DATA STRUCTURES AND ALGORITHMS LECTURE 6

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In Lecture 5...

- Singly Linked List
- Doubly Linked List
- Sorted Lists
- Circular Lists

Today

- XOR lists
- Skip Lists
- Linked lists on array

XOR Linked List

- Doubly linked lists are better than singly linked lists because they offer better complexity for some operations
- Their disadvantage is that they occupy more memory, because you have two links to memorize, instead of just one.
- A memory-efficient solution is to have a XOR Linked List, which is a doubly linked list (we can traverse it in both directions), where every node retains one single link, which is the XOR of the previous and the next node.

XOR Linked List - Example



• How do you traverse such a list?

XOR Linked List - Example



- How do you traverse such a list?
 - We start from the head (but we can have a backward traversal starting from the tail in a similar manner), the node with A
 - \bullet The address from node A is directly the address of node B (NIL XOR B = B)
 - When we have the address of node B, its link is A XOR C. To get the address of node C, we have to XOR B's link with the address of A (it's the previous node we come from): A XOR C XOR A = A XOR A XOR C = NIL XOR C = C



XOR Linked List - Representation

 We need two structures to represent a XOR Linked List: one for a node and one for the list

XORNode:

info: TELem

link: ↑ XORNode

XORList:

head: ↑ XORNode tail: ↑ XORNode

XOR Linked List - Traversal

```
subalgorithm printListForward(xorl) is:
//pre: xorl is a XORList
//post: true (the content of the list was printed)
  prevNode \leftarrow NIL
  currentNode \leftarrow xorl.head
  while currentNode ≠ NIL execute
     print [currentNode].info
     nextNode ← prevNode XOR [currentNode].link
     prevNode \leftarrow currentNode
     currentNode \leftarrow nextNode
  end-while
end-subalgorithm
```

• Complexity: $\Theta(n)$

XOR Linked List - addToBeginning

• How can we add an element to the beginning of the list?

XOR Linked List - addToBeginning

• How can we add an element to the beginning of the list?

```
subalgorithm addToBeginning(xorl, elem) is:
//pre: xorl is a XORList
//post: a node with info elem was added to the beginning of the list
   newNode \leftarrow allocate()
   [newNode].info \leftarrow elem
   [newNode].link \leftarrow xorl.head
   if xorl head = NII then
      xorl head ← newNode
      xorl.tail \leftarrow newNode
   else
      [xorl.head].link \leftarrow [xorl.head].link XOR newNode
      xorl.head \leftarrow newNode
   end-if
end-subalgorithm
```

Complexity:

XOR Linked List - addToBeginning

• How can we add an element to the beginning of the list?

```
subalgorithm addToBeginning(xorl, elem) is:
//pre: xorl is a XORList
//post: a node with info elem was added to the beginning of the list
   newNode \leftarrow allocate()
   [newNode].info \leftarrow elem
   [newNode].link \leftarrow xorl.head
   if xorl head = NII then
      xorl head ← newNode
      xorl.tail \leftarrow newNode
   else
      [xorl.head].link \leftarrow [xorl.head].link XOR newNode
      xorl.head \leftarrow newNode
   end-if
end-subalgorithm
```

• Complexity: $\Theta(1)$

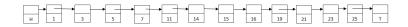
- Assume that we want to memorize a sequence of sorted elements. The elements can be stored in:
 - dynamic array
 - linked list (let's say doubly linked list)
- We know that the most frequently used operation will be the insertion of a new element, so we want to choose a data structure for which insertion has the best complexity. Which one should we choose?

• We can divide the insertion operation into two steps: *finding* where to insert and inserting the elements

- We can divide the insertion operation into two steps: finding where to insert and inserting the elements
 - For a dynamic array finding the position can be optimized (binary search $O(log_2n)$), but the insertion is O(n)
 - For a linked list the insertion is optimal $(\Theta(1))$, but finding where to insert is O(n)

- A skip list is a data structure that allows fast search in an ordered sequence.
- How can we do that?

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- How can we do that?



- Starting from an ordered linked list, we add to every second node another pointer that skips over one element.
- We add to every fourth node another pointer that skips over 3 elements.
- etc.

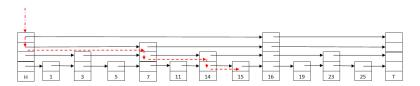




• H and T are two special nodes, representing *head* and *tail*. They cannot be deleted, they exist even in an empty list.

