EXECUTIVE SUMMARY: PREDICT THE REUSE OF FIRST STAGE BY SPACEX

- Project Overview: To predict if SpaceX will reuse the first stage, we aimed to use a trained machine learning model and public information to determine the cost of a launch.
 - ▶ Sub Point 1
 - ▶ Sub Point 2

► Approach:

- Data collection and Wranglinfd: We collected data using spaceX API and webscraping
- Exploratory Data Analysis: we conducted EDA to identify patterns and key features within the data
- Predictive Analysis: We engineered new features, and evaluated various machine learning algorithms including logistic regression, support vector machine(SVM), Decision tree, KNN.

▶ Results:

- ► EDA: Launch success improved over time, KSC LC-39A had the most successful landing rate and Orbits ES/1, GEO, HEO, and SSO have a 100% success rate
- Visualization: Most Lauch sites were closer to the equator and to the coast
- ▶ Predictive Analysis:: All models performed well on the test set.

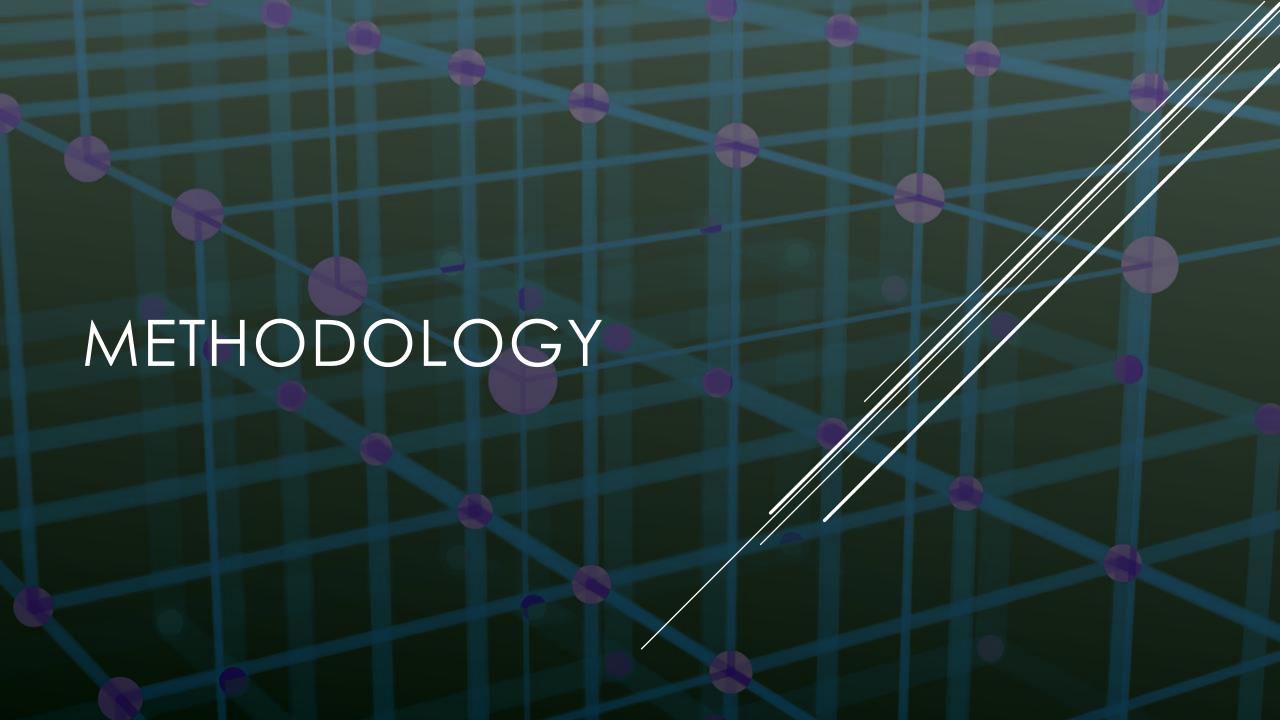


Introduction

SpaceX, led by Elon Musk, has revolutionized aerospace with reusable rocket technology, notably reusing Falcon 9 first stages. Data science plays a pivotal role in predicting first stage reusability by analyzing historical data, telemetry, and machine learning. This predictive capability impacts space industry finances and environmental sustainability.

In this study, we embark on a journey to harness the power of machine learning models to predict whether SpaceX will achieve successful first stage recovery and reuse. By examining historical data on SpaceX's launches, mission details, and outcomes, we aim to build a predictive model that earlinform stakeholders, enthusiasts, and decision-makers about the likelihood of successful reuse.

