

### 机器学习A 15.支持向量机 SVM

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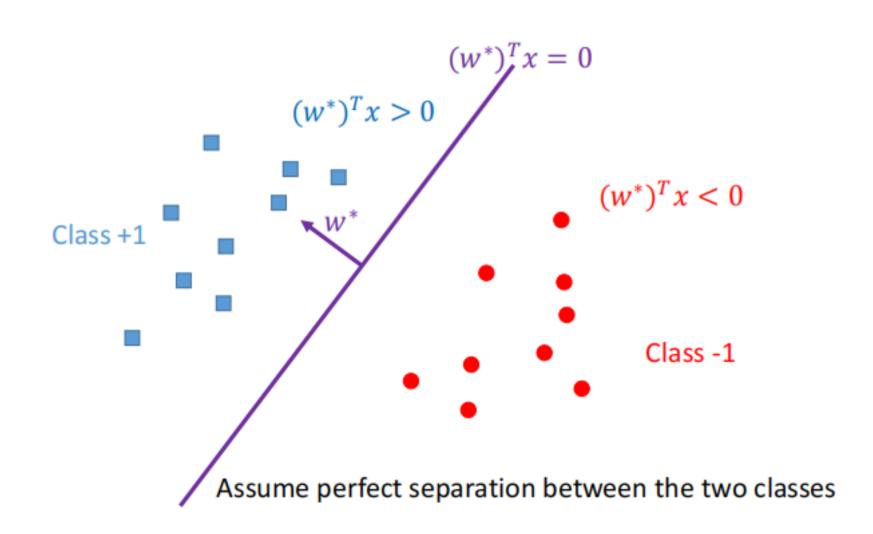
#### Motivation 动机

#### Motivation

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#### Linear classification 线性分类





#### Attempt 尝试

- Given training data  $\{(x_i, y_i): 1 \le i \le n\}$  i.i.d. from distribution D 给定训练数据  $\{(x_i, y_i): 1 \le i \le n\}$ ,它们是从分布D独立同分布采样的
- Hypothesis  $y = \text{sign}(f_w(x)) = \text{sign}(w^T x)$

