

# Signal Decoding in Multicorrelated High-Dimensional Spaces

Roman Isachenko

Skoltech advisor: Maxim Fedorov

MIPT advisor: Vadim Strijov

April 27, 2018.

# Signal decoding problem

## Goal

- Investigate input, latent, and target spaces for signal decoding problem.
- Build a stable model for time series decoding in the case of multicorrelated object description.
- Suggest dimensionality reduction algorithm for signal decoding problem.

## Challenge

- Measurements of spatial-temporal data are interacted since sensors are close to each other.
- Target variable is a vector whose elements are dependent.

## Solution

Propose to use joint description of independent and target variables. This description allows to reduce the multicorrelation and to build stable adequate model with acceptable accuracy.

## Related works

- Katrutsa A., Strijov V. Comprehensive study of feature selection methods to solve multicollinearity problem according to evaluation criteria. // *Expert Systems with Applications* 76, 2017.
- Li J. et al. Feature selection: A data perspective // *ACM Computing Surveys (CSUR)* 50(6), 2017.
- Eliseyev A. et al. Iterative N-way partial least squares for a binary self-paced brain-computer interface in freely moving animals // *Journal of neural engineering* 4(8), 2011.
- Rodriguez-Lujan I. et al. Quadratic programming feature selection // *Journal of Machine Learning Research* 11(Apr), 2010.
- Motrenko A., Strijov V. Multi-way Feature Selection for ECoG-based Brain-Computer Interface // *Expert Systems with Applications* Submitted to the journal.

# Application: Brain Computer Interface (BCI)

## Aim

Develop systems to help people with a severe motor control disability recover mobility.

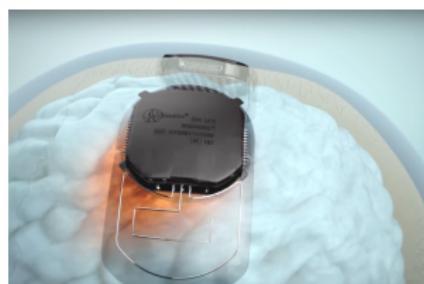
## Hypothesis

"When we imagine making a movement, we trigger the same electrical activity in the motor cortex of the brain as when we actually perform that activity." \*

## Solution

Record electrical signals – electrocorticograms (ECoG), decode them to drive complex objects, for example, to move the limbs of an exoskeleton.

\* [http://clinatec.fr/](http://clinatec.fr;);



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Eliseyev A. et al. CLINATEC BCI platform based on the ECoG-recording implant WIMAGINE and the innovative signal-processing: preclinical results, 2014.

## Multivariate regression

### Model

Forecast a dependent variable  $\mathbf{y} \in \mathbb{R}^r$  from an independent input object  $\mathbf{x} \in \mathbb{R}^n$

$$\mathbf{y} = \Theta \mathbf{x} + \varepsilon, \quad \Theta \in \mathbb{R}^{r \times n}$$

### Given

Dataset  $(\mathbf{X}, \mathbf{Y})$ , design matrix  $\mathbf{X} \in \mathbb{R}^{m \times n}$ , target matrix  $\mathbf{Y} \in \mathbb{R}^{m \times r}$ ,

$$\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_m]^T = [\chi_1, \dots, \chi_n]; \quad \mathbf{Y} = [\mathbf{y}_1, \dots, \mathbf{y}_m]^T = [\nu_1, \dots, \nu_r].$$

### Error function

$$S(\Theta | \mathbf{X}, \mathbf{Y}) = \left\| \mathbf{Y}_{m \times r} - \mathbf{X}_{m \times n} \cdot \Theta_{r \times n}^T \right\|_2^2 \rightarrow \min_{\Theta}.$$
$$\Theta = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}.$$

The linear dependent columns of the matrix  $\mathbf{X}$  leads to an instable solution.  
To avoid the strong linear dependence, feature selection and dimensionality reduction techniques are used.

## Feature selection problem statement

### Goal

Find the index set  $\mathcal{A} = \{1, \dots, n\}$  of  $\mathbf{X}$  columns.

### Quality Criteria

To select the set  $\mathcal{A}$  among all possible  $2^n - 1$  subsets, introduce the feature selection quality criteria

$$\mathcal{A} = \arg \max_{\mathcal{A}' \subseteq \{1, \dots, n\}} Q(\mathcal{A}' | \mathbf{X}, \mathbf{Y}).$$

Once the solution  $\mathcal{A}$  is known:

$$S(\boldsymbol{\Theta}_{\mathcal{A}} | \mathbf{X}_{\mathcal{A}}, \mathbf{Y}) = \left\| \mathbf{Y} - \mathbf{X}_{\mathcal{A}} \boldsymbol{\Theta}_{\mathcal{A}}^T \right\|_2^2 \rightarrow \min_{\boldsymbol{\Theta}_{\mathcal{A}}},$$

where the subscript  $\mathcal{A}$  indicates columns with indices from the set  $\mathcal{A}$ .

## Quadratic Programming Feature Selection

$$\|\nu - \mathbf{X}\theta\|_2^2 \rightarrow \min_{\theta \in \mathbb{R}^n} .$$

## Quadratic Programming Feature Selection

$$(1 - \alpha) \cdot \underbrace{\mathbf{a}^T \mathbf{Q} \mathbf{a}}_{\text{Sim}(\mathbf{X})} - \alpha \cdot \underbrace{\mathbf{b}^T \mathbf{a}}_{\text{Rel}(\mathbf{X}, \nu)} \rightarrow \min_{\substack{\mathbf{a} \geq \mathbf{0}_n \\ \mathbf{1}_n^T \mathbf{a} = 1}} .$$

- $\mathbf{a} \in \mathbb{R}^n$  — feature importances;
- $\mathbf{Q} \in \mathbb{R}^{n \times n}$  - pairwise feature similarities;
- $\mathbf{b} \in \mathbb{R}^n$  - feature relevances to the target vector.

