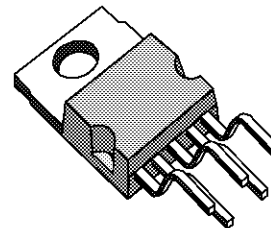


3A POWER OPERATIONAL AMPLIFIER

- OUTPUT CURRENT UP TO 3A
- LARGE COMMON-MODE AND DIFFERENTIAL MODE RANGES
- SOA PROTECTION
- THERMAL PROTECTION
- $\pm 18V$ SUPPLY

DESCRIPTION

The L165 is a monolithic integrated circuit in Pentawatt® package, intended for use as power operational amplifier in a wide range of applications, including servo amplifiers and power supplies. The high gain and high output power capability provide superior performance wherever an operational amplifier/power booster combination is required.



Pentawatt®

ORDERING NUMBER : L165V

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V_s	Supply voltage	± 18	V
V_5, V_4	Upper power transistor V_{CE}	36	V
V_4, V_3	Lower power transistor V_{CE}	36	V
V_i	Input voltage	V_s	
V_j	Differential input voltage	± 15	V
I_o	Peak output current (internally limited)	3.5	A
P_{tot}	Power dissipation at $T_{case} = 90^\circ C$	20	W
T_{stg}, T_j	Storage and junction temperature	-40 to 150	$^\circ C$

APPLICATION CIRCUITS

Figure 1. Gain > 10.

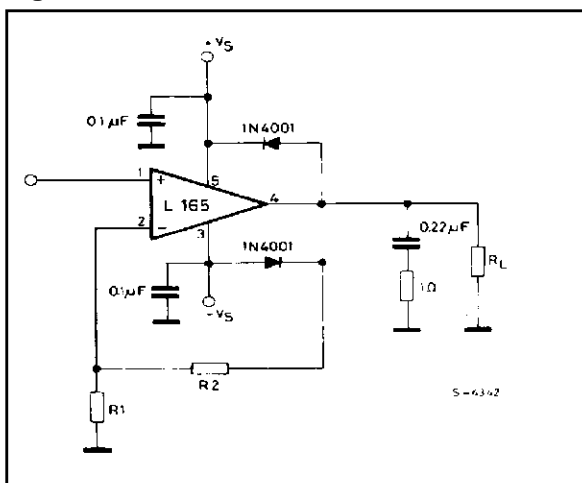
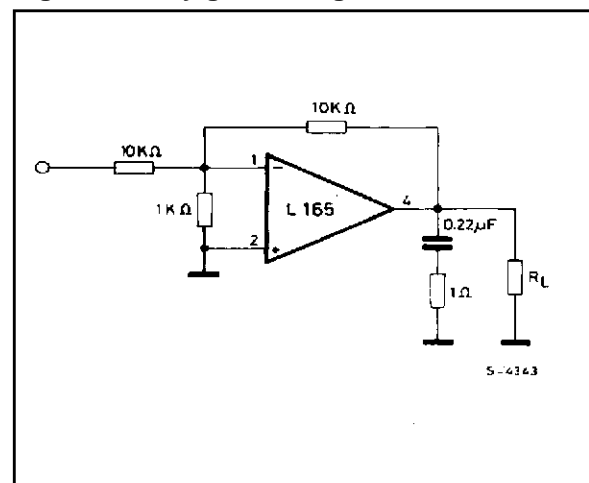
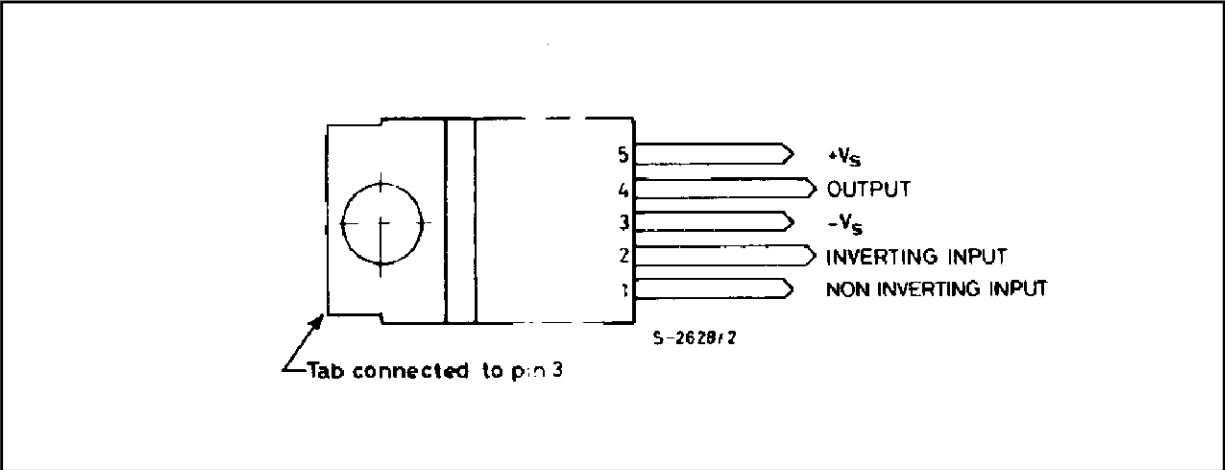


