$A^{(0)T}A^{(0)} = I = R^{(1)T}R^{(1)} \rightsquigarrow R^{(1)} = I$ Algorithm doesn't proceed. So,  $Q^{(1)} = A^{(0)}$ But notice that Thm 28.4 doesn't break  $A^{(1)} = Q^{(1)}$ since A doesn't satisfy the 1st assumption : λ=±l. 2 (a) From the structure of QR,  $r_{ij} = f_i^* a_j & f_j \in \langle a_i, \dots, a_j \rangle$ .  $\wedge \rangle (x) \leq 0$ ,  $f_i$  is a linear combination of them So, in general, we can assert that  $r_{ij}=0$  when i+2 < j for arbitrary tridiagonal A. (: The structure of tridiagonal A) Denote  $a_i$  be  $i^{th}$  column of A. As we can see, for  $i^{th}$  entries,  $a_i^{th} a_j = 0$  if  $i^{th} 2 < j$ . So,  $a_j \perp \langle a_1, \dots, a_i \rangle$  for  $\forall j > i+2 ( \rightarrow \varphi_i * a_j = 0 \text{ for } \forall j > i+2)$  $(r_{i,j}=0 \text{ for } i\neq j, i\neq j-1, i\neq j-2)$  And also by (\*), Q is an upper Hessenberg ./x's are representing the form of A, and the line represents generally  $\neq 0$  $A^{T} = A \in \mathbb{R}^{m \times m}$ . (b) Note that our discussion in the lecture assumed Now, consider RQ. We have to show it is tridiagonal. Notice that  $RQ = Q^TQRQ = Q^TAQ$ . As A is symmetric, so does the similar matrix RQ. Claim: RQ is upper-Hessenberg (Then, it is automatically tridiagonal by symmetry) pf) Let's consider (RQ); j = \( \sum\_{k=1} \mathbb{r}\_{i,k} \beta\_{k,j} \) with arbitrary i&j in 1,2,..., m where i>j+1. (If it is 0, done) By (a),  $r_{i,k} = 0$  for  $\forall k > i+2$ . & i > k  $\Rightarrow$   $(RQ)_{i,j} = (r_{i,i}) f_{i,j} + (r_{i,i+1}) f_{i+1,j} + (r_{i,i+2}) f_{i+2,j}$ And, by (a) Q is upper-Hessenberg,  $q_{l,k}=0$  for  $\forall l>k+1$ . So  $q_{i,j}=q_{i+1,j}=q_{i+2,j}=0$  as i>j+1. ..(RQ)¿,j = 0 for Vi>j+1 (c) Consider Householder reflect. At each ith column, we don't have to consider aitz, i ~am, i So, we can consider only one below the diagonal, azz, i. Then, Householder reflector can be reduced to 2x2 in our algorithm: O(1) flops clearly. (as x, e1 are 2x1 vectors?) for k=1 to m , 2X1 x = Ak:kH,k  $V_{k} = \operatorname{sign}(x_{1}) \|x\|_{2} e_{1} + x$ It was the dominant part in the original algorithm  $(O(m^2))$ but it be comes O(1)?  $V_{K} = V_{K} / ||V_{K}||_{2}$ Ak:k+1, k: k+1 = Ak:k+1, k: k+1 - 20k (Vk\*Ak:k+1, k: k+1) ~ 2x2 matrices operation So,  $O(m^3)$  (original)  $\longrightarrow O(m)$ : reduced dramatically.

This argument can be applied to Givens rotation, too. In QR Factorization with Givens rotation, it is needed to calculate sin & cos of  $a_{i,i}$  &  $a_{i+1,i} \sim a_{m,i}$  and multiply matrixically to A at each ith step. But, as A is tridiagonal, we can calculate only sin & cos for  $a_{i,i}$  &  $a_{i+1,i}$ . (Notice that it takes And, in terms of matrix multiplication, there only O(1) operands in A at each step  $\sum_{x \neq x} \frac{5}{x \times x} \sum_{x \neq x} \frac{5}{x \times x} \sum_{x \neq x} \frac{5}{x \times x} \sum_{x \neq x} \sum_{x \neq x} \frac{5}{x \times x} \sum_{x \neq x} \sum_{x \neq x} \frac{5}{x \times x} \sum_{x \neq$ 

