}_j)]_{i,j=1}^n.$$

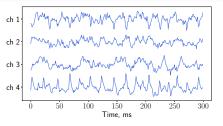
BIC

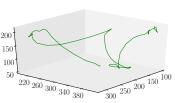
Bayesian Information Criteria is a trade-off between prediction quality and the number of selected features $\|\mathbf{a}\|_0$:

$$\mathsf{BIC} = m \ln \left(\mathsf{MSE}(\mathbf{Y}, \widehat{\mathbf{Y}}_{\mathsf{a}}) \right) + \|\mathbf{a}\|_{0} \cdot \log m.$$



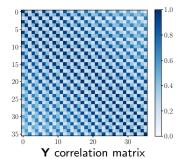
Computational experiment



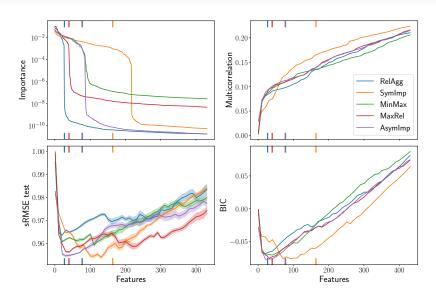


$$\mathbf{X} \in \mathbb{R}^{m \times (32 \cdot 27)}$$
; $\mathbf{Y} \in \mathbb{R}^{m \times 3k}$.

$$\mathbf{Y} = \begin{pmatrix} x_1 \ y_1 \ z_1 & \dots & x_k & y_k & z_k \\ x_2 \ y_2 \ z_2 & \dots & x_{k+1} \ y_{k+1} \ z_{k+1} \\ \dots & \dots & \dots \\ x_m \ y_m \ z_m & \dots & x_{m+k} \ y_{m+k} \ z_{m+k} \end{pmatrix}$$



Quality criteria evaluation



Stability of selected feature subsets

Experiment design

• generate bootstrap data

$$(\mathbf{X},\mathbf{Y}) \rightarrow \big\{ (\mathbf{X}_1,\mathbf{Y}_1),\ldots,(\mathbf{X}_s,\mathbf{Y}_s) \big\};$$

solve feature selection problem

$$\big\{(\boldsymbol{X}_1,\boldsymbol{Y}_1),\ldots,(\boldsymbol{X}_s,\boldsymbol{Y}_s)\big\}\to\{\boldsymbol{z}_1,\ldots,\boldsymbol{z}_s\};$$

calculate statistics

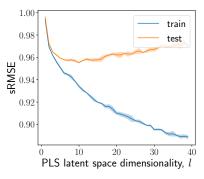
$$\{\mathbf{z}_1,\ldots,\mathbf{z}_s\} \to \{\mathsf{RMSE}, \|\mathbf{a}\|_0, \mathsf{Spearman}\ \rho, \ell_2\ \mathsf{dist}\}.$$

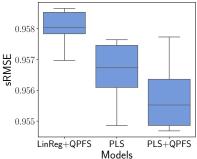
	sRMSE	$\ \mathbf{a}\ _0$	Spearman $ ho$	ℓ_2 dist
RelAgg	0.965 ± 0.002	26.8 ± 3.8	0.915 ± 0.016	0.145 ± 0.018
SymImp	0.961 ± 0.001	224.4 ± 9.0	0.910 ± 0.017	0.025 ± 0.002
MinMax	0.961 ± 0.002	101.0 ± 2.1	0.932 ± 0.009	0.059 ± 0.004
MaxRel	0.958 ± 0.003	41.2 ± 5.2	0.862 ± 0.027	0.178 ± 0.010
AsymImp	0.955 ± 0.001	85.8 ± 10.2	0.926 ± 0.011	0.078 ± 0.007

QPFS vs PLS

Design of experiment

To compare feature selection and dimensionality reduction for linear regression and PLS regression models.





Results

- The problem of ECoG signal decoding in high dimensional spaces is investigated.
- Dimensionality reduction technique with space structure analysis is investigated.
- Feature selection methods which take into accout structure of both input and target spaces are proposed.
- The combination of feature selection and dimensionality reduction is proposed.
- Proposed feature selection algorithms give the stable and adequate solutions.

Conclusion

Publications

- Isachenko R., Strijov V. Metric learning for time series multiclass classification *Informatics and Applications*, 10(2), 2016.
- Isachenko R. et al. Feature Generation for Physical Activity Classification.
 Artificial Intellegence and Decision Making, 2018, submitted to the journal.
- Isachenko R., Strijov V. Quadratic programming optimization for Newton method. Lobachevskii Journal of Mathematics, 2018, accepted to the journal.
- Isachenko R., Strijov V. Dimensionality reduction for multivariate ECoG-based data. Chemometrics, 2018, ready for submission.

Conferences

- Lomonosov, 2016, Moscow. Metric learning in multiclass time series classification.
- Intelligent Data Processing Conference, 2016, Barcelona. Multimodel forecasting multiscale time series in internet of things.
- MMRO, 2017, Taganrog. Local models for classification of complex structured objects.