

NATIONAL UNIVERSITY OF SINGAPORE
Department of Mathematics

MA1522 Linear Algebra for Computing

Tutorial 11

1. (i) Determine whether the following are linear transformations.
- (ii) Write down the standard matrix for each other the linear transformations.
- (iii) Find a basis for the range for each of the linear transformations.
- (iv) Find a basis for the kernel for each of the linear transformations.

(a) $T_1: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that $T_1 \left(\begin{pmatrix} x \\ y \end{pmatrix} \right) = \begin{pmatrix} x+y \\ y-x \end{pmatrix}$ for $\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2$.

(b) $T_2: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that $T_1 \left(\begin{pmatrix} x \\ y \end{pmatrix} \right) = \begin{pmatrix} 2^x \\ 0 \end{pmatrix}$ for $\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2$.

(c) $T_3: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ such that $T_3 \left(\begin{pmatrix} x \\ y \end{pmatrix} \right) = \begin{pmatrix} x+y \\ 0 \\ 0 \end{pmatrix}$ for $\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2$.

(d) $T_4: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ such that $T_4 \left(\begin{pmatrix} x \\ y \\ z \end{pmatrix} \right) = \begin{pmatrix} 1 \\ y-x \\ y-z \end{pmatrix}$ for $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3$.

(e) $T_5: \mathbb{R}^5 \rightarrow \mathbb{R}$ such that $T_5 \left(\begin{pmatrix} x_1 \\ \vdots \\ x_5 \end{pmatrix} \right) = x_3 + 2x_4 - x_5$ for $\begin{pmatrix} x_1 \\ \vdots \\ x_5 \end{pmatrix} \in \mathbb{R}^5$.

(f) $T_6: \mathbb{R}^n \rightarrow \mathbb{R}$ such that $T_6(\mathbf{x}) = \mathbf{x} \cdot \mathbf{x}$ for $\mathbf{x} \in \mathbb{R}^n$.

2. Let $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ and $G: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be linear transformations such that

$$F \left(\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \right) = \begin{pmatrix} x_1 - 2x_2 \\ x_1 + x_2 - 3x_3 \\ 5x_2 - x_3 \end{pmatrix} \text{ and } G \left(\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \right) = \begin{pmatrix} x_3 - x_1 \\ x_2 + 5x_1 \\ x_1 + x_2 + x_3 \end{pmatrix},$$

and let \mathbf{A}_F and \mathbf{B}_G be the standard matrix of F and G , respectively.

- (a) Find \mathbf{A}_F and \mathbf{B}_G .

- (b) Define

$$(F + G)(\mathbf{x}) := F(\mathbf{x}) + G(\mathbf{x}), \text{ for all } \mathbf{x} \in \mathbb{R}^3.$$

Is $(F + G)$ a linear transformation? If it is, find its standard matrix.

- (c) Write down the formula for $F(G(\mathbf{x}))$ and find its standard matrix.
- (d) Find a linear transformation $H: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ such that

$$H(G(\mathbf{x})) = \mathbf{x}, \text{ for all } \mathbf{x} \in \mathbb{R}^3.$$

3. For each of the following linear transformations, (i) determine whether there is enough information for us to find the formula of T ; and (ii) find the formula and the standard matrix for T if possible.

(a) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ such that

$$T \left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right) = \begin{pmatrix} 1 \\ 3 \\ 0 \\ 1 \end{pmatrix}, \quad T \left(\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 2 \\ -1 \\ 4 \end{pmatrix}, \quad \text{and} \quad T \left(\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right) = \begin{pmatrix} 0 \\ 4 \\ 1 \\ 6 \end{pmatrix}.$$

(b) $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that

$$T \left(\begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 0 \end{pmatrix}, \quad T \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) = \begin{pmatrix} 0 \\ 2 \end{pmatrix}, \quad \text{and} \quad T \left(\begin{pmatrix} 2 \\ 0 \end{pmatrix} \right) = \begin{pmatrix} 2 \\ 2 \end{pmatrix}.$$

(c) $T : \mathbb{R}^3 \rightarrow \mathbb{R}$ such that

$$T \left(\begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \right) = -1, \quad T \left(\begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} \right) = 1 \quad \text{and} \quad T \left(\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \right) = 0.$$

4. For each of the following linear transformations T , determine its rank and nullity, and whether it is one-to-one, and/or onto.

(a) $T : \mathbb{R}^4 \rightarrow \mathbb{R}^6$ such that the rank is 4.

(b) $T : \mathbb{R}^6 \rightarrow \mathbb{R}^4$ such that the nullity is 2.

(c) $T : \mathbb{R}^4 \rightarrow \mathbb{R}^6$ such that the reduce row-echelon form of its standard matrix has 3 nonzero rows.

(d) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ such that T is one-to-one.

Extra problems

1. (a) Show that if λ is an eigenvalue of a stochastic matrix \mathbf{P} , then $|\lambda| \leq 1$.
Hint: Pick an eigenvector \mathbf{v} of \mathbf{P}^T associated with λ . Let $k \in \{1, 2, \dots, n\}$ be a coordinate of \mathbf{v} with the maximum absolute value, $|v_k| \geq |v_i|$ for all $i = 1, \dots, n$. Consider the k -th coordinate of the equation $\mathbf{P}^T \mathbf{v} = \lambda \mathbf{v}^T$.
(b) Let \mathbf{P} be a stochastic matrix. For any vector \mathbf{v} , define $\mathbf{v}^{(k)} = \mathbf{P}^k \mathbf{v}$. Show that if \mathbf{v} is an eigenvector of \mathbf{P} that is not associated to eigenvalue 1, then $\mathbf{v}^{(k)} \rightarrow 0$ as $k \rightarrow \infty$.
2. Let $\{\mathbf{u}_1, \dots, \mathbf{u}_n\}$ be a basis for \mathbb{R}^n and $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ be some vectors in \mathbb{R}^m . Prove that there is a unique transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that $T(\mathbf{u}_i) = \mathbf{v}_i$ for $i = 1, \dots, n$.
3. Prove that $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a bijective (one-to-one and onto) linear transformation if and only if there is a basis $S = \{\mathbf{u}_1, \dots, \mathbf{u}_n\}$ such that the standard matrix of T is a transition matrix from S to E , where E is the standard basis for \mathbb{R}^n .