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1 (a) Fix \forall \lambda \in \mathbb{C}. Consider A - \lambda I. Notice that B = (A - \lambda I)_{2:m,2:m} (eliminating 1st row & last column)
     is full rank as it is an upper triangular with nonzero diagonals which correspond to A's subdiagonal.
                                                  : \beta_{\dot{i}\dot{i}} = (A - \lambda I)_{\dot{i}+1,\dot{i}} = A_{\dot{i}+1,\dot{i}} \quad (1 \le \dot{i} \le m-1)
                                                   and B_{ij} = (A - \lambda I)_{i+1,j} = A_{i+1,j} = 0 for \{z > j \text{ by def of tridiagonal}\}
     So, if rank (A-\lambda I) \leq m-2, there must be a linearly dependent pair of rows in B,
      which contradicts to full rank of B.
      \Rightarrow rank (A - \lambda I) \ge m - l
     Now, as A hermitian, by Thm 24.7, it diagonalizable by A = X^* / L X. And by Thm 24.3, L \& A
      have the exactly same eigenvalues which appear on 1
       X = X^* \times X = X \times X 
       As A - \lambda I & \Lambda - \lambda I similar, have the same rank i.e, rank (\Lambda - \lambda I) \ge m-1.
       Denote \lambda_i = (\Lambda)_{ii} (1 \le i \le m). And each \lambda_i is the eigenvalue of A. Spse the eigenvalues of A are not
       distinct, i.e. \lambda_i = \lambda_j for some 2&j. Fix \lambda = \lambda_i = \lambda_j
       Since \Lambda - \lambda I is diagonal, rank (\Lambda - \lambda I) = (\# \text{ of nonzero diagonals}). But, as (\Lambda - \lambda I)_{ii} = (")_{ij} = 0,
        rank (A - \lambda I) = rank (A - \lambda I) \le m - 2 (contradiction) \Rightarrow the eigenvalues of A are distinct.
     (b) | | -1 0 ] = A
                                                                                                 det(\lambda I - A) = |\lambda - 1|
                                                                                                                                                                                  0
                                                                                                                                                                                                = (\lambda - 1) (\lambda^2 - 1 + 1) - (\lambda - 1)
                   Fi\-1-1
                                                                                                                                                                                                     = (\lambda^{2}-1)(\lambda-1) = (\lambda+1)(\lambda-1)^{2}
                  nonzero
                                                                                                                                                                                                                                                                () \lambda=1 with algebraic mult
               4 Hessenberg
                                                                                                                                                                                                                                                                           2 ⇒ not distinct.
                   as az j = 0 for all 2>j+1
    |3|(a)<mark>(ji)</mark>
     By left multiplication of some Householder reflectors,
                                                                                                                                                                                       \begin{bmatrix} X & X & X \\ X & X & X \end{bmatrix} \rightarrow \begin{bmatrix} X & X & X \\ 0 & X & X \end{bmatrix}
      For some appropriate Householder reflectors, we can construct Q_2 \begin{bmatrix} x & x & x \end{bmatrix}^* = Q_2 \begin{bmatrix} x & 0 & 0 \end{bmatrix} = \begin{bmatrix} x & 0 & 0 \end{bmatrix}

C_2 \begin{bmatrix} x & x & x \end{bmatrix} = \begin{bmatrix} x & 0 & 0 \end{bmatrix} = \begin{bmatrix} x & 0 & 0 \end{bmatrix} = \begin{bmatrix} x & 0 & 0 \end{bmatrix}
      S_0, \begin{bmatrix} X & X & X \\ 0 & X & X \\ 0 & X & X \end{bmatrix} Q_2 = \begin{bmatrix} X & X & 0 \\ 0 & X & X \\ 0 & X & X \end{bmatrix}
     Again, left multiplication of some Householder reflectors Q3 makes

\begin{array}{ccc}
\mathbf{Q}_{3} \begin{bmatrix} \mathbf{X} & \mathbf{X} & \mathbf{0} \\ \mathbf{0} & \mathbf{X} & \mathbf{X} \\ \mathbf{0} & \mathbf{X} & \mathbf{X} \end{bmatrix} = \begin{bmatrix} \mathbf{X} & \mathbf{X} & \mathbf{0} \\ \mathbf{0} & \mathbf{X} & \mathbf{X} \\ \mathbf{0} & \mathbf{0} & \mathbf{X} \end{bmatrix}

