# MH-Z16 Intelligent Infrared Gas Module Manual

# 1 Profile



# Main functions and features:

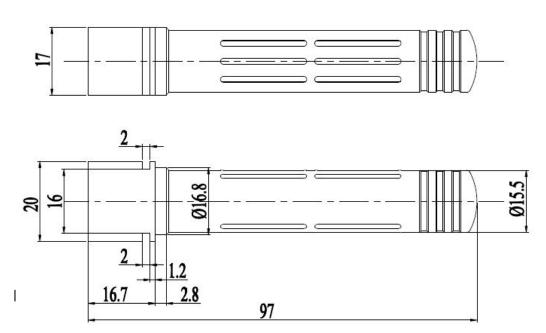
- ➤ High sensitivity, High resolution
- > Low power consumption
- Output method:UART, analog voltage signal, PWM wave
- Quick responce
- > Temperature compensation, excellent linear output
- Good stability
- ➤ Long lifespan
- > Anti water vapor interference
- No poisoning

# 2 Main technical paremeters

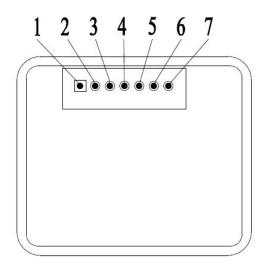
Working voltage	4.5 V ~ 5.5V DC
Average current	< 85 mA
Interface level	3.3 V
Measuring range	0~5%VOL optional
Output signal	PWM
Output signal	UART
Preheat time	3min
Reponse Time	T <sub>90</sub> < 30s
Working temperature	0℃~50℃
Working humidity	0~95%RH
Weight	21 g
Lifespan	>5 year

Target Gas	Measuring Range	Accuracy	Mark
	0~2000ppm		Temperature compensation
	0~5000ppm	±(50ppm	Temperature compensation
Carbon Dioxide (CO2)	0~1%VOL	+5%readin g value)	Temperature compensation
	0~3%VOL		Temperature compensation
	0~5%VOL		Temperature compensation

# 3.Structure

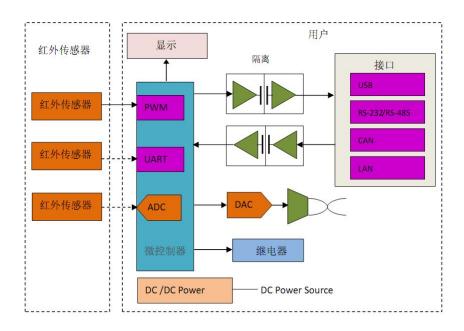


# 4.Pin



PIN	Description					
Pad4	Vin(input voltage $4.5V\sim5.5V$ )					
Pad3	GND					
Pad2	Vout $(0.4\sim2V, \text{custom made})$					
Pad7	PWM					
Pad1	HD					
Pad5	UART (RXD) $0{\sim}3.3$ V input digital					
Pad6	UART (TXD) $0\sim3.3$ V output digital					

# 5.Circuit



# 6. Operating instruction

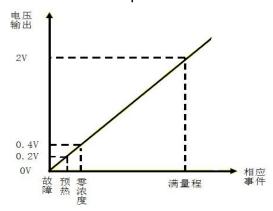
# **6.1 Analog output connections**

The output value of Vout is 0.4-2.0V, which stands for 0 to full range

Vin -5V

**GND-Power Ground** 

Vout-ADC input



## 6.2PWM output (taking PWM output from 2000ppm as example):

CO2 output range: 0ppm-2000ppm Cycle:  $1004ms\pm5\%$  High level output for beginning: 2ms (in name) Middle of cycle:  $1000ms\pm5\%$  Low level output for ending: 2ms (in name)

Account formula for CO2 concentration which gets through PWM:

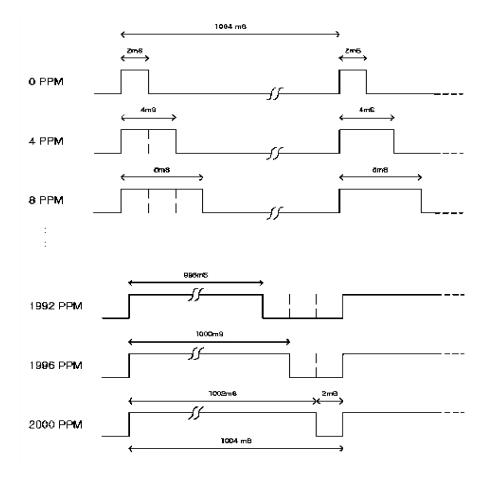
$$C_{ppm}=2000\times(T_H-2ms)/(T_H+T_L-4ms)$$

Among:

 $C_{\it ppm}$  is calculated CO2 concentration, unit is ppm;

 $T_{\!\scriptscriptstyle H}$  is time for high level during an output cycle;

 $T_{\!\scriptscriptstyle L}$  is time for low level during an output cycle.



