



INDIAN INSTITUTE OF TECHNOLOGY BOMBAY

EE 324: CONTROL SYSTEMS LAB

PROBLEM SHEET 1 REPORT

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1 Question 1

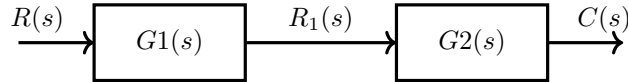
We have two components with transfer functions $G1(s)$ and $G2(s)$ as follows:

$$G1(s) = \frac{10}{s^2 + 2s + 10}$$

$$G2(s) = \frac{5}{s + 5}$$

we have to obtain the transfer functions of the following systems:

1.1 Part a - Cascade System



After the first system, the output $R_1(s)$ will be

$$R_1(s) = G1(s) R(s)$$

Now $R_1(s)$ will be the input to the second system $G2(s)$ and hence the output $C(s)$ will be

$$C(s) = G2(s) R_1(s) = G1(s) G2(s) R(s)$$

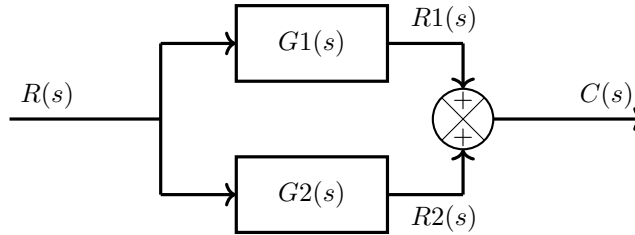
Hence the transfer function of this cascade system is

$$T(s) = G1(s) G2(s)$$

By using Scilab, we get

$$T(s) = \frac{50}{50 + 20s + 7s^2 + s^3}$$

1.2 Part b - Parallel System



In this case, the output $C(s)$ will be the sum of the outputs $R1(s)$ and $R2(s)$, i.e.,

$$C(s) = R1(s) + R2(s)$$

$$C(s) = G1(s) R(s) + G2(s) R(s)$$

$$C(s) = (G1(s) + G2(s)) R(s)$$

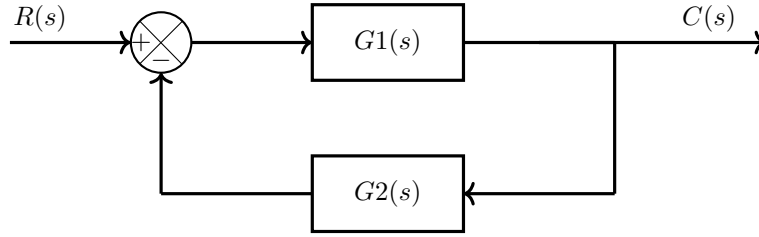
Hence the transfer function $T(s)$ will be

$$T(s) = G1(s) + G2(s)$$

By using Scilab, we get

$$T(s) = \frac{100 + 20s + 5s^2}{50 + 20s + 7s^2 + s^3}$$

1.3 Part c - Feedback (closed loop) System



The relation between input and the output in this case is

$$g1(t) * (r(t) - g2(t) * c(t)) = c(t)$$

$$\implies g1(t) * r(t) = c(t) + (g1(t) * g2(t)) * c(t)$$

On taking the Laplace transform of this equation, we will have

$$G1(s) R(s) = C(s)(1 + G1(s) G2(s))$$

$$\implies C(s) = \frac{G1(s)}{1 + G1(s) G2(s)} R(s)$$

Hence, the transfer function $T(s)$ will be

$$T(s) = \frac{G1(s)}{1 + G1(s) G2(s)}$$

By using Scilab, we get

$$T(s) = \frac{50 + 10s}{100 + 20s + 7s^2 + s^3}$$

1.4 Part d - Step Response of $G1(s)$

We need to plot the step response of the system with $G1(s)$ as the transfer function. This has been done using the `csim` and the `plot` commands.

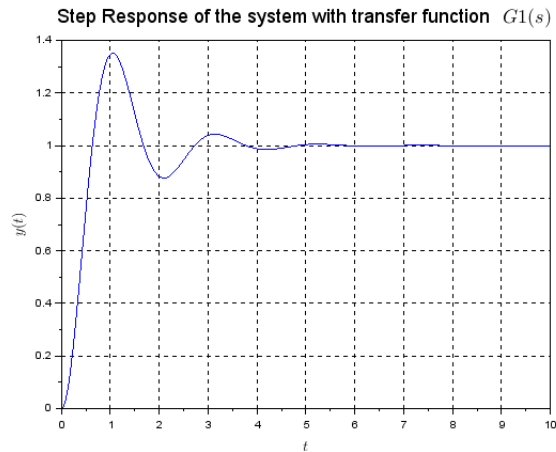


Figure 1: Unit Step Response

2 Problem 2

The poles and zeros of the system have been found using the Scilab command `tf2zp` which returns all the poles, zeros and gains. The poles and zeros were plotted using `plzr` command.