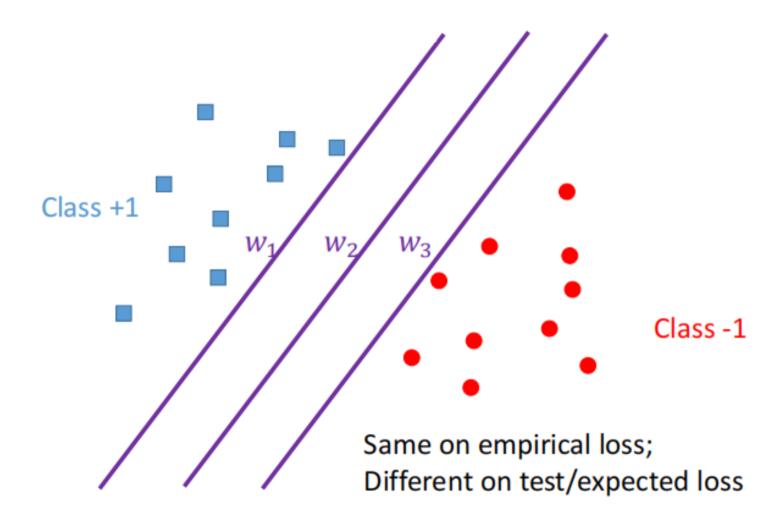
• 
$$y = +1$$
 if  $w^T x > 0$ 

• 
$$y = -1$$
 if  $w^T x < 0$ 

Let's assume that we can optimize to find w

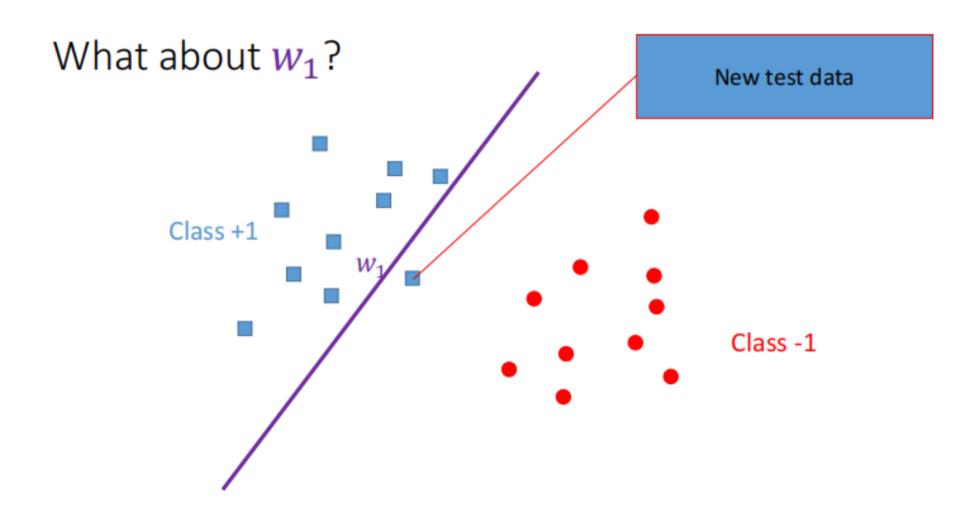


# Multiple optimal solutions? <a href="#">多个最优解?</a>





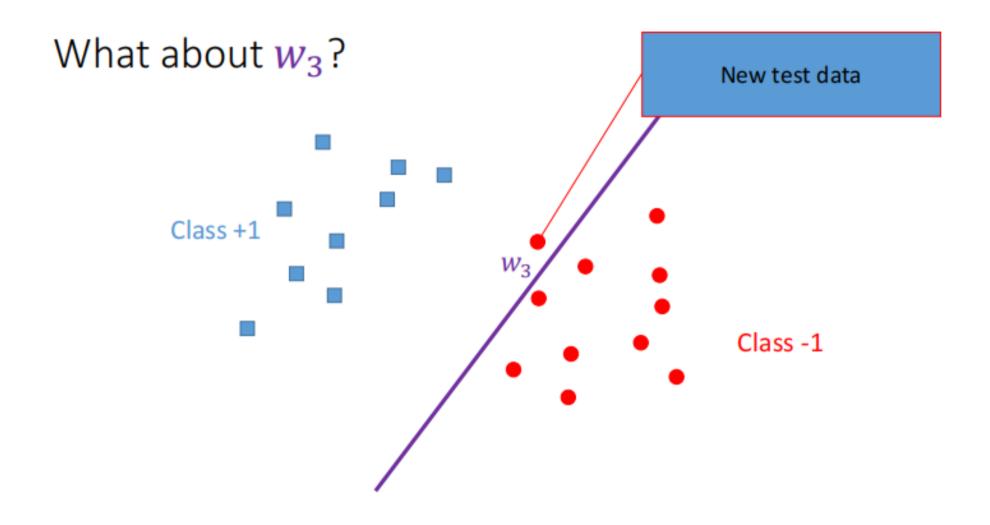
# Multiple optimal solutions? 多个最优解?





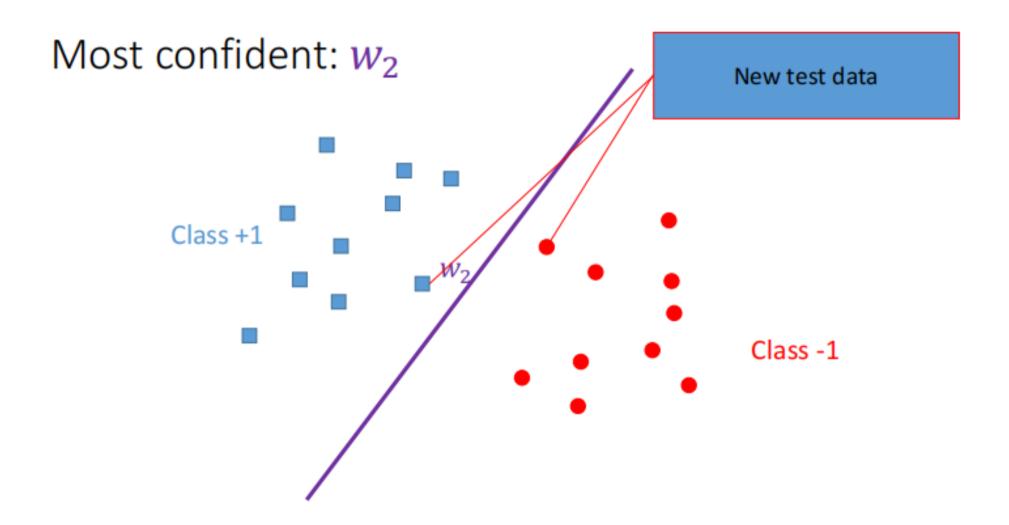
### Multiple optimal solutions?

多个最优解?





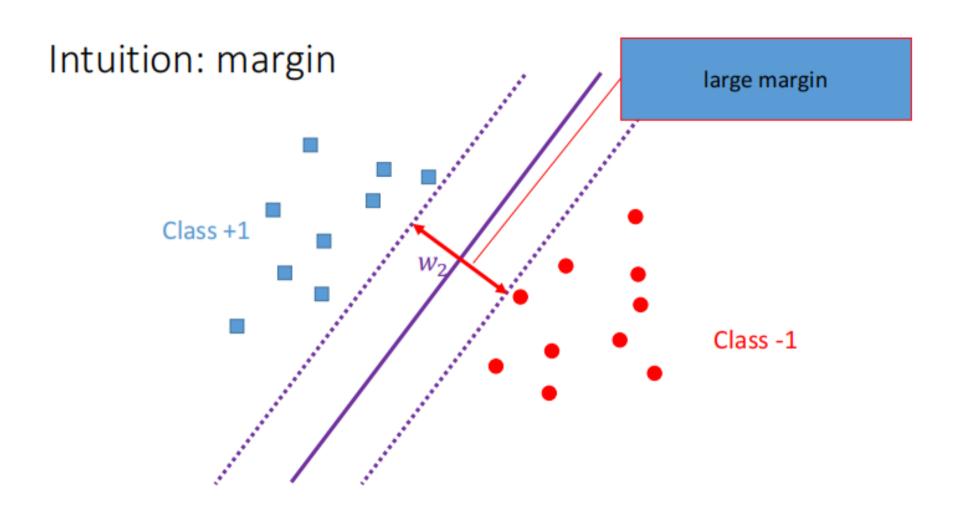
# Multiple optimal solutions? <a href="#">多个最优解?</a>



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# Multiple optimal solutions? 多个最优解?







