

# Image Processing in the Frequency Domain

**Pengolahan Citra**

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Laksmi Rahadiani, Aniati Murni

Fakultas Ilmu Komputer Universitas Indonesia

# Basic Concepts

Richard G. Lyons (2011). *Understanding Digital Signal Processing, 3<sup>rd</sup> edition*. Prentice Hall.

Allen B. Downey (2016). *Think DSP: Digital Signal Processing in Python*. O'Reilly Media.

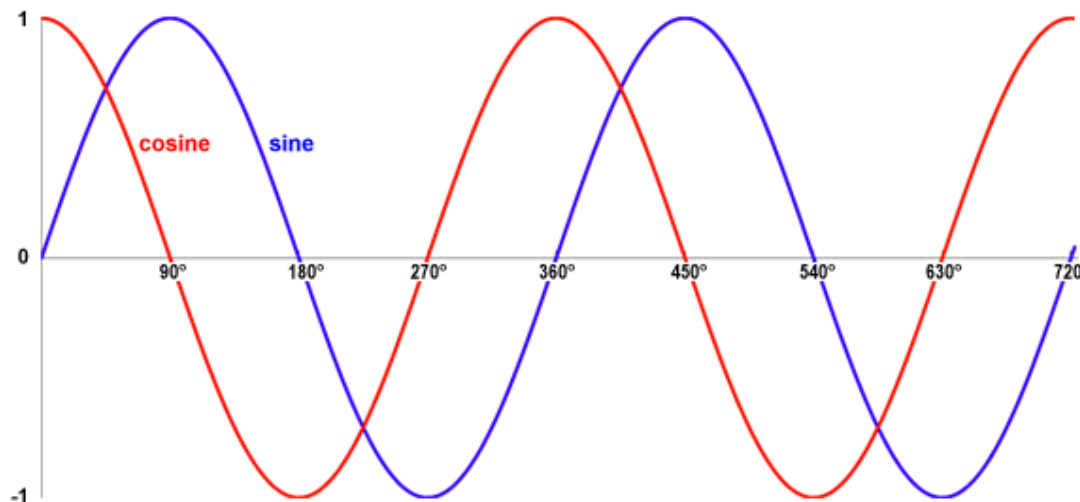
# History

- Jean Baptiste Joseph Fourier (1768-1830)
  - Ahli matematika dan fisika dari Perancis
- Memulai penelitian mengenai *fourier series*
  - Dikembangkan menjadi *fourier transform* dan *fourier law*
- “*Théorie analytique de la chaleur (The Analytical Theory of Heat)*”
  - Fourier series untuk transfer kalor dan getaran
  - Greenhouse effect

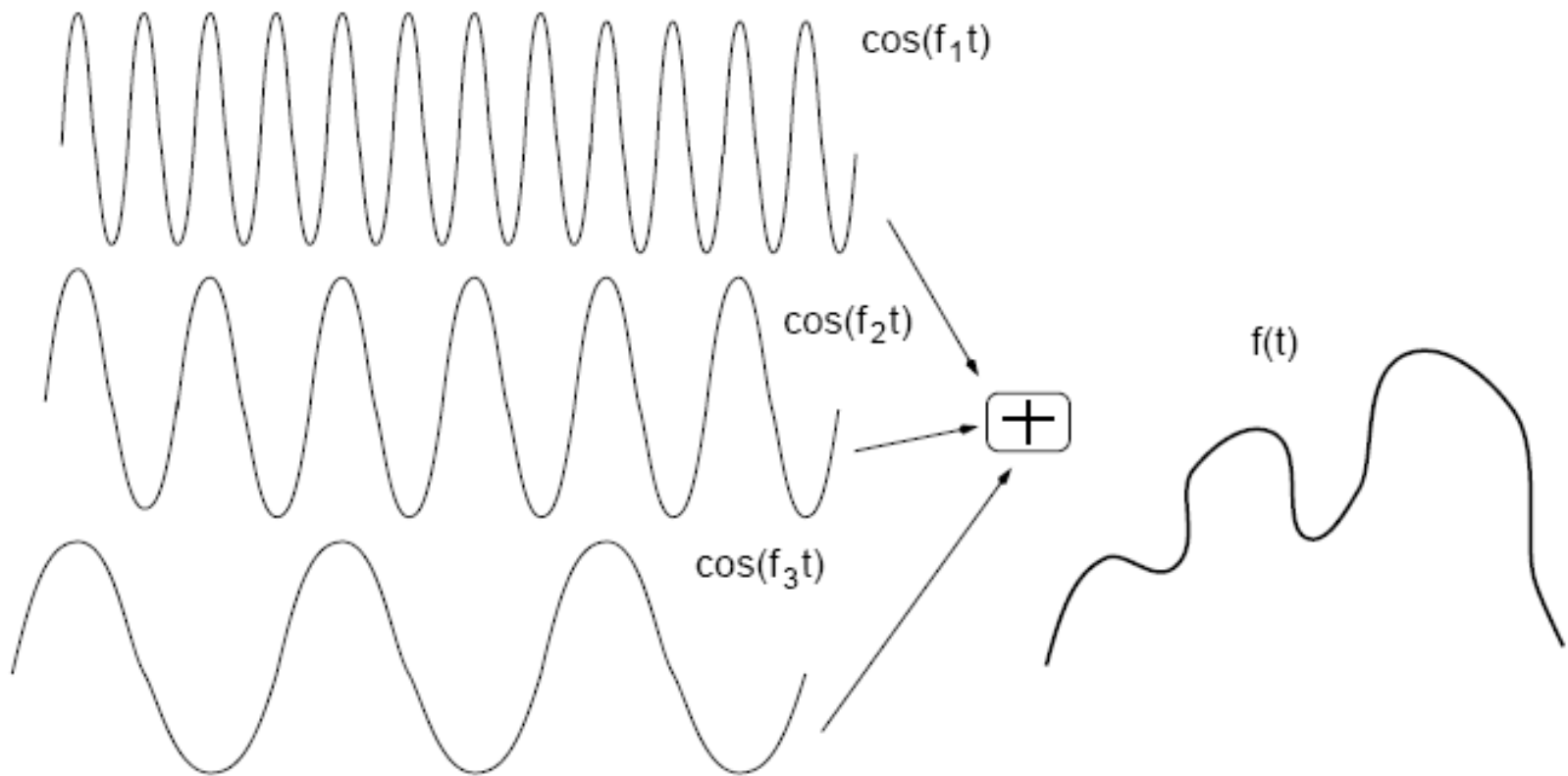
# Sekilas tentang Seri Fourier

*“Fungsi periodik manapun dapat dinyatakan sebagai jumlahan dari fungsi-fungsi sinus dan/atau kosinus.”*

- Fungsi Periodik:
  - Fungsi yang berulang pada interval tertentu.
- Fungsi sinus/kosinus



# Visualisasi Seri Fourier



# Seri Fourier

- Untuk suatu fungsi  $f(t)$  pada variabel kontinu  $t$  yang periodik dengan periode  $T$ .

$$f(t) = \sum_{n=-\infty}^{\infty} c_n e^{j\frac{2\pi n}{T}t}$$

- $c_n$  adalah koefisien pemberat untuk setiap fungsi sinus / cosinus, di mana

$$c_n = \frac{1}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} f(t) e^{-j\frac{2\pi n}{T}t} dt, \quad \text{for } n = 0, \pm 1, \pm 2, \dots$$

# The Fourier Transform

- Fungsi dapat dinyatakan sebagai integral dari fungsi sin dan/atau cosinus yang dikalikan dengan suatu fungsi pemberat (*weighting function*).
  - Tidak harus periodikpun, asalkan area di bawah kurjanya berhingga.

Fourier Transform gives us these weights.

- Poin penting!
  - Seri dan transformasi fourier dapat dikembalikan ke bentuk asal menggunakan suatu proses inverse

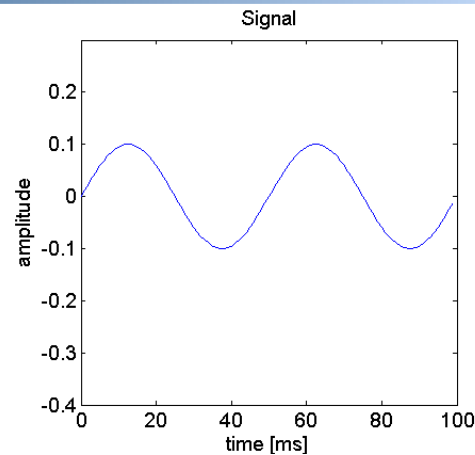
# Fourier Transform

- Another way to look at it:

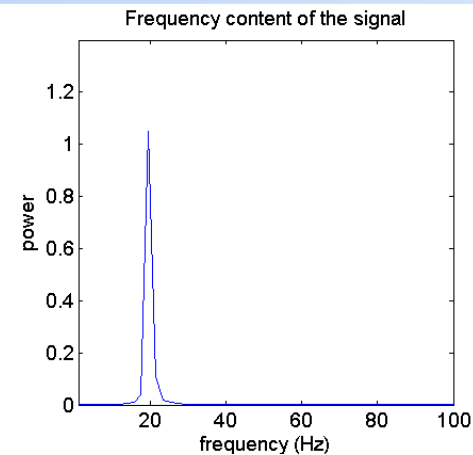
Fourier Transform transforms signal from Time domain to Frequency domain.