This research is not only a testament to the growing synergy between advanced data analytics and space technology but also an attempt to provide valuable insights into SpaceX's pioneering efforts in rocket recovery and reuse. As we delve into the methodology, data collection, feature engineering, and model development, we anticipate that our findings will shed light on the future of sustainable space travel and inspire further innovations in the aerospace industry.



DATA COLLECTION - API

Import Libraries

Request and parse

Filter

Data Wrangling

- Import libraries and define Auxiliary functions
- Requests
- Pandas
- Numpy
- Datetime

- Request and parse
 SpaceX launch date using GET request
- Request data from API
- Decode response using .json() and convert to data frame using pd.json_normalize
- Create dictionary
- Create data frame from dictionary

 Filter the Data frame only to include
 Falcon9 launches

- Dealing with missing values
 - Isnull().sum()
 - .mean()
 - np.nan

DATA COLLECTION - WEBSCRAPING

Import

- •Sys
- BeautifulSoup
- ·Unicodedata
- ·Pandas

Request

- ·Perform HTTP GET method
- ·Create BeautifulSoup Object from HTML response

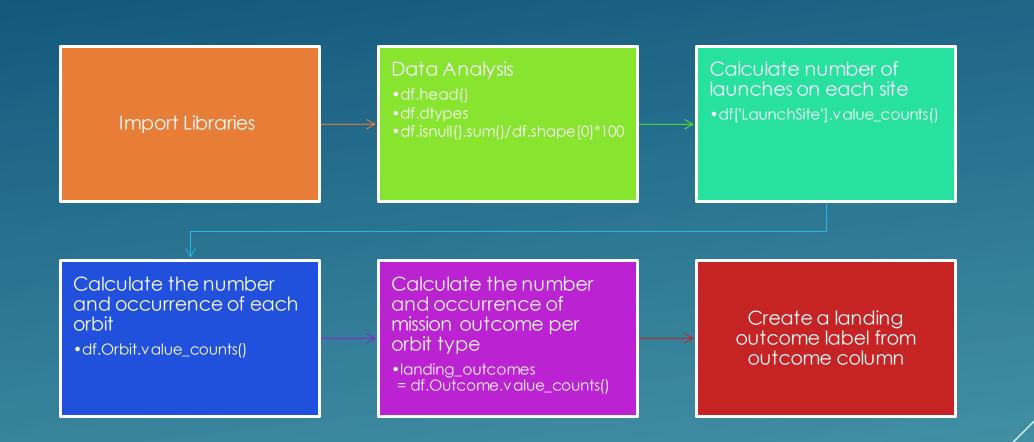
Extract Columns

- ·Use find all function
- ·Extract column names from HTML table header

Create Data frame

- ·Create an empty dictionary from data
- ·Fill in dictionary with extracted records from table rows
- ·Create data frame from the dictionary

DATA WRANGLING



```
ror_mod = modifier_ob.
 mirror object to mirror
mirror_mod.mirror_object
peration == "MIRROR_X":
irror_mod.use_x = True
mirror_mod.use_y = False
!rror_mod.use_z = False
 _operation == "MIRROR_Y"
lrror_mod.use_x = False
 lrror_mod.use y = True
 irror_mod.use_z = False
 operation == "MIRROR Z"
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  rror_mod.use_y = False
  rror_mod.use_z = True
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  int("please select exaction
 --- OPERATOR CLASSES ----
      mirror to the selected
    ect.mirror_mirror_x"
  **xt.active_object is not
```

EDA WITH SQL

We connected to the database

Displayed

- unique launch sites
- •5 records where launch sites began with 'CCA'
- the total payload mass carried by boosters launched by NASA (CRS)
- •average payload mass carried by booster version F9 v1.1

Listed

- Date of first successful landing on ground pad
- •Names of boosters which had success landing on drone ship and have payload mass greater than 4000 but less than 6000
- Total number of successful and failed missions
- •Names of booster version which have carried max payload
- Failed landing outcomes on drone ship, their booster version and launch site for the months in the year 2015
- •Count of landing outcomes between 2010-06-04 and 2017-03-20 (desc)

