ROS Cheat Sheet

ROS Shell Command	
roscd	Move to ROS package directory
rosls	Check ROS package file list
rosed	Edit ROS package
rospd	Add dir to ROS directory Index

ROS Run Command	
roscore	-master -rosout -parameter server
rosrun	Run node
roslaunch	Run multiple nodes and set running option
rosclean	Delete or Check ROS log file

ROS Information Command	
rostopic	Check ROS topic information
rosservice	Check ROS service information
rosnode	Check ROS node information
rosparam	Check or Edit ROS parameter
rosbag	Write or Replay ROS message log
rosmsg	Check ROS message information
rossrv	Check ROS service
rosversion	version of ROS package and release

ROS catkin Command	
catkin_create_pkg	Create package automatically
catkin_make	Build based on catkin build system
catkin_eclipse	Change to be usable in Eclipse
catkin_prepare_release	Manage or Version tag logs for release
catkin_generate_changelog	Create or Edit CHANGE.rst when release
catkin_init_workspace	Reset workspace of catkin build system
catkin_find	Search catkin

ROS Package Command	
rospack	Look information of ROS packages
rosinstall	Install additional package of ROS
rosdep	Install dependencies of package

Reference : Pyo's ROS seminar
 - https://github.com/robotpilot/ros-seminar

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