### Margin

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#### Margin 间隔

• Lemma 1: x has distance 
$$\frac{|f_w(x)|}{||w||}$$
 to the hyperplane  $f_w(x) = w^T x = 0$ 

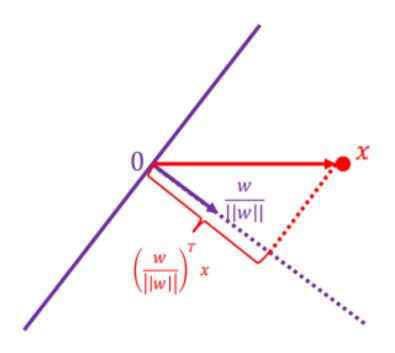
#### Proof:

• w is orthogonal to the hyperplane w与超平面正交

• The unit direction is  $\frac{w}{||w||}$ 单位方向

• The projection of x is  $\left(\frac{w}{||w||}\right)^T x = \frac{f_w(x)}{||w||}$ x的投影

$$\left(\frac{w}{||w||}\right)^T x = \frac{f_w(x)}{||w||}$$





#### Margin: with bias 间隔: 带偏置的情况

• Claim 1: w is orthogonal to the hyperplane  $f_{w,b}(x) = w^T x + b = 0$  声明1: w与超平面正交

Proof:

• pick any  $x_1$  and  $x_2$  on the hyperplane 选择超平面上的任意 $x_1$  和 $x_2$ 

• 
$$w^T x_1 + b = 0$$

$$\bullet w^T x_2 + b = 0$$

• So 
$$w^T(x_1 - x_2) = 0$$



#### Margin: with bias 间隔:带偏置的情况

• Claim 2: 0 has distance  $\frac{-b}{||w||}$  to the hyperplane  $w^Tx + b = 0$ 

#### Proof:

- pick any  $x_1$  the hyperplane 选择超平面上的任意 $x_1$
- Project  $x_1$  to the unit direction  $\frac{w}{||w||}$  to get the distance

$$\bullet \left( \frac{w}{||w||} \right)^T x_1 = \frac{-b}{||w||} \text{ since } w^T x_1 + b = 0$$



#### Margin: with bias 间隔: 带偏置的情况

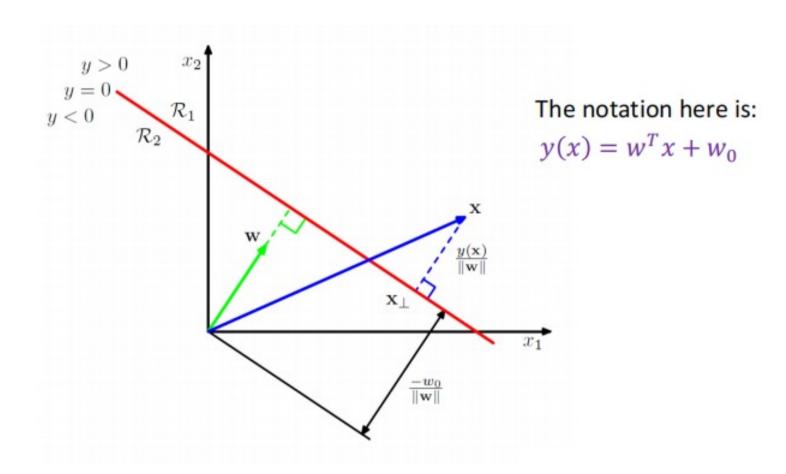
• Lemma 2: x has distance  $\frac{|f_{w,b}(x)|}{||w||}$  to the hyperplane  $f_{w,b}(x) = w^Tx + b = 0$ 

#### Proof:

- Let  $x = x_{\perp} + r \frac{w}{||w||}$ , then |r| is the distance
- Multiply both sides by  $w^T$  and add b 两边都乘以 $w^T$ 并加上b
- Left hand side:  $w^T x + b = f_{w,b}(x)$
- Right hand side:  $w^T x_{\perp} + r \frac{w^T w}{||w||} + b = 0 + r ||w||$



#### Margin: with bias 间隔: 带偏置的情况





#### Support Vector Machine (SVM) 支持向量机 (SVM)

### Support Vector Machine (SVM)

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#### SVM: objective SVM: 优化目标函数

• Margin over all training data points: 所有训练数据点的边距:

$$\gamma = \min_{i} \frac{|f_{w,b}(x_i)|}{||w||}$$

• Since only want correct  $f_{w,b}$ , and recall  $y_i \in \{+1, -1\}$ , we have

$$\gamma = \min_{i} \frac{y_i f_{w,b}(x_i)}{||w||}$$

• If  $f_{w,b}$  incorrect on some  $x_i$  , the margin is negative 边距为负



#### SVM: objective SVM: 优化目标函数

• Maximize margin over all training data points: 最大化所有训练数据点的边距

$$\max_{w,b} \gamma = \max_{w,b} \min_{i} \frac{y_i f_{w,b}(x_i)}{||w||} = \max_{w,b} \min_{i} \frac{y_i (w^T x_i + b)}{||w||}$$