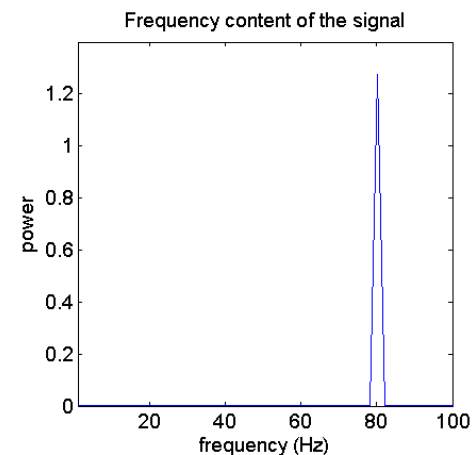
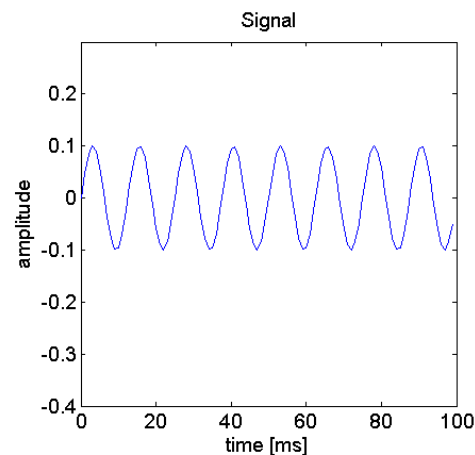
# Time to Frequency Domain



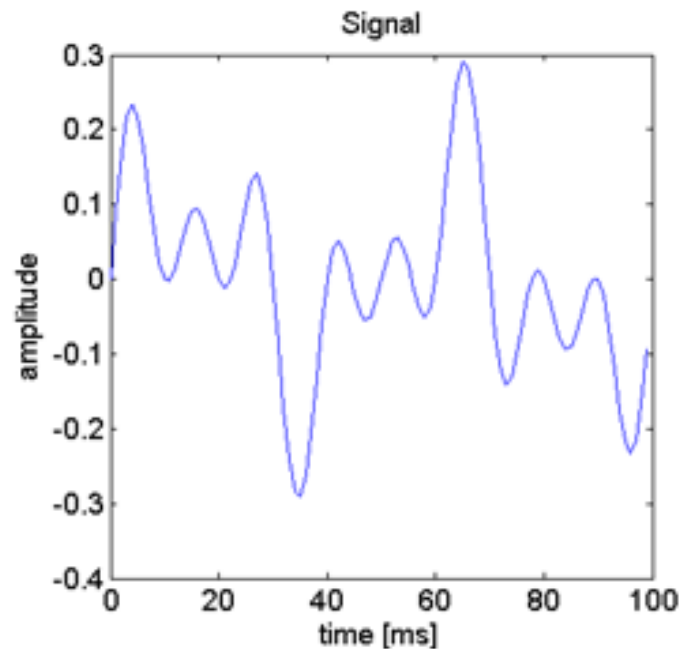
time domain



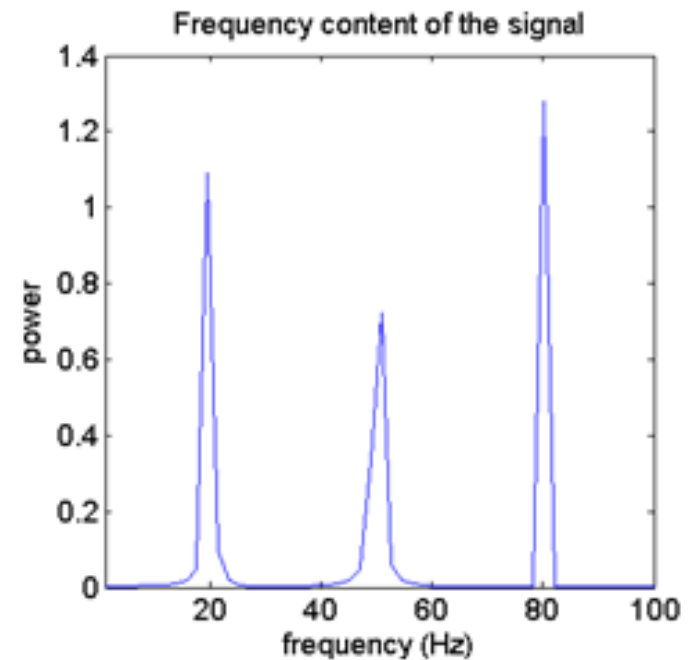
frequency domain



# Time to Frequency Domain (2)



time domain



frequency domain

# Fungsi Impulse

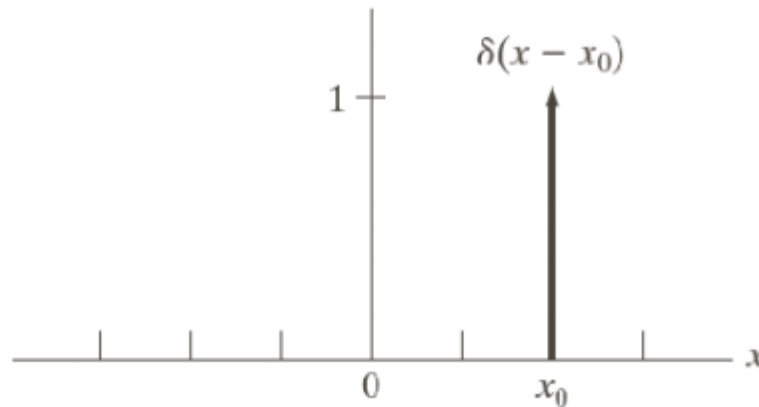
- The Dirac delta function, or  $\delta(t)$  function, is zero for all values of  $t$  except when the  $t$  is equal to zero, and its integral over the parameter from  $-\infty$  to  $\infty$  is equal to one

$$\delta(t) = \begin{cases} \infty & t = 0 \\ 0 & t \neq 0 \end{cases}$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

# Fungsi Impulse (2)

- Generalized, we can define any discrete impulse where  $\delta$  is zero everywhere except at  $x = x_0$



# Complex Numbers

$$C = R + jI$$

- Where  $R$  and  $I$  are real numbers,  $j$  is an imaginary number equal to the square of -1.
  - $R$  denotes the *real part* of the complex number
  - $I$  denotes the *imaginary part* of the complex number
- Can be plotted geometrically on a complex plane as a point  $(R, I)$ 
  - The x-axis or the *real axis* for all the real values of the complex number
  - The y-axis or the *imaginary axis* for all the imaginary values of the complex number

# The Derivation of Fourier Transform

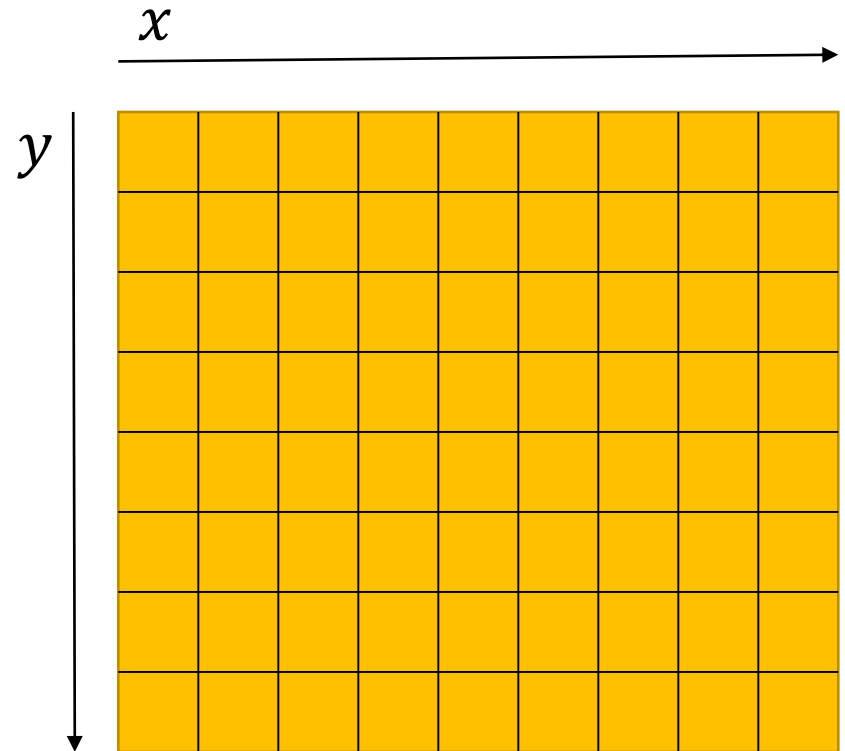
- Gonzales & Woods, Digital Image Processing, section 4.2-4.5.
  - Please read if you are interested
  - Not covered in this class
- We are more interested how we can use it for image processing.

# Fourier Transform

Rahat Khan (2010). CIMET Course Slides. Laboratory Hurbert Curien, Universite Jean Monnet Saint Etienne.

# Fourier Transform on Digital Images

- Discrete Values
- We need discrete fourier transform





# 1D Discrete Fourier Transform

Forward DFT 
$$F(u) = \frac{1}{N} \sum_{x=0}^{N-1} f(x) e^{j \frac{2\pi ux}{N}}, \quad u = 0, 1, \dots, N-1$$

Inverse DFT 
$$f(x) = \sum_{u=0}^{N-1} F(u) e^{j \frac{2\pi ux}{N}}, \quad x = 0, 1, \dots, N-1$$

# 1D Discrete Fourier Transform Process

$$F(u) = \frac{1}{N} \sum_{x=0}^{N-1} f(x) e^{j2\pi ux/N} = \frac{1}{N} \sum_{x=0}^{N-1} f(x) \left( \cos \frac{2\pi ux}{N} + j \sin \frac{2\pi ux}{N} \right)$$

$$e^{\pm j\theta} = \cos \theta \pm j \sin \theta$$

Start

$u_1 = \text{some value}$

$f(x) * e^{\frac{-j2\pi ux}{N}}$

Sum up

Divide by N

$F(u) = x \pm iy$

increment  $u_n$

No

Last  $u_n$ ?

