



Errors in
Concurrency

Walter Cazzola

Error
Handling
links
monitors

References

Errors in Concurrency

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Errors in Concurrent Programs

Error Handling on Exit

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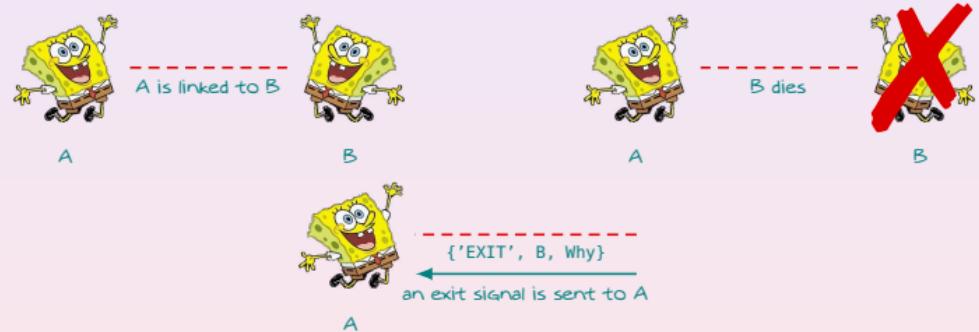
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When two processes are related

- the errors of one affect the behavior of the other process;
- the BIF link function helps to monitor.



If A is linked to B

- when B dies an exit signal is sent to A;
- the signal is a message like {"EXIT", Pid, ...}.





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```
-module(dies).
-export([on_exit/2]).

on_exit(Pid, Fun) ->
    spawn(fun() ->
        process_flag(trap_exit, true),
        link(Pid),
        receive
            {'EXIT', Pid, Why} -> Fun(Why)
        end
    end).
```

```
1> F = fun() -> receive X -> list_to_atom(X) end end.
#Fun<erl_eval.20.67289768>
2> Pid = spawn(F).
<0.35.0>
3> dies:on_exit(Pid, fun(Why) -> io:format("~p died with:-p~n",[Pid, Why]) end).
<0.37.0>
4> Pid ! hello.
<0.35.0> died with:{badarg,[{erlang,list_to_atom,[hello]}]}

=ERROR REPORT==== 9-Nov-2011::17:50:20 ===
Error in process <0.35.0> with exit value:  badarg,[{erlang,list_to_atom,[hello]}]
hello
```





Errors in Concurrent Programs

Details of Error Handling

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Links

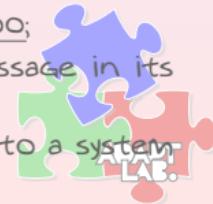
- defines an error propagation path between two processes;
- if a process dies an exit signal is sent to the other process;
- the set of processes linked to a given process is called link set.

Exit Signals

- they are generated by a process when it dies;
- signals are broadcast to all processes in the link set of the dying process;
- the exit signal contains an argument explaining why the process died (**exit(Reason)** or implicitly set).
- when a process “naturally dies” the exit reason is normal;
- exit signals can be explicitly sent via **exit(Pid, X)**: the sender does not die (“fake death”).

System Processes

- a non system process that receives a exit signal dies too;
- a system process receives the signal as a normal message in its mailbox;
- **process_flag(trap_exit, true)** transform a process into a system process.





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Details of Error Handling (Cont'd)

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Receiver's Behavior

trap_exit	Exit Signal	Action
true	kill	dies ≠ Broadcasts it to its link set
true	X	adds {'EXIT', Pid, X} to the mailbox
false	normal	continues ≠ the signal vanishes
false	kill	dies ≠ Broadcasts it to its link set
false	X	dies ≠ Broadcasts it to its link set

Privileged (System process)

Alternatives

- I don't care if a process I create crashes.
`Pid = spawn(fun() -> ... end)`
- I want to die if a process I create crashes.
`Pid = spawn_link(fun() -> ... end)`
- I want to handle errors if a process I create crashes
`process_flag(trap_exits, true),
Pid = spawn_link(fun() -> ... end).`





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Going into Details of Error Handling

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```
-module(edemo1).
-export([start/2]).

start(Bool, M) ->
    A = spawn(fun() -> a() end),
    B = spawn(fun() -> b(A, Bool) end),
    C = spawn(fun() -> c(B, M) end),
    sleep(1000), status(b, B), status(c, C).

a() -> process_flag(trap_exit, true), wait(a).
b(A, Bool) -> process_flag(trap_exit, Bool), link(A), wait(b).
c(B, M) -> link(B),
    case M of
        {die, Reason} -> exit(Reason);
        {divide, N} -> 1/N, wait(c);
        normal -> true
    end.
```

This starts 3 processes: A, B and C

- A will trap exits and watch for exits from B;
- B will trap exits if Bool is true and
- C will die with exit reason M.