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  rror_mod.use_y = False
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  ata.objects[one.name].sel
  int("please select exaction
  --- OPERATOR CLASSES ----
      mirror to the selected
    ect.mirror_mirror_x"
  ext.active_object is not
```

- To understand how certain features affected the launch, we visualized the relationships between
 - Flight number and Payload Mass
 - Flight number and launch site
 - Success rate of each orbit using the group by function
 - Flight number and orbit type
 - Payload and orbit type
- Visualized the launched success yearly trend
- Performed features engineering by using one hot encoding
- Casted all numeric columns to float64 using .astype()

INTERACTIVE VISUALIZATION WITH FOLIUM

Marked all launch sites

- Created a blue circle at NASA Johnson Space Centre's coordinate with a popup label
- Added red circles at all launch sites coordinates with a popup label

Coloured Markers of Launch outcome

 Added coloured markers of successful and unsuccessful launches at each launch site

Distances between launch sites and proximities

• Added lines to indicate the distances between launch sites and its proximity to the nearest coastline, railway and city.

DASHBOARD WITH PLOTLY DASH

Drop down list with launches

- Allow users to select all launch sites or certain launch site
- Added red circles at all launch sites coordinates with a popup label

Pie chart showing successful launches

• Allow users to visualize successful and unsuccessful launches

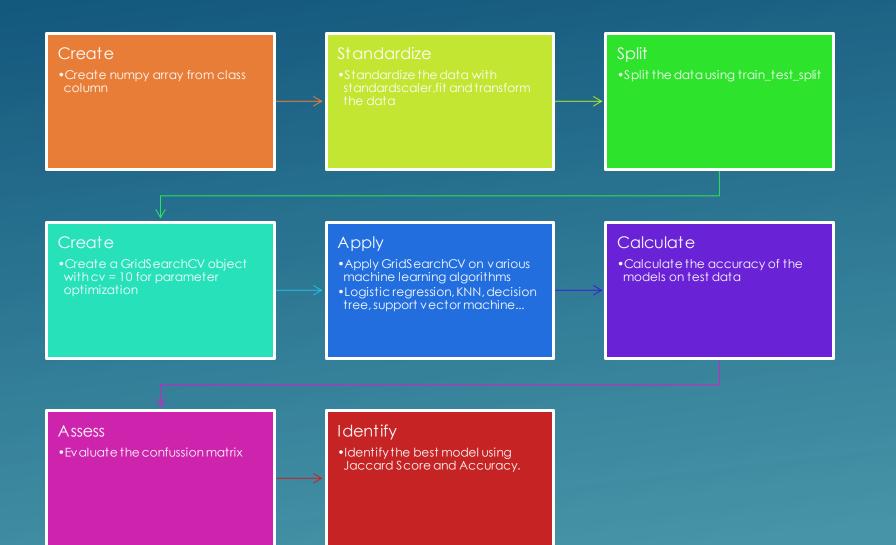
Slider of payload mass range

Allow users to select payload mass range

Scatter chart

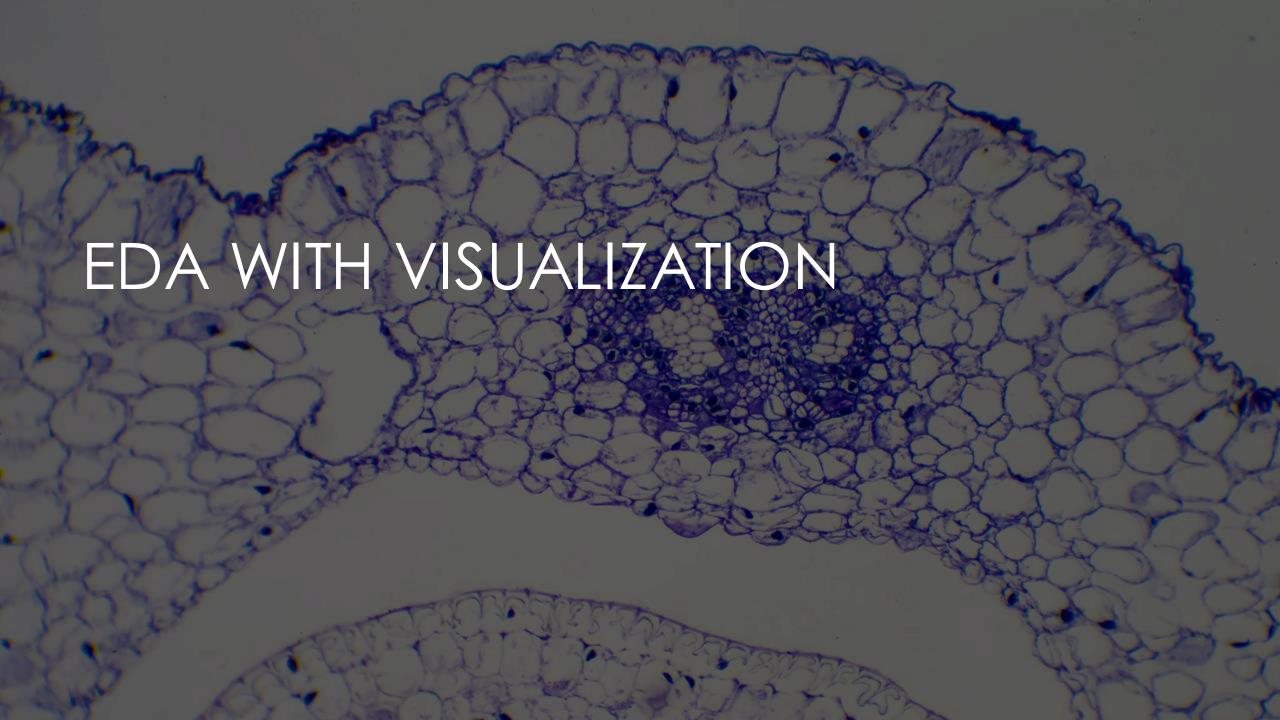
Allow users to visualize the relationship between payload mass and launch success

PREDICTIVE ANALYSIS

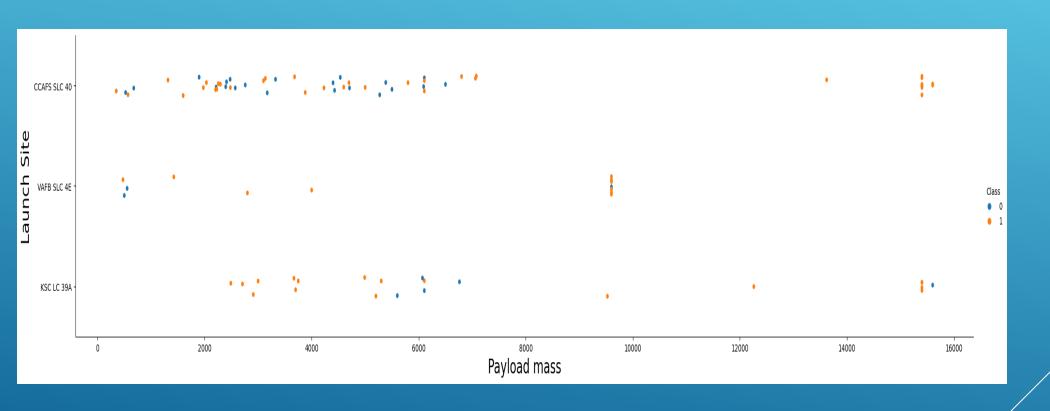




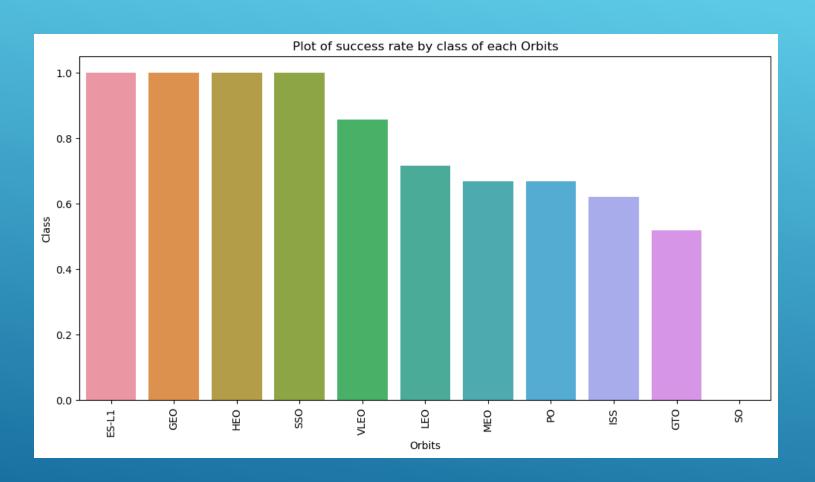
RESULTS



KSC LC-39A and CCAFS SLC-40 had more success when the payload mass increased



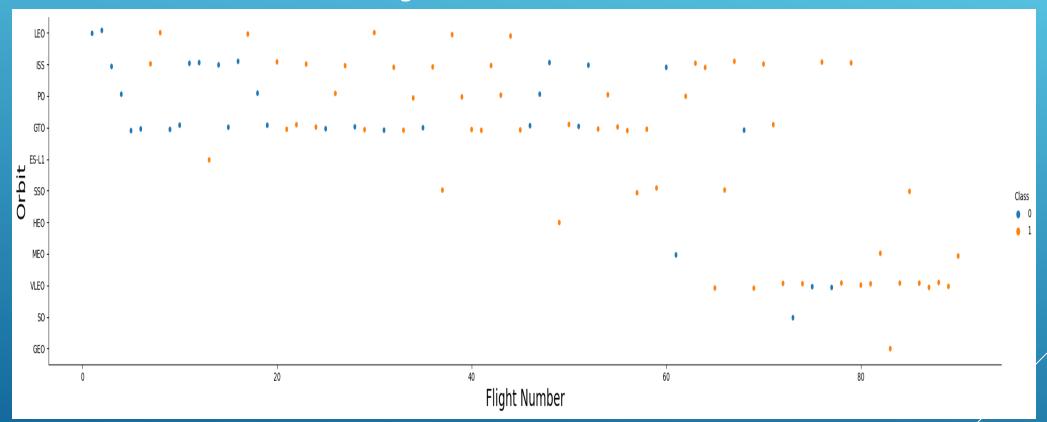