2.1 Part a - Cascade System

$$T(s) = \frac{50}{50 + 20s + 7s^2 + s^3}$$

This system has no zeros as it is evident from the transfer function.

Poles	Zeros
-5	
$-1 + 3i$	-
$-1 - 3i$	

Table 1: Poles and Zeros

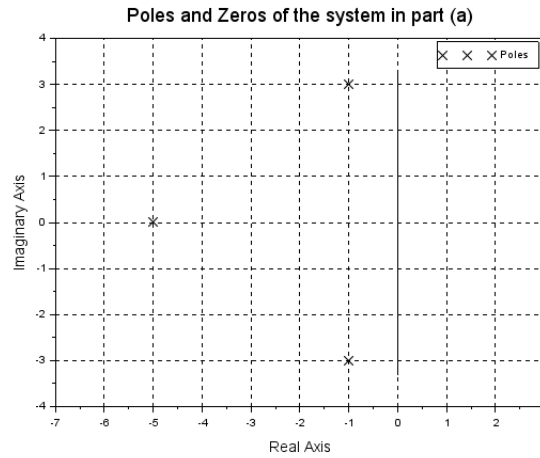


Figure 2: Poles and Zeros of Cascade System

2.2 Part b - Parallel System

$$T(s) = \frac{100 + 20s + 5s^2}{50 + 20s + 7s^2 + s^3}$$

This system will have 2 zeros and 3 poles.

Poles	Zeros
-5	
$-1 + 3i$	$-2 + 4i$
$-1 - 3i$	$-2 - 4i$

Table 2: Poles and Zeros

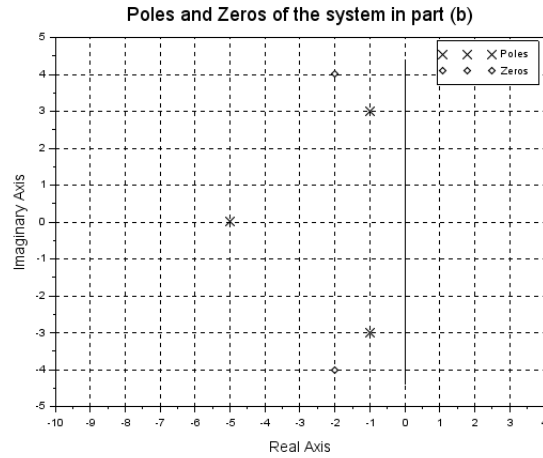


Figure 3: Poles and Zeros of Parallel System

2.3 Part c - Feedback (closed loop) System

$$T(s) = \frac{50 + 10s}{100 + 20s + 7s^2 + s^3}$$

This system will have 1 zero and 3 poles.

Poles	Zeros
-6.3347665	-5
$-0.3326167 + 3.9592004i$	
$-0.3326167 - 3.9592004i$	

Table 3: Poles and Zeros

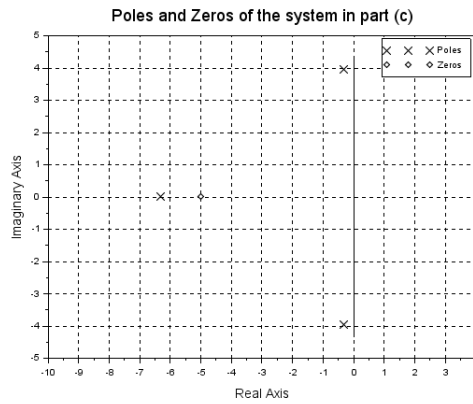


Figure 4: Poles and Zeros of Closed Loop Feedback System

3 Some computations on matrices using Scilab

Consider the following matrix:

$$A = \begin{bmatrix} s & \frac{1}{s} & \frac{s+1}{s-1} \\ 1 & s^3 & 0 \\ 1+s^2 & 2s & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 2 & 1 \\ 1 & s & 9 \\ -1 & 0 & 0 \end{bmatrix}$$