Skip List - Search

Search for element 15.



- Start from head and from highest level.
- If possible, go right.
- If cannot go right (next element is greater), go down a level.

- Lowest level has all n elements.
- Next level has $\frac{n}{2}$ elements.
- Next level has $\frac{n}{4}$ elements.
- etc.
- \Rightarrow there are approx $log_2 n$ levels.
- From each level, we check at most 2 nodes.
- Complexity of search: $O(log_2 n)$

Skip List - Insert

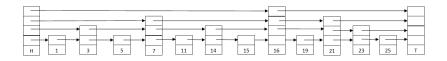
• Insert element 21.



• How high should the new node be?

Skip List - Insert

Height of a new node is determined randomly, but in such a
way that approximately half of the nodes will be on level 2, a
quarter of them on level 3, etc.



• Assume we randomly generate the height 3 for the node with 21.

- Skip Lists are *probabilistic* data structures, since we decide randomly the height of a newly inserted node.
- There might be a worst case, where every node has height 1 (so it is just a linked list).
- In practice, they function well.

- Usually, when we work with arrays, we store the elements in the array starting from the leftmost position and place them one after the other (no empty spaces in the middle of the list are allowed).
- The order of the elements is given by the order in which they are placed in the array.

	1	2	3	4	5	6	7	8	9	10
elems	46	78	11	6	59	19				

• Order of the elements: 46, 78, 11, 6, 59, 19

 We can define a linked data structure on an array, if we consider that the order of the elements is not given by their relative positions in the array, but by an integer number associated with each element, which shows the index of the next element in the array (thus we have a singly linked list).

	1	2	3	4	5	6	7	8	9	10
elems	46	78	11	6	59	19				
next	5	6	1	-1	2	4				

head = 3

• Order of the elements: 11, 46, 59, 78, 19, 6

 Now, if we want to delete the number 46 (which is actually the second element of the list), we do not have to move every other element to the left of the array, we just need to modify the links:

	1	2	3	4	5	6	7	8	9	10
elems		78	11	6	59	19				
next		6	5	-1	2	4				

head = 3

• Order of the elements: 11, 59, 78, 19, 6

If we want to insert a new element, for example 44, at the 3rd position in the list, we can put the element anywhere in the array, the important part is setting the links correctly:

	1	2	3	4	5	6	7	8	9	10
elems		78	11	6	59	19		44		
next		6	5	-1	8	4		2		

head = 3

• Order of the elements: 11, 59, 44, 78, 19, 6

• When a new element needs to be inserted, it can be put to any empty position in the array. However, finding an empty position has O(n) complexity, which will make the complexity of any insert operation (anywhere in the list) O(n). In order to avoid this, we will keep a linked list of the empty positions as well.

	1	2	3	4	5	6	7	8	9	10
elems		78	11	6	59	19		44		
next	7	6	5	-1	8	4	9	2	10	-1

head = 3

firstEmpty = 1

- In a more formal way, we can simulate a singly linked list on an array with the following:
 - an array in which we will store the elements.
 - an array in which we will store the links (indexes to the next elements).
 - the capacity of the arrays (the two arrays have the same capacity, so we need only one value).
 - an index to tell where the head of the list is.
 - an index to tell where the first empty position in the array is.

SLL on Array - Representation

 The representation of a singly linked list on an array is the following:

SLLA:

elems: TElem[]
next: Integer[]
cap: Integer
head: Integer

firstEmpty: Integer

 Optionally, we can keep the size (number of occupied pozitions) of the list as well

SLLA - Operations

- We can implement for a SLLA any operation that we can implement for a SLL:
 - insert at the beginning, end, at a position, before/after a given value
 - delete from the beginning, end, from a position, a given element
 - search for an element
 - get an element from a position

SLLA - Init

```
subalgorithm init(slla) is:
//pre: true; post: slla is an empty SLLA
  slla.cap \leftarrow INIT\_CAPACITY
  slla.elems ← @an array with slla.cap positions
  slla.next \leftarrow @an array with slla.cap positions
  slla head \leftarrow -1
  //we need to initialize the list of empty positions
  for i \leftarrow 1, slla.cap-1 execute
     slla.next[i] \leftarrow i + 1
  end-for
  slla.next[slla.cap] \leftarrow -1
  slla.firstEmpty \leftarrow 1
end-subalgorithm
```