$$j \in \mathcal{A}^* \Leftrightarrow a_j > \tau$$

## Quality Criteria

$$\mathcal{A} = \arg \max_{\mathcal{A}' \subseteq \{1, \dots, n\}} Q(\mathcal{A}' | \mathbf{X}, \nu) \Leftrightarrow \arg \min_{\mathbf{a} \geq \mathbf{0}_n, \mathbf{1}_n^T \mathbf{a} = 1} [\mathbf{a}^T \mathbf{Q} \mathbf{a} - \alpha \cdot \mathbf{b}^T \mathbf{a}] .$$

# Quadratic Programming Feature Selection

## Quality Criteria

$$\mathcal{A} = \arg \max_{\mathcal{A}' \subseteq \{1, \dots, n\}} Q(\mathcal{A}' | \mathbf{X}, \nu) \Leftrightarrow \arg \min_{\mathbf{a} \geq \mathbf{0}_n, \mathbf{1}_n^T \mathbf{a} = 1} [\mathbf{a}^T \mathbf{Q} \mathbf{a} - \alpha \cdot \mathbf{b}^T \mathbf{a}].$$

## Similarity measure

- Correlation

$$|\text{corr}(\mathbf{x}, \mathbf{y})| = \left| \frac{\text{cov}(\mathbf{x}, \mathbf{y})}{\sqrt{\text{Var}(\mathbf{x})\text{Var}(\mathbf{y})}} \right|$$

- Mutual information

$$I(\mathbf{x}, \mathbf{y}) = \int \int p(\mathbf{x}, \mathbf{y}) \log \frac{p(\mathbf{x}, \mathbf{y})}{p(\mathbf{x})p(\mathbf{y})} d\mathbf{x}d\mathbf{y}.$$

$$\mathbf{Q} = \{|\text{corr}(\chi_i, \chi_j)|\}_{i,j=1}^n, \quad \mathbf{b} = \{|\text{corr}(\chi_i, \nu)|\}_{i=1}^n.$$

## Statement

In the case of semidefinite matrix  $\mathbf{Q}$  the QPFS problem is convex.

$$\mathbf{Q} \rightarrow \mathbf{Q} - \lambda_{\min} \mathbf{I}$$

## Multivariate QPFS

### Relevance aggregation

$$\mathbf{Q} = \left\{ |\text{corr}(\chi_i, \chi_j)| \right\}_{i,j=1}^n, \quad \mathbf{b} = \left\{ \sum_{k=1}^r |\text{corr}(\chi_i, \nu_k)| \right\}_{i=1}^n.$$

This approach does not use the dependencies in the columns of the matrix  $\mathbf{Y}$ .

### Example:

$$\mathbf{X} = [\chi_1, \chi_2, \chi_3], \quad \mathbf{Y} = [\underbrace{\nu_1, \nu_1, \dots, \nu_1}_{r-1}, \nu_2],$$
$$\mathbf{Q} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0.8 \\ 0 & 0.8 & 1 \end{bmatrix}, \quad \mathbf{B} = \underbrace{\begin{bmatrix} 0.4 & \dots & 0.4 & 0 \\ 0.5 & \dots & 0.5 & 0.8 \\ 0.8 & \dots & 0.8 & 0.1 \end{bmatrix}}_{r-1}, \quad \mathbf{b} = \begin{bmatrix} (r-1) \cdot 0.4 + 0 \\ (r-1) \cdot 0.5 + 0.8 \\ (r-1) \cdot 0.8 + 0.1 \end{bmatrix}$$

Best subset:  $[\chi_1, \chi_2]$ .

QPFS ( $r = 2$ ):  $\mathbf{a} = [0.37, 0.61, 0.02]$ .

QPFS ( $r = 5$ ):  $\mathbf{a} = [0.40, 0.17, 0.43]$ .

## Symmetric Importance

Penalize correlated targets by  $\text{Sim}(\mathbf{Y})$

$$\alpha_1 \cdot \underbrace{\mathbf{a}_x^T \mathbf{Q}_x \mathbf{a}_x}_{\text{Sim}(\mathbf{X})} - \alpha_2 \cdot \underbrace{\mathbf{a}_x^T \mathbf{B} \mathbf{a}_y}_{\text{Rel}(\mathbf{X}, \mathbf{Y})} + \alpha_3 \cdot \underbrace{\mathbf{a}_y^T \mathbf{Q}_y \mathbf{a}_y}_{\text{Sim}(\mathbf{Y})} \rightarrow \min_{\substack{\mathbf{a}_x \geq \mathbf{0}_n, \mathbf{1}_n^T \mathbf{a}_x = 1 \\ \mathbf{a}_y \geq \mathbf{0}_r, \mathbf{1}_r^T \mathbf{a}_y = 1}}.$$

$$\mathbf{Q}_x = \{|\text{corr}(\chi_i, \chi_j)|\}_{i,j=1}^n, \quad \mathbf{Q}_y = \{|\text{corr}(\nu_i, \nu_j)|\}_{i,j=1}^r, \quad \mathbf{B} = \{|\text{corr}(\chi_i, \nu_j)|\}_{\substack{i=1, \dots, n \\ j=1, \dots, r}}.$$

$$\alpha_1 + \alpha_2 + \alpha_3 = 1 \quad \alpha_i \geq 0, \quad i = 1, 2, 3.$$

### Statement

Balance between the terms  $\text{Sim}(\mathbf{X})$  and  $\text{Rel}(\mathbf{X}, \mathbf{Y})$  for the problem is achieved by the following coefficients:

$$\alpha_1 = \frac{(1 - \alpha_3)\bar{\mathbf{B}}}{\bar{\mathbf{Q}}_x + \bar{\mathbf{B}}}; \quad \alpha_2 = \frac{(1 - \alpha_3)\bar{\mathbf{Q}}_x}{\bar{\mathbf{Q}}_x + \bar{\mathbf{B}}}; \quad \alpha_3 \in [0, 1],$$

where  $\bar{\mathbf{Q}}_x, \bar{\mathbf{B}}$  are the mean values of  $\mathbf{Q}_x$  and  $\mathbf{B}$  respectively.

