


```

    else (BLAS.CHECKARRAY DESTMATRIX)
      (if (NOT (EQUAL (ARRAY-DIMENSIONS DESTMATRIX)
                     (LIST N M)))
          then (HELP "DESTMATRIX of incorrect size" DESTMATRIX)))
  (if (ILESSP M N)
      then (bind (SOURCEBASE _ (ARRAYBASE SOURCEMATRIX))
                 (DESTBASE _ (ARRAYBASE DESTMATRIX)) for I from 0 to (SUB1 M)
                 do (\FLOATARRAYBLT SOURCEBASE (ITIMES N I)
                     1 DESTBASE I M N))
      else (bind (SOURCEBASE _ (ARRAYBASE SOURCEMATRIX))
                 (DESTBASE _ (ARRAYBASE DESTMATRIX)) for J from 0 to (SUB1 N)
                 do (\FLOATARRAYBLT SOURCEBASE J N DESTBASE (ITIMES J M)
                     1 M)))
  (RETURN DESTMATRIX])

```

(MINVERT

[LAMBDA (MATRIX SOLUTION)

(* jop: "26-May-86 18:35")

(* * Solves to system $Ax = b$. BVECTOR should to the RHS of the system.
Returns SOLUTION)

```

(LET [(PIVOTVECTOR (MAKE-ARRAY (ARRAY-DIMENSION MATRIX 0)
                                (LUIVERSE (LUFACTOR MATRIX PIVOTVECTOR)
                                             PIVOTVECTOR SOLUTION))

```

(LSOLV

[LAMBDA (LMATRIX CVECTOR BVECTOR)

(* jop: "27-May-86 16:25")

(* * Calculate the solution vector BVECTOR for the system of linear equations $R*B=C$, where LMATRIX is lower triangular $M \times N$ with non-zero diagonal elements. BVECTOR and CVECTOR must be of size N.
Always returns BVECTOR)

```

(BLAS.CHECKARRAY LMATRIX)
(BLAS.CHECKARRAY CVECTOR)
(PROG ((M (ARRAY-DIMENSION LMATRIX 0))
      (N (ARRAY-DIMENSION LMATRIX 1))))

(* * Arg Checks)

(if (ILESSP M N)
    then (HELP "Order of system less than" N))
(if (NOT (EQL (ARRAY-TOTAL-SIZE CVECTOR)
              N))
    then (HELP "CVECTOR not of size" N))
(if (NULL BVECTOR)
    then (SETQ BVECTOR (MAKE-ARRAY N (QUOTE :ELEMENT-TYPE)
                                     (QUOTE FLOAT)))
    else (BLAS.CHECKARRAY BVECTOR)
          (if (NOT (EQL (ARRAY-TOTAL-SIZE BVECTOR)
                        N))
              then (HELP "BVECTOR not of size" N))) (* Check for zero diagonal elements)
(if (for I from 0 to (SUB1 N) thereis (UFEQP 0.0 (\FLOATAREF LMATRIX I I)))
    then (HELP "LMATRIX has a zero diagonal element"))

(* * Solution by forward substitution)

(BLAS.ARRAYBLT CVECTOR 0 1 BVECTOR 0 1 N) (* Copy CVECTOR to BVECTOR)
(\FLOATASET (FQUOTIENT (\FLOATAREF BVECTOR 0) (* Compute the first value)
               (\FLOATAREF LMATRIX 0 0))
  BVECTOR 0)
(for J from 1 to (SUB1 N) do (BLAS.AXPY (FMINUS (\FLOATAREF BVECTOR (SUB1 J)))
    LMATRIX
    (IPLUS (SUB1 J)
           (ITIMES J N))
    N BVECTOR J 1 (IDIFFERENCE N J))
  (\FLOATASET (FQUOTIENT (\FLOATAREF BVECTOR J)
                          (\FLOATAREF LMATRIX J J))
    BVECTOR J))

(RETURN BVECTOR])

```

(LUFACTOR

[LAMBDA (MATRIX PIVOTVECTOR FACTORMATRIX)

(* jop: "27-May-86 20:21")

(* * Computes the LU decomposition of the $N \times N$ matrix MATRIX by Gauss elimination with row pivoting.
FACTORMATRIX will be overwritten with the packed result. PIVOTVECTOR will be a vector of smallposp's, holding the pivot permutation, and must be supplied. Returns NIL in the normal case, else returns the row index)