Complexity:

SLLA - Init

```
subalgorithm init(slla) is:
//pre: true; post: slla is an empty SLLA
  slla.cap \leftarrow INIT\_CAPACITY
  slla.elems ← @an array with slla.cap positions
  slla.next \leftarrow @an array with slla.cap positions
  slla.head \leftarrow -1
  //we need to initialize the list of empty positions
  for i \leftarrow 1, slla.cap-1 execute
     slla.next[i] \leftarrow i + 1
  end-for
  slla.next[slla.cap] \leftarrow -1
  slla.firstEmpty \leftarrow 1
end-subalgorithm
```

• Complexity: $\Theta(n)$ - where n is the initial capacity

SLLA - Search

```
function search (slla, elem) is:
//pre: slla is a SLLA, elem is a TElem
//post: return True is elem is in slla, False otherwise
  current ← slla.head
  while current \neq -1 and slla.elems[current] \neq elem execute
     current ← slla.next[current]
  end-while
  if current \neq -1 then
     search ← True
  else
     search ← False
  end-if
end-function
```

Complexity:

SLLA - Search

```
function search (slla, elem) is:
//pre: slla is a SLLA, elem is a TElem
//post: return True is elem is in slla, False otherwise
  current ← slla.head
  while current \neq -1 and slla.elems[current] \neq elem execute
     current ← slla.next[current]
  end-while
  if current \neq -1 then
     search ← True
  else
     search ← False
  end-if
end-function
```

Complexity: O(n)

SLLA - Search

- From the search function we can see how we can go through the elements of a SLLA (and how similar this traversal is to the one done for a SLL):
 - We need a current element used for traversal, which is initialized to the index of the head of the list.
 - We stop the traversal when the value of *current* becomes -1
 - We go to the next element with the instruction: current ← slla.next[current].

```
subalgorithm insertPosition(slla, elem, poz) is:
//pre: slla is an SLLA, elem is a TElem, poz is an integer number
//post: the element elem is inserted into slla at position pos
//throws an exception if the position is not valid
  if pos < 1 then
     @error, invalid position
  end-if
  if slla.firstEmpty = -1 then
     newElems \leftarrow @an array with slla.cap * 2 positions
     newNext \leftarrow @an array with slla.cap * 2 positions
     for i \leftarrow 1, slla.cap execute
        newElems[i] \leftarrow slla.elems[i]
        newNext[i] \leftarrow slla.next[i]
     end-for
//continued on the next slide...
```

```
for i \leftarrow slla.cap + 1, slla.cap*2 - 1 execute
        newNext[i] \leftarrow i + 1
     end-for
     newNext[slla.cap*2] \leftarrow -1
     //free slla.elems and slla.next if necessary
     slla.elems \leftarrow newElems
     slla.next \leftarrow newNext
     slla.firstEmpty \leftarrow slla.cap+1
     slla.cap \leftarrow slla.cap * 2
  end-if
  if poz = 1 then
     newPosition ← slla.firstEmpty
     slla.elems[newPosition] \leftarrow elem
     slla.firstEmpty ← slla.next[slla.firstEmpty]
     slla.next[newPosition] \leftarrow slla.head
     slla.head \leftarrow newPosition
  else
//continued on the next slide...
```

```
pozCurrent \leftarrow 1
     nodCurrent ← slla.head
     while nodCurrent \neq -1 and pozCurrent < poz - 1 execute
        pozCurrent \leftarrow pozCurrent + 1
        nodCurrent \leftarrow slla.next[nodCurrent]
     end-while
     if nodCurrent \neq -1 atunci
        newElem \leftarrow slla.firstEmpty
        slla.firstEmpty \leftarrow slla.next[firstEmpty]
        slla.elems[newElem] \leftarrow elem
        slla.next[newElem] \leftarrow slla.next[nodCurrent]
        slla.next[nodCurrent] \leftarrow newElem
     else
//continued on the next slide...
```

```
@error, invalid position
  end-if
  end-subalgorithm
```

Complexity:

```
@error, invalid position
  end-if
  end-subalgorithm
```

• Complexity: O(n)

- Observations regarding the *insertPosition* subalgorithm
 - Similar to the SLL, we iterate through the list until we find the element after which we insert (denoted in the code by nodCurrent - which is an index in the array).
 - We treat as a special case the situation when we insert at the first position (no node to insert after).
 - Since it is an operation which takes as parameter a position we need to check if it is a valid position
 - Since the elements are stored in an array, we need to see at every add operation if we still have space or if we need to do a resize. And if we do a resize, the extra positions have to be added in the list of empty positions.