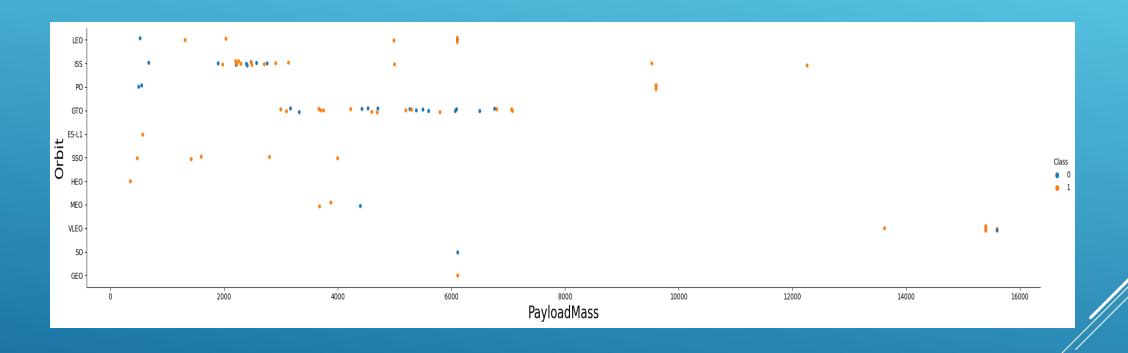
Orbits Success Rates

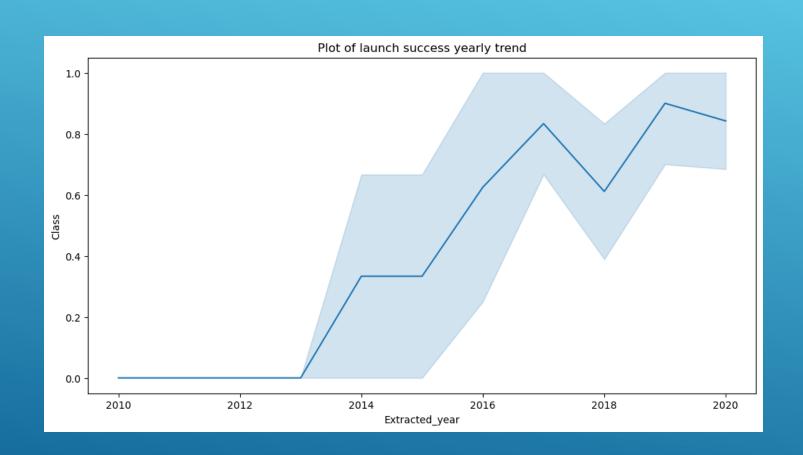
- ES-L1, GEO, HEO and SSO had 100% success rate
- VLEO, MEO, PO, ISS and GTO had above 50% success rate
- 50 had a 0% success rate

Higher flight number influenced increased the success rates of some orbits while lower flight number influenced the success rates of other orbits. It can be that flight number is not a factor that influenced success rates in general.



Orbits had more success rate when the payload mass was between 2000 and 6000 kg.





There was an increase in successful launches as the year increases. This good be due to advancement in technology and infrastructure.

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   irror ob.select = 0
  bpy.context.selected_obje
  lata.objects[one.name].sell
 int("please select exactle
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    X mirror to the selected
    pes.Operator):
   ject.mirror_mirror_x"
 ext.active_object is not
```

