

MC14194B

4-Bit Bidirectional Universal Shift Register

The MC14194B is a 4-bit static shift register capable of operating in the parallel load, serial shift left, serial shift right, or hold mode. The asynchronous Reset input, when at a low level, overrides all other inputs, resets all stages, and forces all outputs low. When Reset is at a logic 1 level, the two mode control inputs, S0 and S1, control the operating mode as shown in the truth table. Both serial and parallel operation are triggered on the positive-going transition of the Clock input. The Parallel Data, Data Shift, and mode control inputs must be stable for the specified setup and hold times before and after the positive-going Clock transition.

- Synchronous Right/Left Serial Operation
- Synchronous Parallel Load
- Asynchronous Hold (Do Nothing) Mode
- Functional Pin for Pin Equivalent of LS194

MAXIMUM RATINGS* (Voltages Referenced to V_{SS})

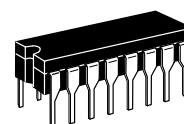
Symbol	Parameter	Value	Unit
V _{DD}	DC Supply Voltage	− 0.5 to + 18.0	V
V _{in} , V _{out}	Input or Output Voltage (DC or Transient)	− 0.5 to V _{DD} + 0.5	V
I _{in} , I _{out}	Input or Output Current (DC or Transient), per Pin	± 10	mA
P _D	Power Dissipation, per Package†	500	mW
T _{stg}	Storage Temperature	− 65 to + 150	°C
T _L	Lead Temperature (8-Second Soldering)	260	°C

* Maximum Ratings are those values beyond which damage to the device may occur.

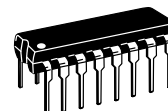
† Temperature Derating:

Plastic "P and D/DW" Packages: − 7.0 mW/°C From 65°C To 125°C

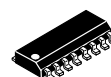
Ceramic "L" Packages: − 12 mW/°C From 100°C To 125°C



L SUFFIX
CERAMIC
CASE 620



P SUFFIX
PLASTIC
CASE 648



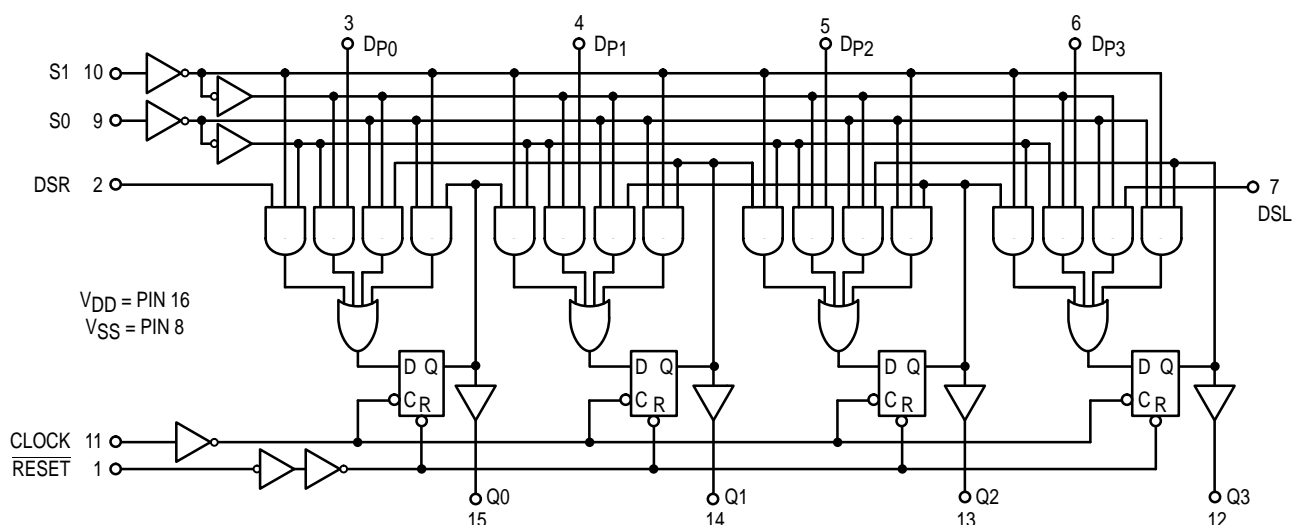
D SUFFIX
SOIC
CASE 751B

ORDERING INFORMATION

MC14XXXBCP	Plastic
MC14XXXBCL	Ceramic
MC14XXXBD	SOIC

T_A = − 55° to 125°C for all packages.

