$\langle$ OCP $\rangle$

Phase #0

Model: KINOVA_arm_reverse.bioMod
Phase duration: 0.5 s
Shooting nodes: 30
Dynamics: CUSTOM
ODE: RK4
Control type: CONSTANT

Parameters
No parameter set

Lagrange
$(MINIMIZE\_CONTROL)^2$
Weight: 1
key: tau
Index in list: 0

$(MINIMIZE\_STATE)^2$
Weight: 1
key: q
Index in list: 1

$(MINIMIZE\_STATE)^2$
Weight: 1
key: qdot
Index in list: 2

Mayer
No Mayer set

Constraints
SUPERIMPOSE_MARKERS
Min bound: 0
Max bound: 0
first_marker: mg1
second_marker: md0
Index in list: 0
Shooting nodes index: 0

SUPERIMPOSE_MARKERS
Min bound: 0
Max bound: 0
first_marker: mg2
second_marker: md0
Index in list: 1
Shooting nodes index: 30

SUPERIMPOSE_MARKERS
Min bound: 0
Max bound: 0
first_marker: grd_contact1
second_marker: Contact_mk1
Index in list: 2
Shooting nodes index: 0