Yes

End

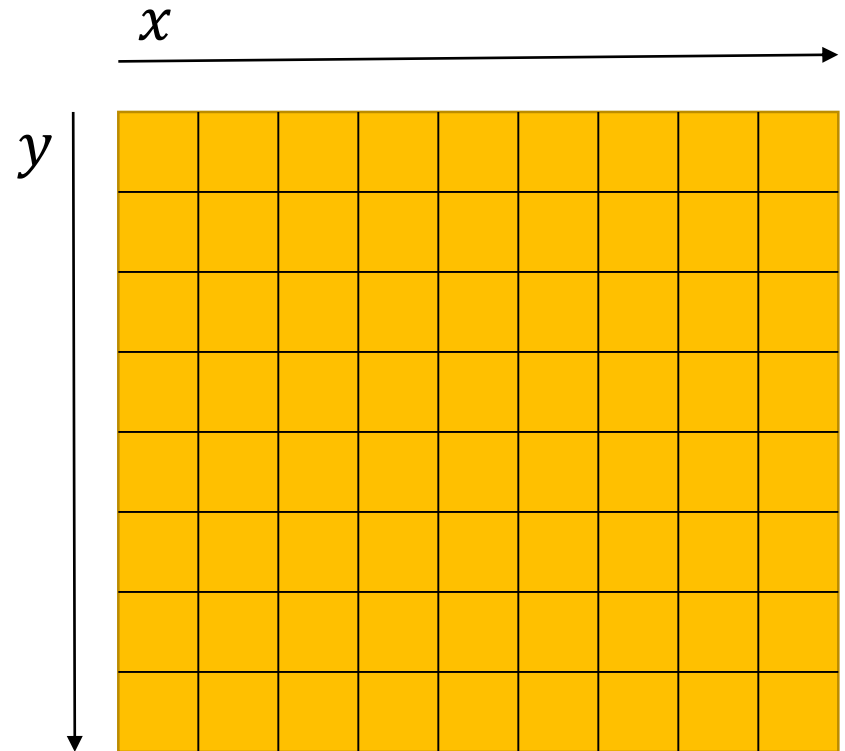
# Properties of the Fourier Transform

$$F(u) = \frac{1}{N} \sum_{x=0}^{N-1} f(x) \cos \frac{2\pi ux}{N} - \frac{1}{N} \sum_{x=0}^{N-1} f(x)j \sin \frac{2\pi ux}{N}$$

- **F(u)** is a complex function:  $F(u) = R(u) + jI(u)$
- Magnitude of FT (spectrum):  $|F(u)| = \sqrt{R^2(u) + I^2(u)}$
- Phase of FT:  $\phi(F(u)) = \tan^{-1}\left(\frac{I(u)}{R(u)}\right)$
- Power of  $f(x)$ :  $\mathbf{P(u)} = |F(u)|^2 = R^2(u) + I^2(u)$

# Fourier Transform on Digital Images

- Images have 2 dimensions,  $x$ , and  $y$ .
- We must apply the 1D fourier transform in both directions



# 2D Discrete Fourier Transform (DFT)

- Assume that  $f(x,y)$  is  $M \times N$  image.

Forward DFT

$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(\frac{ux}{M} + \frac{vy}{N})}$$

$$u = 0, 1, \dots, M-1, v = 0, 1, 2, \dots, N-1$$

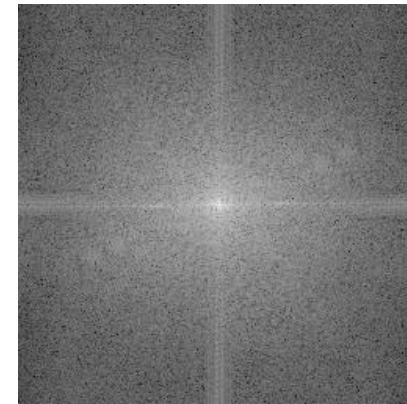
Inverse DFT

$$f(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{-j2\pi(\frac{ux}{M} + \frac{vy}{N})}$$

$$x = 0, 1, \dots, M-1, y = 0, 1, 2, \dots, N-1$$

# 2D DFT (2)

$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(\frac{ux}{M} + \frac{vy}{N})}$$



$f(x, y)$

$|F(u, v)|$

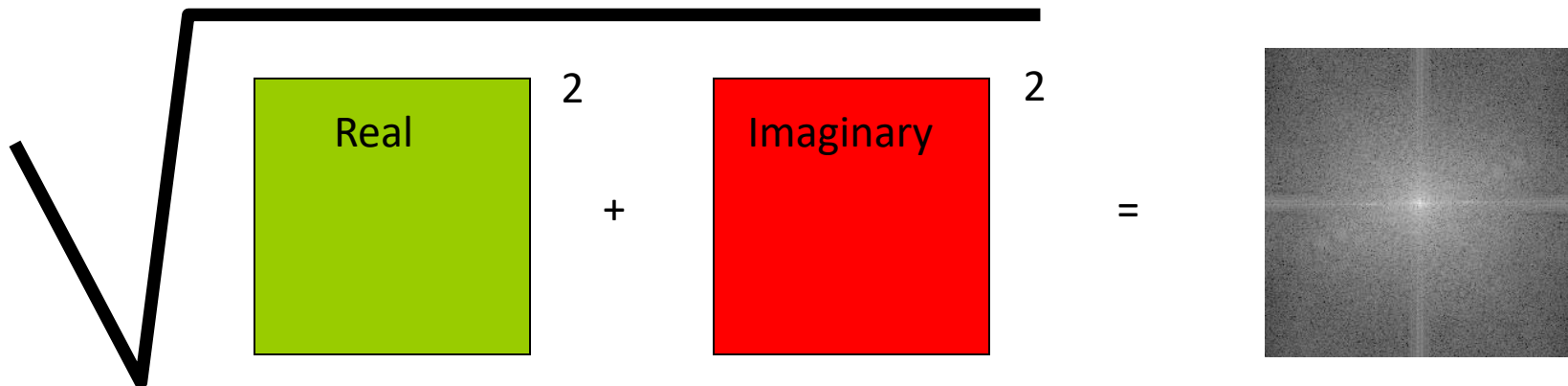
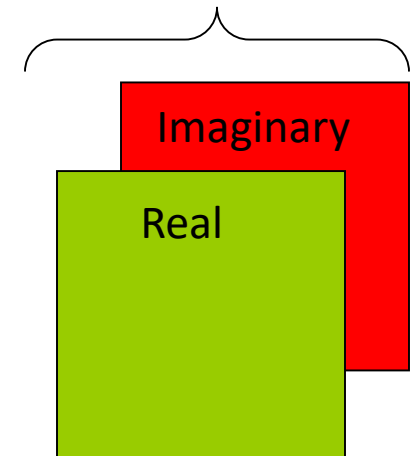
Identical in Size!

# 2D DFT (3)



$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(\frac{ux}{M} + \frac{vy}{N})}$$

complex valued matrix



# Real and Imaginary Results of DFT

$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(\frac{ux}{M} + \frac{vy}{N})}$$

M=N=64 (image size), u=6 AND v=6 (index)