• A bit complicated ... 有点复杂



### SVM: simplified objective SVM: 简化目标函数

• Observation: when (w, b) scaled by a factor c, the margin unchanged  $\exists (w, b)$ 被一个因子c缩放时,边距不变

$$\frac{y_i(cw^T x_i + cb)}{||cw||} = \frac{y_i(w^T x_i + b)}{||w||}$$

Let's consider a fixed scale such that

$$y_{i^*}(w^Tx_{i^*}+b)=1$$

where  $x_{i*}$  is the point closest to the hyperplane 其中 $x_{i*}$  是离超平面最近的点。



### SVM: simplified objective SVM: 简化目标函数

Let's consider a fixed scale such that

$$y_{i^*}(w^Tx_{i^*}+b)=1$$

where  $x_{i*}$  is the point closest to the hyperplane 其中 $x_{i*}$  是离超平面最近的点。

Now we have for all data

$$y_i(w^Tx_i+b) \ge 1$$

and at least for one i the equality holds 至少对某个i成立等式

• Then the margin is  $\frac{1}{||w||}$ 



## SVM: simplified objective SVM: 简化目标函数

• Optimization simplified to 优化问题简化为

$$\min_{w,b} \frac{1}{2} ||w||^2$$

$$y_i(w^T x_i + b) \ge 1, \forall i$$

• How to find the optimum  $\hat{w}^*$ ?



## SVM: principle for hypothesis class 支持向量机: 假设类的原则

### SVM: principle for hypothesis class

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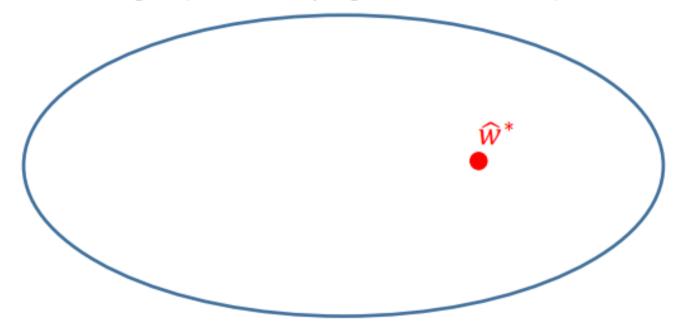


• Suppose pick an R, and suppose can decide if exists w satisfying 假设选择一个R,并假设可以确定是否存在满足条件的w

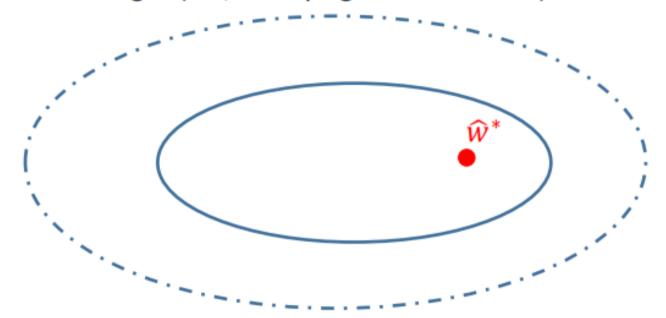
$$\frac{1}{2} ||w||^2 \le R$$
$$y_i(w^T x_i + b) \ge 1, \forall i$$