SLLA - DeleteElement

```
subalgorithm deleteElement(slla, elem) is:
//pre: slla is a SLLA; elem is a TElem
//post: the element elem is deleted from SLLA
   nodC ← slla head
   prevNode \leftarrow -1
   while nodC \neq -1 and slla.elems[nodC] \neq elem execute
      prevNode \leftarrow nodC
      nodC \leftarrow slla.next[nodC]
   end-while
  if nodC \neq -1 then
      if nodC = slla.head then
         slla.head ← slla.next[slla.head]
      else
         slla.next[prevNode] \leftarrow slla.next[nodC]
      end-if
//continued on the next slide...
```

SLLA - DeleteElement

```
//add the nodC position to the list of empty spaces
slla.next[nodC] ← slla.firstEmpty
slla.firstEmpty ← nodC
else
@the element does not exist
end-if
end-subalgorithm
```

• Complexity: O(n)

SLLA - Iterator

- Iterator for a SSLA is a combination of an iterator for an array and of an iterator for a singly linked list:
- Since the elements are stored in an array, the currentElement will be an index from the array.
- But since we have a linked list, going to the next element will not be done by incrementing the *currentElement* by one; we have to follow the *next* links.
- Also, initialization will be done with the position of the head, not position 1.

DLLA

- Obviously, we can define a doubly linked list as well without pointers, using arrays.
- For the DLLA we will see another way of representing a linked list on arrays:
 - The main idea is the same, we will use array indexes as links between elements
 - We are using the same information, but we are going to structure it differently
 - However, we can make it look more similar to linked lists with dynamic allocation

DLLA - Node

- Linked Lists with dynamic allocation are made of nodes. We can define a structure to represent a node, even if we are working with arrays.
- A node (for a doubly linked list) contains the information and links towards the previous and the next nodes:

DLLANode:

info: TElem next: Integer prev: Integer

DLLA

- Having defined the DLLANode structure, we only need one array, which will contain DLLANodes.
- Since it is a doubly linked list, we keep both the head and the tail of the list.

DLLA:

nodes: DLLANode[]

cap: Integer head: Integer tail: Integer

firstEmpty: Integer

size: Integer //it is not mandatory, but useful

DLLA - Allocate and free

 To make the representation and implementation even more similar to a dynamically allocated linked list, we can define the allocate and free functions as well.

```
function allocate(dlla) is:
//pre: dlla is a DLLA
//post: a new element will be allocated and its position returned
   newElem \leftarrow dlla.firstEmpty
   if newElem \neq -1 then
      dlla.firstEmpty \leftarrow dlla.nodes[dlla.firstEmpty].next
      if dlla.firstEmpty \neq -1 then
         dlla.nodes[dlla.firstEmpty].prev \leftarrow -1
      end-if
      dlla.nodes[newElem].next \leftarrow -1
      dlla.nodes[newElem].prev \leftarrow -1
   end-if
   allocate ← newElem
end-function
```

DLLA - Allocate and free

```
subalgorithm free (dlla, poz) is:
//pre: dlla is a DLLA, poz is an integer number
//post: the position poz was freed
  dlla.nodes[poz].next \leftarrow dlla.firstEmpty
  dlla.nodes[poz].prev \leftarrow -1
  if dlla.firstEmpty \neq -1 then
     dlla.nodes[dlla.firstEmpty].prev \leftarrow poz
  end-if
  dlla.firstEmpty \leftarrow poz
end-subalgorithm
```

```
subalgorithm insertPosition(dlla, elem, poz) is:
//pre: dlla is a DLLA, elem is a TElem, poz is an integer number
//post: the element elem is inserted in dlla at position poz
   if poz < 1 OR poz > dlla.size + 1 execute
      Othrow exception
   end-if
   newElem ← alocate(dlla)
   if newElem = -1 then
      Oresize
      newElem \leftarrow alocate(dlla)
   end-if
   dlla.nodes[newElem].info \leftarrow elem
   if poz = 1 then
      if dlla.head = -1 then
         dlla.head \leftarrow newElem
         dlla.tail ← newElem
      else
//continued on the next slide...
```

```
dlla.nodes[newElem].next \leftarrow dlla.head
         dlla.nodes[dlla.head].prev \leftarrow newElem
         dlla.head ← newElem
      end-if
   else
      nodC ← dlla.head
      pozC \leftarrow 1
      while nodC \neq -1 and pozC < poz - 1 execute
         nodC \leftarrow dlla.nodes[nodC].next
         pozC \leftarrow pozC + 1
      end-while
      if nodC \neq -1 then //it should never be -1, the position is correct
         nodNext \leftarrow dlla.nodes[nodC].next
         dlla.nodes[newElem].next \leftarrow nodNext
         dlla.nodes[newElem].prev \leftarrow nodC
         dlla.nodes[nodC].next \leftarrow newElem
//continued on the next slide...
```