Real Part



Imaginary Part

**These are known as Fourier Basis functions**

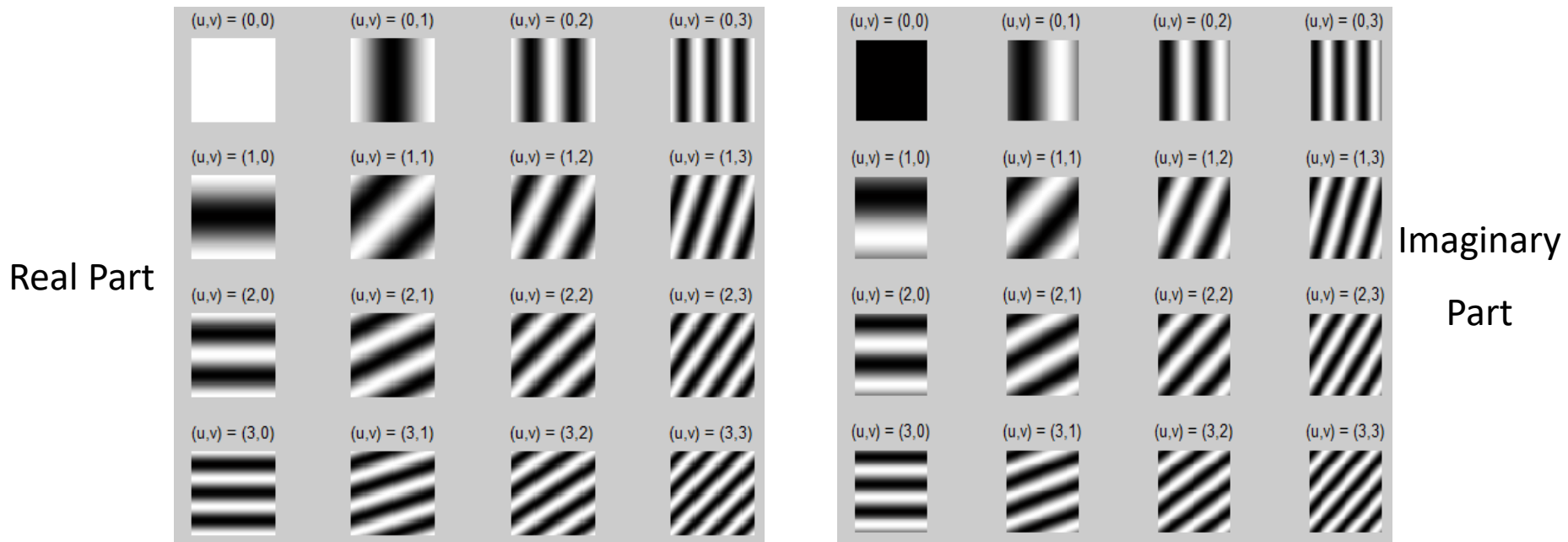


# Fourier Basis Functions



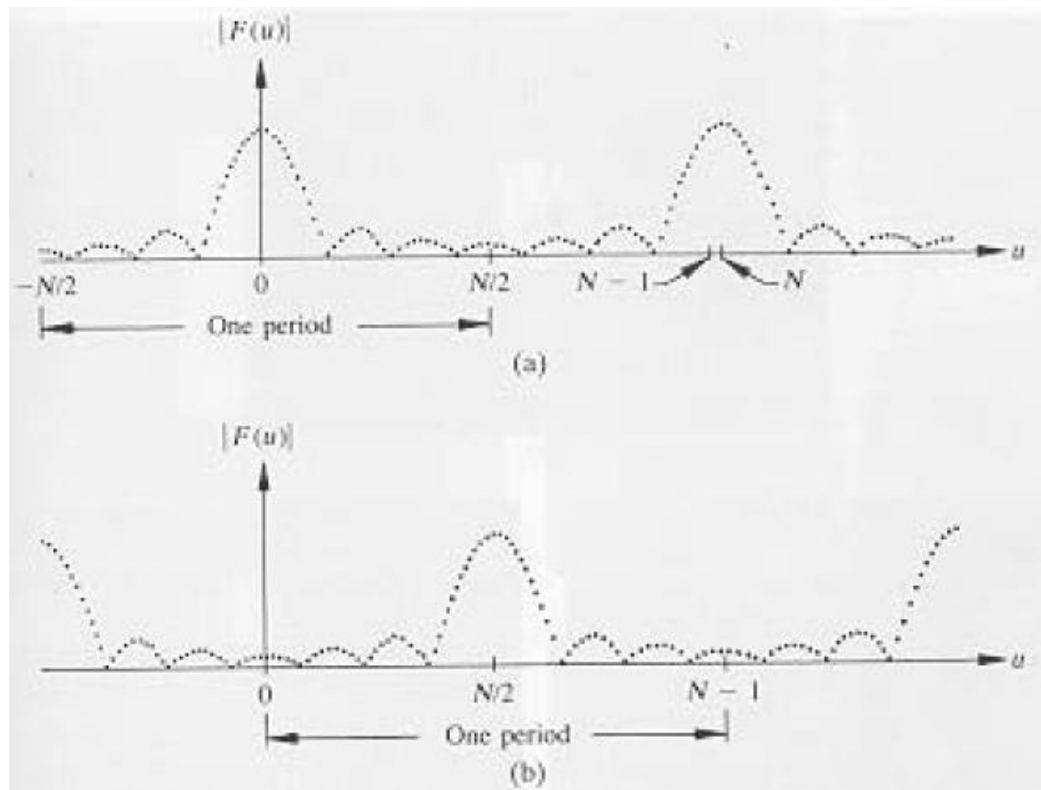
# Fourier Basis Functions (2)

- In this example, we used a 64 X 64 image.
- The Fourier transform result has the same size.
- Thus, we have  $64 \times 64 = 4096$  complex basis functions for this size of images.



# Visualizing 2D DFT – Shifting

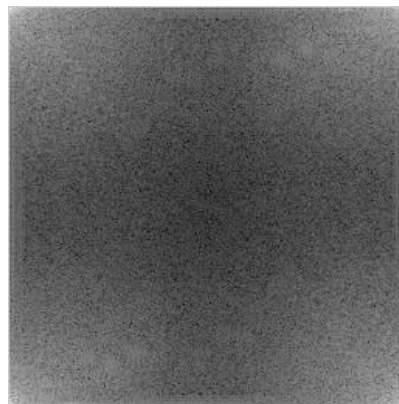
- A Fourier Transform is well visualized with the Zero Frequency component in the center  $N/2$  ( $N/2, N/2$  in case of 2D)



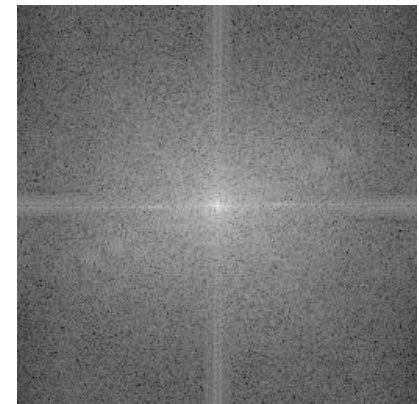
# Visualizing 2D DFT – Shifting (2)



original image



before shifting



after shifting

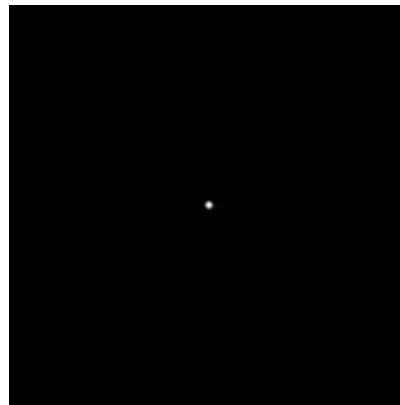
# Visualizing 2D DFT - Scaling

- The Dynamic range of Fourier spectra usually is much higher than the typical display device is able to reproduce faithfully. Therefore, we often use the logarithm function to perform the appropriate compression of the range.

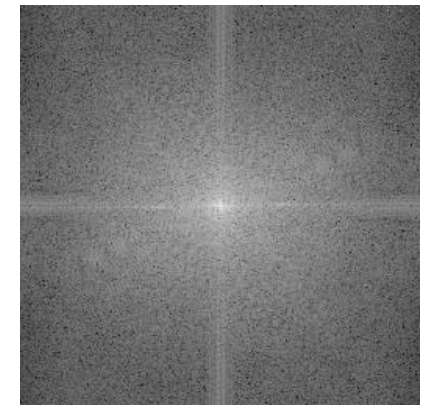
$$D(u, v) = c \log(1 + |F(u, v)|)$$



original image



before scaling

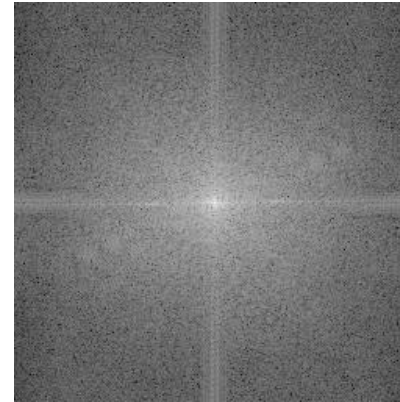


after scaling

# Visualizing 2D DFT



original image



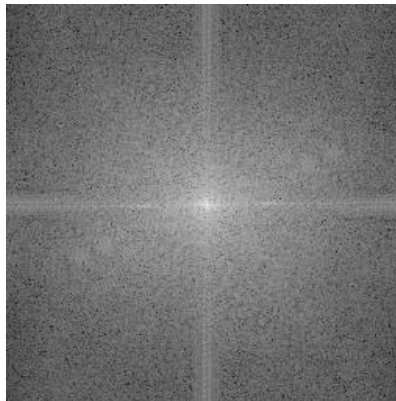
after scaling

```
F = fft2( f );  
imshow ( log (abs ( fftshift ( F ) ) + 1), [ ] )
```

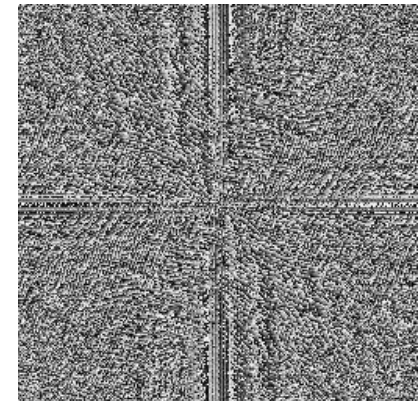
# Visualizing 2D DFT (3)