• Decrease R until cannot find w satisfying the inequalities 减小R,直到找不到满足不等式的w为止。

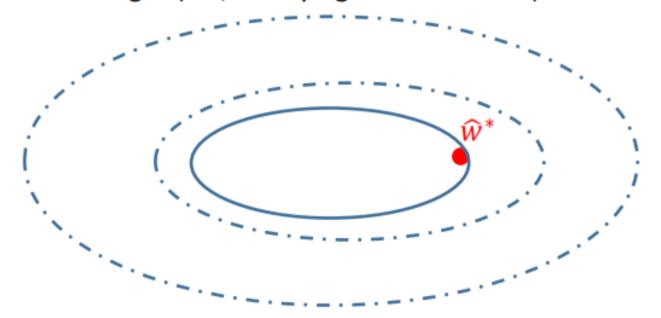




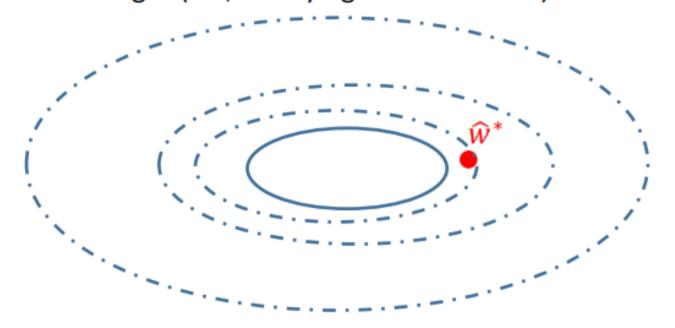




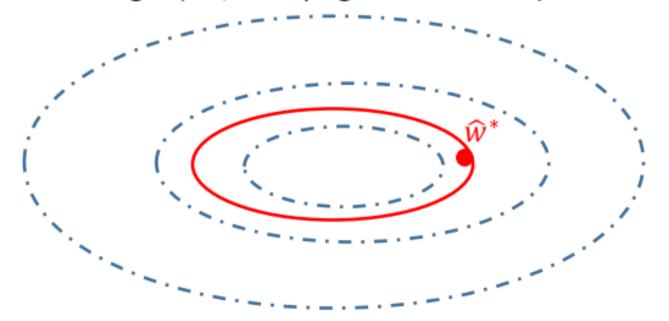








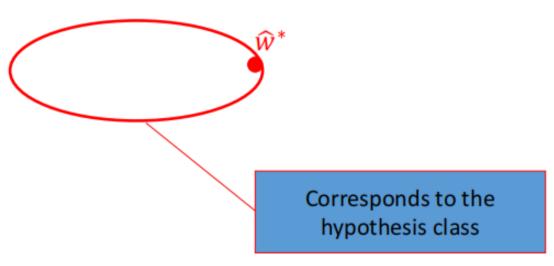






- To handle the difference between empirical and expected losses →
   为了处理经验损失和期望损失之间的差异
- Choose large margin hypothesis (high confidence) →
   选择大边距假设(高置信度)
- Choose a small hypothesis class

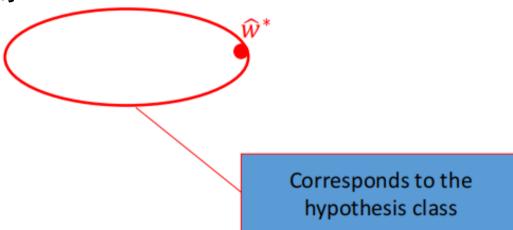
选择一个较小的假设类





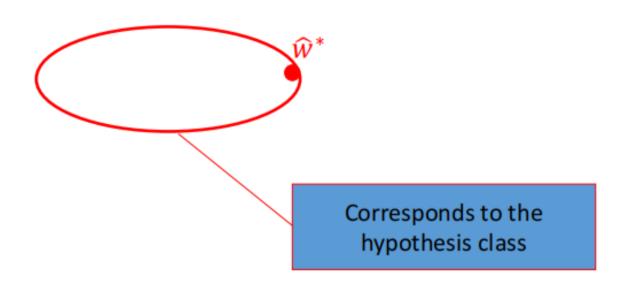
- Principle: use smallest hypothesis class still with a correct/good one 使用仍包含正确/良好假设的最小假设类
  - Also true beyond SVM
  - Also true for the case without perfect separation between the two classes 即使在两类之间无法完全分离的情况下也同样适用
  - Math formulation: VC-dim theory, etc.

数学形式化:如 VC 维理论等





- Principle: use smallest hypothesis class still with a correct/good one 使用仍包含正确/良好假设的最小假设类
  - Whatever you know about the ground truth, add it as constraint/regularizer 将其添加为约束或正则项



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### SVM: optimization SVM: 优化器

• Optimization (Quadratic Programming): (二次规划)

$$\min_{w,b} \frac{1}{2} ||w||^2$$

$$y_i(w^T x_i + b) \ge 1, \forall i$$

• Solved by Lagrange multiplier method: 通过拉格朗日乘数法求解

$$\mathcal{L}(w,b,\pmb{\alpha}) = \frac{1}{2} \left| |w| \right|^2 - \sum_i \alpha_i [y_i(w^Tx_i+b) - 1]$$

where  $\alpha$  is the Lagrange multiplier 其中 $\alpha$  是拉格朗日乘数

Details in next lecture



#### Lagrange multiplier 拉格朗日乘数法

### Lagrange multiplier

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#### Lagrangian 拉格朗日函数

• Consider optimization problem: 考虑优化问题

$$\min_{w} f(w)$$

$$h_i(w) = 0, \forall 1 \le i \le l$$

• Lagrangian:

$$\mathcal{L}(w, \boldsymbol{\beta}) = f(w) + \sum_{i} \beta_{i} h_{i}(w)$$

where  $\beta_i$ 's are called Lagrange multipliers 其中 $\beta_i$ '被称为拉格朗日乘数



#### Lagrangian 拉格朗日函数

• Consider optimization problem: 考虑优化问题

$$\min_{w} f(w)$$

$$h_i(w) = 0, \forall 1 \le i \le l$$

Solved by setting derivatives of Lagrangian to 0
 通过将拉格朗日函数的导数设为 0 来求解

$$\frac{\partial \mathcal{L}}{\partial w_i} = 0; \quad \frac{\partial \mathcal{L}}{\partial \beta_i} = 0$$