(* * Lifted from LINPACK algorithm SGESL)

```

(BLAS.CHECKARRAY MATRIX)
(if (NOT (AND (type? ARRAY PIVOTVECTOR)
              (EQ (ARRAY-ELEMENT-TYPE PIVOTVECTOR)
                  T)))
    then (HELP "Must be a pointer array" PIVOTVECTOR))

```



```

else (BLAS.CHECKARRAY SOLUTION)
  (if [NOT (AND (EQL 2 (ARRAY-RANK SOLUTION))
                (EQUAL (ARRAY-DIMENSIONS LUMATRIX)
                        (ARRAY-DIMENSIONS SOLUTION))
            ]
      then (HELP "SOLUTION not an N x N array" SOLUTION)))
      (* copy LUMATRIX to SOLUTION)
(BLAS.ARRAYBLT LUMATRIX 0 1 SOLUTION 0 1)

(* * first compute INVERSE (U))

[bind TEMP for K from 0 to (SUB1 N) do (\FLOATASET (FQUOTIENT 1.0 (\FLOATAREF SOLUTION K K))
                                         SOLUTION K K)
    (SETQ TEMP (FMINUS (\FLOATAREF SOLUTION K K)))
    (BLAS.SCAL TEMP SOLUTION K N K)
    (bind TEMP for J from (ADD1 K) to (SUB1 N)
      do (SETQ TEMP (\FLOATAREF SOLUTION K J))
          (\FLOATASET 0.0 SOLUTION K J)
          (BLAS.AXPY TEMP SOLUTION K N SOLUTION J N (ADD1 K))

(* * Form INVERSE (U) * INVERSE (L))

(bind (TEMPARRAY _ (MAKE-ARRAY N (QUOTE :ELEMENT-TYPE)
                                (QUOTE FLOAT)))
  L for K from (IDIFFERENCE N 2) to 0 by -1
  do (for I from (ADD1 K) to (SUB1 N) do (\FLOATASET (\FLOATAREF SOLUTION I K)
                                                       TEMPARRAY I)
      (\FLOATASET 0.0 SOLUTION I K))
    (bind TEMP for J from (ADD1 K) to (SUB1 N)
      do (SETQ TEMP (\FLOATAREF TEMPARRAY J))
          (BLAS.AXPY TEMP SOLUTION J N SOLUTION K N N))
    (SETQ L (PAREF PIVOTVECTOR K))
    (if (NEQ L K)
      then (BLAS.SWAP SOLUTION K N SOLUTION L N N)))
(RETURN SOLUTION)]

```

(LUSOLV

```

[LAMBDA (LUMATRIX PIVOTVECTOR CVECTOR SOLUTION) (* jop: "27-May-86 20:39")

```

```

(* * Solves to system  $Ax = b$ . LUMATRIX and PIVOTVECTOR should be the outputs of LUFACTOR.
CVECTOR should be the RHS of the system. Returns SOLUTION)

```

```

(* * lifted from LINPACK SGESL)

```

```

(BLAS.CHECKARRAY LUMATRIX)
(if (NOT (AND (type? ARRAY PIVOTVECTOR)
              (EQ (ARRAY-ELEMENT-TYPE PIVOTVECTOR)
                  T)))
  then (HELP "Must be an array of pointers" PIVOTVECTOR))
(BLAS.CHECKARRAY CVECTOR)
(PROG ((N (ARRAY-DIMENSION LUMATRIX 0)))

(* * Arg Checks)

(if [AND (EQL 2 (ARRAY-RANK LUMATRIX))
        (NOT (EQL N (ARRAY-DIMENSION LUMATRIX 1))
            (HELP "MATRIX not square" LUMATRIX))
    (if [NOT (AND (EQL 1 (ARRAY-RANK PIVOTVECTOR))
                  (EQL N (ARRAY-TOTAL-SIZE PIVOTVECTOR))
              ]
        then (HELP "PIVOTVECTOR not a vector of size N" PIVOTVECTOR))
    (if [NOT (AND (EQL 1 (ARRAY-RANK CVECTOR))
                  (EQL N (ARRAY-TOTAL-SIZE CVECTOR))
              ]
        then (HELP "CVECTOR not a vector of size N" CVECTOR))
    (if (NULL SOLUTION)
      then (SETQ SOLUTION (MAKE-ARRAY N (QUOTE :ELEMENT-TYPE)
                                         (QUOTE FLOAT)))

else (BLAS.CHECKARRAY SOLUTION)
  (if [NOT (AND (EQL 1 (ARRAY-RANK SOLUTION))
                (EQL N (ARRAY-TOTAL-SIZE SOLUTION))
            ]
      then (HELP "SOLUTION not a vector of size N" SOLUTION)))
      (* Copy CVECTOR to SOLUTION)
(BLAS.ARRAYBLT CVECTOR 0 1 SOLUTION 0 1 N)

(* * First solve  $L^*y = b$ )

[bind PIVOTINDEX TEMP for K from 0 to (IDIFFERENCE N 2)
  do (SETQ PIVOTINDEX (PAREF PIVOTVECTOR K))
      (SETQ TEMP (\FLOATAREF SOLUTION PIVOTINDEX))
      (if (NOT (EQL PIVOTINDEX K))
        then (* interchange)
              (\FLOATASET (\FLOATAREF SOLUTION K)
                           SOLUTION PIVOTINDEX)
              (\FLOATASET TEMP SOLUTION K))
        (BLAS.AXPY TEMP LUMATRIX (IPLUS K (ITIMES N (ADD1 K)))
          N SOLUTION (ADD1 K))
        1
        (IDIFFERENCE N (ADD1 K))