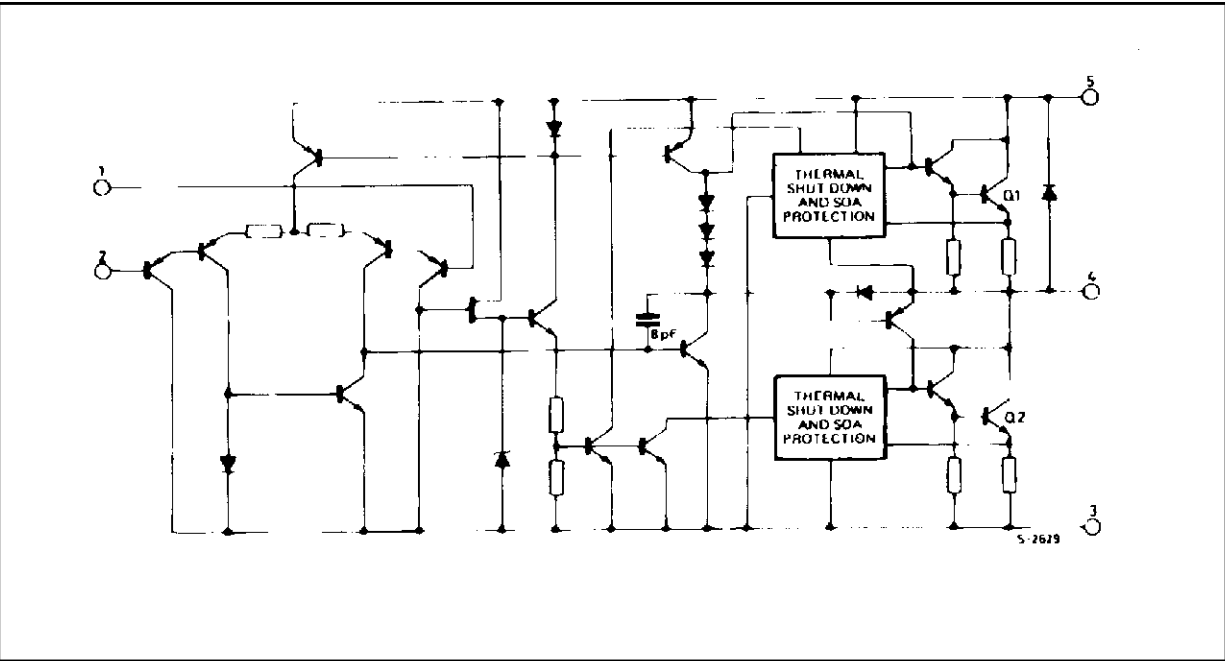
Figure 2. Unity gain configuration.



