



**Phase #0**



**Model:** ConnectedArm.bioMod  
**Phase duration:** 0.1 s  
**Shooting nodes:** 20  
**Dynamics:** TORQUE\_DRIVEN  
**ODE:** RK4  
**Control type:** CONSTANT

**Parameters**

No parameter set

**Lagrange**

No Lagrange set

**Mayer**

No Mayer set

**Constraints**

SUPERIMPOSE\_MARKERS

**Min bound:** 0

**Max bound:** 0

**first marker:** m0

**second marker:** mg3

**Index in list:** 0

**Shooting nodes index:** 0