EDA RESULTS WITH SQL

EDA RESULTS WITH SQL

Launch_Site

CCAFS LC-40

VAFB SLC-4E

KSC LC-39A

CCAFS SLC-40

Launch_Site

CCAFS LC-40

CCAES LC-40

CCAFS LC-40

CCAFS LC-40

CCAFS LC-40

- The launch sites used in this research were
 - CCAFS LC-40
 - VAFB SLC-4E
 - · KSC LC-39A
 - CCAFS SLC-40

TotalPayloadMass Customer 48213 NASA (CRS)

AveragePayloadMass

2534.6666666666665

min(Date)	Landing_Outcome
2015-12-22	Success (ground pad)

Landing_Outcome	PAYLOAD_MASS_KG_
Success (drone ship)	4696
Success (drone ship)	4600
Success (drone ship)	5300
Success (drone ship)	5200
	Success (drone ship) Success (drone ship) Success (drone ship)

- Total payload mass was 48, 213kg carried by boosters launched by NASA (CRS)
- Average payload mass was 2534.67kg carries by booster version F9 v1.1
- First successful landing on ground pad was 22-12-2015
- Boosters that had successful outcome on drone ship with payload mass greater that 4000 but less than 6000 are
 - F9 FT B1022
 - F9 FT B1026
 - F9 FT B1021.2
 - F9 FT B1031.2

EDA RESULTS WITH SQL

•There were 1 failure(inflight), 99 successful outcomes and 1 success (unclear payload status)

Mission_Outcome	total_number
Failure (in flight)	1
Success	98
Success	1
Success (payload status unclear)	1

[7]:	month	Date	Booster_Version	Launch_Site	Landing_Outcome
	5-	2015-10-01	F9 v1.1 B1012	CCAFS LC-40	Failure (drone ship)
	5-	2015-04-14	F9 v1.1 B1015	CCAFS LC-40	Failure (drone ship)

There were two failure outcomes in drone ship in 2015 with boosters
F9 v1.1 B1012
F9 v1.1 B1015

EDA RESULTS WITH SQL

EDA RESULTS WITH SQL

Booster_Version

F9 B5 B1048.4

F9 B5 B1049.4

F9 B5 B1051.3

F9 B5 B1056.4

F9 B5 B1048.5

F9 B5 B1051.4

F9 B5 B1049.5

F9 B5 B1060.2

F9 B5 B1058.3

F9 B5 B1051.6

F9 B5 B1060.3

F9 B5 B1049.7

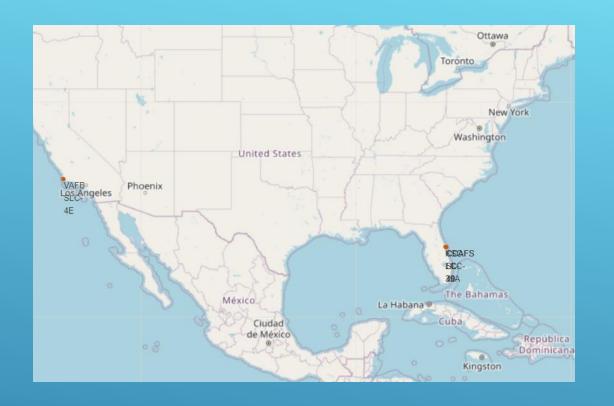
Booster Version carrying maximum payload mass



	Launch Site	Lat	Long	class
46	KSC LC-39A	28.573255	-80.646895	1
47	KSC LC-39A	28.573255	-80.646895	1
48	KSC LC-39A	28.573255	-80.646895	1
49	CCAFS SLC-40	28.563197	-80.576820	1
50	CCAFS SLC-40	28.563197	-80.576820	1
51	CCAFS SLC-40	28.563197	-80.576820	0
52	CCAFS SLC-40	28.563197	-80.576820	0
53	CCAFS SLC-40	28.563197	-80.576820	0
54	CCAFS SLC-40	28.563197	-80.576820	1
55	CCAFS SLC-40	28.563197	-80.576820	0

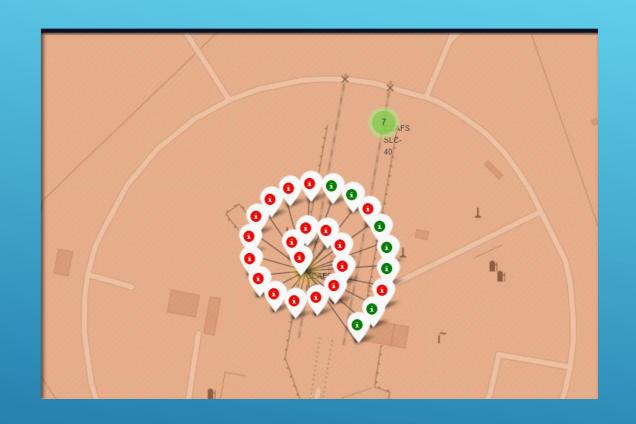
marker_color	class	Long	Lat	Launch Site	
green	1	-80.646895	28.573255	KSC LC-39A	46
green	1	-80.646895	28.573255	KSC LC-39A	47
green	1	-80.646895	28.573255	KSC LC-39A	48
green	1	-80.576820	28.563197	CCAFS SLC-40	49
green	1	-80.576820	28.563197	CCAFS SLC-40	50
red	0	-80.576820	28.563197	CCAFS SLC-40	51
red	0	-80.576820	28.563197	CCAFS SLC-40	52
red	0	-80.576820	28.563197	CCAFS SLC-40	53
green	1	-80.576820	28.563197	CCAFS SLC-40	54
red	0	-80.576820	28.563197	CCAFS SLC-40	55

INTERACTIVE MAP WITH FOLIUM



• The closer the launch site is to the equator, the easier it is to launch to equatorial orbit.