# 6.3 Digital connects:

Vin-5V power

**GND- Power Ground** 

**RXD** connect sensor TXD

TXD connect sensor RXD

You can read gas concentration via Uart, no need to calculate.

# 6.3.1communication protocol

# 1.General Settings

Baud rate	9600
Date byte	8 byte
Stop byte	1byte
Calibrate byte	no

### 2.Command

Each command or return: Contains 9 bytes (byte  $0 \sim 8$ ) starting byte fixed 0 XFF

# command contains sensor number (factory default to 0 x01) to check and end

### **Command List:**

	0x86	Gas concentration
	0x87	Calibrate zero point (ZERO)
Ī	0x88	Calibrate span point (SPAN)

# Read gas concentration

	Send command									
Byte0	Byte1	Byte2	Byte3	Byte4	Byte5	Byte6	Byte7	Byte8		
Start	Sensor	command	-	-	-	-	-	Check		
ing	No.							value		
byte										
0XFF	0x01	0x86	0x00	0x00	0x00	0x00	0x00	0x79		

### **Return value**

	Return									
Byte0	Byte1	Byte2	Byte3	Byte4	Byte5	Byte6	Byte7	Byte		
								8		
Start	command	High	Low	-	-	-	-	Chec		
ing		level	level					k		
byte		concentr	concentr					valu		
		ation	ation					е		
0XFF	0x86	0x02	0x60	0x47	0x00	0x00	0x00	0xD1		

# Gas concentration= high level \*256+low level

# Calibrate zero point

	Send command										
Byte0	Byte1	Byte2	Byte3	Byte4	Byte5	Byte6	Byte7	Byte8			
Start	Sensor	command	-	-	-	-	-	Check			
ing	No.							value			
byte											
0XFF	0x01	0x87	0x00	0x00	0x00	0x00	0x00	0x78			

### No return value

# Calibrate span point

	•										
	Send command										
Byte0	Byte1	Byte2	Byte3	Byte4	Byte5	Byte6	Byte7	Byte8			
Start	Sensor	command	High	Low	-	-	-	Check			
ing	No.		level	level				value			
byte			span	span							
			point	point							
0XFF	0x01	0x88	0x07	0xD0	0x00	0x00	0x00	0xA0			

### No return value

### 3. Calibrate and calculate

The checksum = (invert (byte 1 + ... + 7)) + 1

### **Reading gas concentration:**

	Send command									
Byte0	Byte1	Byte2	Byte3	Byte4	Byte5	Byte6	Byte7	Byte8		
Start	Sensor	command	-	-	-	-	-	Check		
ing	No.							value		
byte										
0XFF	0x01	0x86	0x00	0x00	0x00	0x00	0x00	0x79		

### Except byte 0, add the other bytes together

```
0x1 + 0x86 + 0 + 0 + 0 + 0 + 0 = 0x87
```

Get the value from the first step, then invert it.

```
0xff - 0x87 = 0x78
```

### The second value plus one

```
0x78 + 0x01 = 0x79
```

### **Program: Clanguage**

```
char getCheckSum(char *packet)
{
    char i, checksum;
    for( i = 1; i < 8; i++)
    {
        checksum += packet[i];
    }
    checksum = 0xff - checksum;
    checksum += 1;
    return checksum;
}</pre>
```

### 7. Notes for maintenance

- 7.1 The sensor should be calibrated regularly. The cycle time is better to be no more than 6 months.
- 7.2 Do not use the sensor in the high dusty environment for long time.
- 7.3 Please use the sensor with correct power supply.
- 7.4 Forbidden to cut the sensor pin.

### Zhengzhou Winsen Electronics Technology Co., Ltd

Add.: NO.299 Jin Suo Road, National Hi-Tech Zone,

Zhengzhou, 450001 China

Tel.: 0086-371-67169097 67169670

Fax:0371-60932988

E-mail:sales@winsensor.com