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```
wait(Prog) ->
    receive
        Any ->
            io:format("Process ~p received ~p~n", [Prog, Any]),
            wait(Prog)
    end.

sleep(T) ->
    receive
        after T -> true
    end.

status(Name, Pid) ->
    case erlang:is_process_alive(Pid) of
        true -> io:format("process ~p (~p) is alive~n", [Name, Pid]);
        false -> io:format("process ~p (~p) is dead~n", [Name, Pid])
    end.
```

This starts 3 processes: A, B and C

- wait/1 just prints any message it receives;
- sleep/1 awakes the invoking process after a period of time;
- status/2 prints the aliveness of the invoking process.





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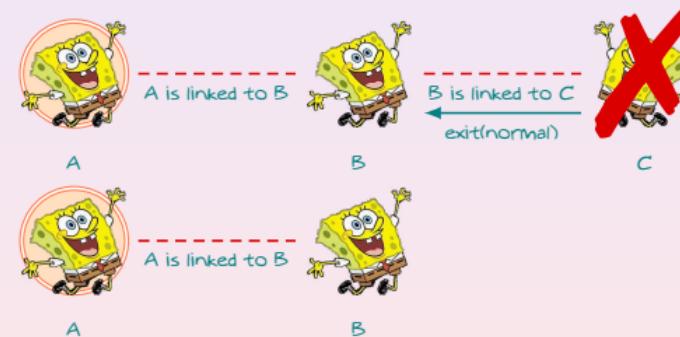
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References

```
1> edemol:start(false, {die,normal}).  
process b (<0.48.0>) is alive  
process c (<0.49.0>) is dead  
ok
```



- B is not a system process;
- when C dies with normal signal, B doesn't die.





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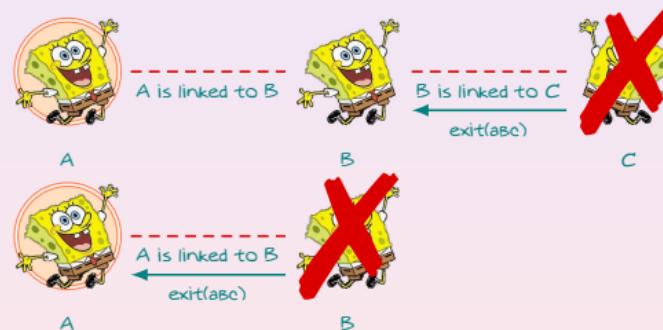
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References

```
1> edemo1:start(false, {die, abc}).  
Process a received {'EXIT',<0.40.0>,abc}  
process b (<0.40.0>) is dead  
process c (<0.41.0>) is dead  
ok
```



- B is not a system process;
- when C evaluates **exit(abc)**, process B dies;
- when B exits rebroadcasts the unmodified exit signal to its link set
- A traps the exit signal and convert it to the error message





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Going into Details of Error Handling (Cont'd)

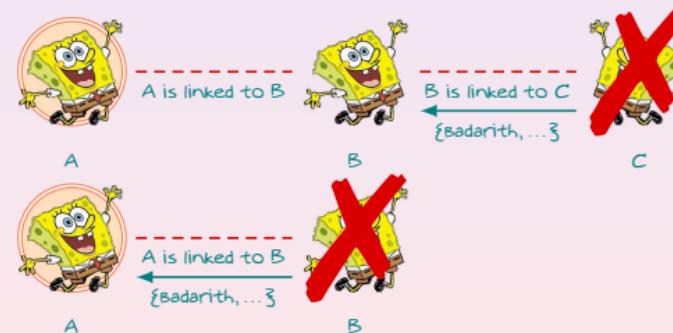
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```
6> edemol:start(false, {divide,0}).  
Process a received {'EXIT',<0.56.0>,{badarith,[{edemol,c,2}]}}  
=ERROR REPORT==== 11-Nov-2011::18:03:29 ===  
Error in process <0.57.0> with exit value: {badarith,[{edemol,c,2}]}  
process b (<0.56.0>) is dead  
process c (<0.57.0>) is dead  
ok
```



- B is not a system process;
- when C tries to divide by zero an error occurs and C dies with a `{badarith, ...}` error;
- B receives this and dies and the error is propagated to A.





