



Phase #0

Model: SliderXY_1Leg.bioMod
Phase duration: 0.5 s
Shooting nodes: 20
Dynamics: CUSTOM
ODE: RK4
Control type: CONSTANT

Parameters

No parameter set

Lagrange

(MINIMIZE CONTROL)²

Weight: 0.1

key: tau

Index in list: 0

Mayer

No Mayer set

Constraints

TRACK CONTACT FORCES

Min bound: -inf

Max bound: inf

Index in list: 0

Shooting nodes index: all

SUPERIMPOSE MARKERS

Min bound: 0

Max bound: 0

first marker: ms1

second marker: mg1

Index in list: 1

Shooting nodes index: 0

SUPERIMPOSE MARKERS

Min bound: 0

Max bound: 0

first marker: ms1

second marker: mg2

Index in list: 2

Shooting nodes index: 20