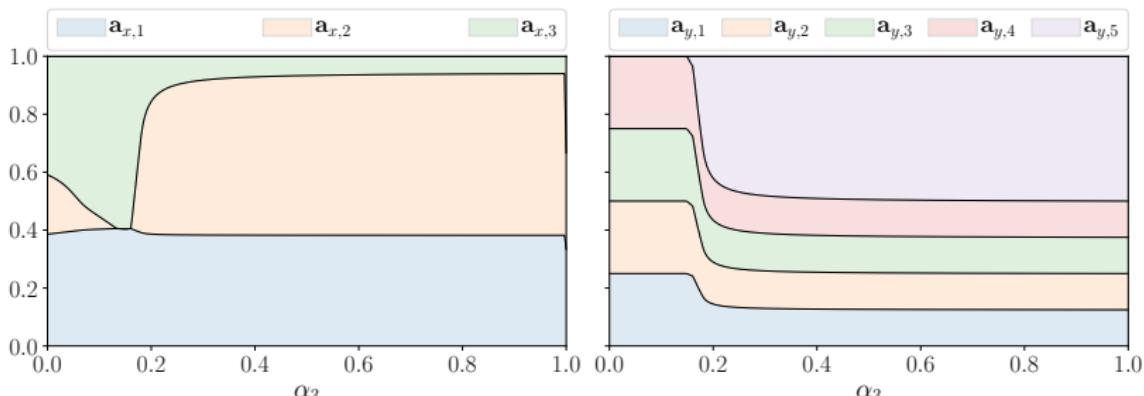
## Multivariate QPFS

Example:

$$\mathbf{X} = [\chi_1, \chi_2, \chi_3], \quad \mathbf{Y} = [\underbrace{\nu_1, \nu_1, \dots, \nu_1}_{r-1}, \nu_2],$$
$$\mathbf{Q} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0.8 \\ 0 & 0.8 & 1 \end{bmatrix}, \quad \mathbf{B} = \underbrace{\begin{bmatrix} 0.4 & \dots & 0.4 & 0 \\ 0.5 & \dots & 0.5 & 0.8 \\ 0.8 & \dots & 0.8 & 0.1 \end{bmatrix}}_{r-1}, \quad \mathbf{b} = \begin{bmatrix} (r-1) \cdot 0.4 + 0 \\ (r-1) \cdot 0.5 + 0.8 \\ (r-1) \cdot 0.8 + 0.1 \end{bmatrix}$$

$$\mathbf{Q}_x = \mathbf{Q}; \mathbf{Q}_y : \text{corr}(\nu_1, \nu_2) = 0.2 \text{ all others entries} = 1.$$

Best subset:  $[\chi_1, \chi_2]$ .



## Min-max / Max-min

Symmetric Importances penalizes targets that are correlated and are not sufficiently explained by the features.

$$\alpha_1 \cdot \underbrace{\mathbf{a}_x^T \mathbf{Q}_x \mathbf{a}_x}_{\text{Sim}(\mathbf{X})} - \alpha_2 \cdot \underbrace{\mathbf{a}_x^T \mathbf{B} \mathbf{a}_y}_{\text{Rel}(\mathbf{X}, \mathbf{Y})} \rightarrow \min_{\substack{\mathbf{a}_x \geq \mathbf{0}_n, \\ \mathbf{1}_n^T \mathbf{a}_x = 1}} ; \quad \alpha_3 \cdot \underbrace{\mathbf{a}_y^T \mathbf{Q}_y \mathbf{a}_y}_{\text{Sim}(\mathbf{Y})} + \alpha_2 \cdot \underbrace{\mathbf{a}_x^T \mathbf{B} \mathbf{a}_y}_{\text{Rel}(\mathbf{X}, \mathbf{Y})} \rightarrow \min_{\substack{\mathbf{a}_y \geq \mathbf{0}_r, \\ \mathbf{1}_r^T \mathbf{a}_y = 1}} .$$

## Min-max / Max-min

$$\min_{\substack{\mathbf{a}_x \geq \mathbf{0}_n \\ \mathbf{1}_n^T \mathbf{a}_x = 1}} \max_{\substack{\mathbf{a}_y \geq \mathbf{0}_r \\ \mathbf{1}_r^T \mathbf{a}_y = 1}} \left( \text{or} \max_{\substack{\mathbf{a}_y \geq \mathbf{0}_r \\ \mathbf{1}_r^T \mathbf{a}_y = 1}} \min_{\substack{\mathbf{a}_x \geq \mathbf{0}_n \\ \mathbf{1}_n^T \mathbf{a}_x = 1}} \right) \left[ \alpha_1 \cdot \underbrace{\mathbf{a}_x^T \mathbf{Q}_x \mathbf{a}_x}_{\text{Sim}(\mathbf{X})} - \alpha_2 \cdot \underbrace{\mathbf{a}_x^T \mathbf{B} \mathbf{a}_y}_{\text{Rel}(\mathbf{X}, \mathbf{Y})} - \alpha_3 \cdot \underbrace{\mathbf{a}_y^T \mathbf{Q}_y \mathbf{a}_y}_{\text{Sim}(\mathbf{Y})} \right] .$$

$$\mathcal{A} = \arg \max_{\mathcal{A}' \subseteq \{1, \dots, n\}} Q(\mathcal{A}' | \mathbf{X}, \mathbf{Y}) \Leftrightarrow \arg \min_{\mathbf{a}_x \geq \mathbf{0}_n, \mathbf{1}_n^T \mathbf{a}_x = 1} \left[ \max_{\substack{\mathbf{a}_y \geq \mathbf{0}_r \\ \mathbf{1}_r^T \mathbf{a}_y = 1}} f(\mathbf{a}_x, \mathbf{a}_y) \right] .$$

## Theorem

For positive definite matrices  $\mathbf{Q}_x$  and  $\mathbf{Q}_y$  the max-min and min-max problems have the same optimal value.