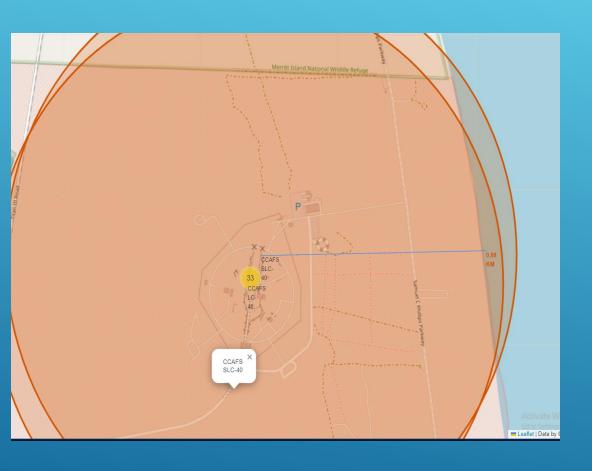
INTERACTIVE MAP WITH FOLIUM



- ► Green markers indicate a successful launch
- ▶ Red marker indicate that the launch was unsuccessful
- ► Launch site CCAFS SLC-40 had low success rates

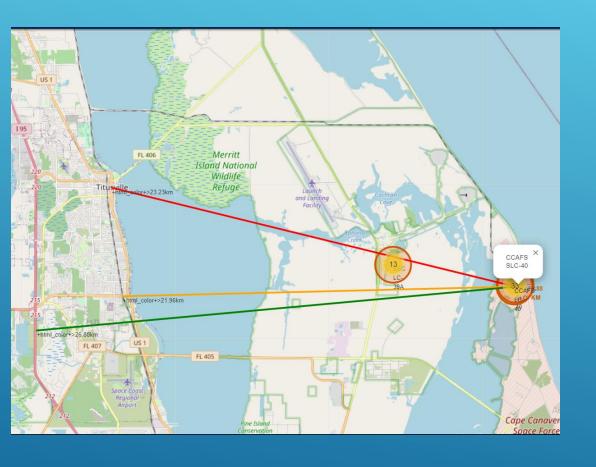
INTERACTIVE MAP WITH FOLIUM

INTERACTIVE MAP WITH FOLIUM



The distance from the launch site CCAFS-SLC-40 to the nearest coastline is 0.88km.

INTERACTIVE MAP WITH FOLIUM



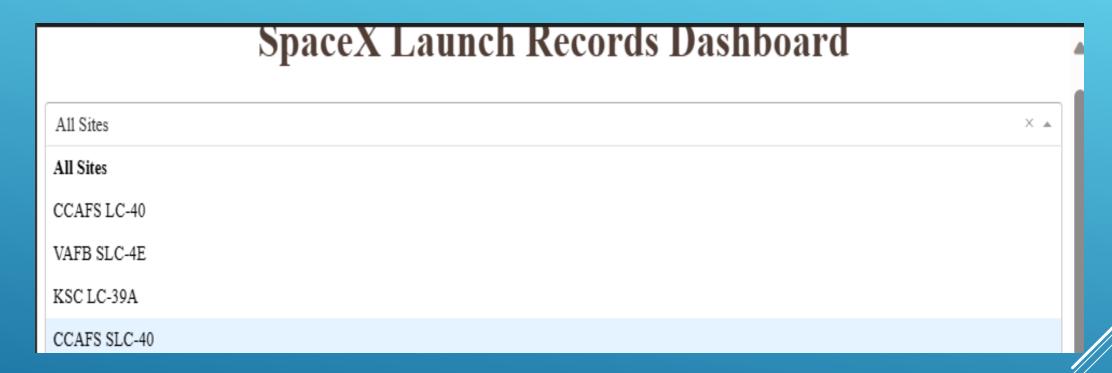
·CCAFS SLC-40

- .88KM to nearest coastline
- ·21.96km to nearest railway
- •23.3km to nearest city
- ·26.88km to nearest railway

Overall, the launch sites are closest to coastlines but farther away from cities, railways and highways.