```

```

(* * Then solve U*x = y)

(bind TEMP for K from (SUB1 N) to 0 by -1 do (SETQ TEMP (FMINUS (\FLOATASET (FQUOTIENT (\FLOATAREF
                                                                    SOLUTION K
                                                                    )
                                                                    (\FLOATAREF LUMATRIX
                                                                    K K))
                                                                    SOLUTION K)))
      (BLAS.AXPY TEMP LUMATRIX K N SOLUTION 0 1 K))

(RETURN SOLUTION])

```

(MTIMES

[LAMBDA (A B PRODUCT)

(* jop: "4-Jun-86 13:08")

(* * Matrix multiply. A may be an N vector or a (M x N) matrix and B may be a N vector or a N x P matrix.
PRODUCT defaults to a M x P array. RETURNS PRODUCT)

```

(BLAS.CHECKARRAY A)
(BLAS.CHECKARRAY B)
(LET ((RANKA (ARRAY-RANK A))
      (RANKB (ARRAY-RANK B))
      M N P RESULTDIMS)
  (if (NOT (OR (EQ RANKA 1)
               (EQ RANKA 2)))
      then (HELP "A not a one-d or two-d array" A))
  (if (NOT (OR (EQ RANKB 1)
               (EQ RANKB 2)))
      then (HELP "B not a one-d or two-d array" B))
  (SETQ M (if (EQ RANKA 1)
              then 1
              else (ARRAY-DIMENSION A 0)))
  (SETQ N (if (EQ RANKA 1)
              then (ARRAY-DIMENSION A 0)
              else (ARRAY-DIMENSION A 1)))
  (SETQ P (if (EQ RANKB 1)
              then 1
              else (ARRAY-DIMENSION B 1)))
  [SETQ RESULTDIMS (if (EQ M 1)
                      then (if (EQ P 1)
                              then NIL
                              else (LIST P))
                      else (if (EQ P 1)
                              then (LIST M)
                              else (LIST M P))

  (* * Check args)

  (if (NOT (EQ (ARRAY-DIMENSION B 0)
              N))
      then (HELP "Leading dimension of B not N" B))
  (if (NULL PRODUCT)
      then (SETQ PRODUCT (MAKE-ARRAY RESULTDIMS (QUOTE :ELEMENT-TYPE)
                                          (QUOTE FLOAT)))
      elseif (NOT (EQUAL (ARRAY-DIMENSIONS PRODUCT)
                        RESULTDIMS))
      then (HELP "C of incorrect size" PRODUCT))

  (* * Do the multiply)

  [bind (ABASE _ (ARRAYBASE A))
        (BBASE _ (ARRAYBASE B))
        (CBASE _ (ARRAYBASE PRODUCT)) for I from 0 to (SUB1 M)
  do (for J from 0 to (SUB1 P) as COFFSET from (MUL2 (ITIMES P I)) by 2
      do (bind (FTEMP _ 0.0) declare (TYPE FLOATP FTEMP) for K from 0 to (SUB1 N) as AOFFSET
              from (MUL2 (ITIMES N I)) by 2 as BOFFSET from (MUL2 J) by (MUL2 P)
              do [SETQ FTEMP (FPLUS FTEMP (FTIMES (\GETBASEFLOATP ABASE AOFFSET)
                                                    (\GETBASEFLOATP BBASE BOFFSET)
                                                    finally (\PUTBASEFLOATP CBASE COFFSET FTEMP]
              finally (\PUTBASEFLOATP CBASE COFFSET FTEMP]
      finally (\PUTBASEFLOATP CBASE COFFSET FTEMP]
  PRODUCT])