#### Generalized Lagrangian 广义拉格朗日函数

• Consider optimization problem:考虑优化问题

$$\min_{w} f(w)$$

$$g_{i}(w) \leq 0, \forall 1 \leq i \leq k$$

$$h_{j}(w) = 0, \forall 1 \leq j \leq l$$

• Generalized Lagrangian: 广义拉格朗日函数

$$\mathcal{L}(w, \boldsymbol{\alpha}, \boldsymbol{\beta}) = f(w) + \sum_{i} \alpha_{i} g_{i}(w) + \sum_{j} \beta_{j} h_{j}(w)$$

where  $\alpha_i$ ,  $\beta_i$ 's are called Lagrange multipliers



## Generalized Lagrangian 广义拉格朗日函数

Consider the quantity:

$$\theta_P(w) \coloneqq \max_{\boldsymbol{\alpha}, \boldsymbol{\beta}: \alpha_i \ge 0} \mathcal{L}(w, \boldsymbol{\alpha}, \boldsymbol{\beta})$$

- Why?  $\mu_P(w) = \begin{cases} f(w), & \text{if } w \text{ satisfies all the constraints} \\ +\infty, & \text{if } w \text{ does not satisfy the constraints} \end{cases}$
- So minimizing f(w) is the same as minimizing  $\theta_P(w)$

$$\min_{w} f(w) = \min_{w} \theta_{P}(w) = \min_{w} \max_{\alpha, \beta: \alpha_{i} \geq 0} \mathcal{L}(w, \alpha, \beta)$$



• The primal problem 原问题

$$p^* \coloneqq \min_w f(w) = \min_w \max_{\alpha, \beta: \alpha_i \ge 0} \mathcal{L}(w, \alpha, \beta)$$

• The dual problem 对偶问题

$$d^* \coloneqq \max_{\boldsymbol{\alpha}, \boldsymbol{\beta}: \alpha_i \ge 0} \min_{w} \mathcal{L}(w, \boldsymbol{\alpha}, \boldsymbol{\beta})$$

Always true:

$$d^* \leq p^*$$



• The primal problem 原问题

$$p^* \coloneqq \min_{w} f(w) = \min_{w} \max_{\alpha, \beta: \alpha_i \ge 0} \mathcal{L}(w, \alpha, \beta)$$

• The dual problem 对偶问题

$$d^* \coloneqq \max_{\boldsymbol{\alpha}, \boldsymbol{\beta}: \alpha_i \ge 0} \min_{w} \mathcal{L}(w, \boldsymbol{\alpha}, \boldsymbol{\beta})$$

Interesting case: when do we have

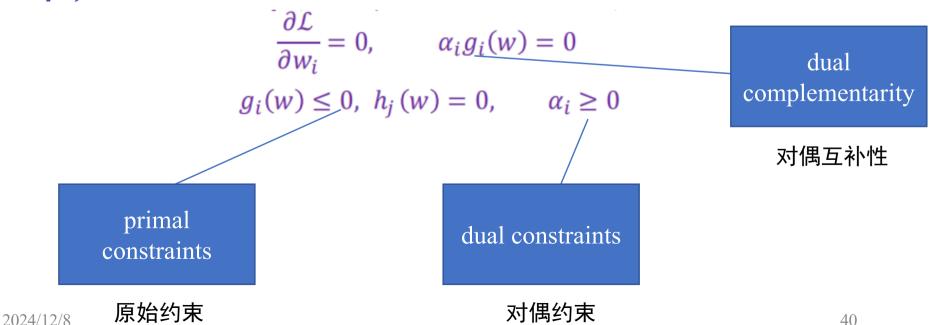
$$d^* = p^*$$
?



• Theorem: under proper conditions, there exists  $(w^*, \alpha^*, \beta^*)$  such that 在适当条件下,存在 $(w^*, \alpha^*, \beta^*)$ ,使得

$$d^* = \mathcal{L}(w^*, \boldsymbol{\alpha}^*, \boldsymbol{\beta}^*) = p^*$$

Moreover,  $(w^*, \alpha^*, \beta^*)$  satisfy Karush-Kuhn-Tucker (KKT) conditions:  $(w^*, \alpha^*, \beta^*)$ 满足Karush-Kuhn-Tucker (KKT) 条件:





- What are the proper conditions?
   什么是适当的条件?
- A set of conditions (Slater conditions):
- f,  $g_i$  convex,  $h_i$  affine f,  $g_i$  是凸的,  $h_i$  是仿射的
- Exists w satisfying all  $g_i(w) < 0$
- There exist other sets of conditions
   还有其他条件集
  - Search Karush-Kuhn-Tucker conditions on Wikipedia



# SVM: optimization SVM: 优化器

**SVM:** optimization



#### **SVM:** optimization SVM: 优化器

• Optimization (Quadratic Programming): (二次规划)

$$\min_{w,b} \frac{1}{2} ||w||^2$$

$$y_i(w^T x_i + b) \ge 1, \forall i$$

● Generalized Lagrangian: 广义拉格朗日函数

$$\mathcal{L}(w,b,\boldsymbol{\alpha}) = \frac{1}{2} \left| |w| \right|^2 - \sum_i \alpha_i [y_i(w^T x_i + b) - 1]$$

where  $\alpha$  is the Lagrange multiplier 其中 $\alpha$  是拉格朗日乘数



# SVM: optimization SVM: 优化器

• KKT conditions: KKT条件:

$$\frac{\partial \mathcal{L}}{\partial w} = 0, \Rightarrow w = \sum_{i} \alpha_{i} y_{i} x_{i}$$
(1) 
$$\frac{\partial \mathcal{L}}{\partial b} = 0, \Rightarrow 0 = \sum_{i} \alpha_{i} y_{i}$$
(2)