$f(x, y)$



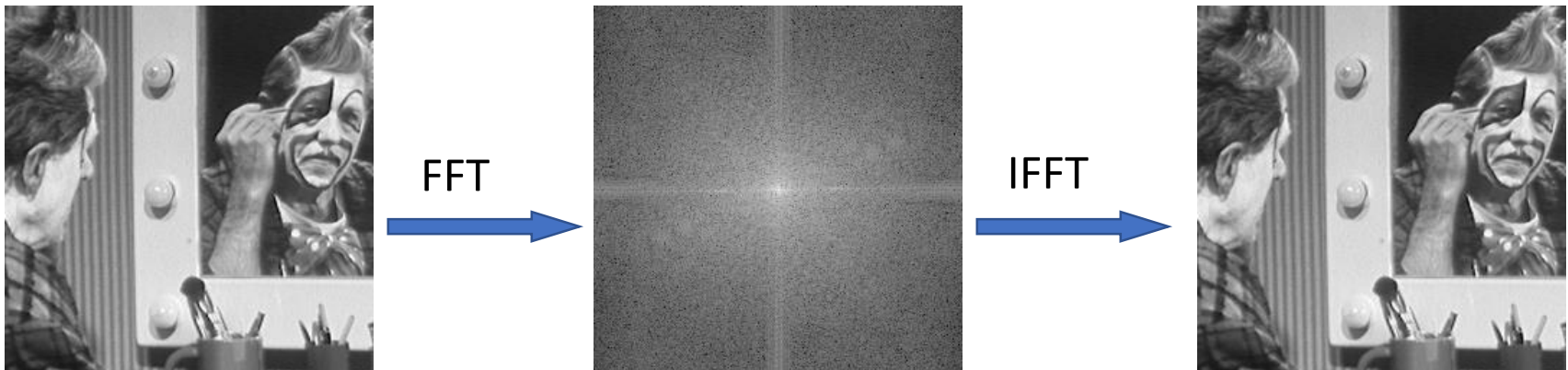
Magnitude  
 $|F(u, v)|$



Phase  
 $\Phi(F(u, v))$

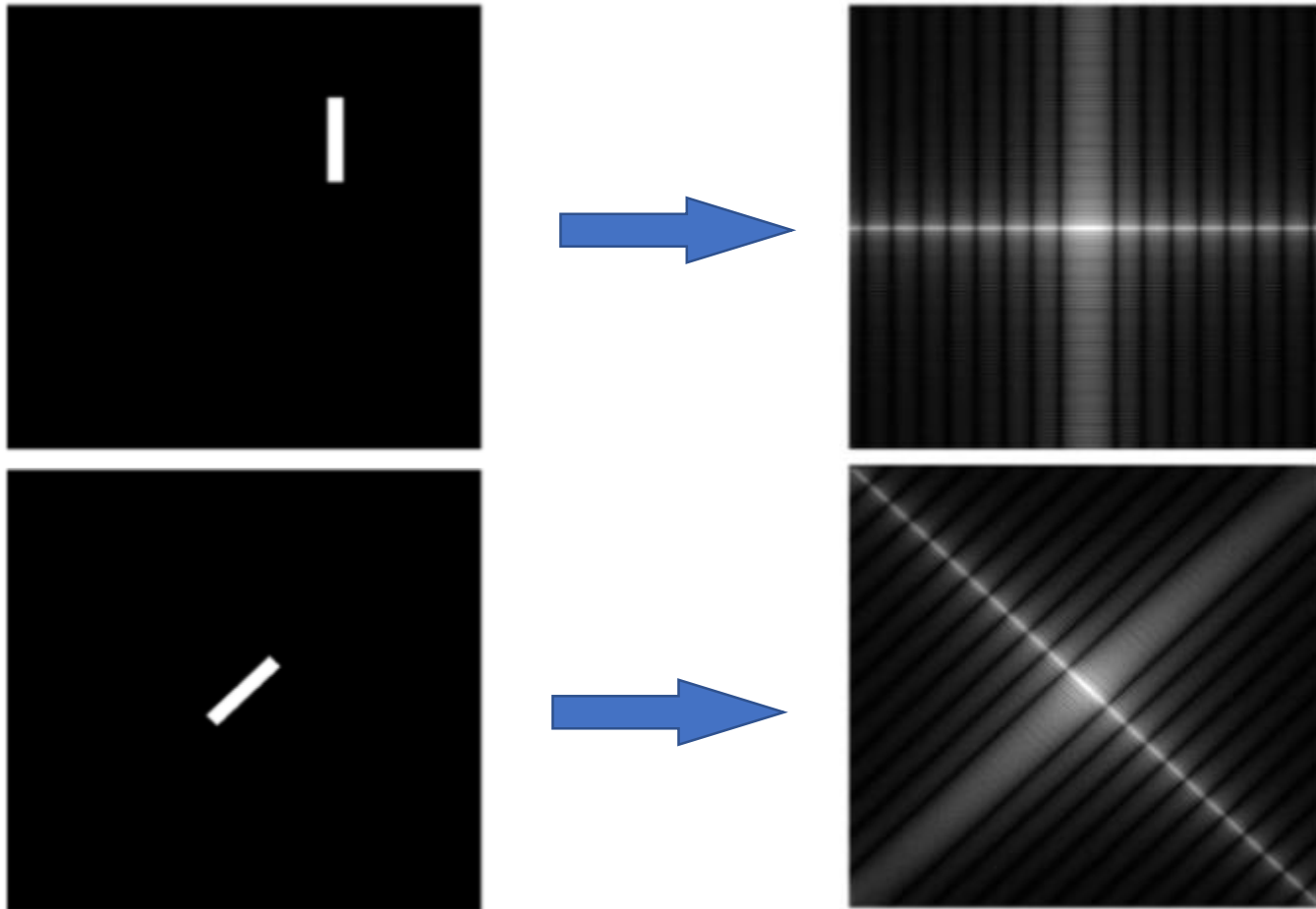
# Inverse Fourier Transform

- Seri dan transformasi fourier dapat dikembalikan ke bentuk asal menggunakan suatu proses inverse
- Memudahkan untuk pindah domain, mengerjakan frequency processing, lalu kembali ke asal