## Min-max / Max-min

Lagrangian for fixed  $\mathbf{a}_x$

$$L(\mathbf{a}_x, \mathbf{a}_y, \lambda, \mu) = \alpha_1 \cdot \mathbf{a}_x^T \mathbf{Q}_x \mathbf{a}_x - \alpha_2 \cdot \mathbf{a}_x^T \mathbf{B} \mathbf{a}_y - \alpha_3 \cdot \mathbf{a}_y^T \mathbf{Q}_y \mathbf{a}_y + \lambda \cdot (\mathbf{1}_r^T \mathbf{a}_y - 1) + \mu^T \mathbf{a}_y.$$

### Theorem

Min-max problem is equivalent to the following quadratic problem with  $n + r + 1$  variables

$$\min_{\substack{\mathbf{a}_x \geq \mathbf{0}_n, \mathbf{1}_n^T \mathbf{a}_x = 1 \\ \lambda, \mu \geq \mathbf{0}_r}} g(\mathbf{a}_y, \lambda, \mu), \quad \text{where}$$

$$\begin{aligned} g(\mathbf{a}_x, \lambda, \mu) &= \max_{\mathbf{a}_y \in \mathbb{R}^r} L(\mathbf{a}_x, \mathbf{a}_y, \lambda, \mu) = \mathbf{a}_x^T \left( -\frac{\alpha_2^2}{4\alpha_3} \mathbf{B} \mathbf{Q}_y^{-1} \mathbf{B}^T - \alpha_1 \cdot \mathbf{Q}_x \right) \mathbf{a}_x \\ &\quad - \frac{1}{4\alpha_3} \lambda^2 \cdot \mathbf{1}_r^T \mathbf{Q}_y^{-1} \mathbf{1}_r - \frac{1}{4\alpha_3} \mu^T \mathbf{Q}_y^{-1} \mu + \frac{\alpha_2}{2\alpha_3} \lambda \cdot \mathbf{1}_r^T \mathbf{Q}_y^{-1} \mathbf{B}^T \mathbf{a}_x \\ &\quad - \frac{1}{2\alpha_3} \lambda \cdot \mathbf{1}_r^T \mathbf{Q}_y^{-1} \mu + \frac{\alpha_2}{2\alpha_3} \mu^T \mathbf{Q}_y^{-1} \mathbf{B}^T \mathbf{a}_x + \lambda. \end{aligned}$$

The problem is not convex. If we shift the spectrum for the matrix of quadratic form, the optimality is lost.

## Minimax Relevances

Drop the term  $\text{Sim}(\mathbf{Y})$ .

$$\min_{\substack{\mathbf{a}_x \geq \mathbf{0}_n \\ \mathbf{1}_n^T \mathbf{a}_x = 1}} \max_{\substack{\mathbf{a}_y \geq \mathbf{0}_r \\ \mathbf{1}_r^T \mathbf{a}_y = 1}} \left[ (1 - \alpha) \cdot \mathbf{a}_x^T \mathbf{Q}_x \mathbf{a}_x - \alpha \cdot \mathbf{a}_x^T \mathbf{B} \mathbf{a}_y \right].$$

Dual function

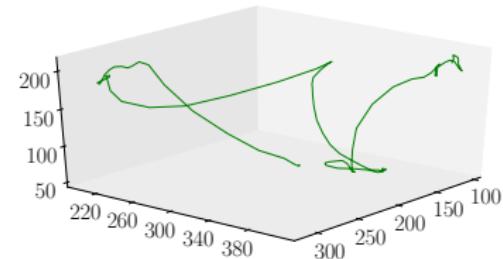
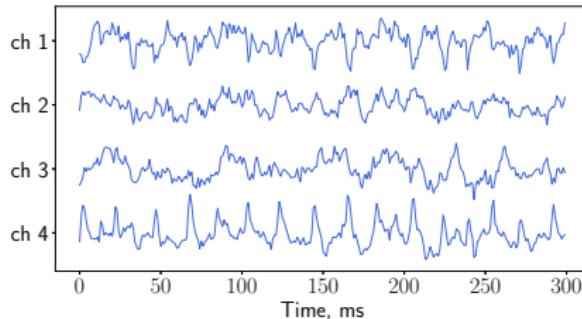
$$g(\mathbf{a}_x, \lambda, \mu) = \begin{cases} (1 - \alpha) \cdot \mathbf{a}_x^T \mathbf{Q}_x \mathbf{a}_x - \lambda, & \alpha \cdot \mathbf{B}^T \mathbf{a}_x = \lambda \cdot \mathbf{1}_r + \mu; \\ +\infty, & \text{otherwise.} \end{cases}$$

Statement

*For the case  $r = 1$  the proposed strategies coincide with the original QPFS algorithm.*