LOGIC DIAGRAM



ELECTRICAL CHARACTERISTICS (Voltages Referenced to V_{SS})

Characteristic	Symbol	V_{DD} Vdc	– 55°C		25°C			125°C		Unit
			Min	Max	Min	Typ #	Max	Min	Max	
Output Voltage $V_{in} = V_{DD}$ or 0	VOL	5.0	—	0.05	—	0	0.05	—	0.05	Vdc
		10	—	0.05	—	0	0.05	—	0.05	
		15	—	0.05	—	0	0.05	—	0.05	
	VOH	5.0	4.95	—	4.95	5.0	—	4.95	—	Vdc
		10	9.95	—	9.95	10	—	9.95	—	
		15	14.95	—	14.95	15	—	14.95	—	
Input Voltage ($V_O = 4.5$ or 0.5 Vdc) ($V_O = 9.0$ or 1.0 Vdc) ($V_O = 13.5$ or 1.5 Vdc)	VIL	5.0	—	1.5	—	2.25	1.5	—	1.5	Vdc
		10	—	3.0	—	4.50	3.0	—	3.0	
		15	—	4.0	—	6.75	4.0	—	4.0	
	VIH	5.0	3.5	—	3.5	2.75	—	3.5	—	Vdc
		10	7.0	—	7.0	5.50	—	7.0	—	
		15	11	—	11	8.25	—	11	—	
Output Drive Current ($V_{OH} = 2.5$ Vdc) ($V_{OH} = 4.6$ Vdc) ($V_{OH} = 9.5$ Vdc) ($V_{OH} = 13.5$ Vdc)	Source IOH	5.0	– 3.0	—	– 2.4	– 4.2	—	– 1.7	—	mAdc
		5.0	– 0.64	—	– 0.51	– 0.88	—	– 0.36	—	
		10	– 1.6	—	– 1.3	– 2.25	—	– 0.9	—	
		15	– 4.2	—	– 3.4	– 8.8	—	– 2.4	—	
	Sink IOL	5.0	0.64	—	0.51	0.88	—	0.36	—	mAdc
		10	1.6	—	1.3	2.25	—	0.9	—	
		15	4.2	—	3.4	8.8	—	2.4	—	
Input Current	Iin	15	—	± 0.1	—	± 0.00001	± 0.1	—	± 1.0	µAdc
Input Capacitance ($V_{in} = 0$)	Cin	—	—	—	—	5.0	7.5	—	—	pF
Quiescent Current (Per Package)	IDD	5.0	—	5.0	—	0.005	5.0	—	150	µAdc
		10	—	10	—	0.010	10	—	300	
		15	—	20	—	0.015	20	—	600	
Total Supply Current**† (Dynamic plus Quiescent, Per Package) ($C_L = 50$ pF on all outputs, all buffers switching)	IT	5.0 10 15	$I_T = (0.95 \mu A/kHz) f + I_{DD}$ $I_T = (1.90 \mu A/kHz) f + I_{DD}$ $I_T = (2.90 \mu A/kHz) f + I_{DD}$							µAdc

#Data labelled "Typ" is not to be used for design purposes but is intended as an indication of the IC's potential performance.

**The formulas given are for the typical characteristics only at 25°C.

†To calculate total supply current at loads other than 50 pF:

$$I_T(C_L) = I_T(50 \text{ pF}) + (C_L - 50) V_{fk}$$

where: I_T is in µA (per package), C_L in pF, $V = (V_{DD} - V_{SS})$ in volts, f in kHz is input frequency, and $k = 0.002$.