```

(QRFACOR

[LAMBDA (MATRIX QRAUX FACTORMATRIX)

(* jop: "27-May-86 16:27")

(* * Computes the LU decomposition of the N x N matrix MATRIX by Gauss elimination with row pivoting.
FACTORMATRIX will be overwritten with the packed result. QRAUX will be a vector of smallposp's, holding the pivot
permutation, and must be supplied. Returns NIL in the normal case, else returns the row index)

(* * Lifted from LINPACK algorithm SGESL)

```

(BLAS.CHECKARRAY MATRIX)
(BLAS.CHECKARRAY QRAUX)
(LET ((N (ARRAY-DIMENSION MATRIX 0))
      (P (ARRAY-DIMENSION MATRIX 1)))

```

```

(* * Arg Checks)

(if [NOT (AND (EQL 1 (ARRAY-RANK QRAUX))
              (EQL P (ARRAY-TOTAL-SIZE QRAUX))
            )]
  then (HELP "QRAUX not of size P" QRAUX))
(if (NULL FACTORMATRIX)
  then (SETQ FACTORMATRIX (MAKE-ARRAY (ARRAY-DIMENSIONS MATRIX)
                                       (QUOTE :ELEMENT-TYPE)
                                       (QUOTE FLOAT)))
  else (BLAS.CHECKARRAY FACTORMATRIX)
        (if (NOT (EQUAL (ARRAY-DIMENSIONS FACTORMATRIX)
                        (ARRAY-DIMENSIONS MATRIX)))
          then (HELP "Illegal FACTORMATRIX" FACTORMATRIX)))
(* Copy MATRIX to FACTORMATRIX)
(BLAS.ARRAYBLT MATRIX 0 1 FACTORMATRIX 0 1)

(* * Compute the QR decomposition of FACTORMATRIX)

(for I from 0 to (SUB1 P) do (\FLOATASET 0.0 QRAUX I))
(bind NRMXL for L from 0 to (SUB1 (IMIN N P)) unless (EQL L (SUB1 N))
  do
    (* Compute the Householder transformation for column L)
    (SETQ NRMXL (BLAS.NRM2 FACTORMATRIX (IPLUS L (ITIMES P L))
                  P
                  (IDIFFERENCE N L)))
    (if (FGREATERP NRMXL 0.0)
      then (if (FLESSP (\FLOATAREF FACTORMATRIX L L)
                       0.0)
        then (SETQ NRMXL (FMINUS NRMXL)))
        (BLAS.SCAL (FQUOTIENT 1.0 NRMXL)
                   FACTORMATRIX
                   (IPLUS L (ITIMES P L))
                   P
                   (IDIFFERENCE N L))
        (\FLOATASET (FPLUS 1.0 (\FLOATAREF FACTORMATRIX L L))
                     FACTORMATRIX L L)
        (* apply the transform to the remaining columns)
        (bind TEMP for J from (ADD1 L) to (SUB1 P)
          do [SETQ TEMP (FMINUS (FQUOTIENT (BLAS.DOTPROD FACTORMATRIX (IPLUS L (ITIMES P L))
                                                           P
                                                           (IDIFFERENCE N L))
                                           (\FLOATAREF FACTORMATRIX L L)
                                           P
                                           FACTORMATRIX (IPLUS J (ITIMES P L))
                                           P
                                           (IDIFFERENCE N L))
                                (BLAS.AXPY TEMP FACTORMATRIX (IPLUS L (ITIMES P L))
                                             P
                                             FACTORMATRIX (IPLUS J (ITIMES P L))
                                             P
                                             (IDIFFERENCE N L))
                                (\FLOATASET (\FLOATAREF FACTORMATRIX L L)
                                              QRAUX L)
                                (\FLOATASET (FMINUS NRMXL)
                                              FACTORMATRIX L L))
          FACTORMATRIX])
    FACTORMATRIX])

```

(QROLS

[LAMBDA (QRMATRIX QRAUX Y QTY B RSD YHAT)

(* jop: "27-May-86 17:21")