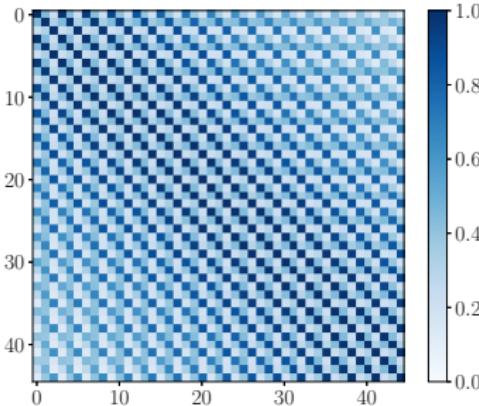
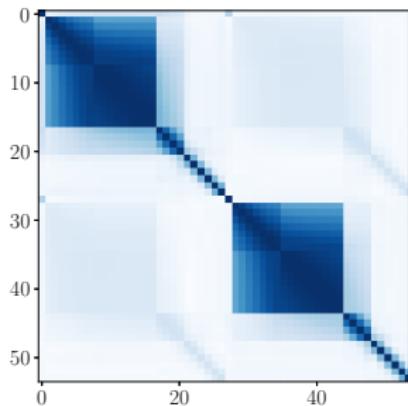
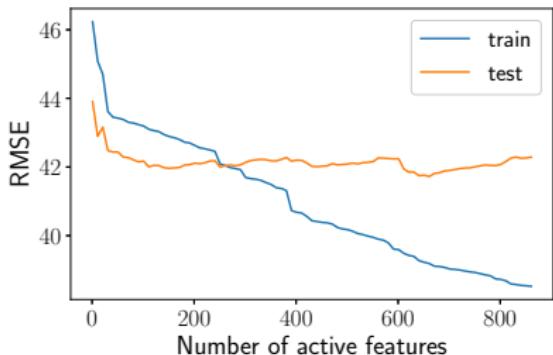
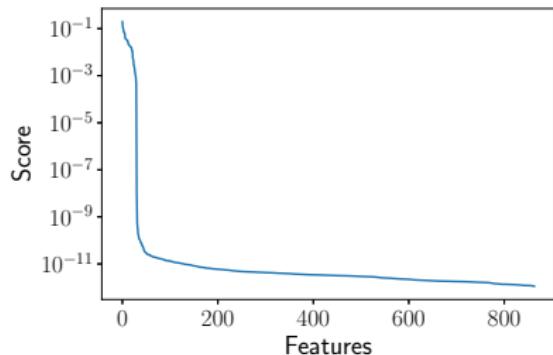
# Computational experiment

## Data example

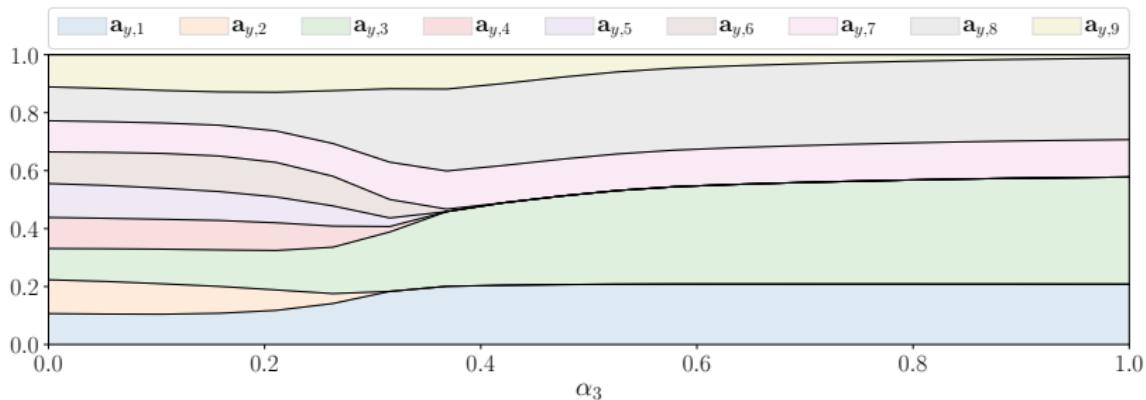
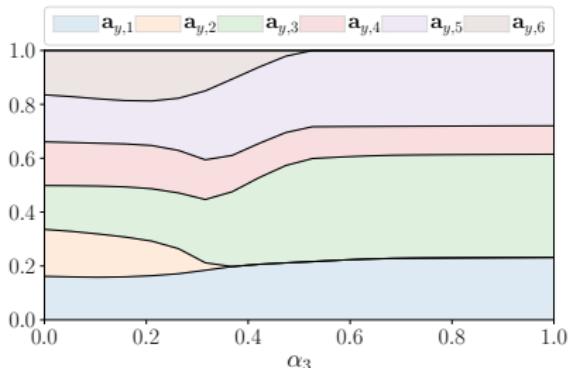
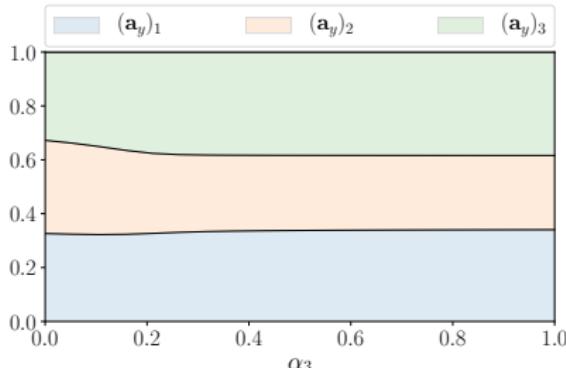


$$\mathbf{X} \in \mathbb{R}^{m \times (32 \cdot 27)}, \quad \mathbf{Y} = \begin{pmatrix} x_1 & y_1 & z_1 & \dots & x_k & y_k & z_k \\ x_2 & y_2 & z_2 & \dots & x_{k+1} & y_{k+1} & z_{k+1} \\ \dots & \dots & \dots & & \dots & & \dots \\ x_m & y_m & z_m & \dots & x_{m+k} & y_{m+k} & z_{m+k} \end{pmatrix} \in \mathbb{R}^{m \times 3k}.$$

