MC74HC194

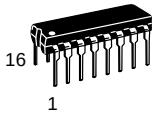
4-Bit Bidirectional Universal Shift Register

High–Performance Silicon–Gate CMOS

The MC74HC194 is identical in pinout to the LS194 and the MC14194B metal gate CMOS device. The device inputs are compatible with standard CMOS outputs; with pull–up resistors, they are compatible with LSTTL outputs.

This static shift register features parallel load, serial load (shift right and shift left), hold, and reset modes of operation. These modes are tabulated in the Function Table, and further explanation can be found in the Pin Description section.

- Output Drive Capability: 10 LSTTL Loads
- Outputs Directly Interface to CMOS, NMOS, and TTL
- Operating Voltage Range: 2 to 6 V
- Low Input Current: 1 μA
- High Noise Immunity Characteristic of CMOS Devices
- In Compliance with the Requirements Defined by JEDEC Standard No. 7A
- Chip Complexity 164 FETs or 41 Equivalent Gates

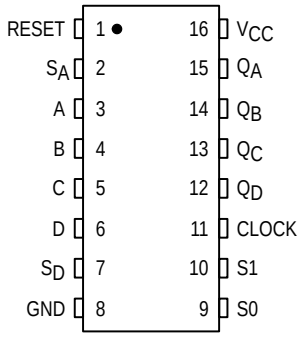


N SUFFIX
PLASTIC PACKAGE
CASE 648–08

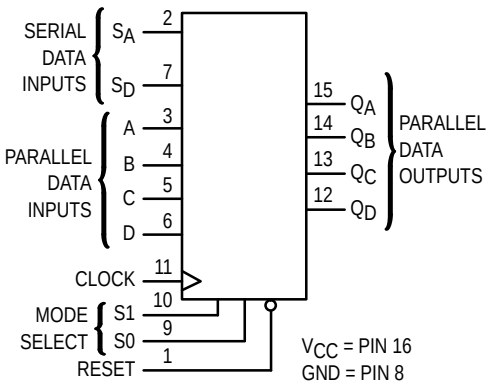
ORDERING INFORMATION

MC74HCXXXN Plastic

PIN ASSIGNMENT



LOGIC DIAGRAM



FUNCTION TABLE

Inputs										Outputs				Operating Mode
	Mode Select			Serial Data		Parallel Data								
Reset	S1	S0	Clock	S_D	S_A	A	B	C	D	Q_A	Q_B	Q_C	Q_D	
L	X	X	X	X	X	X	X	X	X	L	L	L	L	Reset
H	H	H	↗	X	X	a	b	c	d	a	b	c	d	Parallel Load
H	L	H	↗	X	H	X	X	X	X	H	Q_{An}	Q_{Bn}	Q_{Cn}	Shift Right
H	L	H	↗	X	L	X	X	X	X	L	Q_{An}	Q_{Bn}	Q_{Cn}	
H	H	L	↗	H	X	X	X	X	X	Q_{Bn}	Q_{Cn}	Q_{Dn}	H	Shift Left
H	H	L	↗	L	X	X	X	X	X	Q_{Bn}	Q_{Cn}	Q_{Dn}	L	
H	L	L	X	X	X	X	X	X	X	No Change				Hold
H	X	X	L	X	X	X	X	X	X	No Change				
H	X	X	H	X	X	X	X	X	X	No Change				

H = high level (steady state)
L = low level (steady state)
X = don't care
↗ = transition from low to high level.

a, b, c, d = the level of steady–state input at inputs A, B, C, or D, respectively.
Q_{An}, Q_{Bn}, Q_{Cn}, Q_{Dn} = the level of Q_A, Q_B, Q_C, or Q_D, respectively, before the most recent ↗ transition of the clock.

MAXIMUM RATINGS*

Symbol	Parameter	Value	Unit
V_{CC}	DC Supply Voltage (Referenced to GND)	– 0.5 to + 7.0	V
V_{in}	DC Input Voltage (Referenced to GND)	– 1.5 to V_{CC} + 1.5	V
V_{out}	DC Output Voltage (Referenced to GND)	– 0.5 to V_{CC} + 0.5	V
I_{in}	DC Input Current, per Pin	± 20	mA
I_{out}	DC Output Current, per Pin	± 25	mA
I_{CC}	DC Supply Current, V_{CC} and GND Pins	± 50	mA
P_D	Power Dissipation in Still Air Plastic DIP†	750	mW
T_{stg}	Storage Temperature	– 65 to + 150	°C
T_L	Lead Temperature, 1 mm from Case for 10 Seconds (Plastic DIP)	260	°C

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high–impedance circuit. For proper operation, V_{in} and V_{out} should be constrained to the range GND ≤ (V_{in} or V_{out}) ≤ V_{CC}.