PIN CONNECTION (top view)



SCHEMATIC DIAGRAM



THERMAL DATA

Symbol	Parameter	Value	Unit
R _{th-j-case}	Thermal resistance junction-case	max 3	°C/W

ELECTRICAL CHARACTERISTICS ($V_s = \pm 15\text{ V}$, $T_j = 25\text{ }^\circ\text{C}$ unless otherwise specified)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Unit
V_s	Supply Voltage		± 6		± 18	V
I_d	Quiescent Drain Current	$V_s = \pm 18\text{ V}$		40	60	mA
I_b	Input Bias Current			0.2	1	μA
V_{os}	Input Offset Voltage			± 2	± 10	mV
I_{os}	Input Offset Current			± 20	± 200	nA
SR	Slew-rate	$G_v = 10$		8		V/ μs
		$G_v = 1\text{ }(^{\circ})$		6		
V_o	Output Voltage Swing	$f = 1\text{ kHz}$ $I_p = 0.3\text{ A}$ $I_p = 3\text{ A}$		27 24		V_{pp}
		$f = 10\text{ kHz}$ $I_p = 0.3\text{ A}$ $I_p = 3\text{ A}$		27 23		V_{PP}
R	Input Resistance (pin 1)	$f = 1\text{ kHz}$	100	500		K Ω
G_v	Voltage Gain (open loop)			80		dB
e_N	Input Noise Voltage	$B = 10\text{ to }10\,000\text{ Hz}$		2		μV
i_N	Input Noise Current			100		pA
CMR	Common-mode Rejection	$R_g \leq 10\text{ K}\Omega$ $G_v = 30\text{ dB}$		70		dB
SVR	Supply Voltage Rejection	$R_g = 22\text{ K}\Omega$ $V_{\text{ripple}} = 0.5\text{ V}_{\text{rms}}$ $f_{\text{ripple}} = 100\text{ Hz}$	$G_v = 10$	60		dB
			dB $G_v = 100$	40		dB
	Efficiency	$f = 1\text{ kHz}$ $R_L = 4\text{ }\Omega$	$I_p = 1.6\text{ A}; P_o = 5\text{ W}$	70		%
			$I_p = 3\text{ A}; P_o = 18\text{ W}$	60		%
T_{sd}	Thermal Shut-down Case Temperature	$P_{\text{tot}} = 12\text{ W}$		110		$^\circ\text{C}$
		$P_{\text{tot}} = 6\text{ W}$		130		

Figure 3. Open loop frequency response.

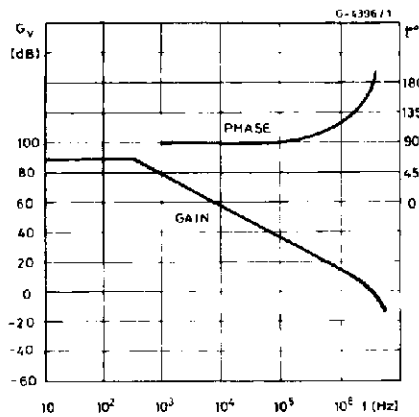


Figure 4. Closed loop frequency response (circuit of figure 2).

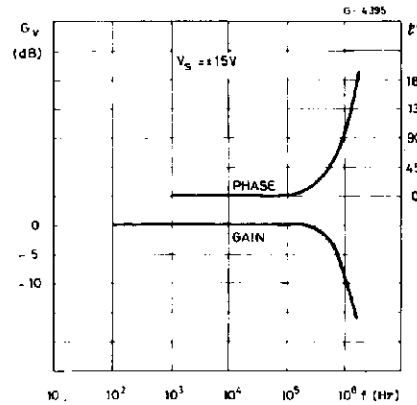


Figure 5. Large signal frequency response.

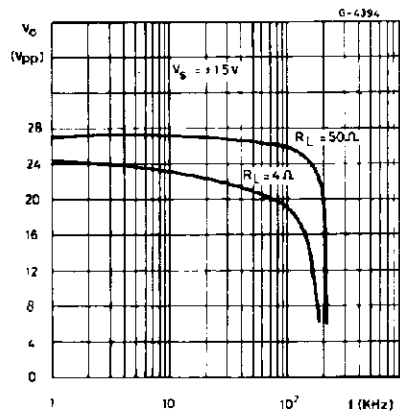


Figure 6. Maximum output current vs. voltage [VCE] across each output transistor.

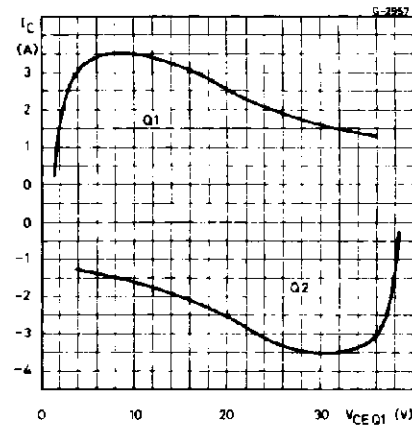


Figure 7. Safe operating area and collector characteristics of the protected power transistor.