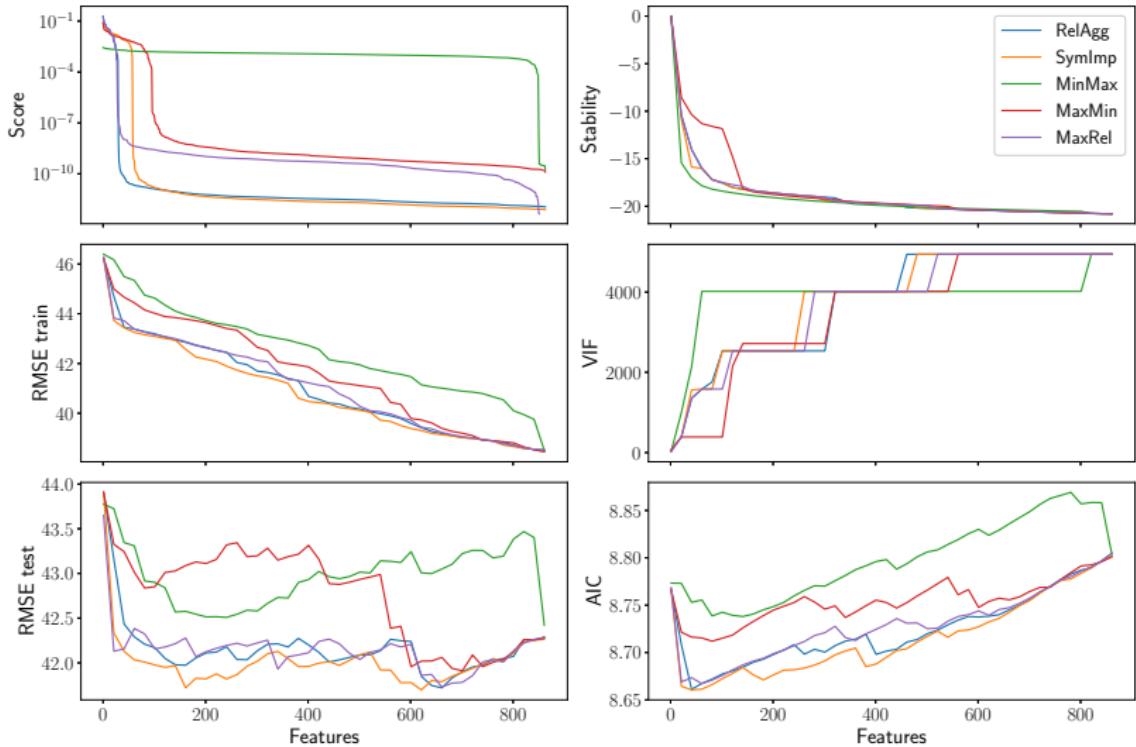
## Data redundancy



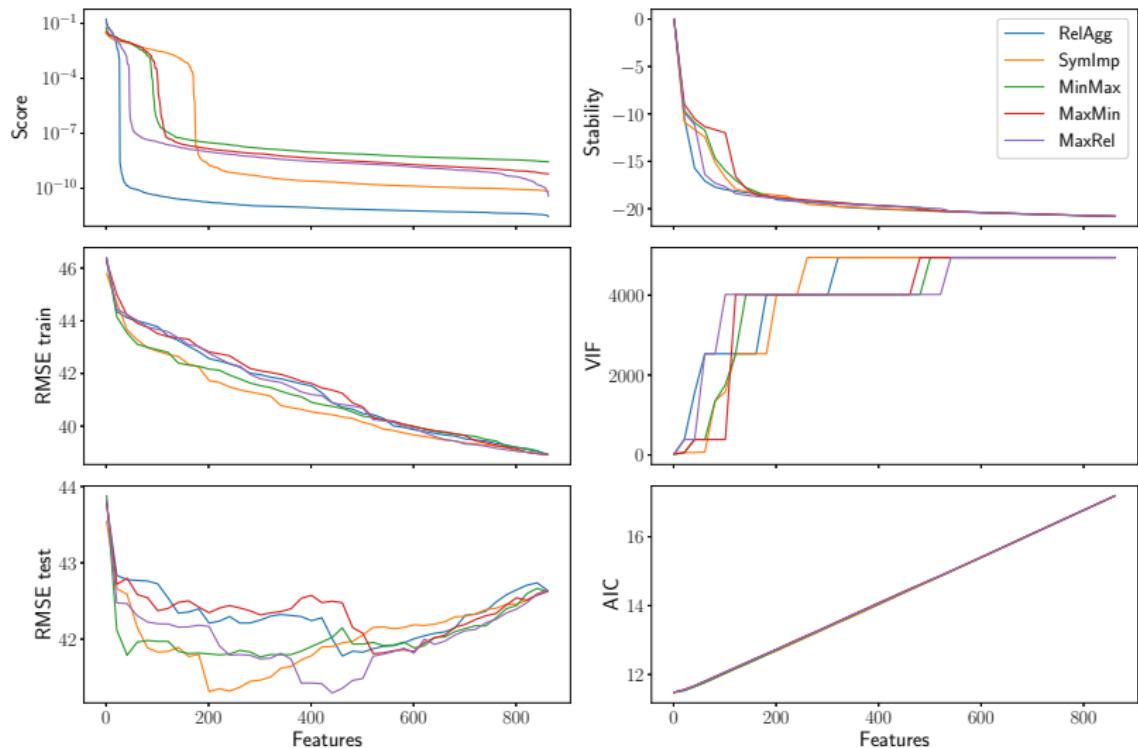
## Target importances



## Autoregression step = 1



## Autoregression step = 30



## Conclusion

- BCI signal decoding problem is investigated.
- Feature selection algorithms for spatio-temporal data are proposed.
- Suggested algorithms are explored and compared.

## Publications

- Isachenko R. et al. Feature Generation for Physical Activity Classification. *Artificial Intelligence and decision making*, submitted.
- Isachenko R., Strijov V. Quadratic programming optimization for Newton method. *Lobachevskii Journal of Mathematics*, submitted.
- Isachenko R., Vladimirova M., Strijov V. Dimensionality reduction for time series decoding and forecasting problems. Ready for submission.