Unused inputs must always be tied to an appropriate logic voltage level (e.g., either GND or V_{CC}). Unused outputs must be left open.

* Maximum Ratings are those values beyond which damage to the device may occur.
Functional operation should be restricted to the Recommended Operating Conditions.
†Derating — Plastic DIP: – 10 mW/°C from 65° to 125°C
For high frequency or heavy load considerations, see Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

RECOMMENDED OPERATING CONDITIONS

Symbol	Parameter		Min	Max	Unit
V_{CC}	DC Supply Voltage (Referenced to GND)		2.0	6.0	V
V_{in}, V_{out}	DC Input Voltage, Output Voltage (Referenced to GND)		0	V_{CC}	V
T_A	Operating Temperature, All Package Types		– 55	+ 125	°C
t_r, t_f	Input Rise and Fall Time (Figure 1)	V_{CC} = 2.0 V V_{CC} = 4.5 V V_{CC} = 6.0 V	0 0 0	1000 500 400	ns

DC ELECTRICAL CHARACTERISTICS (Voltages Referenced to GND)

Symbol	Parameter	Test Conditions	V_{CC} V	Guaranteed Limit			Unit
				– 55 to 25°C	≤ 85°C	≤ 125°C	
V_{IH}	Minimum High–Level Input Voltage	V_{out} = 0.1 V or V_{CC} – 0.1 V $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	1.5 3.15 4.2	1.5 3.15 4.2	1.5 3.15 4.2	V
V_{IL}	Maximum Low–Level Input Voltage	V_{out} = 0.1 V or V_{CC} – 0.1 V $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	0.3 0.9 1.2	0.3 0.9 1.2	0.3 0.9 1.2	V
V_{OH}	Minimum High–Level Output Voltage	V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	1.9 4.4 5.9	1.9 4.4 5.9	1.9 4.4 5.9	V
		V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 4.0 mA $\|I_{out}\|$ ≤ 5.2 mA	4.5 6.0	3.98 5.48	3.84 5.34	3.70 5.20	
V_{OL}	Maximum Low–Level Output Voltage	V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 20 μA	2.0 4.5 6.0	0.1 0.1 0.1	0.1 0.1 0.1	0.1 0.1 0.1	V
		V_{in} = V_{IH} or V_{IL} $\|I_{out}\|$ ≤ 4.0 mA $\|I_{out}\|$ ≤ 5.2 mA	4.5 6.0	0.26 0.26	0.33 0.33	0.40 0.40	
I_{in}	Maximum Input Leakage Current	V_{in} = V_{CC} or GND	6.0	± 0.1	± 1.0	± 1.0	μA
I_{CC}	Maximum Quiescent Supply Current (per Package)	V_{in} = V_{CC} or GND I_{out} = 0 μA	6.0	8	80	160	μA

NOTE: Information on typical parametric values can be found in Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

AC ELECTRICAL CHARACTERISTICS (C_L = 50 pF, Input $t_r = t_f$ = 6 ns)

Symbol	Parameter	V_{CC} V	Guaranteed Limit			Unit
			– 55 to 25°C	≤ 85°C	≤ 125°C	
f_{max}	Maximum Clock Frequency (50% Duty Cycle) (Figures 1 and 4)	2.0 4.5 6.0	6.0 30 35	4.8 24 28	4.0 20 24	MHz
t_{PLH}, t_{PHL}	Maximum Propagation Delay, Clock to Q (Figures 1 and 4)	2.0 4.5 6.0	145 29 25	180 36 31	220 44 38	ns
t_{PHL}	Maximum Propagation Delay, Reset to Q (Figures 2 and 4)	2.0 4.5 6.0	150 30 26	190 38 33	225 45 38	ns
t_{TLH}, t_{THL}	Maximum Output Transition Time, Any Output (Figures 1 and 4)	2.0 4.5 6.0	75 15 13	95 19 16	110 22 19	ns
C_{in}	Maximum Input Capacitance	—	10	10	10	pF

NOTES:
1. For propagation delays with loads other than 50 pF, see Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).
2. Information on typical parametric values can be found in Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

		Typical @ 25°C, V_{CC} = 5.0 V	
C_{PD}	Power Dissipation Capacitance (Per Package)*	90	pF