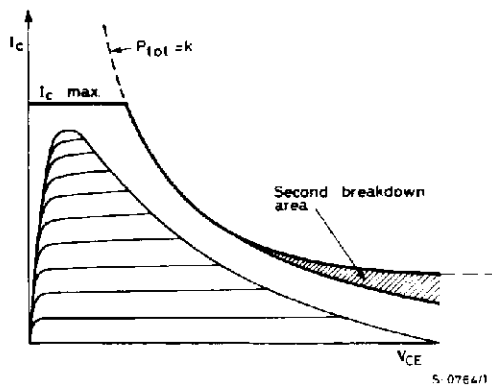


Figure 8. Maximum allowable power dissipation vs. ambient temperature.

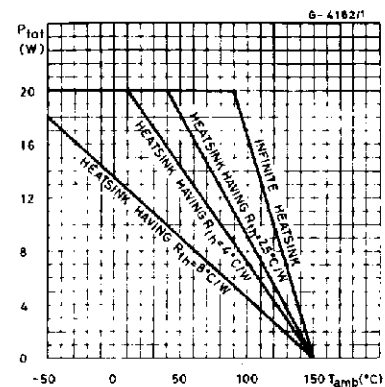


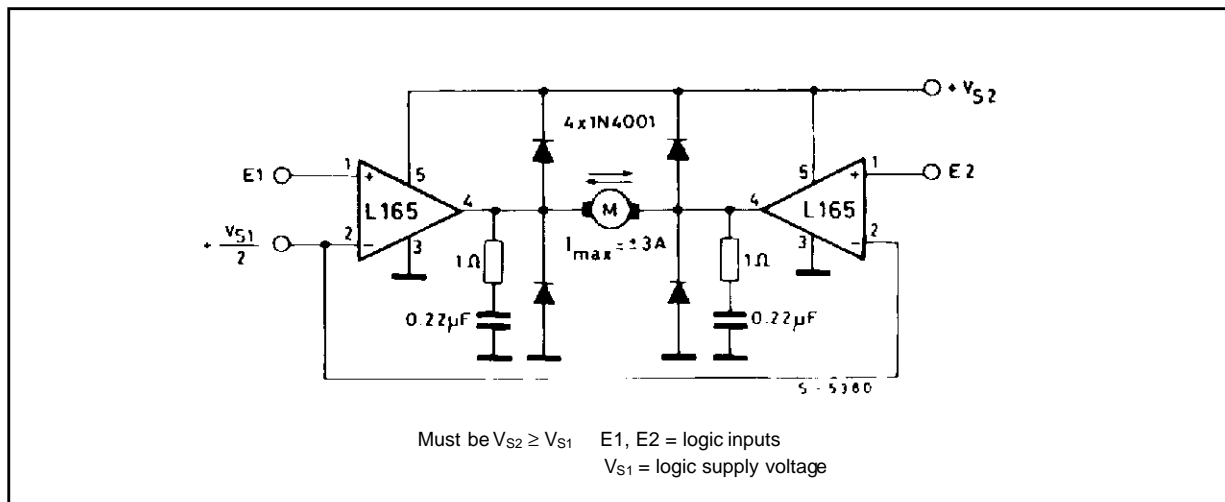
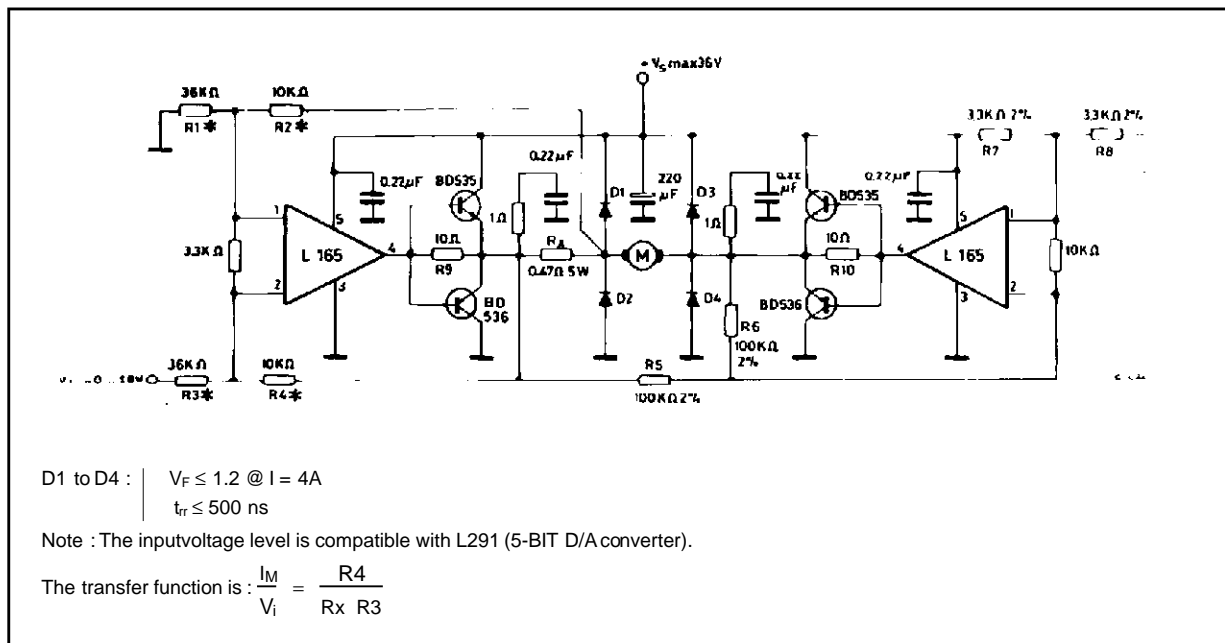
Figure 9. Bidirectional DC motor control with TTL/CMOS/ μ P compatible inputs.Figure 10. Motor current control circuit with external power transistors ($I_{\text{motor}} > 3.5\text{A}$).