## Feature categorization

1. non-relevant features

$$\{j : \text{corr}(\chi_j, \nu_k) = 0, \forall k \in \{1, \dots, r\}\};$$

2. non-**X**-correlated features, which are relevant to non-**Y**-correlated targets

$$\{j : (\text{VIF}(\chi_j) < 10) \text{ and } (\text{VIF}(\nu_k) < 10, \forall k \in \{1, \dots, r\} : \text{corr}(\chi_j, \nu_k) \neq 0)\};$$

3. non-**X**-correlated features, which are relevant to **Y**-correlated targets

$$\{j : (\text{VIF}(\chi_j) < 10) \text{ and } (\exists k \in \{1, \dots, r\} : \text{VIF}(\nu_k) > 10 \& \text{corr}(\chi_j, \nu_k) \neq 0)\};$$

4. **X**-correlated features, which are relevant to non-**Y**-correlated targets

$$\{j : (\text{VIF}(\chi_j) > 10) \text{ and } (\text{VIF}(\nu_k) < 10, \forall k \in \{1, \dots, r\} : \text{corr}(\chi_j, \nu_k) \neq 0)\};$$

5. **X**-correlated features, which are relevant to **Y**-correlated targets

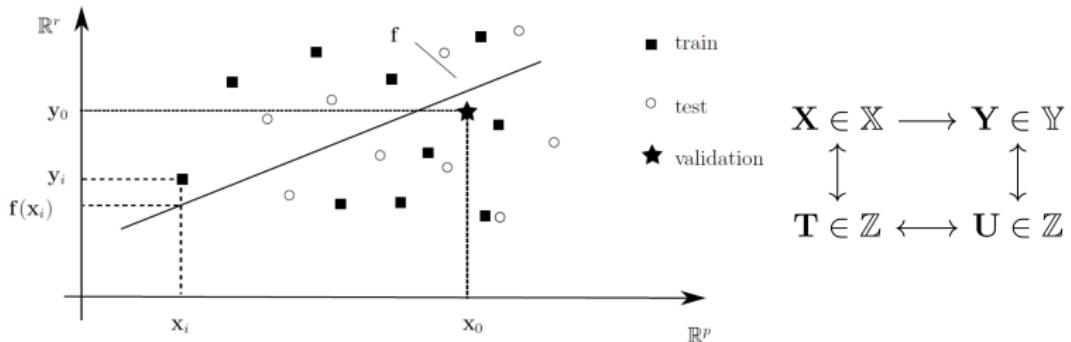
$$\{j : (\text{VIF}(\chi_j) > 10) \text{ and } (\exists k \in \{1, \dots, r\} : \text{VIF}(\nu_k) > 10 \& \text{corr}(\chi_j, \nu_k) \neq 0)\}.$$

$$r = \text{corr}(\chi, \nu), \quad t = \frac{r\sqrt{m-2}}{1-r^2} \sim \text{St}(m-2).$$

$$\text{VIF}(\chi_j) = \frac{1}{1-R_j^2}, \quad \text{VIF}(\nu_k) = \frac{1}{1-R_k^2},$$

where  $R_j^2$  ( $R_k^2$ ) are coefficients of determination for the regression of  $\chi_j$  ( $\nu_k$ ) on the other features(targets).

## Problem Statement



## Partial Least Squares (PLS)

$$\mathbf{X}_{m \times n} = \mathbf{T}_{m \times l} \cdot \mathbf{P}^T_{l \times n} + \mathbf{F}_{m \times n} = \sum_{k=1}^l \mathbf{t}_k \cdot \mathbf{p}_k^T + \mathbf{F}_{m \times n}$$

$$\mathbf{Y}_{m \times r} = \mathbf{U}_{m \times l} \cdot \mathbf{Q}^T_{l \times r} + \mathbf{E}_{m \times r} = \sum_{k=1}^l \mathbf{t}_k \cdot \mathbf{q}_k^T + \mathbf{E}_{m \times r}$$

- map  $\mathbf{X}$  into low-dimensional  $\mathbf{T}$ ;
- map  $\mathbf{Y}$  into low-dimensional  $\mathbf{U}$ ;
- maximize correlation between  $\mathbf{t}_k$  and  $\mathbf{u}_k$ .

$$\hat{\mathbf{Y}} = \mathbf{T} \text{diag}(\beta) \mathbf{Q}^T = \mathbf{X} \Theta.$$

## PLS Example

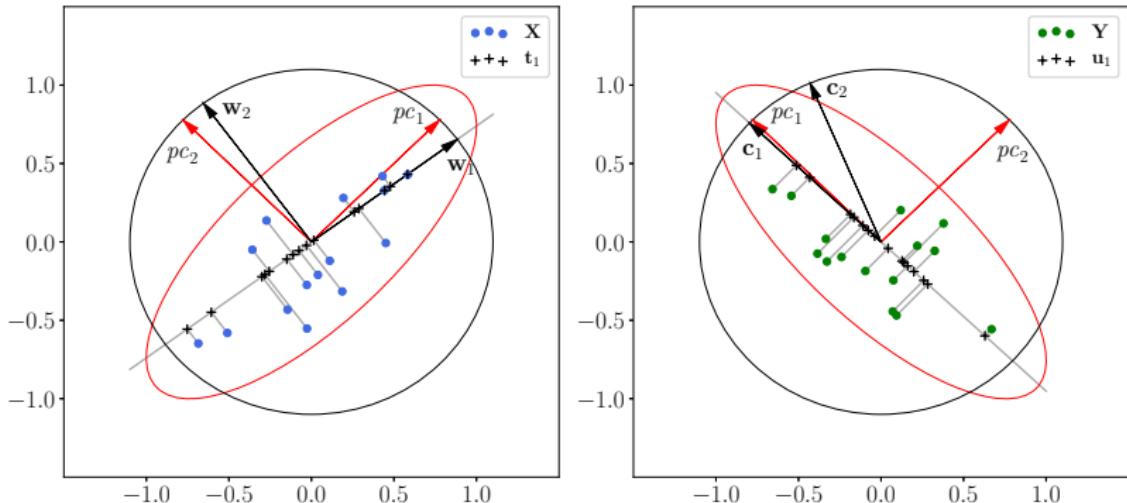


Figure: The result of the PLS algorithm for the case  $n = r = l = 2$ .