* Used to determine the no–load dynamic power consumption: $P_D = C_{PD} V_{CC}^2 f + I_{CC} V_{CC}$. For load considerations, see Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

TIMING REQUIREMENTS (Input $t_r = t_f$ = 6 ns)

Symbol	Parameter	V_{CC} V	Guaranteed Limit			Unit
			– 55 to 25°C	≤ 85°C	≤ 125°C	
t_{su}	Minimum Setup Time, Parallel Data Inputs to Clock (Figure 3)	2.0 4.5 6.0	100 20 17	125 25 21	150 30 26	ns
t_{su}	Minimum Setup Time, S1 or S2 to Clock (Figure 3)	2.0 4.5 6.0	100 20 17	125 25 21	150 30 26	ns
t_{su}	Minimum Setup Time, S_A or S_D to Clock (Figure 3)	2.0 4.5 6.0	100 20 17	125 25 21	150 30 26	ns
t_h	Minimum Hold Time, Clock to any Input (except Reset) (Figure 3)	2.0 4.5 6.0	3 3 3	3 3 3	3 3 3	ns
t_{rec}	Minimum Recovery Time, Reset Inactive to Clock (Figure 2)	2.0 4.5 6.0	5 5 5	5 5 5	5 5 5	ns
t_w	Minimum Pulse Width, Clock (Figure 1)	2.0 4.5 6.0	80 16 14	100 20 17	120 24 20	ns
t_w	Minimum Pulse Width, Reset (Figure 2)	2.0 4.5 6.0	80 16 14	100 20 17	120 24 20	ns
t_r, t_f	Maximum Input Rise and Fall Times (Figure 1)	2.0 4.5 6.0	1000 500 400	1000 500 400	1000 500 400	ns

NOTE: Information on typical parametric values can be found in Chapter 2 of the Motorola High–Speed CMOS Data Book (DL129/D).

PIN DESCRIPTIONS

DATA INPUTS

A, B, C, D (Pins 3, 4, 5, 6)

Parallel data inputs.

S_A (Pin 2)

Serial–data input when using shift–right mode.

S_D (Pin 7)

Serial–data input when using shift–left mode.

OUTPUTS

Q_A, Q_B, Q_C, Q_D (Pins 15, 14, 13, 12)

Parallel data outputs.

CONTROL INPUTS

Clock (Pin 11)

Clock Input. The shift register is completely static, allowing Clock rates down to DC in a continuous or intermittent mode.

Reset (Pin 1)

A low level applied to this pin resets all stages and forces all outputs low.

S0, S1 (Pins 9, 10)

Mode–select inputs. These inputs control the mode of operation as described in the function table and below.

Parallel Load Mode (S1 = H, S0 = H)

Data is loaded into the device with a positive transition of the Clock input.

Shift Right Mode (S1 = L, S0 = H)

With a positive transition of the Clock input, each bit is shifted right (in the direction Q_A toward Q_D) one stage and data on the S_A Serial Data Input is shifted into stage A.

Shift Left Mode (S1 = H, S0 = L)

With a positive transition of the Clock input, each bit is shifted left (in the direction Q_D toward Q_A) one stage and data on the S_D Serial Data Input is shifted into stage D.

Hold Mode (S1 = L, S0 = L)

Outputs are held.

SWITCHING WAVEFORMS

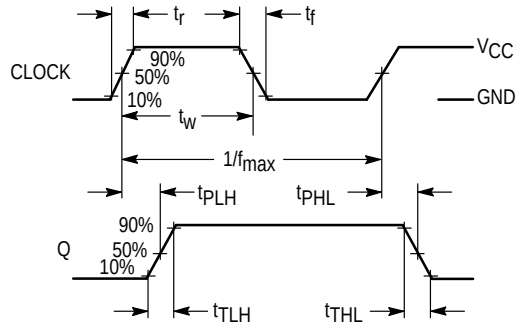


Figure 1.

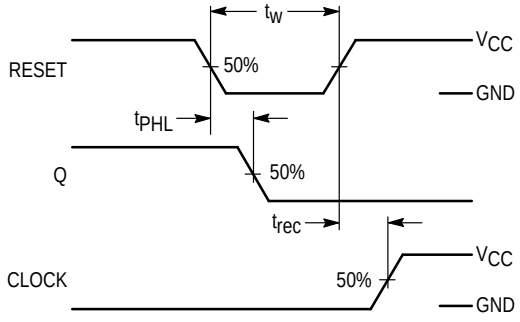


Figure 2.

