



Phase #0

Model: Slider1Leg.bioMod
Phase duration: 0.2 s
Shooting nodes: 20
Dynamics: TORQUE_DRIVEN
ODE: RK4

Parameters

No parameter set

Lagrange

(MINIMIZE CONTROL)²

Weight: 0.1

key: tau

Index in list: 0

Mayer

No Mayer set

Constraints

TRACK CONTACT FORCES

Min bound: 0

Max bound: inf

contact index: 0

Index in list: 0

Shooting nodes index: all