We then have

$$A + B = \begin{bmatrix} 1+s & \frac{1+2s}{s} & \frac{2s}{s-1} \\ 2 & s+s^3 & 9 \\ s^2 & 2s & 2 \end{bmatrix}$$

$$A \times B = \begin{bmatrix} \frac{-1-2s^2+s^3}{-s+s^2} & 1+2s & \frac{-9+10s+s^3}{-s+s^2} \\ 1+s^3 & 2+s^4 & 1+9s^3 \\ 2s+s^2 & 2+4s^2 & 2+18s+s^2 \end{bmatrix}$$

$$\det(A) = \frac{-1 + 3.14 \times 10^{-16}s - 2s^2 - 4s^3 - 3s^4 - s^5 - s^6}{s}$$

4 Problem 3

The circuit given is as follows:

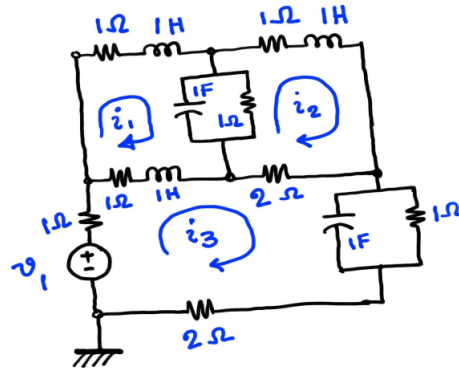
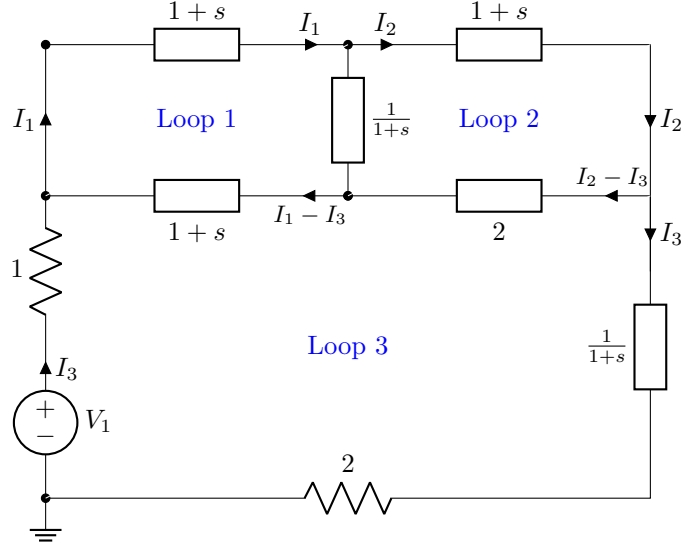


Figure 5: Original Circuit

After converting our analysis to the Laplace domain and reducing all the parallel R-C pair, we will have:

Please see the next page



If we use the Kirchhoff's Voltage Law in each of the three loops, we will get -

For Loop 1:

$$I_1 [1 + 2(s+1)^2] + I_2 [-1] + I_3 [-(s+1)^2] = 0 \quad (1)$$

For Loop 2:

$$I_1 + I_2 [-(s+2)^2] + I_3 [2(1+s)] = 0 \quad (2)$$

For Loop 3:

$$I_1 [-(s+1)] + I_2 [-2] + I_3 \left[s + 6 + \frac{1}{s+1} \right] = V_1 \quad (3)$$

By representing the above three equations in matrix form, we will have

$$\begin{bmatrix} 1 + 2(s+1)^2 & -1 & -(s+1)^2 \\ -1 & (s+2)^2 & -2(s+1) \\ -(s+1)^2 & -2(s+1) & s^2 + 7s + 7 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ V_1(s+1) \end{bmatrix}$$

On comparing the above equation with $Z(s) I(s) = V(s)$ we have

$$Z(s) = \begin{bmatrix} 1 + 2(s+1)^2 & -1 & -(s+1)^2 \\ -1 & (s+2)^2 & -2(s+1) \\ -(s+1)^2 & -2(s+1) & s^2 + 7s + 7 \end{bmatrix}$$

and

$$V(s) = \begin{bmatrix} 0 \\ 0 \\ V_1(s+1) \end{bmatrix}$$

On solving the above matrix equation for $I(s)$ using Scilab, we get

$$I(s) = Z^{-1}(s) V(s)$$

$$\begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = V_1 \times \begin{bmatrix} \frac{6+14s+13s^2+6s^3+s^4}{57+144s+147s^2+74s^3+17s^4+s^5} \\ \frac{7+16s+13s^2+4s^3}{57+144s+147s^2+74s^3+17s^4+s^5} \\ \frac{11+28s+27s^2+12s^3+2s^4}{57+144s+147s^2+74s^3+17s^4+s^5} \end{bmatrix}$$