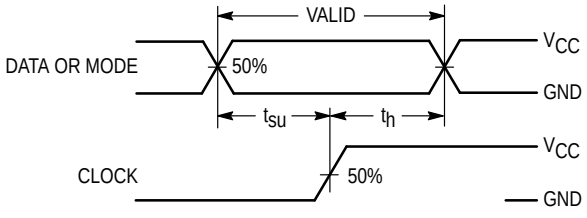
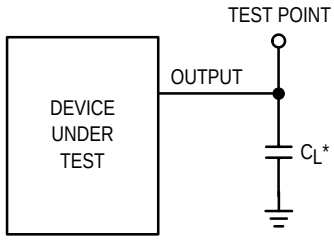


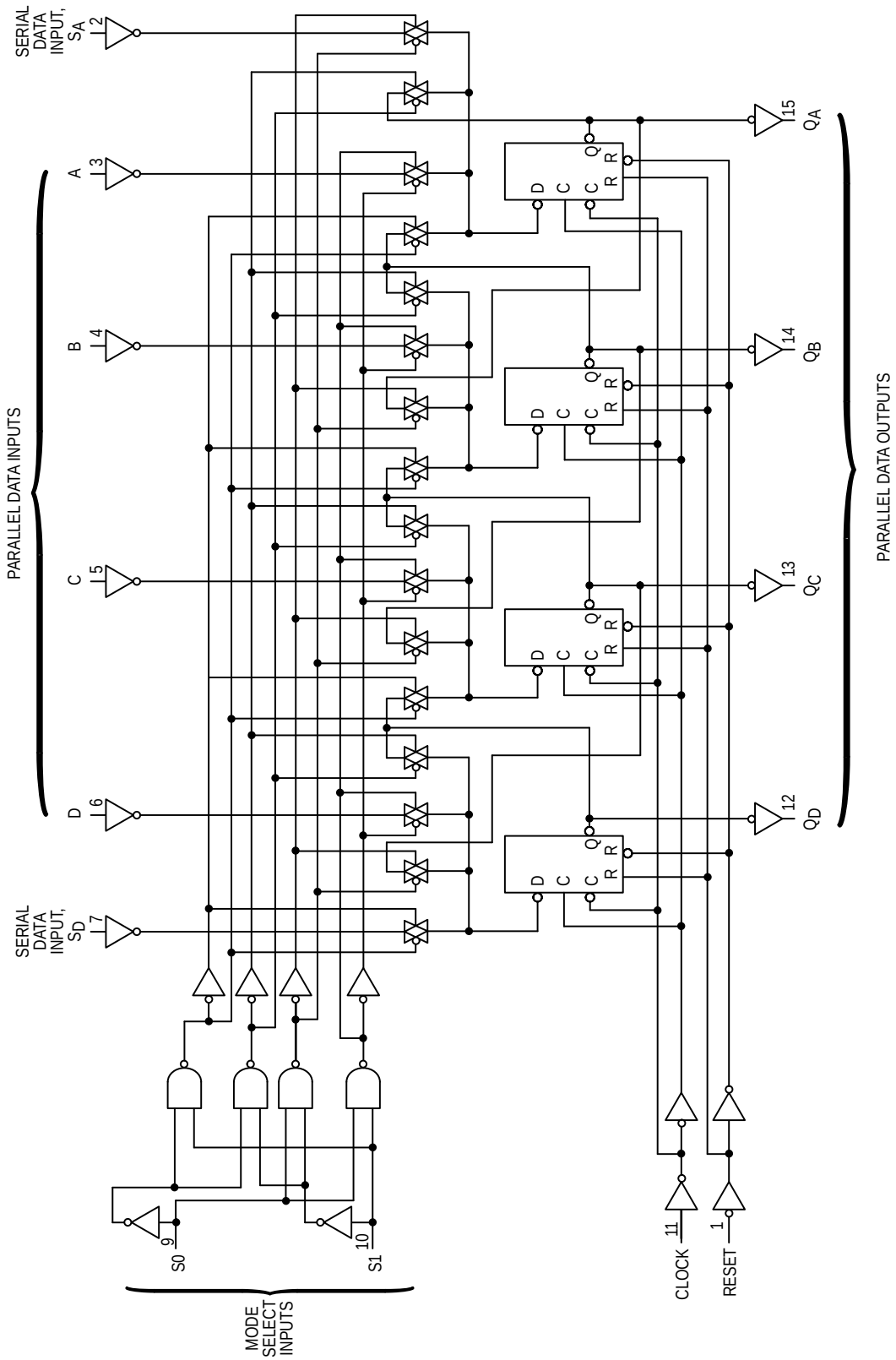
Figure 3.