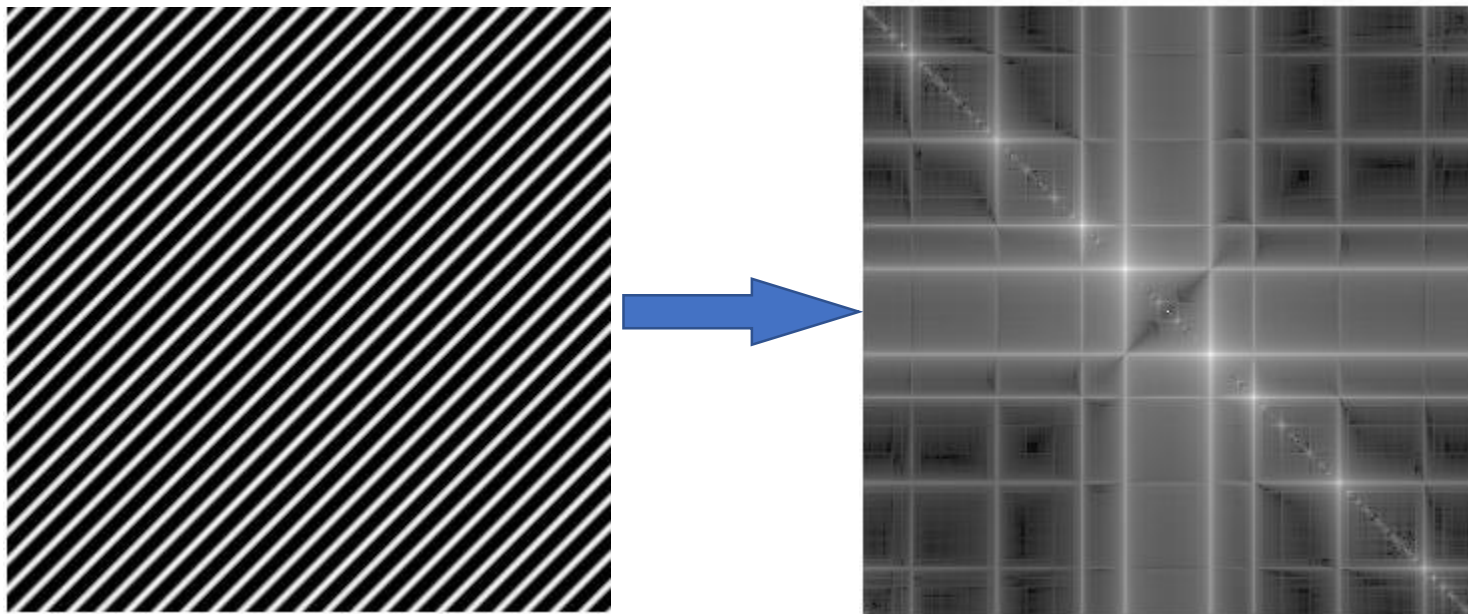




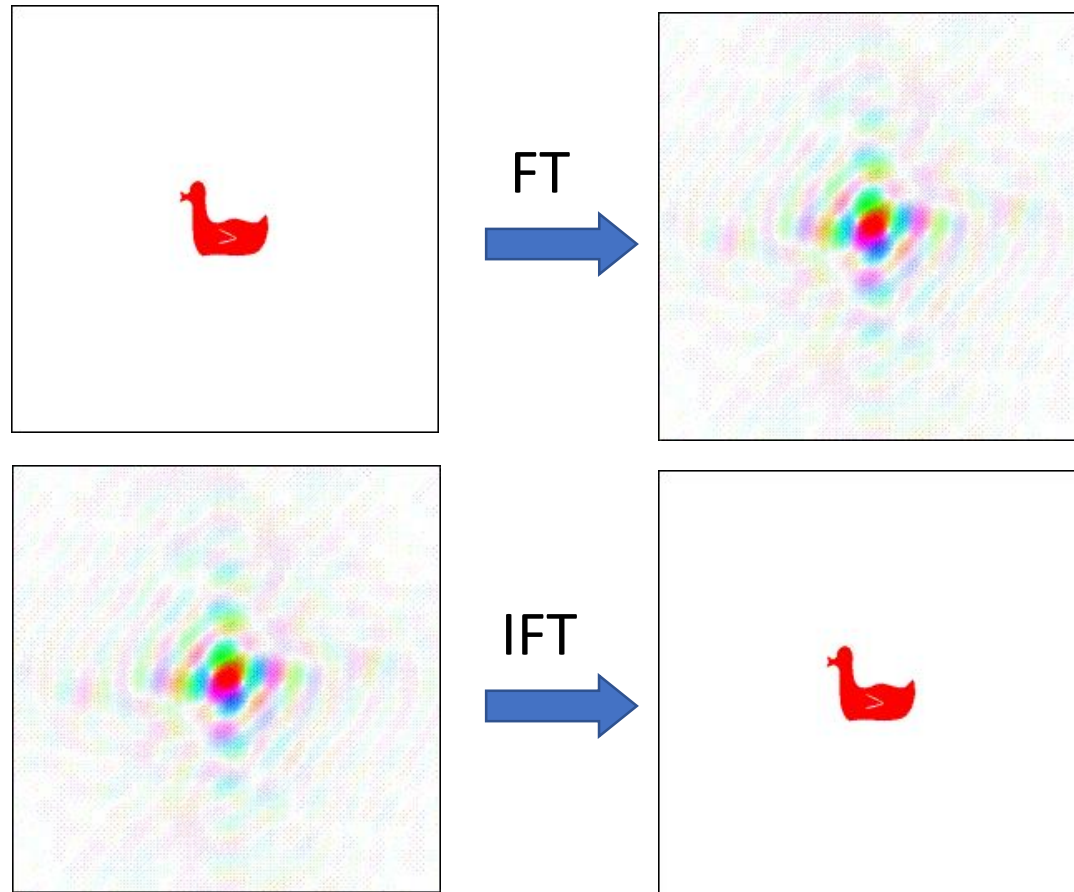
# Fourier Transform of Basic Shapes

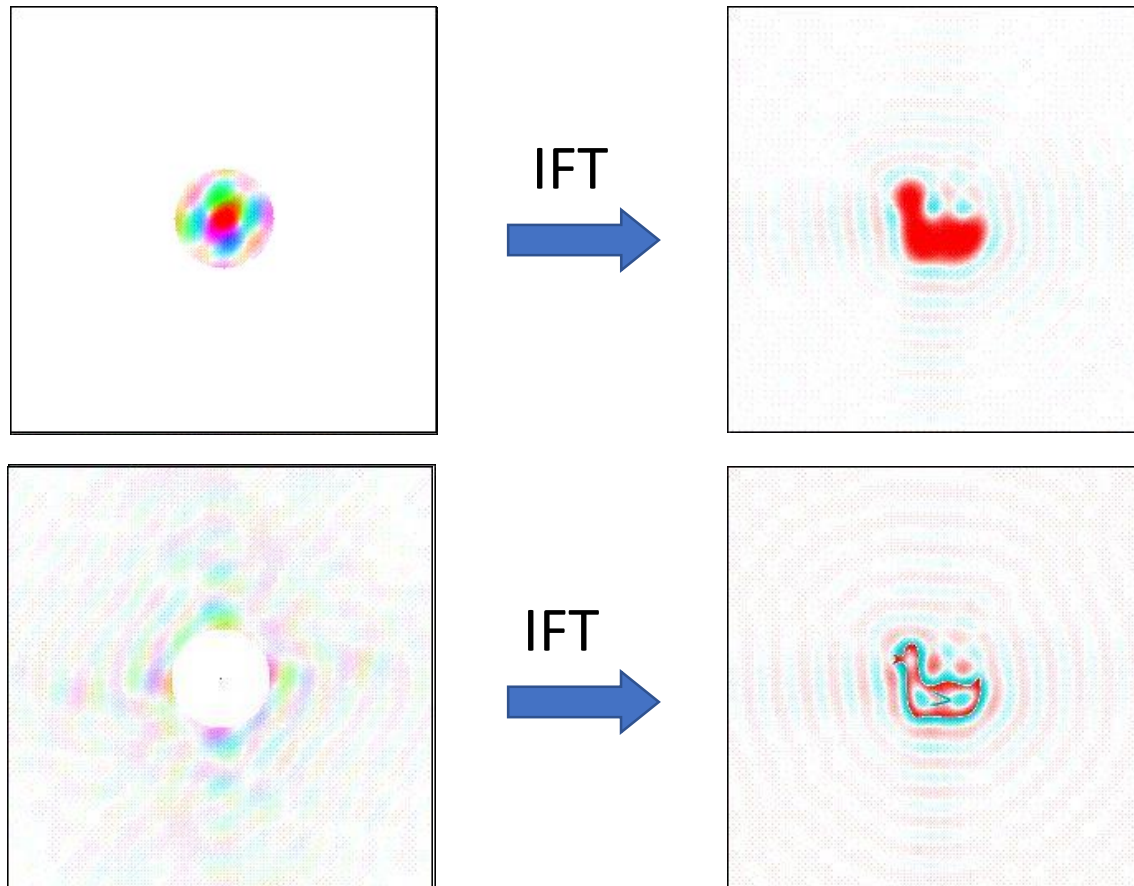


# Fourier Transform of an Image with a Specific Frequency

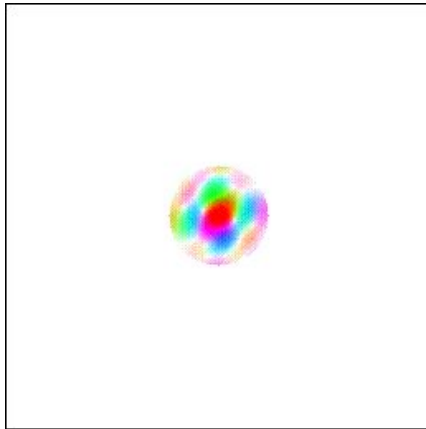


# Some Applications

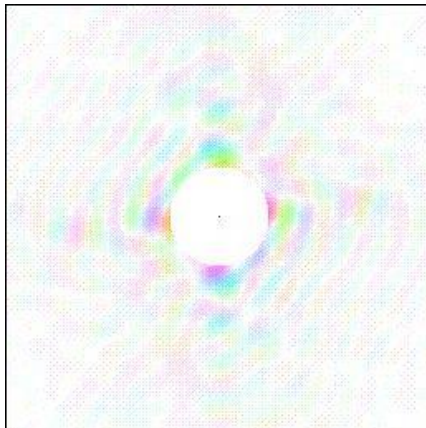




# Different Frequencies in the FT



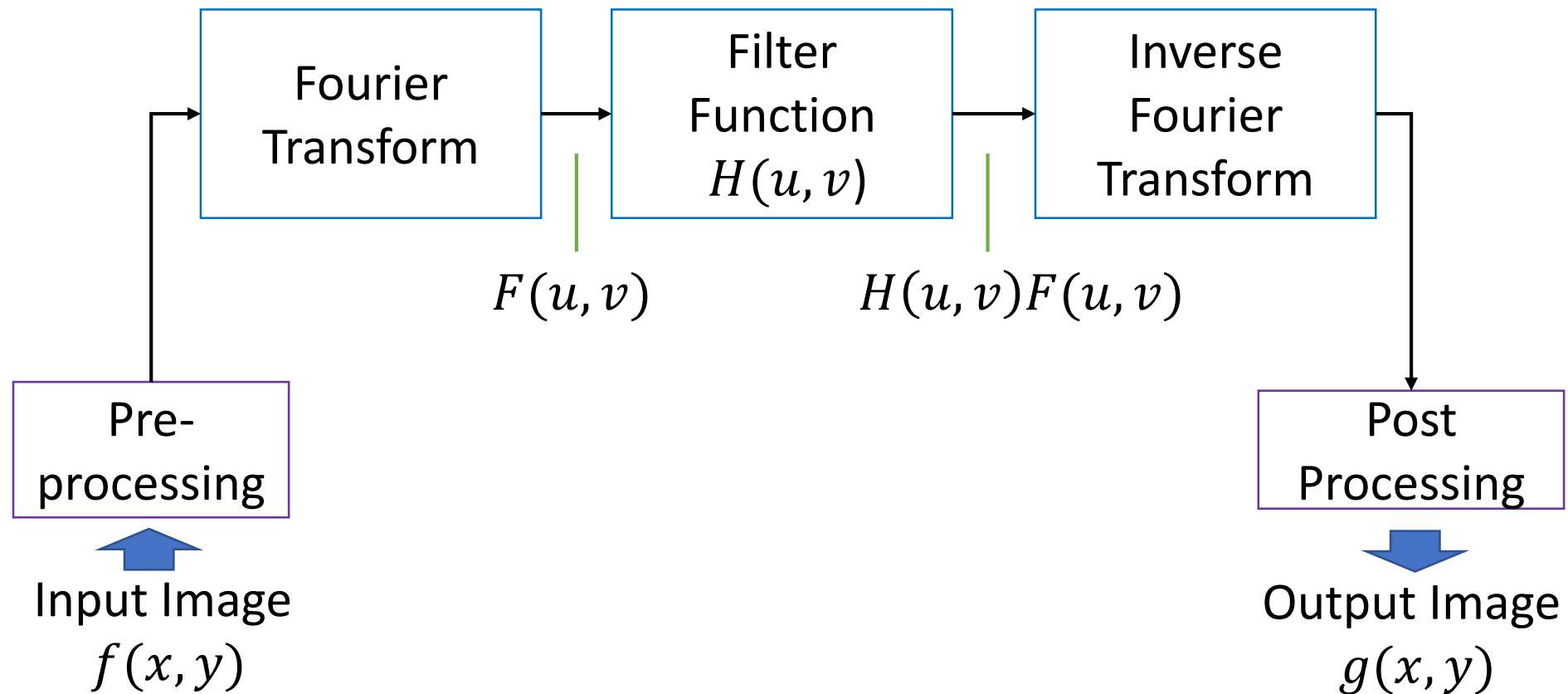
The central part of FT, i.e. the low frequency components are responsible for the general gray-level appearance of an image.



The high frequency components of FT are responsible for the detail information of an image.

# Filtering in the Frequency Domain

# Basic Steps for Filtering in the Frequency Domain



# Filtering in the Frequency Domain

- Filtering is done in the frequency domain

$$G(u, v) = H(u, v)F(u, v)$$

- Band Pass Filters
  - Low Pass
  - High Pass
- Band Reject Filters
- Other



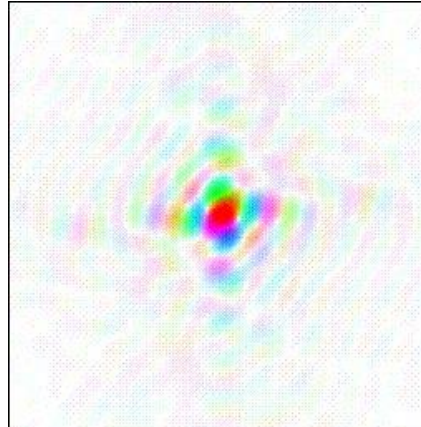
# Low Pass Filters

- Yang diambil adalah frekuensi-frekuensi rendah yang ada pada citra.

Smoothing (low pass filter): informasi komponen frekuensi tinggi hilang.

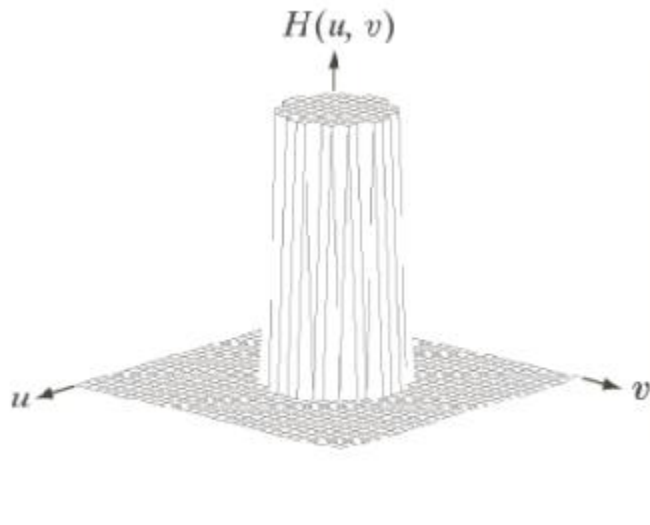
- Smoothing terjadi karena noise bersifat high frequency. Dengan *Low Pass Filter* kita bisa membuang info high frequency tersebut.
- *But!* Bisa kehilangan informasi detail pada citra.