(* * Lifted from LINPACK algorithm SQRS�)

```

(BLAS.CHECKARRAY QRMATRIX)
(BLAS.CHECKARRAY QRAUX)
(BLAS.CHECKARRAY Y)
(LET ((N (ARRAY-DIMENSION QRMATRIX 0))
      (P (ARRAY-DIMENSION QRMATRIX 1)))
  (* * Arg Checks)

  (if [NOT (AND (EQL 1 (ARRAY-RANK QRAUX))
                (EQL P (ARRAY-TOTAL-SIZE QRAUX))
              )]
    then (HELP "QRAUX not of size P" QRAUX))
  (if [NOT (AND (EQL 1 (ARRAY-RANK Y))
                (EQL N (ARRAY-TOTAL-SIZE Y))
              )]
    then (HELP "Y not of size N" Y))
  (if (NULL QTY)
    then (SETQ QTY (MAKE-ARRAY N (QUOTE :ELEMENT-TYPE)
                                (QUOTE FLOAT)))
    else (BLAS.CHECKARRAY QTY)
          (if (NOT (EQL N (ARRAY-TOTAL-SIZE QTY)))
            then (HELP "QTY not of size N" QTY)))
  (if (NULL B)
    then (SETQ B (MAKE-ARRAY P (QUOTE :ELEMENT-TYPE)
                              (QUOTE FLOAT)))
    else (BLAS.CHECKARRAY B)
          (if (NOT (EQL P (ARRAY-TOTAL-SIZE B)))
            then (HELP "B not of size P" B)))
  (if RSD
    then (BLAS.CHECKARRAY RSD)
          (if (NOT (EQL N (ARRAY-TOTAL-SIZE RSD)))
            then (HELP "RSD not of size N" RSD)))

```



```

else (BLAS.CHECKARRAY PRODUCT)
  (if (NOT (EQL N (ARRAY-TOTAL-SIZE PRODUCT)))
    then (HELP "PRODUCT not of size N" PRODUCT)))
(BLAS.ARRAYBLT Y 0 1 PRODUCT 0 1 N)
(bind TEMP for J from 0 to (IMIN P (SUB1 N))
  do (if (NOT (UFEQP (\FLOATAREF QRAUX J)
    0.0))
    then (SETQ TEMP (\FLOATAREF QRMATRIX J J))
      (\FLOATASET (\FLOATAREF QRAUX J)
        QRMATRIX J J)
      (BLAS.AXPY (FMINUS (FQUOTIENT (BLAS.DOTPROD QRMATRIX (IPLUS J (ITIMES P J))
        P PRODUCT J 1 (IDIFFERENCE N J))
        (\FLOATAREF QRMATRIX J J)))
        QRMATRIX
        (IPLUS J (ITIMES P J))
        P PRODUCT J 1 (IDIFFERENCE N J))
      (\FLOATASET TEMP QRMATRIX J J)))
PRODUCT])

```

(QRQY

[LAMBDA (QRMATRIX QRAUX Y PRODUCT)

(* jop: "27-May-86 16:30")

(* * COMPUTE QX given a QR factorization described by QRMATRIX and QRAUX where Y is an N vector)

(* * Lifted from LINPACK algorithm SQRSL)

```

(BLAS.CHECKARRAY QRMATRIX)
(BLAS.CHECKARRAY QRAUX)
(BLAS.CHECKARRAY Y)
(LET ((N (ARRAY-DIMENSION QRMATRIX 0))
      (P (ARRAY-DIMENSION QRMATRIX 1)))
  (* * Arg Checks)
  (if [NOT (AND (EQL 1 (ARRAY-RANK QRAUX))
    (EQL P (ARRAY-TOTAL-SIZE QRAUX))
    then (HELP "QRAUX not of size P" QRAUX))
    (if [NOT (AND (EQL 1 (ARRAY-RANK Y))
      (EQL N (ARRAY-TOTAL-SIZE Y))
      then (HELP "Y not of size N" Y))
      (if (NULL PRODUCT)
        then (SETQ PRODUCT (MAKE-ARRAY N (QUOTE :ELEMENT-TYPE)
          (QUOTE FLOAT)))
        else (BLAS.CHECKARRAY PRODUCT)
          (if (NOT (EQL N (ARRAY-TOTAL-SIZE PRODUCT)))
            then (HELP "PRODUCT not of size N" PRODUCT)))
      (BLAS.ARRAYBLT Y 0 1 PRODUCT 0 1 N)
      (bind TEMP for J from (SUB1 (IMIN P (SUB1 N))) to 0 by -1
        do (if (NOT (UFEQP (\FLOATAREF QRAUX J)
          0.0))
          then (SETQ TEMP (\FLOATAREF QRMATRIX J J))
            (\FLOATASET (\FLOATAREF QRAUX J)
              QRMATRIX J J)
            (BLAS.AXPY (FMINUS (FQUOTIENT (BLAS.DOTPROD QRMATRIX (IPLUS J (ITIMES P J))
              P PRODUCT J 1 (IDIFFERENCE N J))
              (\FLOATAREF QRMATRIX J J)))
              QRMATRIX
              (IPLUS J (ITIMES P J))
              P PRODUCT J 1 (IDIFFERENCE N J))
            (\FLOATASET TEMP QRMATRIX J J)))
        PRODUCT]))