But, notice that it can't be obtained only by (i) "generally"
Consider A = \begin{bmatrix} b & b & b \end{bmatrix} for arbitrary a, b, c where at least one of a, b, c is nonzero. Fix any unit vector (x \neq 0)
                                                                                                                                                                                                                                                                                                                              4.
                                                                                                                                                                                                                                                                                         (8+0)
To make the right upper entry to 0, we need Q = I_3 - 2gg \times let \begin{bmatrix} V_{11} & V_{12} & V_{13} \\ V_{21} & V_{22} & V_{23} \\ V_{31} & V_{32} & V_{33} \end{bmatrix} (it can't be \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}, or \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} for a \neq 0)
                                                                                                                                                                                                                                                                                            r) so do
(it can't be [00], or [00] for a = 0)
                                                                                                                                                                                                                                                                                                 V12, V22, V32 &
                                                                                                                                                                             one of them must g_1^2 + g_2^2 + g_3^2 = |
                                                                                                                                                                                                                                                                                                V13, V23, V33.
 Then, we can see that left multiplication of these Q is the row operation (*const, add/sub between rows)
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=> applying 0 again, it is easy to show	that is again the form of b' b' b' b'.
So, the form [* * *] of A must	be [0 0 0]
LööXJ	
But, as Q invertible, rank (Q A) = r	
Thus, again, at least one of a',b',	c' is nonzero.
is implies inductively we can't ge by (i).	t rid of this nonzero rows, so A can't be [XX0]
It is much straightforward if Q is	Givens rotation. As it is rotation, Q is the form of
	with a24b2=1 For A-[NNX] QIA=[X. N]
	with $a^2+b^2=1$. For $A = \begin{bmatrix} x & y & y \\ y & y & y \end{bmatrix}$, $Q_1A = \begin{bmatrix} x & y & y \\ Ay-bz & ay-bz & ay-bz \end{bmatrix}$ it can't be $a=b=0$. $Q_2A = \cdots$, $Q_3A = \cdots$
let Q ₁ Q ₂ .	it can't be a=b=0. QA- Lbytaz bytaz bytaz
	(it is simple calculation & shows the same
So, again, left multiplication of each Qi	is the row operation (*const, add/sub between rows) results)
(b) (ii)	
From (a), $\begin{bmatrix} x & x & 0 \\ 0 & x & x \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} x \\ 0 & 0 \end{bmatrix}$	$\begin{bmatrix} x & 0 \\ 0 & x \end{bmatrix}$ can be obtained (so, left \rightarrow right \rightarrow left \rightarrow right)
Note that [0 0] = [I,	for $v = \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}$ $\Rightarrow \frac{vv^*}{v^*v} = \begin{bmatrix} 1/2 & -1/2 \\ -1/2 & 1/2 \end{bmatrix}$
so Householder reflector,	J
For same reason with (n), it can't	be obtained by just left multiplications for arbitrary 3x3 matrix
(c) (iii)	
$\det \left(\left[\begin{smallmatrix} X & X & 0 \\ 0 & 0 & X \end{smallmatrix} \right] \right) = 0 \text{ clearly.}$	
Spse a nonsingular 3x3 matrix A is	given and for appropriate Qj's,
$Q_k \cdots Q_i \wedge Q_i' \cdots Q_i = \begin{bmatrix} x & y & y \\ y & 0 & x \end{bmatrix}$. The	n det $(QAQ') = 0$
å å'	det(Q) det(Q') det(A).
Since $ \det(Q) = 1$ for unitary matrix	Q, det (A) must be 0 which contradicts to nonsingular.
So, it can't be obtained by any see o	
20711 car (oc opining by any set o	f multiplications by Qja
Solution.	(b) Suppose that structure (b) is obtained from the matrix whose entries are all 1 by
(a) Note that the first and last rows are orthogonal. Since the l	left multiplication of just left multiplication. Since all columns of (b) should be the same, (b) is the zero matrix.
	ring right multiplica- rank. Therefore, (b) cannot be obtained from general matrices by just left multiplication. On the other hand since (b) can be obtained by changing the order of rows.
tion also, (a) can be obtained from general matrix (by singular valu	e decomposition. We

can get a stricter structure).

of the structure (a), (b) can be obtained from general matrix by allowing left and right multiplications.

(c) Since multiplication of unitary matrix preserves the rank of matrix, (c) cannot be obtained from general matrix even if we allow both left and right multiplications of unitary matrices.