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation, V_{in} and V_{out} should be constrained to the range $V_{SS} \leq (V_{in} \text{ or } V_{out}) \leq V_{DD}$. Unused inputs must always be tied to an appropriate logic voltage level (e.g., either V_{SS} or V_{DD}). Unused outputs must be left open.

PIN ASSIGNMENT

\bar{R}	1 ●	16	V_{DD}
DSR	2	15	Q0
Dp0	3	14	Q1
Dp1	4	13	Q2
Dp2	5	12	Q3
Dp3	6	11	C
DSL	7	10	S1
V_{SS}	8	9	S0

TRUTH TABLE

Operating Mode	Inputs (Reset = 1)					Outputs (@ t_{n+1})			
	S1	S0	DSR	DSL	Dp0-3	Q0	Q1	Q2	Q3
Hold	0	0	X	X	X	Q0	Q1	Q2	Q3
Shift Left	1	0	X	0	X	Q1	Q2	Q3	0
	1	0	X	1	X	Q1	Q2	Q3	1
Shift Right	0	1	0	X	X	0	Q0	Q1	Q2
	0	1	1	X	X	1	Q0	Q1	Q2
Parallel	1	1	X	X	0	0	0	0	0
	1	1	X	X	1	1	1	1	1

X = Don't Care

t_{n+1} = State after the next positive-going transition of the clock.

SWITCHING CHARACTERISTICS* ($C_L = 50$ pF, $T_A = 25^\circ\text{C}$)

Characteristic	Symbol	V _{DD} V _{dc}	Min	Typ #	Max	Unit
Output Rise and Fall Time t_{TLH} , $t_{THL} = (1.35 \text{ ns/pF}) C_L + 32 \text{ ns}$ t_{TLH} , $t_{THL} = (0.6 \text{ ns/pF}) C_L + 20 \text{ ns}$ t_{TLH} , $t_{THL} = (0.4 \text{ ns/pF}) C_L + 20 \text{ ns}$	t_{TLH} , t_{THL}	5.0 10 15	— — —	100 50 40	200 100 80	ns
Propagation Delay Time Clock to Q t_{PLH} , $t_{PHL} = (0.9 \text{ ns/pF}) C_L + 230 \text{ ns}$ t_{PLH} , $t_{PHL} = (0.36 \text{ ns/pF}) C_L + 92 \text{ ns}$ t_{PLH} , $t_{PHL} = (0.26 \text{ ns/pF}) C_L + 72 \text{ ns}$	t_{PLH} , t_{PHL}	5.0 10 15	— — —	275 110 85	550 220 170	ns
Reset to Q $t_{PHL} = (0.9 \text{ ns/pF}) C_L + 305 \text{ ns}$ $t_{PHL} = (0.36 \text{ ns/pF}) C_L + 122 \text{ ns}$ $t_{PHL} = (0.26 \text{ ns/pF}) C_L + 97 \text{ ns}$	t_{PHL}	5.0 10 15	— — —	350 140 110	700 280 220	ns
Clock Pulse Width	t_{WH}	5.0 10 15	280 110 85	140 55 40	— — —	ns
Reset Pulse Width	t_{WH}	5.0 10 15	180 70 50	90 35 26	— — —	ns
Clock Pulse Frequency (Shift Right or Left Mode)	f_{cl}	5.0 10 15	— — —	3.6 9.0 12	1.8 4.5 6.0	MHz
Clock Pulse Rise and Fall Time	t_{TLH} , t_{THL}	5.0 10 15	— — —	— — —	15 5 4	μs
Setup Time Data to Clock	t_{su}	5.0 10 15	10 20 40	– 8.0 0 9.0	— — —	ns
Mode Control (S) to Clock		5.0 10 15	200 75 55	100 36 27	— — —	ns
Hold Time Data to Clock		5.0 10 15	180 50 35	90 25 10	— — —	ns
Mode Control (S) to Clock		5.0 10 15	0 0 0	– 40 – 27 – 20	— — —	ns
Reset Removal Time		5.0 10 15	300 110 80	150 55 40	— — —	ns

* The formulas given are for the typical characteristics only at 25°C .