# Low Pass Filters (2)

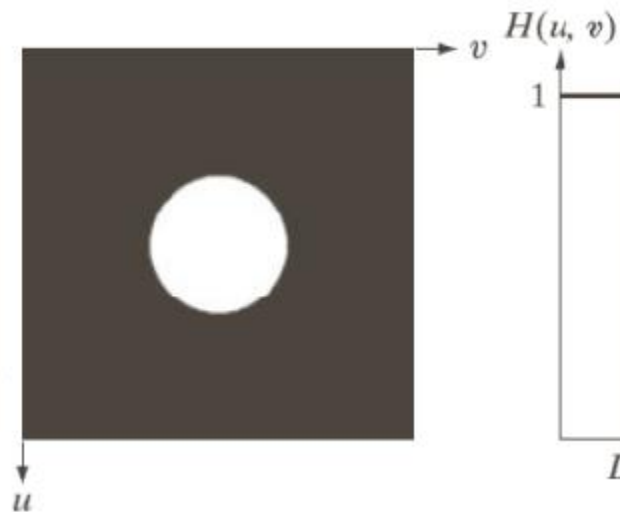


- $H(u,v) = 1$  if  $D(u,v) \leq D_0$   
     $= 0$  if  $D(u,v) > D_0$
- $D_0$  adalah nilai ambang (cutoff frequency locus, nilainya  $> 0$ )
- $D(u,v)$  adalah jarak  $(u,v)$  terhadap titik origin.  $D(u,v) = (u^2 + v^2)^{1/2}$

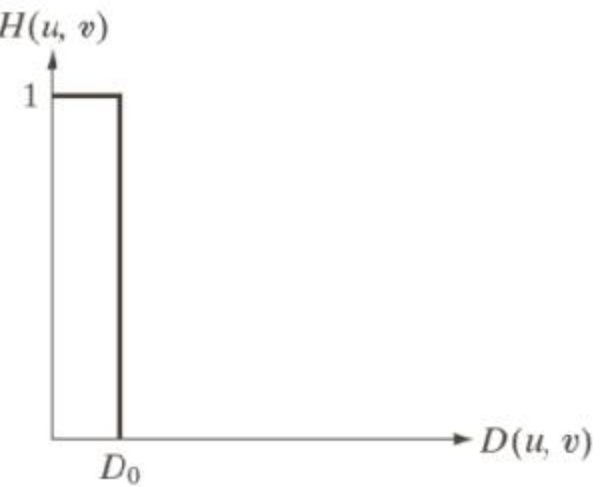
# Ideal Low Pass Filter



Perspective plot of  
ideal LPF

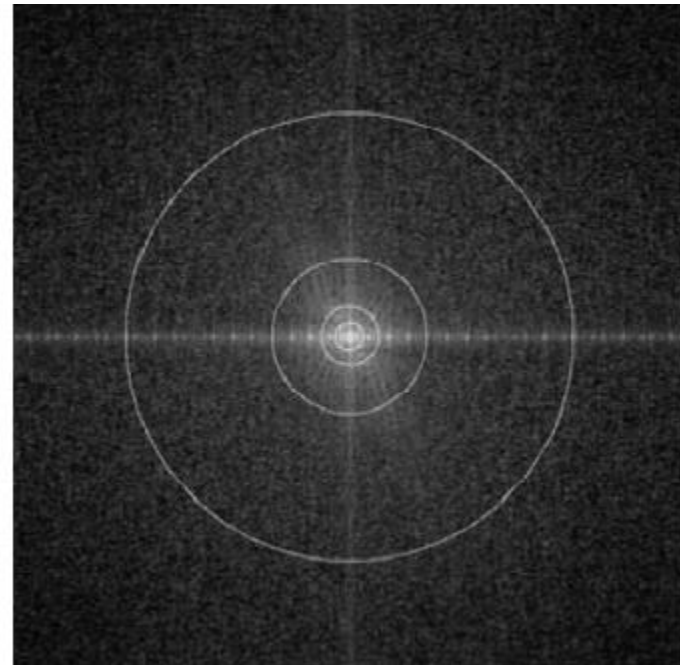
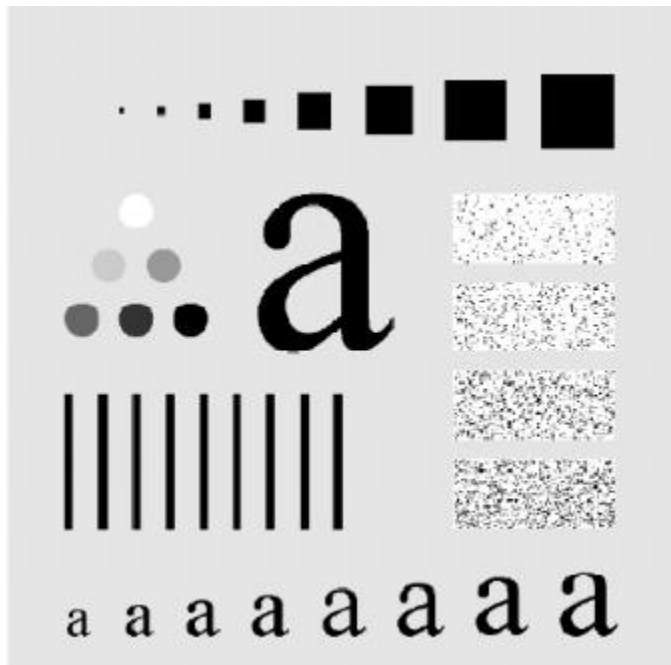


Filter as an image

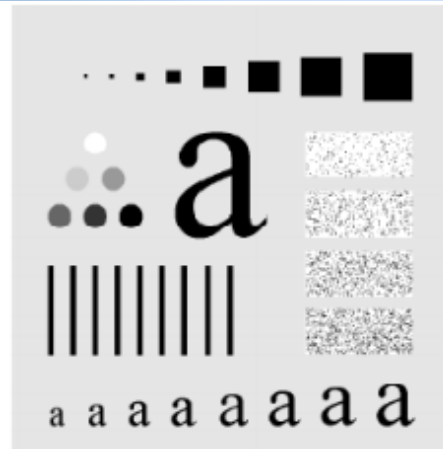


Radial Cross Section

# Ideal Low Pass Filter Example



# Ideal Low Pass Filter Example (2)

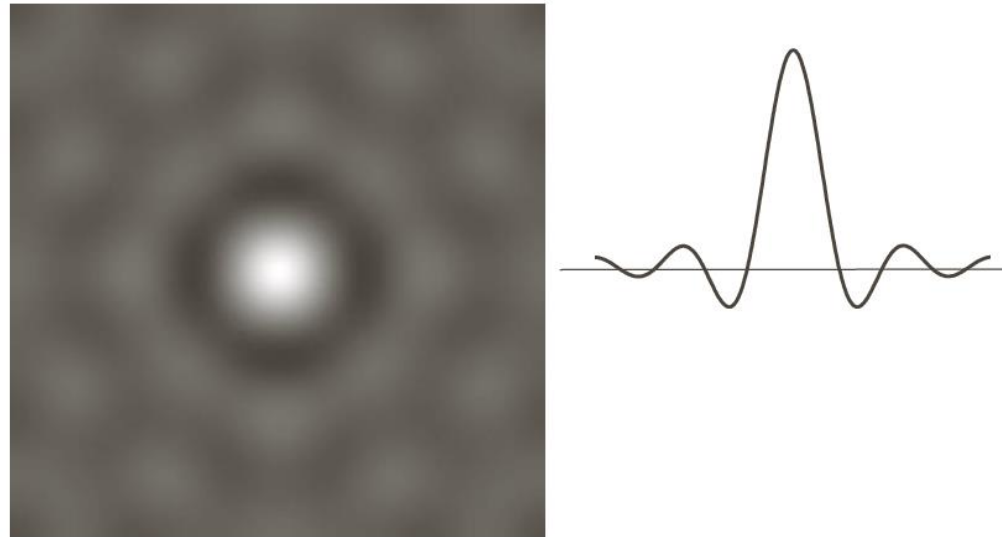


- Radius low pas filter: 10,30,60,160, 460

# Ringling Effect



# Why Ringing Effect?



- Visually, they appear as bands or "ghosts" near edges.
- The term "ringing" is because the output signal oscillates at a fading rate around a sharp transition in the input, similar to a bell after being struck

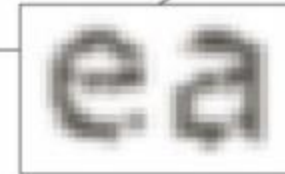
# Potential Applications

- Machine perception and OCR

Historically, certain computer programs were written using only two digits rather than four to define the applicable year. Accordingly, the company's software may recognize a date using "00" as 1900 rather than the year 2000.



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# More on Low Pass Filtering

- Butterworth low pass filter
- Disadvantages of low pass filter
- Potential applications
  - Printing and Publishing Industry
  - Satellite and Aerial Images

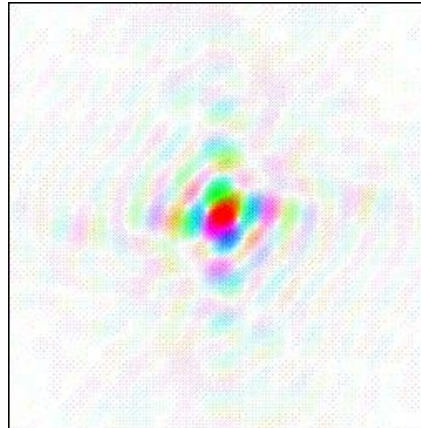
# High Pass Filters

- Yang diambil adalah frekuensi-frekuensi tinggi yang ada pada citra.