```

(QRSOLV

[LAMBDA (QRMATRIX QRAUX BVECTOR SOLUTION)

(* jop: "27-May-86 20:38")

(* * Solves to system $Ax = b$. BVECTOR should to the RHS of the system.
Returns SOLUTION)

```

(RSOLV QRMATRIX (QRQTY QRMATRIX QRAUX BVECTOR SOLUTION)
  SOLUTION])

```

(MREGRESS

[LAMBDA (Y X B RSD YHAT)

(* jop: " 4-Jun-86 14:12")

(* * MREGRESS calculates the least squares (multiple) regression of Y on X.
An N vector Y.)

```

(LET* ((QRAUX (MAKE-ARRAY (ARRAY-DIMENSION X 1)
  (QUOTE :ELEMENT-TYPE)
  (QUOTE FLOAT)))
  (QRMATRIX (QRFACTOR X QRAUX)))
  (QROLS QRMATRIX QRAUX Y NIL B RSD YHAT])

```


(RSOLV

[LAMBDA (RMATRIX CVECTOR BVECTOR)

(* jop: "28-May-86 20:31")

(* Calculate the solution vector BVECTOR for the system of linear equations $R \cdot B = C$, where RMATRIX is upper triangular $M \times N$ with non-zero diagonal elements. BVECTOR and CVECTOR must be of size N.
Always returns BVECTOR)

```
(BLAS.CHECKARRAY RMATRIX)
(BLAS.CHECKARRAY CVECTOR)
(PROG ((M (ARRAY-DIMENSION RMATRIX 0))
      (N (ARRAY-DIMENSION RMATRIX 1))))

(* Arg Checks)

(if (ILESSP M N)
  then (HELP "Order of system less than" N))
(if (NOT (EQL (ARRAY-TOTAL-SIZE CVECTOR)
              N))
  then (HELP "CVECTOR not of size" N))
(if (NULL BVECTOR)
  then (SETQ BVECTOR (MAKE-ARRAY N (QUOTE :ELEMENT-TYPE)
                                   (QUOTE FLOAT)))
  else (BLAS.CHECKARRAY BVECTOR)
        (if (NOT (EQL (ARRAY-TOTAL-SIZE BVECTOR)
                      N))
          then (HELP "BVECTOR not of size" N))) (* Check for zero diagonal elements)
(if (for I from 0 to (SUB1 N) thereis (UFEQP 0.0 (\FLOATAREF RMATRIX I I)))
  then (HELP "RMATRIX has a zero diagonal element"))

(* Solution by backsubstitution.)

(BLAS.ARRAYBLT CVECTOR 0 1 BVECTOR 0 1 N)
(LET ((INDEXLIMIT (SUB1 N))) (* Compute the last value)
  (\FLOATASET (FQUOTIENT (\FLOATAREF BVECTOR INDEXLIMIT)
                        (\FLOATAREF RMATRIX INDEXLIMIT INDEXLIMIT))
              BVECTOR INDEXLIMIT)
  (bind J JLESS1 for JJ from 1 to INDEXLIMIT do (SETQ J (IDIFFERENCE N JJ))
        (SETQ JLESS1 (SUB1 J))
        (BLAS.AXPY (FMINUS (\FLOATAREF BVECTOR J))
                   RMATRIX J N BVECTOR 0 1 J)
        (\FLOATASET (FQUOTIENT (\FLOATAREF BVECTOR JLESS1)
                              (\FLOATAREF RMATRIX JLESS1 JLESS1))
                    BVECTOR JLESS1)))

(RETURN BVECTOR))
```

(MSOLVE

[LAMBDA (MATRIX CVECTOR SOLUTION)

(* jop: "27-May-86 20:40")