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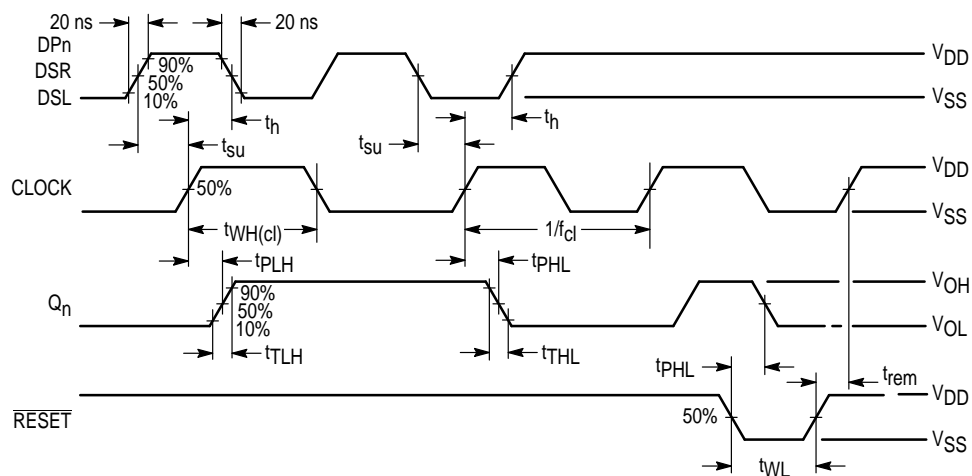
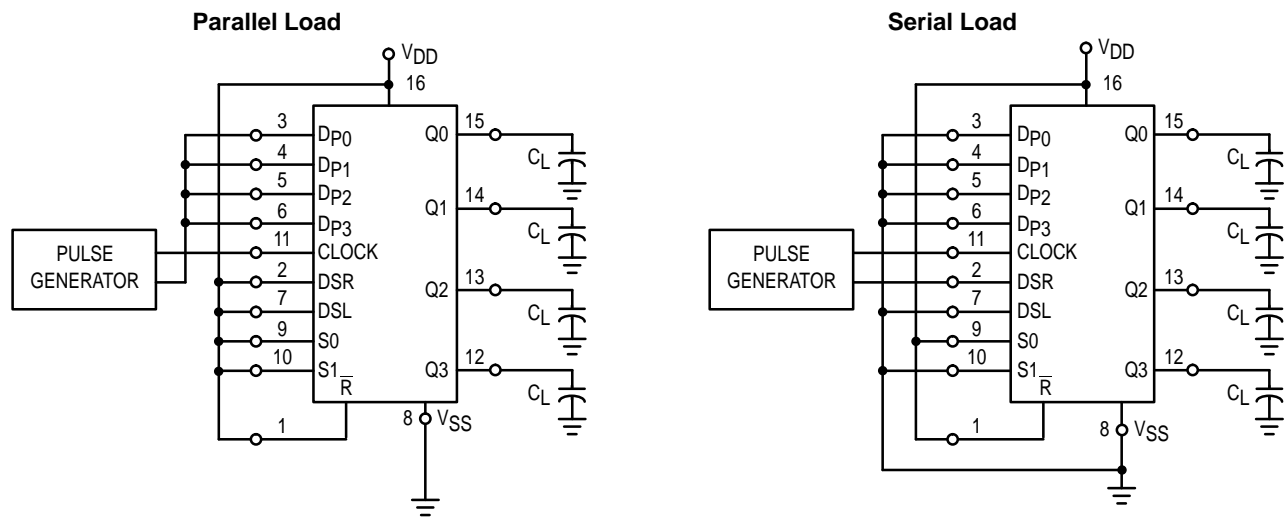