• Complexity: O(n)

DLLA - Iterator

• The iterator for a DLLA contains as *current element* the index of the current node from the array.

DLLAIterator:

list: DLLA

currentElement: Integer

DLLAIterator - init

```
subalgorithm init(it, dlla) is:

//pre: dlla is a DLLA

//post: it is a DLLAIterator for dlla

it.list ← dlla

it.currentElement ← dlla.head

end-subalgorithm
```

- For a (dynamic) array, currentElement is set to 0 when an iterator is created. For a DLLA we need to set it to the head of the list (which might be position 0, but it might be a different position as well).
- Complexity:



DLLAIterator - init

```
subalgorithm init(it, dlla) is:

//pre: dlla is a DLLA

//post: it is a DLLAIterator for dlla

it.list ← dlla

it.currentElement ← dlla.head

end-subalgorithm
```

- For a (dynamic) array, currentElement is set to 0 when an iterator is created. For a DLLA we need to set it to the head of the list (which might be position 0, but it might be a different position as well).
- Complexity: Θ(1)

DLLAIterator - getCurrent

```
subalgorithm getCurrent(it) is:
//pre: it is a DLLAIterator, it is valid
//post: e is a TElem, e is the current element from it
//throws exception if the iterator is not valid
if it.currentElement = -1 then
        @throw exception
end-if
getCurrent ← it.list.nodes[it.currentElement].info
end-subalgorithm
```

Complexity:

DLLAlterator - getCurrent

```
subalgorithm getCurrent(it) is:
//pre: it is a DLLAIterator, it is valid
//post: e is a TElem, e is the current element from it
//throws exception if the iterator is not valid
if it.currentElement = -1 then
     @throw exception
end-if
getCurrent ← it.list.nodes[it.currentElement].info
end-subalgorithm
```

Complexity: Θ(1)

DLLAlterator - next

```
subalgoritm next (it) is:
//pre: it is a DLLAlterator, it is valid
//post: the current elements from it is moved to the next element
//throws exception if the iterator is not valid
if it.currentElement = -1 then
        @throw exception
end-if
it.currentElement ← it.list.nodes[it.currentElement].next
end-subalgorithm
```

- In case a (dynamic) array, going to the next element means incrementing the *currentElement* by one. For a DLLA we need to follow the links.
- Complexity:

DLLAlterator - next

```
subalgoritm next (it) is:
//pre: it is a DLLAlterator, it is valid
//post: the current elements from it is moved to the next element
//throws exception if the iterator is not valid
if it.currentElement = -1 then
        @throw exception
end-if
it.currentElement ← it.list.nodes[it.currentElement].next
end-subalgorithm
```

- In case a (dynamic) array, going to the next element means incrementing the currentElement by one. For a DLLA we need to follow the links.
- Complexity: Θ(1)

DLLAlterator - valid

```
function valid (it) is:
//pre: it is a DLLAIterator
//post: valid return true is the current element is valid, false
otherwise
  if it.currentElement = -1 then
     valid \leftarrow False
  else
     valid ← True
  end-if
end-function
```

Complexity:

DLLAlterator - valid

```
function valid (it) is:
//pre: it is a DLLAIterator
//post: valid return true is the current element is valid, false
otherwise
  if it.currentElement = -1 then
     valid \leftarrow False
  else
     valid ← True
  end-if
end-function
```

• Complexity: $\Theta(1)$