(* Solves to system $A \cdot x = b$. CVECTOR should be the RHS of the system.
Returns SOLUTION)

```
(LET [(PIVOTVECTOR (MAKE-ARRAY (ARRAY-DIMENSION MATRIX 0)
                                (LUSOLV (LUFACTOR MATRIX PIVOTVECTOR)
                                          PIVOTVECTOR CVECTOR SOLUTION))])
```

(SVDFACTOR

[LAMBDA (XMATRIX SVECTOR UMATRIX VMATRIX)

(* jop: "29-May-86 11:29")

(* Singular-value decomposition by means of orthogonalization by plane rotations.
Taken from Nash and Shlien: "Partial svd algorithms." On entry X contains the M by N matrix to be decomposed, SVECTOR must be a vector of length N and VMATRIX must be a square N by N matrix.
On return UMATRIX has been overwritten by the left singular vectors, SVECTOR contains the singular values, and VMATRIX contains the right singular vectors.)

```
(BLAS.CHECKARRAY XMATRIX)
(LET ((M (ARRAY-DIMENSION UMATRIX 0))
      (N (ARRAY-DIMENSION UMATRIX 1)))

  (* Args checks)

  (if (NOT (EQL 2 (ARRAY-RANK XMATRIX)))
    then (HELP "XMATRIX not a matrix" XMATRIX))
  (if (NULL SVECTOR)
    then (SETQ SVECTOR (MAKE-ARRAY N (QUOTE :ELEMENT-TYPE)
                                       (QUOTE FLOAT)))
    else (BLAS.CHECKARRAY SVECTOR)
          (if [NOT (AND (EQL 1 (ARRAY-RANK SVECTOR))
                       (EQL N (ARRAY-TOTAL-SIZE SVECTOR))
                       then (HELP "Illegal SVECTOR" SVECTOR))])
  (if (NULL UMATRIX)
    then (SETQ UMATRIX (MAKE-ARRAY (LIST M N)
                                    (QUOTE :ELEMENT-TYPE)
                                    (QUOTE FLOAT)))
    else (BLAS.CHECKARRAY UMATRIX))
```

```

      (if (NOT (EQUAL (ARRAY-DIMENSIONS UMATRIX)
                     (ARRAY-DIMENSIONS XMATRIX)))
          then (HELP "illegal UMATRIX" UMATRIX)))
    (if (NULL VMATRIX)
        then (SETQ VMATRIX (MAKE-ARRAY (LIST N N)
                                         (QUOTE :ELEMENT-TYPE)
                                         (QUOTE FLOAT)))
        else (BLAS.CHECKARRAY VMATRIX)
              (if (NOT (EQUAL (ARRAY-DIMENSIONS VMATRIX)
                              (LIST N N)))
                  then (HELP "illegal VMATRIX" VMATRIX)))
    (BLAS.ARRAYBLT XMATRIX NIL NIL UMATRIX) (* Copy XMATRIX to UMATRIX)
    (BLAS.ARRAYFILL 0.0 VMATRIX)           (* Initialize VMATRIX to identity matrix.)
    (for I from 0 to (SUB1 N) do (\FLOATASET 1.0 VMATRIX I I))

    (* Start the computation)

    (LET ((NT N))

      (* The main loop: repeatedly sweep over all pairs of columns in U, rotating as needed, until no rotations in a complete
      sweep are effective. Check the opportunity for rank reduction at the conclusion of each sweep.)

      [bind (EPS _ 1.0E-6)
            (SLIMIT _ (IMAX (IQUOTIENT N 4)
                             6))
            (SCOUNT _ 0)
            RCOUNT eachtime (SETQ RCOUNT (IQUOTIENT (ITIMES NT (SUB1 NT))
                                                         2))
            (SETQ SCOUNT (ADD1 SCOUNT))
      repeatwhile (IGREATERP RCOUNT 0)
      do (if (IGREATERP SCOUNT SLIMIT)
            then (HELP "Number of sweeps exceeds sweep limit." SCOUNT))
      [for J from 0 to (IDIFFERENCE NT 2)
        do (bind P Q R C S V for K from (ADD1 J) to (SUB1 NT)
              do (SETQ P (BLAS.DOTPROD UMATRIX J N UMATRIX K N M))
                  (SETQ Q (BLAS.DOTPROD UMATRIX J N UMATRIX J N M))
                  (SETQ R (BLAS.DOTPROD UMATRIX K N UMATRIX K N M))
                  (\FLOATASET Q SVECTOR J)
                  (\FLOATASET R SVECTOR K)
                  (if (FLESSP Q R)
                      then (SETQ Q (FDIFFERENCE (FQUOTIENT Q R)
                                                  1.0))
                          (SETQ P (FQUOTIENT P R))
                          [SETQ V (SQRT (SETQ V (FPLUS (FTIMES 4.0 P P)
                                                         (FTIMES Q Q))
                          [SETQ S (SQRT (FTIMES 0.5 (FDIFFERENCE 1.0 (FQUOTIENT Q V)
                                                         (FLESSP P 0.0))
                          then (SETQ S (FDIFFERENCE 0.0 S))
                              (SETQ C (FQUOTIENT P (FTIMES V S)))
                              (BLAS.ROT C S UMATRIX J N UMATRIX K N M)
                              (BLAS.ROT C S VMATRIX J N VMATRIX K N N)
                          elseif (OR (LEQ (FTIMES Q R)
                                          (FTIMES EPS EPS))
                                     (LEQ (FTIMES (FQUOTIENT P Q)
                                                  (FQUOTIENT P R))
                                          EPS))
                              then (SETQ RCOUNT (SUB1 RCOUNT))
                          else (SETQ R (FDIFFERENCE 1.0 (FQUOTIENT R Q)))
                              (SETQ P (FQUOTIENT P Q))
                              [SETQ V (SQRT (SETQ V (FPLUS (FTIMES 4.0 P P)
                                                         (FTIMES R R))
                              [SETQ C (SQRT (FTIMES 0.5 (FPLUS 1.0 (FQUOTIENT R V)
                                                         (SETQ S (FQUOTIENT P (FTIMES V C)))
                              (* box before the COLROT calls)
                              (BLAS.ROT C S UMATRIX J N UMATRIX K N M)
                              (BLAS.ROT C S VMATRIX J N VMATRIX K N N]
                          (while (AND (IGE Q NT 3)
                                     (LEQ (FQUOTIENT (\FLOATAREF SVECTOR (SUB1 NT))
                                                         (FPLUS (\FLOATAREF SVECTOR 0)
                                                         EPS))
                                     EPS))
                              do (SETQ NT (SUB1 NT])

      (* Finish the decomposition by returning all N singular values, and by normalizing those columns of UMATRIX judged to be
      non-zero.)

      (bind Q for J from 0 to (SUB1 N) do (SETQ Q (SQRT (\FLOATAREF SVECTOR J)))
          (\FLOATASET Q SVECTOR J)
          (if (ILEQ J NT)
              then (BLAS.SCAL (FQUOTIENT 1.0 Q)
                              UMATRIX J N M)))

      SVECTOR]))