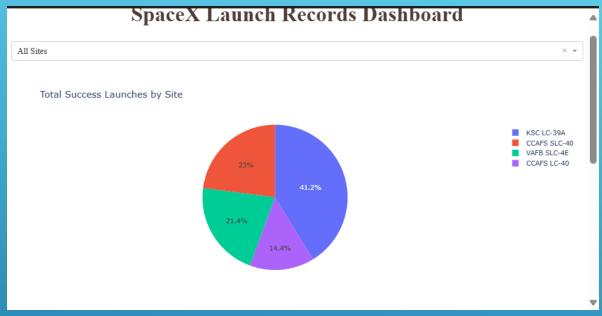
PLOTLY DASHBOARD

PLOTLY DASHBOARD RESULTS



A drop-down menu showing an option of whether to look at all site or individual site.

PLOTLY DASHBOARD RESULTS

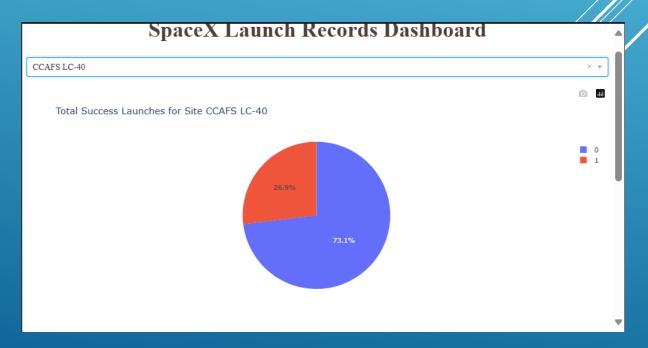


KSC LC-39A had the highest percentage of successful launches (76.9)

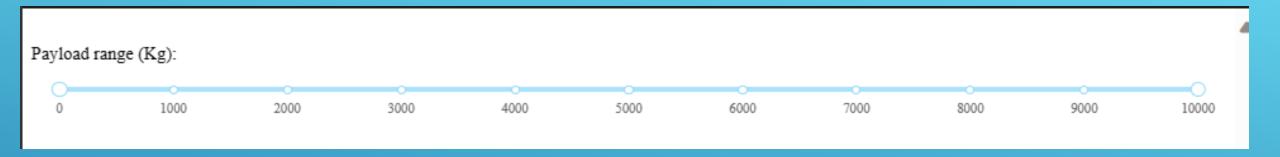
10 successful launches

3 failed launches

KSC LC-39A had the most successful launch having a 41.2%



PLOTLY DASHBOARD RESULTS



Payload masses between 2000kg and 5000kg had the highest success rate

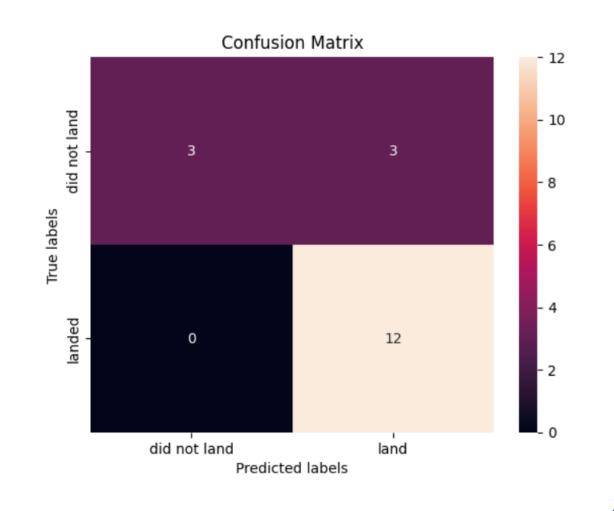


PREDICTIVE ANALYSIS

```
Best model is DecisionTree with a score of 0.9017857142857144

Best params is : {'criterion': 'gini', 'max_depth': 4, 'max_features': 'auto', 'min_samples_leaf': 2, 'min_samples_split': 10, 'splitter': 'random'}
```

The decision tree algorithm outperformed the other algorithms by a slightly smaller margin.



PREDICTIVE ANALYSIS

- ► Confusion matrix gives us an overview of the performance of any classification algorithm.
- ► The confusion matrix for all models were the same



Conclusions

- Launch success increased over time
- Flight number is may not necessarily be a factor that influences the success rates in orbits.
- · Payload masses between 2000kg and 5000kg had the highest success rate
- The decision tree algorithm outperformed the other algorithms by a slightly smaller margin.
- KSC LC-39A had the most successful launch having a 41.2%
- Launch sites are closest to coastlines but farther away from cities, railways and highways.