• Plug into £: 代入£:

$$\mathcal{L}(w,b,\pmb{\alpha}) = \sum_{i} \alpha_{i} - \frac{1}{2} \sum_{ij} \alpha_{i} \alpha_{j} y_{i} y_{j} x_{i}^{T} x_{j} \quad \text{(3)}$$
 combined with  $0 = \sum_{i} \alpha_{i} y_{i}$ ,  $\alpha_{i} \geq 0$ 



# SVM: optimization SVM: 优化器

Only depend on inner products

• Reduces to dual problem:

$$\mathcal{L}(w, b, \boldsymbol{\alpha}) = \sum_{i} \alpha_{i} - \frac{1}{2} \sum_{ij} \alpha_{i} \alpha_{j} y_{i} y_{j} \boldsymbol{x}_{i}^{T} \boldsymbol{x}_{j}$$
$$\sum_{i} \alpha_{i} y_{i} = 0, \alpha_{i} \geq 0$$

• Since  $w = \sum_i \alpha_i y_i x_i$ , we have  $w^T x + b = \sum_i \alpha_i y_i x_i^T x + b$ 



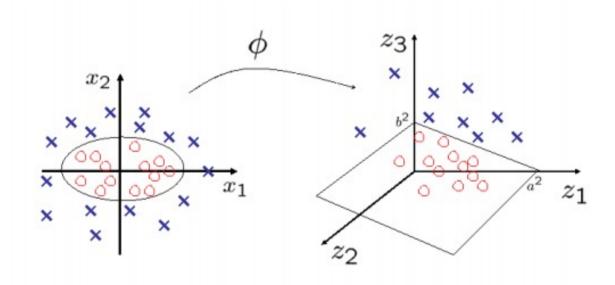
# Kernel methods 核方法

# Kernel methods









$$\phi:(x_1,x_2)\longrightarrow (x_1^2,\sqrt{2}x_1x_2,x_2^2)$$

$$\left(\frac{x_1}{a}\right)^2 + \left(\frac{x_2}{b}\right)^2 = 1 \longrightarrow \frac{z_1}{a^2} + \frac{z_3}{b^2} = 1$$



SVM with a polynomial Kernel visualization

> Created by: Udi Aharoni



- Proper feature mapping can make non-linear to linear 适当的特征映射可以将非线性转化为线性
- Using SVM on the feature space  $\{\phi(x_i)\}$ : only need  $\phi(x_i)^T\phi(x_j)$
- Conclusion: no need to design  $\phi(\cdot)$ , only need to design

$$k(x_i, x_j) = \phi(x_i)^T \phi(x_j)$$



## 多项式核

• Fix degree *d* and constant *c*:

$$k(x, x') = (x^T x' + c)^d$$

- What are  $\phi(x)$ ?
- Expand the expression to get  $\phi(x)$

展开表达式以得到 $\phi(x)$ 



## 多项式核

$$\forall \mathbf{x}, \mathbf{x}' \in \mathbb{R}^2, \quad K(\mathbf{x}, \mathbf{x}') = (x_1 x_1' + x_2 x_2' + c)^2 = \begin{bmatrix} x_1^2 \\ x_2^2 \\ \sqrt{2} x_1 x_2 \\ \sqrt{2c} x_1 \\ \sqrt{2c} x_2 \\ c \end{bmatrix} \cdot \begin{bmatrix} x'_1^2 \\ x'_2^2 \\ \sqrt{2} x'_1 x'_2 \\ \sqrt{2c} x'_1 \\ \sqrt{2c} x'_2 \\ c \end{bmatrix}$$



#### 多项式核

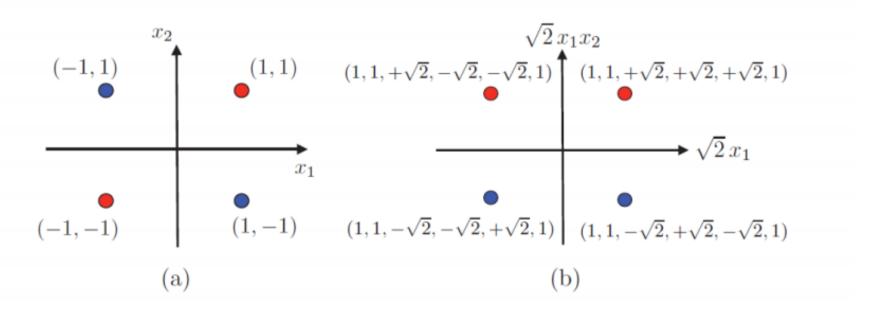


Figure 5.2 Illustration of the XOR classification problem and the use of polynomial kernels. (a) XOR problem linearly non-separable in the input space. (b) Linearly separable using second-degree polynomial kernel.