Figure 1. Switching Time Test Circuits and Waveforms

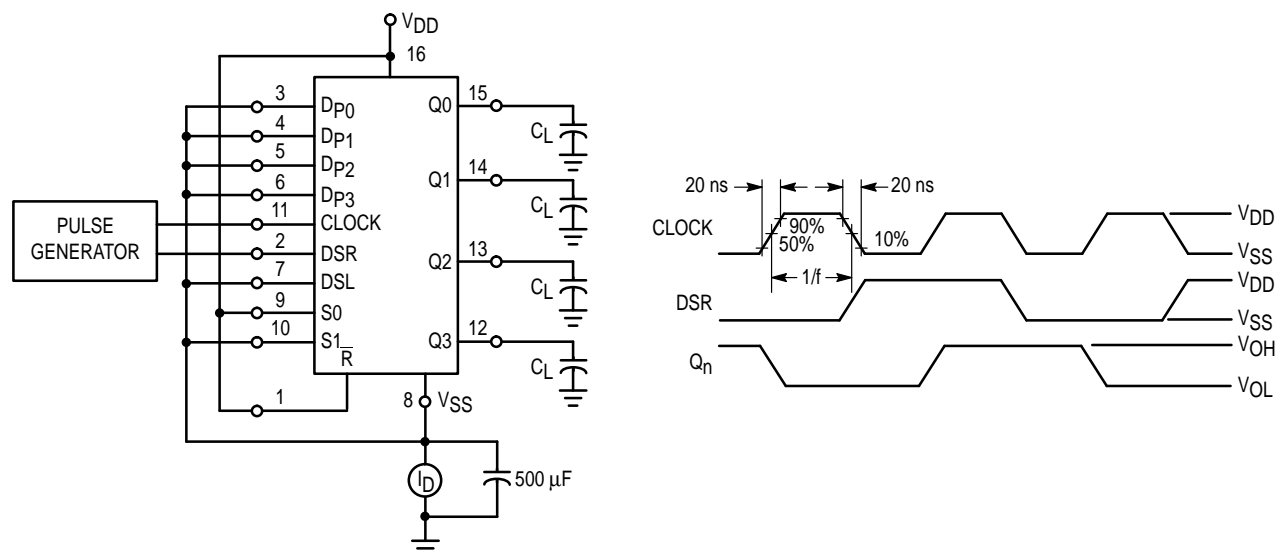
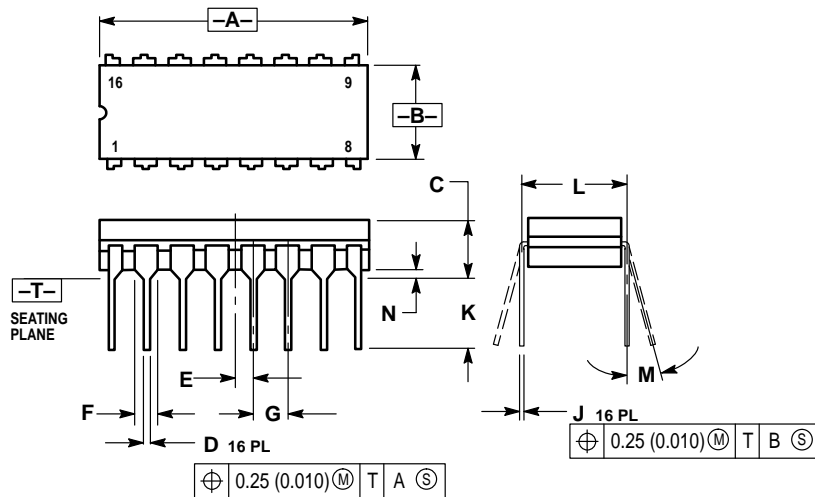


