



Phase #0

Model: Model_JeCh_10DoFs.bioMod
Phase duration: 1.54 s
Shooting nodes: 100
Dynamics: TORQUE_DRIVEN
ODE: RK4
Control type: CONSTANT

Time

Size: 1

Scaling: 1.000

Initial guess: 1.545

Min bound: 1.245

Max bound: 1.245

Lagrange

(MINIMIZE STATE)²

Weight: 1

key: qdot

Index in list: 0

(MINIMIZE MARKERS)²

Weight: 1000

reference_jcs: 3

marker index: 6

Index in list: 1

(MINIMIZE MARKERS)²

Weight: 1000

reference_jcs: 7

marker index: 11

Index in list: 2

Mayer

No Mayer set

Constraints

TIME CONSTRAINT

Min bound: 1.2449999999999999

Max bound: 1.845

Index in list: 0

Shooting nodes index: 100