Hence, the transfer functions are as follows:

$$\frac{I_1(s)}{V_1(s)} = \frac{6 + 14s + 13s^2 + 6s^3 + s^4}{57 + 144s + 147s^2 + 74s^3 + 17s^4 + s^5}$$

$$\frac{I_2(s)}{V_1(s)} = \frac{7 + 16s + 13s^2 + 4s^3}{57 + 144s + 147s^2 + 74s^3 + 17s^4 + s^5}$$

$$\frac{I_3(s)}{V_1(s)} = \frac{11 + 28s + 27s^2 + 12s^3 + 2s^4}{57 + 144s + 147s^2 + 74s^3 + 17s^4 + s^5}$$

5 Code

```

1 clear; clc;
2 // -----
3 // Question 1 //
4 s = poly(0, 's');
5 G1 = 10 / (s^2 + 2*s + 10);
6 G2 = 5 / (s + 5);
7 S1 = syslin('c', G1);
8 S2 = syslin('c', G2);
9 // -----
10 // Part a
11 TA = S1 * S2;
12 disp("Transfer Function for part a");
13 disp(TA);
14 // -----
15 // Part b
16 TB = S1 + S2;
17 disp("Transfer Function for part b");
18 disp(TB);
19 // -----
20 // Part c
21 TC = (S1) / (1 + (S1 * S2));
22 disp("Transfer Function for part c");
23 disp(TC);
24 // -----
25 // Part d
26 t = 0:0.01:10;
27 scf();
28 plot(t, csim('step', t, S1));
29 xgrid(0);
30 title(["Step Response of the system with transfer function", "$G1(s)$"], 'fontsize', 4);
31 xlabel("$t$", 'fontsize', 3);
32 ylabel("$y(t)$", 'fontsize', 3)
33 // -----
34 // Question 2 //
35 // Part a
36 [za, pa, ga] = tf2zp(TA);
37 disp('Zeros of Part a');
38 disp(za);
39 disp('Poles of Part a');
40 disp(pa);

```

```

41 scf();
42 plzr(TA);
43 xgrid(0);
44 title("Poles and Zeros of the system in part (a)", 'fontsize', 4);
45 xlabel("Real Axis", 'fontsize', 3);
46 ylabel("Imaginary Axis", 'fontsize', 3);
47 // -----
48 // Part b
49 [zb, pb, gb] = tf2zp(TB);
50 disp('Zeros of Part b');
51 disp(zb);
52 disp('Poles of Part b');
53 disp(pb);
54 scf();
55 plzr(TB);
56 xgrid(0);
57 title("Poles and Zeros of the system in part (b)", 'fontsize', 4);
58 xlabel("Real Axis", 'fontsize', 3);
59 ylabel("Imaginary Axis", 'fontsize', 3);
60 // -----
61 // Part c
62 [zc, pc, gc] = tf2zp(TC);
63 disp('Zeros of Part c');
64 disp(zc);
65 disp('Poles of Part c');
66 disp(pc);
67 scf();
68 plzr(TC);
69 xgrid(0);
70 title("Poles and Zeros of the system in part (c)", 'fontsize', 4);
71 xlabel("Real Axis", 'fontsize', 3);
72 ylabel("Imaginary Axis", 'fontsize', 3);
73 // -----
74 // Matrices Task //
75 A = [s 1/s (s+1)/(s-1); 1 s^3 0; 1+s^2 2*s 1];
76 B = [1 2 1; 1 s 9; -1 0 1];
77 disp('A+B');
78 disp(A+B);
79 disp('A x B');
80 disp(A * B);
81 disp("det(A)");
82 disp(det(A));
83 // -----
84 // Question 3 //
85 Z = [1+(2*(s+1)^2) -1 -(s+1)^2; -1 (s+2)^2 -2*(s+1); -(s+1)^2 -2*(s+1) (s^2+7*s+7)];
86 V = [0 0 (1+s)];
87 T = V * inv(Z);
88 disp(T);

```