# Computational experiment

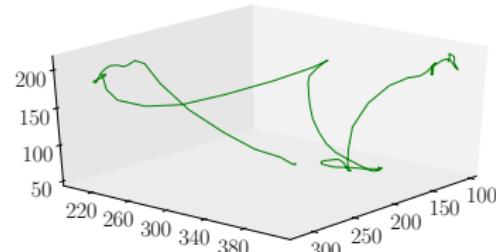
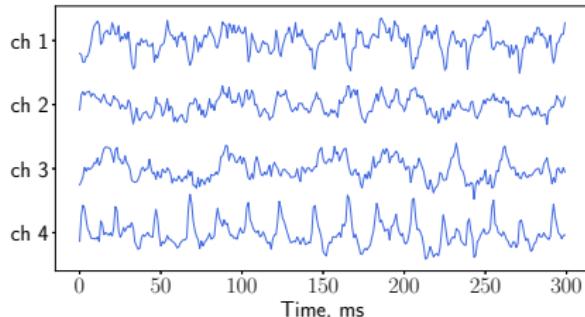
## Datasets

- energy consumption
- electrocorticogram signals (ECoG)

## Autoregressive approach

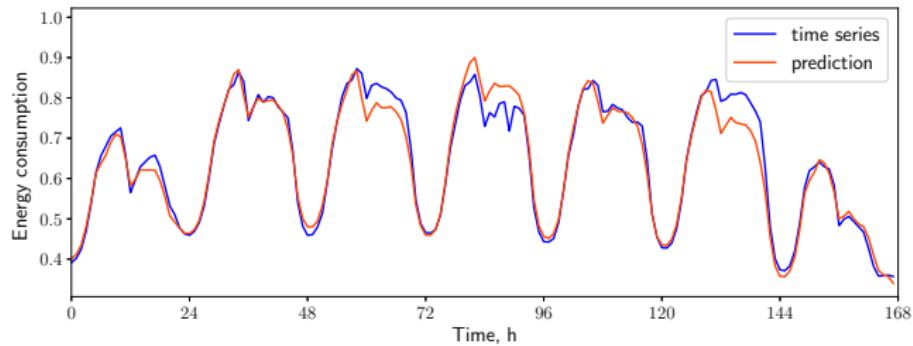
$$\mathbf{X} = \begin{pmatrix} x_1 & x_2 & \dots & x_n \\ x_2 & x_3 & \dots & x_{n+1} \\ \dots & \dots & \dots & \dots \\ x_{T-n+1} & x_{T-n+2} & \dots & x_T \end{pmatrix}$$

## ECoG data



# Computational experiment

## Energy consumption

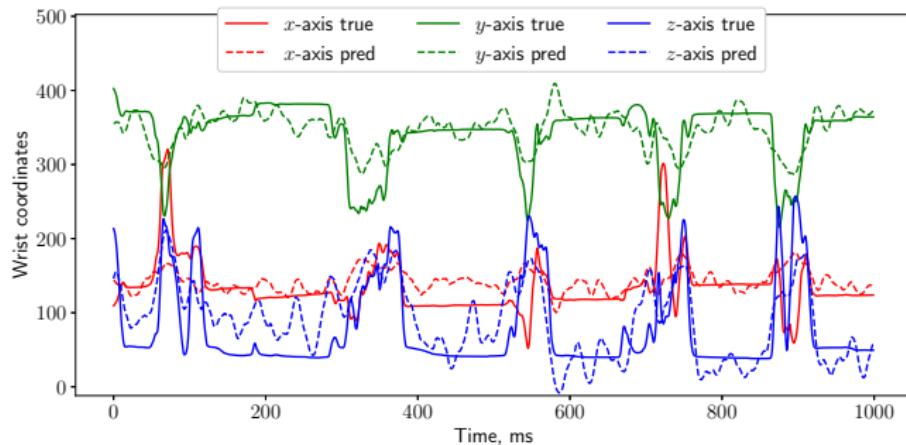


## Results

- Space dimensionalities:  $\mathbf{X} = 700 \times (24 \cdot 7)$ ,  $\mathbf{Y} = 700 \times 24$ .
- Dimensionality of latent space: 14
- NMSE: 0.047

## Computational experiment

ECoG



## Results

- Space dimensionalities:  $\mathbf{X} = 13000 \times (864 \cdot 18)$ ,  $\mathbf{Y} = 13000 \times 3$ .
- Dimensionality of latent space: 16
- NMSE: 0.731

# Quadratic Programming Model Selection

## QPFS

- works for linear problems;
- does not take into account the model;
- ignores the structure of the target space.

## Problem

$$\underbrace{(1 - \alpha)\mathbf{z}^T \mathbf{Q}\mathbf{z}}_{\text{Sim}} - \underbrace{\alpha \mathbf{b}^T \mathbf{z}}_{\text{Rel}} \rightarrow \min_{\substack{\mathbf{z} \in \mathbb{R}_+^P \\ \|\mathbf{z}\|_1=1}} .$$

- $\mathbf{z} \in \mathbb{R}^P$  — weight importances;
- $\mathbf{Q} \in \mathbb{R}^{P \times P}$  - pairwise weights interactions;
- $\mathbf{b} \in \mathbb{R}^P$  - weight relevances to the target vector.

$$w_j = 0 \Leftrightarrow z_j < \tau.$$