# Numerical Methods (ENUME) Assignment B: Approximation of functions Spring Semester 2024

The file f13.p contains a MATLAB function of the following syntax:

function 
$$y = f13(x)$$

implementing a scalar, single-argument mathematical function  $f(x) : \mathbb{R} \to \mathbb{R}$ .

## Task #1

Develop a MATLAB program for estimating the parameters  $a_0, ..., a_K, b_1, ..., b_K \in \mathbb{R}$  of the trigonometric polynomial:

$$\hat{f}(x; a_0, ..., a_K, b_1, ..., b_K) = \sum_{k=0}^K a_k \cos(kx) + \sum_{k=1}^K b_k \sin(kx), \quad K \in \mathbb{N}$$

which minimises the criterion of the least-squares approximation of f(x):

$$J(a_0, ..., a_K, b_1, ..., b_K) = \sum_{n=1}^{N} \left( \hat{f}(x_n; a_0, ..., a_K, b_1, ..., b_K) - f(x_n) \right)^2$$

where  $x_1, ..., x_N$  are equidistant numbers from  $-x_{\text{max}}$  to  $x_{\text{max}}$  with N = 100.

Test the developed program for K = 2, 4, 6 and  $x_{\text{max}} = 0.5, 1.0, 1.5$ .

### Task #2

Determine the dependence of the mean-square approximation error:

$$e = \sqrt{\frac{1}{N} \sum_{n=1}^{N} (\hat{f}(x_n; a_0, ..., a_K, b_1, ..., b_K) - f(x_n))^2}$$

on  $K \in [1, 20]$  for several exemplary values of  $x_{\text{max}} \in [0.5, 2.0]$ .

### **Task #3**

Assuming that f(x) needs to be approximated on the basis of error-corrupted data, modelled as follows:

$$\underline{\tilde{y}_n} = f(x_n) + \underline{\Delta \tilde{y}_n}$$
 for  $n = 1, ..., N$ 

where  $\Delta \tilde{y}_1, ..., \Delta \tilde{y}_N$  are random variables following a zero-mean normal distribution with variance  $\sigma_y^2$ , determine the dependence of the expected value  $\bar{e}$  of the mean-square approximation error e on  $x_{\text{max}} \in [10^{-2}, 10^1]$  for K = 4 and several exemplary values of  $\sigma_y^2 \in [10^{-12}, 10^{-2}]$ .

In order to estimate  $\bar{e}$ , perform the approximation R=100 times, each time using a different sequence of pseudorandom numbers  $\Delta \tilde{y}_1, ..., \Delta \tilde{y}_N$  to emulate the random errors  $\Delta \tilde{y}_1, ..., \Delta \tilde{y}_N$  (randn), and storing the obtained value of the mean-square approximation error as  $e_r$  (for r=1,...,R); estimate  $\bar{e}$  according to the formula:

$$\bar{e} = \sqrt{\frac{1}{R} \sum_{r=1}^{R} e_r^2}$$

### Task #4

Compare the results obtained using MATLAB's backslash operator (\) applied in two ways:

where:

- p represents the vector of parameters  $[a_0, ..., a_K, b_1, ..., b_K]^T$ ,
- Phi represents the matrix of basis functions  $\Phi$  (cf. lecture slides #5-10 and #5-11),
- x represents the vector  $[x_1, ..., x_N]^T$ .