$\diamondsuit$ OCP

Phase #0

Model: ConnectedArm.bioMod
Phase duration: 0.1 s
Shooting nodes: 20
Dynamics: CUSTOM
ODE: RK4
Control type: CONSTANT

Parameters
No parameter set

Lagrange
No Lagrange set

Mayer
No Mayer set

Constraints
SUPERIMPOSE_MARKERS
Min bound: 0
Max bound: 0
first_marker: m0
second_marker: mg3
Index in list: 0
Shooting nodes index: 0