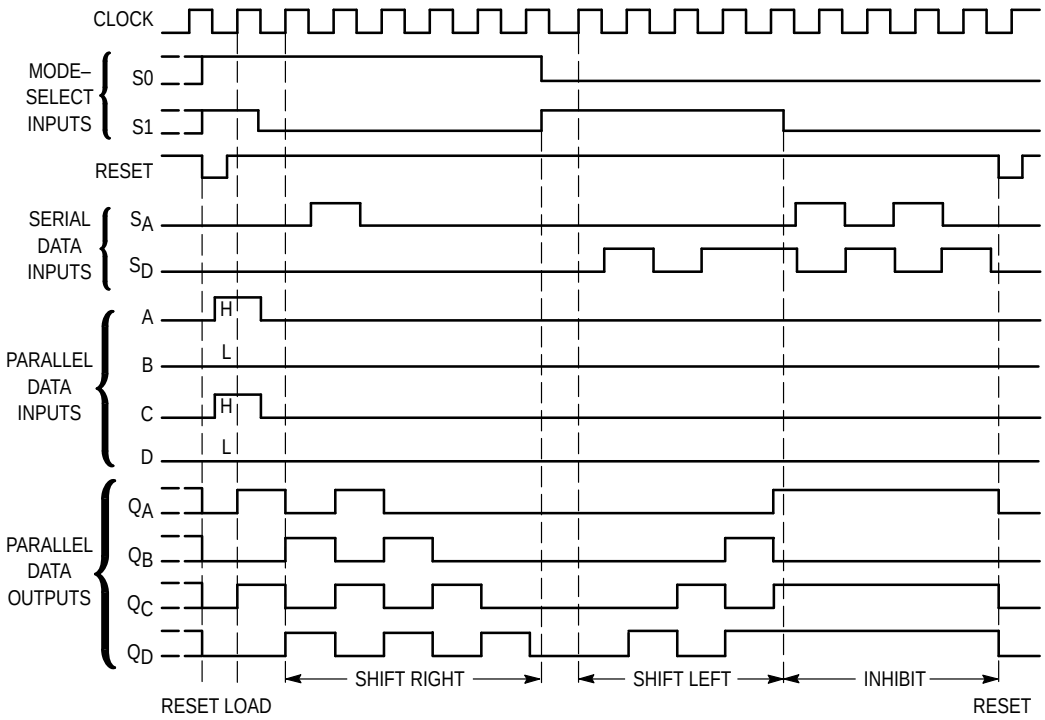
* Includes all probe and jig capacitance

Figure 4. Test Circuit

EXPANDED LOGIC DIAGRAM

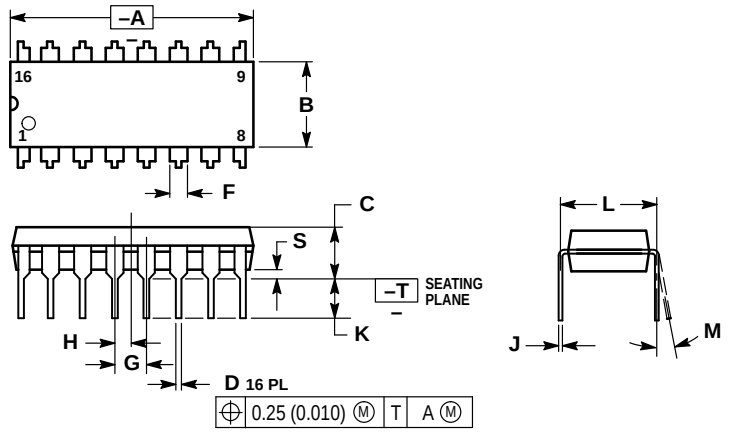


TIMING DIAGRAM



OUTLINE DIMENSIONS

N SUFFIX
PLASTIC PACKAGE
CASE 648–08
ISSUE R



NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

	INCHES		MILLIMETERS	
DIM	MIN	MAX	MIN	MAX
A	0.740	0.770	18.80	19.55
B	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.070	1.02	1.77
G	0.100 BSC		2.54 BSC	
H	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
M	0°	10°	0°	10°
S	0.020	0.040	0.51	1.01

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