```

(TIMEALL (SVDNASH UU SS VV))

[LAMBDA (ARGS)

```

( LLSH , INDEXFORM 1 ] )

```

[LAMBDA (ARGS)

[illegible]

```
(RETURN (BQUOTE (\PUTBASEFLOATP (ARRAYBASE , BARRAY)
                                (LLSH , INDEXFORM 1)
                                , BNEWVALUE])
)

(RPAQQ STACK
  ((80 27 89)
   (80 27 88)
   (75 25 90)
   (62 24 87)
   (62 22 87)
   (62 23 87)
   (62 24 93)
   (62 24 93)
   (58 23 87)
   (58 18 80)
   (58 18 89)
   (58 17 88)
   (58 18 82)
   (58 19 93)
   (50 18 89)
   (50 18 86)
   (50 19 72)
   (50 19 79)
   (50 20 80)
   (56 20 82)
   (70 20 91)))

(DECLARE: EVAL@COMPILE

(PUTPROPS FLOATAREF MACRO (ARGS
  (* *)
  (\FLOATAREFMACRO ARGS)))

(PUTPROPS FLOATASET MACRO (ARGS
  (* *)
  (\FLOATASETMACRO ARGS)))

)

(FILESLoad BLAS)

(PUTPROPS MATRIXOPS COPYRIGHT ("Xerox Corporation" 1986))
```

FUNCTION INDEX

CHOLSKYFACTOR1	LUSOLV4	MTIMES5	QRQTY7	SVDFACTOR9
LSOLV2	MINVERT2	MTRANSPOSE1	QRQY8	SVDTEST10
LUFACTOR2	MREGRESS8	QRFACOR5	QRSOLV8	\FLOATAREFMACRO ..11
LUINVERSE3	MSOLVE9	QROLS6	RSOLV9	\FLOATASETMACRO ..11

MACRO INDEX

\FLOATAREF12	\FLOATASET12
--------------------	--------------------

VARIABLE INDEX

STACK12