Figure 11. High current tracking regulator.

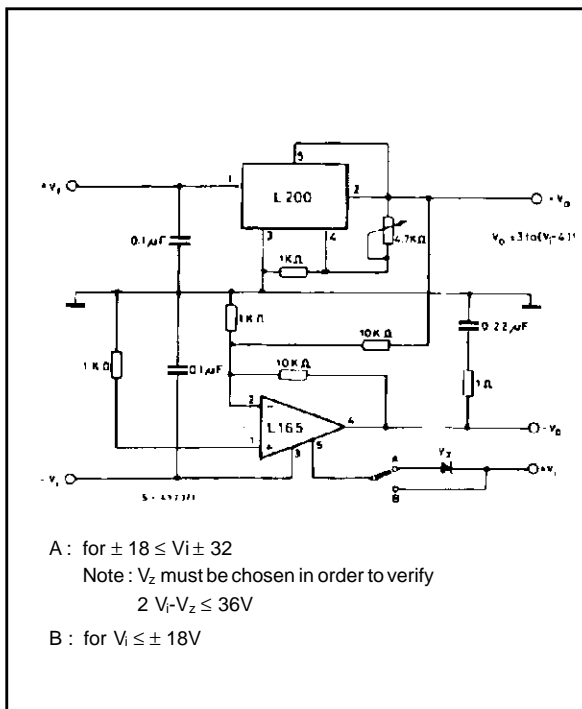


Figure 12. Bidirectional speed control of DC motor (Compensation networks not shown).

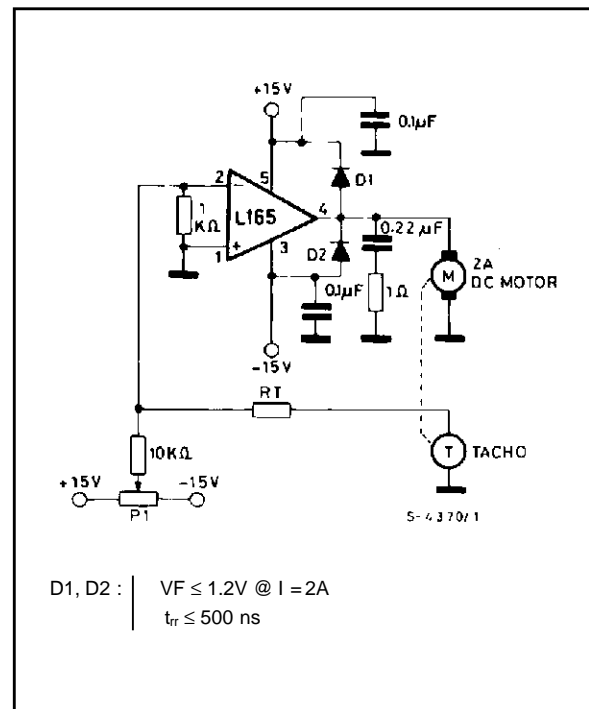


Figure 13. Split power supply.