Figure 2. Dynamic Power Dissipation Test Circuit and Waveforms

OUTLINE DIMENSIONS

L SUFFIX CERAMIC DIP PACKAGE CASE 620-10 ISSUE V

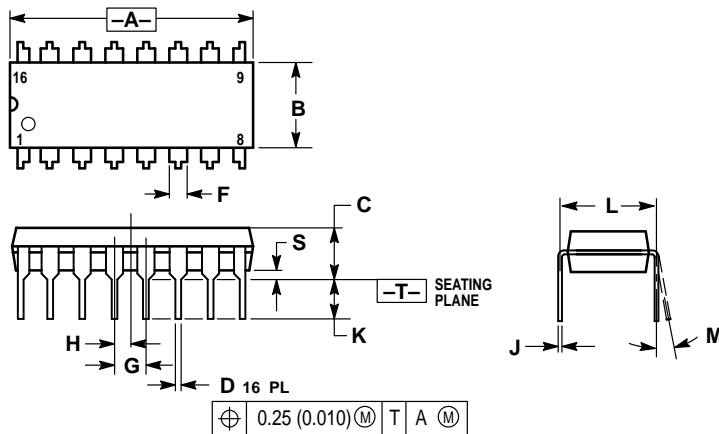


NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
4. DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC BODY.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.750	0.785	19.05	19.93
B	0.240	0.295	6.10	7.49
C	—	0.200	—	5.08
D	0.015	0.020	0.39	0.50
E	0.050 BSC		1.27 BSC	
F	0.055	0.065	1.40	1.65
G	0.100 BSC		2.54 BSC	
H	0.008	0.015	0.21	0.38
K	0.125	0.170	3.18	4.31
L	0.300 BSC		7.62 BSC	
M	0°	15°	0°	15°
N	0.020	0.040	0.51	1.01

P SUFFIX PLASTIC DIP PACKAGE CASE 648-08 ISSUE R



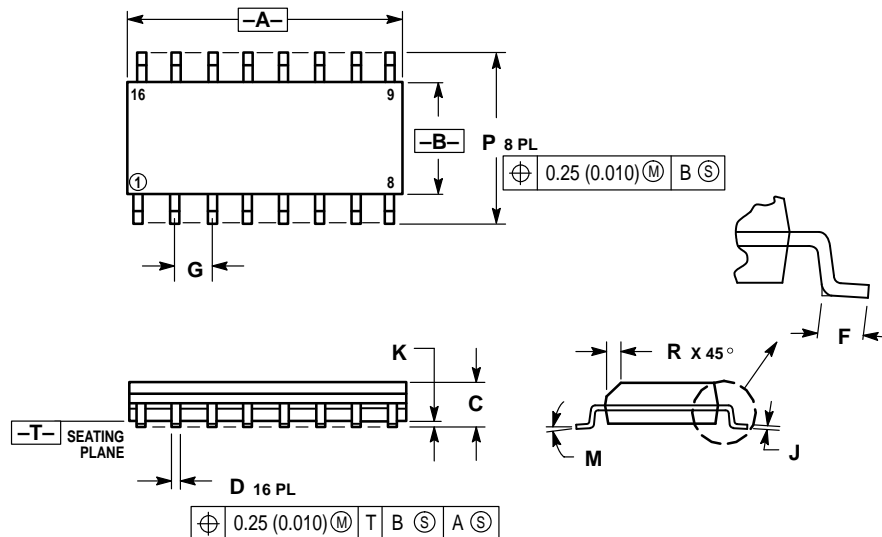
NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.740	0.770	18.80	19.55
B	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.70	1.02	1.77
G	0.100 BSC		2.54 BSC	
H	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
M	0°	10°	0°	10°
S	0.020	0.040	0.51	1.01

OUTLINE DIMENSIONS


D SUFFIX PLASTIC SOIC PACKAGE CASE 751B-05 ISSUE J



NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	9.80	10.00	0.386	0.393
B	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27 BSC		0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
P	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

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MC14194B/D



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