Errors in Concurrent Programs

Going into Details of Error Handling (Cont'd)

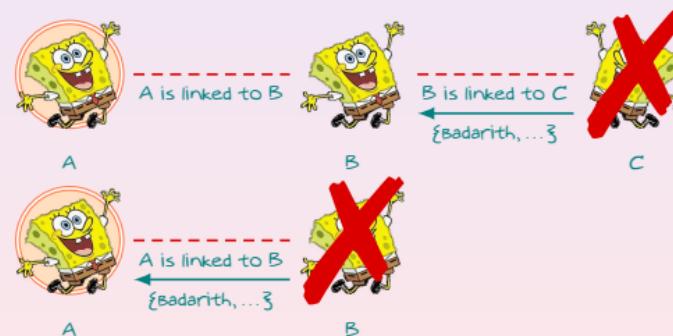
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```
6> edemo1:start(false, {divide,0}).  
Process a received {'EXIT',<0.56.0>,{badarith,[{edemo1,c,2}]}}  
=ERROR REPORT==== 11-Nov-2011::18:03:29 ===  
Error in process <0.57.0> with exit value: {badarith,[{edemo1,c,2}]}  
process b (<0.56.0>) is dead  
process c (<0.57.0>) is dead  
ok
```



- B is not a system process;
- when C tries to divide by zero an error occurs and C dies with a `{badarith, ...}` error;
- B receives this and dies and the error is propagated to A.



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Going into Details of Error Handling (Cont'd)

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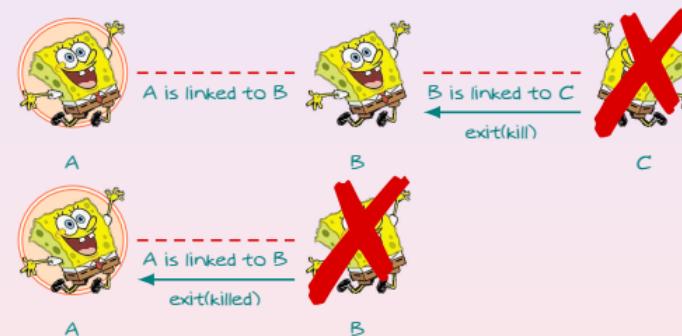
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```
1> edemo1:start(false, {die, kill}).  
Process a received {'EXIT',<0.60.0>,killed}  
process b (<0.60.0>) is dead  
process c (<0.61.0>) is dead  
ok
```



- B is not a system process;
- the exit reason kill causes B to die, and the error is propagated to its link set.





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Going into Details of Error Handling (Cont'd)

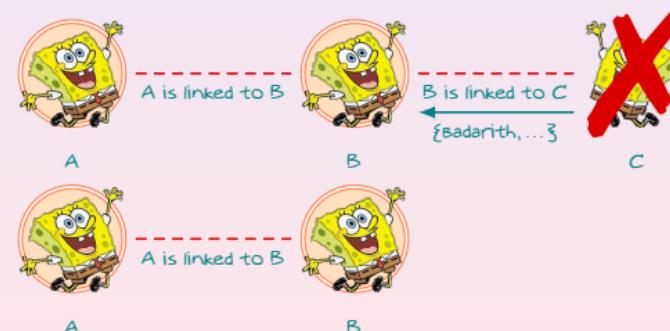
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```
8> edemo1:start(true, {divide,0}).  
Process b received {'EXIT',<0.65.0>,{badarith,[{edemo1,c,2}]} }  
=ERROR REPORT==== 11-Nov-2011::18:16:47 ===  
Error in process <0.65.0> with exit value: {badarith,[{edemo1,c,2}]}  
process b (<0.64.0>) is alive  
process c (<0.65.0>) is dead  
ok
```



- B is a system process;
- in all cases, B traps the error;
- the error is never propagated to A.





Errors in Concurrent Programs

Monitors: Unidirectional Links

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Links are **symmetric**

- i.e., if A dies, B will sent an exit signal and vice versa;
- to prevent a process from dying, we have to make it a system process that is not alway desirable.

A monitor is an **asymmetric link**

- if A monitors B and B dies A will be sent an exit signal but
- if A dies B **will not** be sent a signal.

A can create a monitor for B calling erlang:monitor(process, B)

- if B dies with exit reason Reason a 'DOWN' message

{'DOWN', Ref, process, B, Reason}

is sent to A (Ref is the reference to the monitor).

- the monitor is unidirectional:

- to repeat the above call will create several, independent monitors and each one will send a 'DOWN' message when B terminates.





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References

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