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1 * Recall: How to calculate SVD? (Real matrices)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        A=UZV*
     I. Find eigenvalues of ATA \sim 6_1 = \sqrt{\lambda_1}, 6_2 = \sqrt{\lambda_2},... (nonzero eigenvalues)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        A*A=VZ1*UZV*
    ii. Find the unit eigenvectors of A^TA \rightarrow V_1, V_2, \cdots
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      = V (ZZ!*) V*
    iii. Then, find 4z = \frac{1}{5} Avz
     iv. Extend each {u2}, {ui} to the basis sets of IRM, IRM
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               ~ (A*A) V= V(∑∑*)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   (\Lambda \Lambda^*) \coprod = \coprod (\Sigma^* \Sigma^*)
    (a) A = \begin{bmatrix} 3 & 0 \\ 0 & -2 \end{bmatrix}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               So, LI &V are eigenvectors of
   A^{T}A = \begin{bmatrix} 9 & 0 \\ 0 & 4 \end{bmatrix} \quad \text{det} \quad (A^{T}A - \lambda I) = (9 - \lambda)(4 - \lambda) \quad 6_{1} = 3, \quad 6_{2} = 2.
\begin{bmatrix} 9 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} \chi \\ y \end{bmatrix} = \begin{bmatrix} 9\chi \\ 9\chi \end{bmatrix} \quad & \mathcal{V}_{1} = (1, 0) \quad \mathcal{U}_{1} = (0, 1) \quad \mathcal{U}_{2} = (0, 1) \quad & \mathcal{U}_{2} = (0, 1) \quad & \mathcal{U}_{2} = (0, 1) \quad & \mathcal{U}_{3} = (0, 1) \quad & \mathcal{U}_{4} = (0, 1) \quad & \mathcal{U}_{5} = (
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 AA*& A*A.
                                                                                                                                                                                                                                                                                                                                                                u_1 = \frac{1}{3} A u_1 = (1,0)
                                                                                                                                                                                                                                                                                                                                                           u_2 = \frac{1}{2} A u_2 = (0, -1)
     (b), (c), (d), (e) similar calculations.
    (e) A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \longrightarrow A^{T}A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}
      v_1 = \frac{1}{2} A u_1 = (\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})
                 \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2x + 2y \\ 2x + 2y \end{bmatrix} = \begin{bmatrix} 4 \times \\ 4y \end{bmatrix} \rightarrow \mathcal{U}_1 = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})
                                                                                                                                                                                                                                                                                                                                           extend v_2 = (\frac{12}{2}, -\frac{\sqrt{2}}{2})
           Let a
2 Let A = \begin{bmatrix} a_{11} \\ \vdots \\ a_{m_1} \end{bmatrix} and A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} about the column axis.

Spec A = \begin{bmatrix} a_{11} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{m_n} \end{bmatrix} A = \begin{bmatrix} a_{m_1} \\ \vdots \\ a_{
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                where k=rank(A)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     X It is clear that A&A, has
       B = A^{T}[, \cdot, \cdot] = A^{T}I'
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       the same singular value
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        A = (V^*)^T \sum_{i=1}^{T} U_i^T
         And I' is unitary: I'I' = [, \cdots] [, \cdots] = I_m
         .. B = UZ V*I' = UZ(V')* where V'=(I')*. V, unitary.
     : It is the SVD of B, and has the same I with AT (by the uniqueness of SVD)
  3 See the bottom of the file
| 4 Claim: A&B are unitarily equivalent -> have the same singular value.

Pf) Let B= 以Z V* ~ A= QU Z V*Q*= 以Z V' ~ it is the SVD of A. (by uniqueness of SVD)
      But converse is not true.
        Let A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}
       Spse = unitary Q \in C^{2\times 2} s.t A = QBQ*
\begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} = Q\begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix}\begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} Q* \Leftrightarrow Q\begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} = Q\begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}
                                                                                                                                                                                                                                                                                                                                  (contradiction)
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