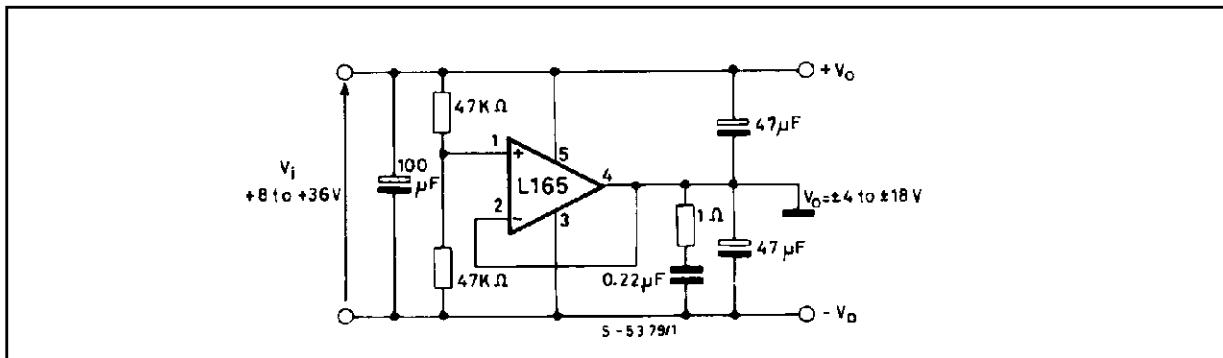
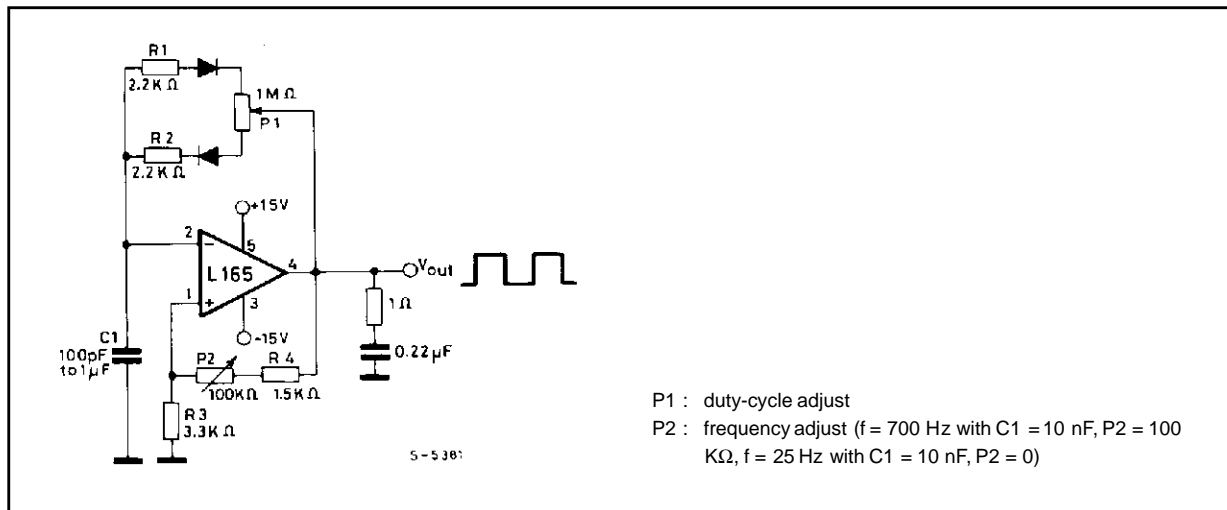


Figure 14. Power squarewave oscillator with independent adjustments for frequency and duty-cycle.



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