# Gaussian kernels 高斯核

• Fix bandwidth  $\sigma$ :

$$k(x, x') = \exp(-||x - x'||^2/2\sigma^2)$$

- Also called radial basis function (RBF) kernels 也称为径向基函数(RBF)核
- What are  $\phi(x)$ ? Consider the un-normalized version 考虑未归一化的版本

$$k'(x, x') = \exp(x^T x' / \sigma^2)$$

• Power series expansion: 幂级数展开:

$$k'(x,x') = \sum_{i}^{+\infty} \frac{(x^T x')^i}{\sigma^i i!}$$



#### Mercer's condition for kenerls 核的 Mercer 条件

• Theorem: k(x, x') has expansion k(x, x')具有展开式

$$k(x, x') = \sum_{i}^{+\infty} a_i \phi_i(x) \phi_i(x')$$

if and only if for any function c(x), 当且仅当对于任意函数c(x),

$$\int \int c(x)c(x')k(x,x')dxdx' \ge 0$$

(Omit some math conditions for k and c) (省略一些关于k和c的数学条件)



# Constructing new kernels 构造新核函数

- Kernels are closed under positive scaling, sum, product, pointwise limit, and composition with a power series  $\sum_{i}^{+\infty} a_{i} k^{i}(x, x')$  核函数在正向缩放、求和、乘积、逐点极限和与幂级数的合成下是封闭的
- Example:  $k_1(x, x')$ ,  $k_2(x, x')$  are kernels, then also is

$$k(x, x') = 2k_1(x, x') + 3k_2(x, x')$$

• Example:  $k_1(x, x')$  is kernel, then also is

$$k(x, x') = \exp(k_1(x, x'))$$



# Kernels v.s. Neural networks 核函数vs神经网络

# Kernels v.s. Neural networks

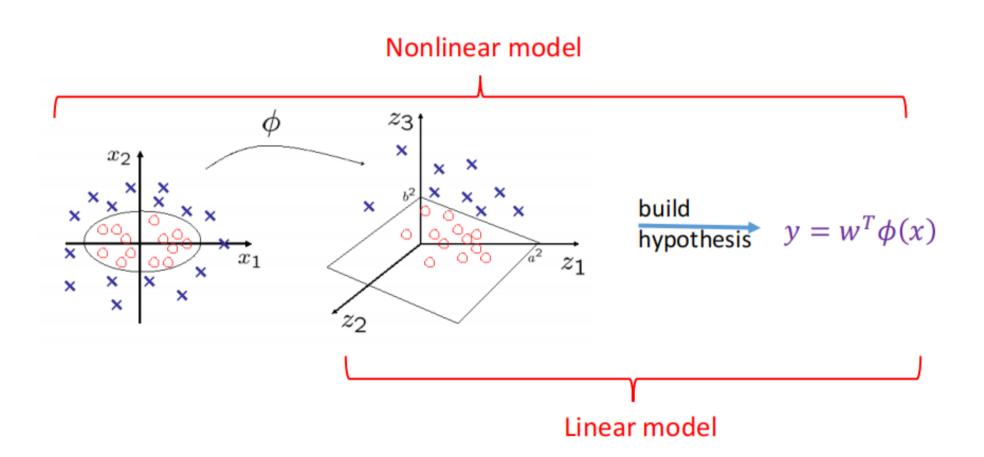






#### Features: part of the model

特征:模型的一部分

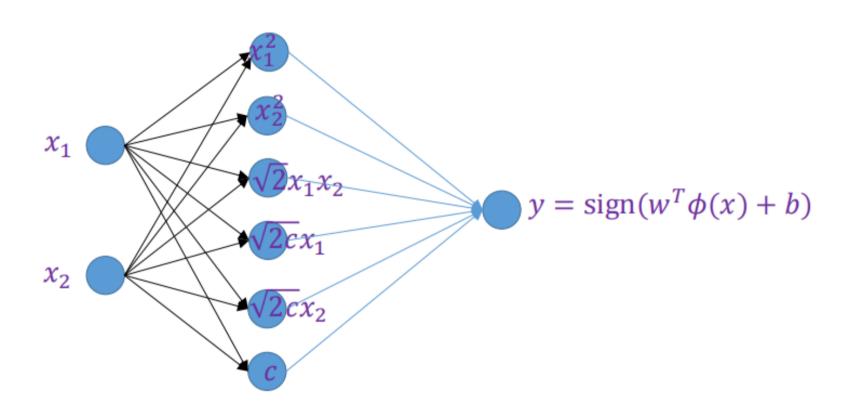




#### 多项式核

$$\forall \mathbf{x}, \mathbf{x}' \in \mathbb{R}^2, \quad K(\mathbf{x}, \mathbf{x}') = (x_1 x_1' + x_2 x_2' + c)^2 = \begin{bmatrix} x_1^2 \\ x_2^2 \\ \sqrt{2} x_1 x_2 \\ \sqrt{2c} x_1 \\ \sqrt{2c} x_2 \\ c \end{bmatrix} \cdot \begin{bmatrix} x_1'^2 \\ x_2'^2 \\ \sqrt{2} x_1' x_2' \\ \sqrt{2c} x_1' \\ \sqrt{2c} x_2' \\ c \end{bmatrix}$$

# Polynomial kernel SVM as two layer neural network 多项式核SVM作为二层神经网络



First layer is fixed. If also learn first layer, it becomes two layer neural network