Sharpening (high pass filter) : meloloskan komponen frekuensi tinggi

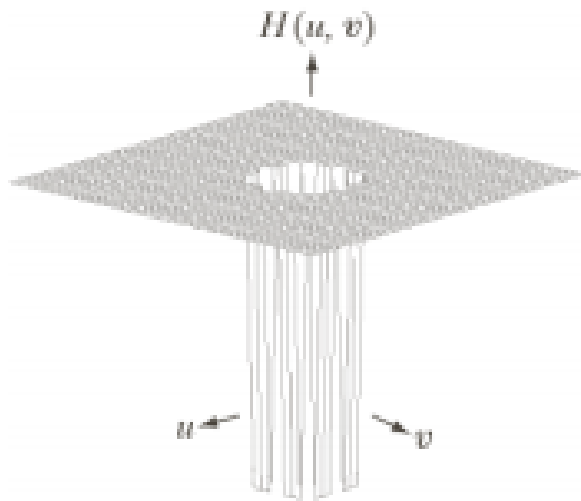
- Edges and abrupt changes in intensities are associated with high-frequency.
- Attenuates the low-frequency components without disturbing high-frequency information.

# High Pass Filters (2)

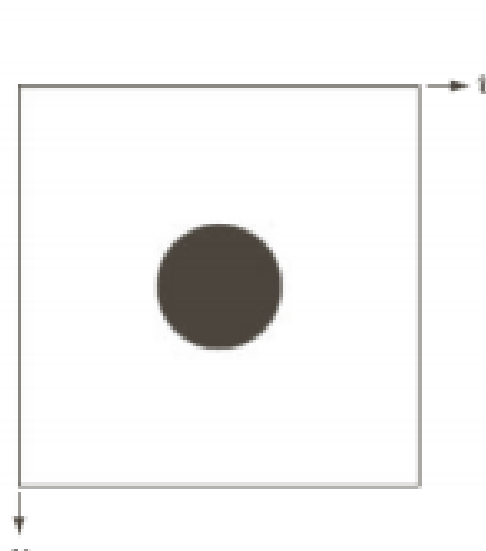


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     $= 1$  if  $D(u,v) > D_0$
- $D_0$  adalah nilai ambang (cutoff frequency locus, nilainya  $> 0$ )
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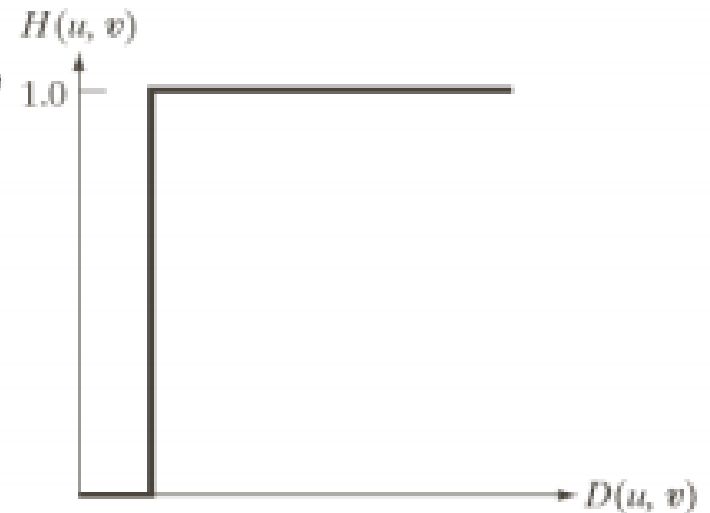
# Ideal High Pass Filter



Perspective plot of  
ideal HPF



Filter as an image



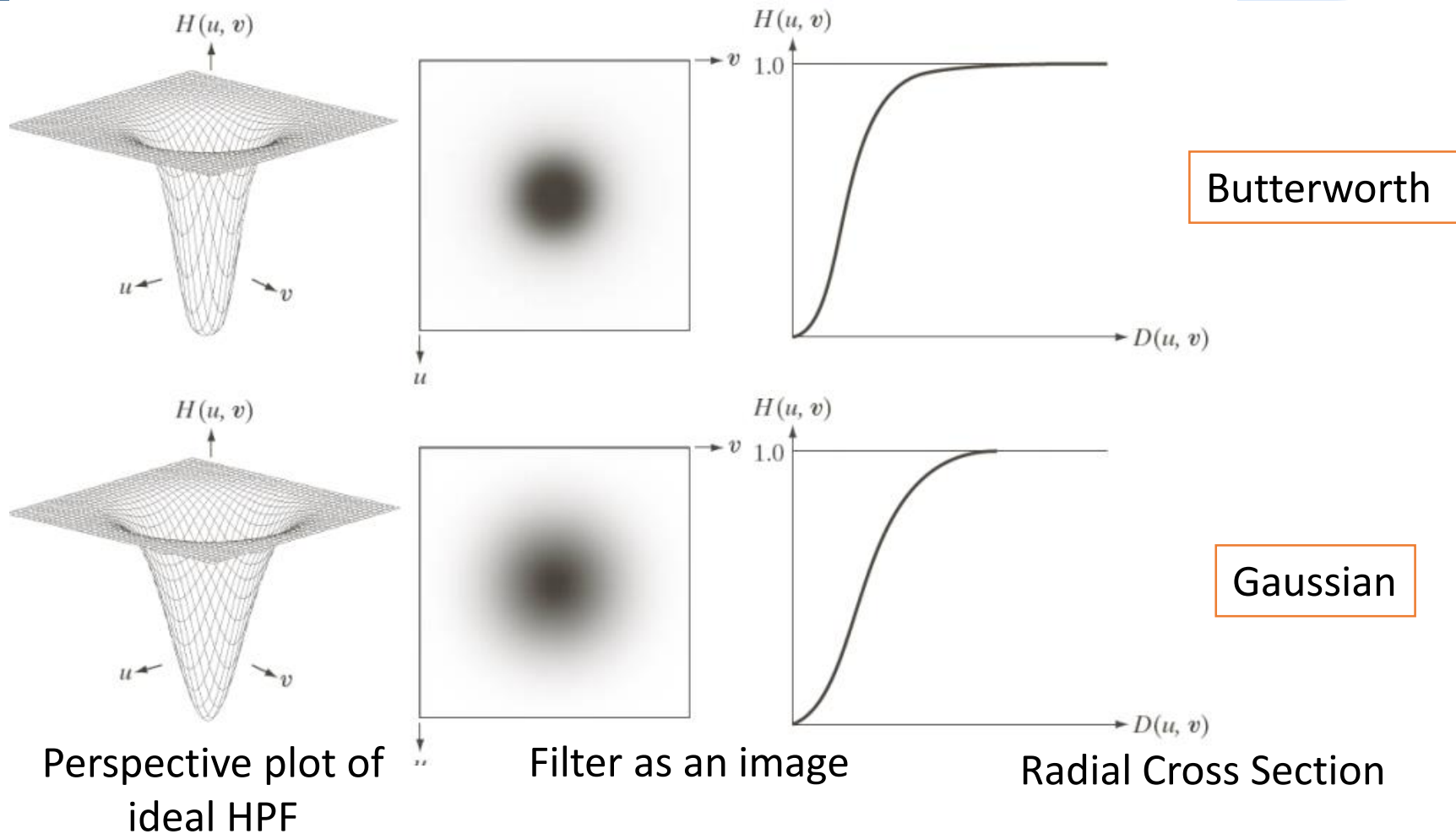
Radial Cross Section

# Ideal High Pass Filter Example

- Ideal High Pass Filter results with  $D_0 = 30, 60, \text{ and } 160$

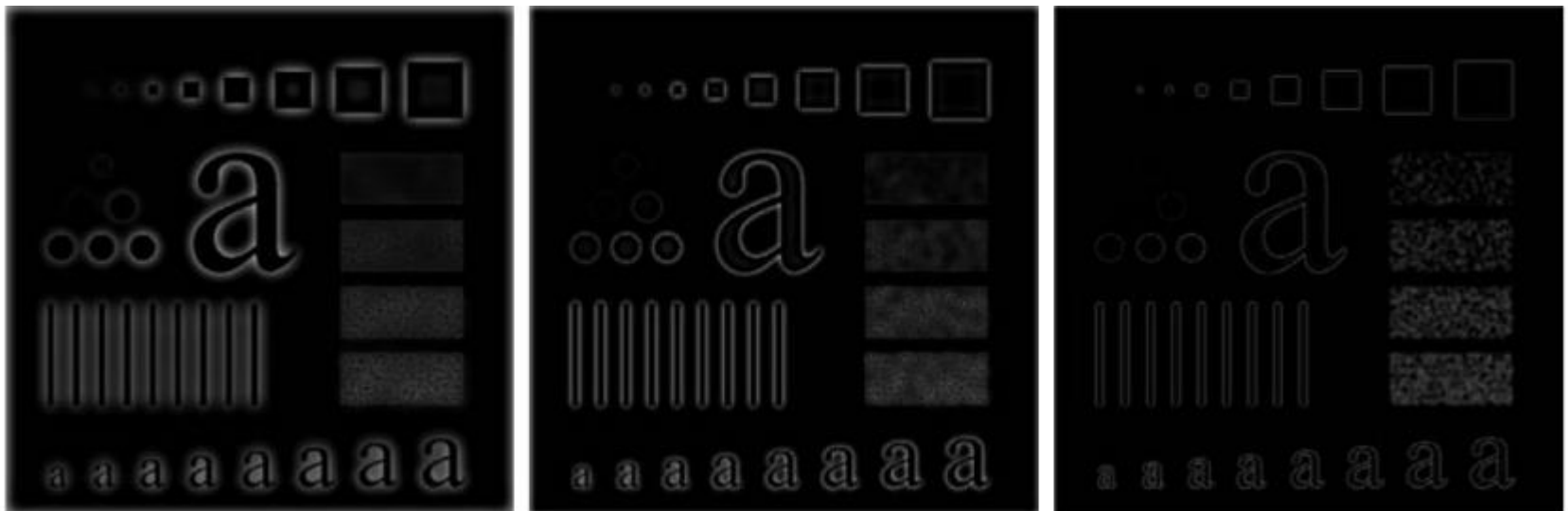


# Butterworth and Gaussian High Pass Filter



# Butterworth High Pass Filter Example

- Butterworth High Pass Filter results with  $D_0 = 30, 60,$  and 160



# Gaussian High Pass Filter Example

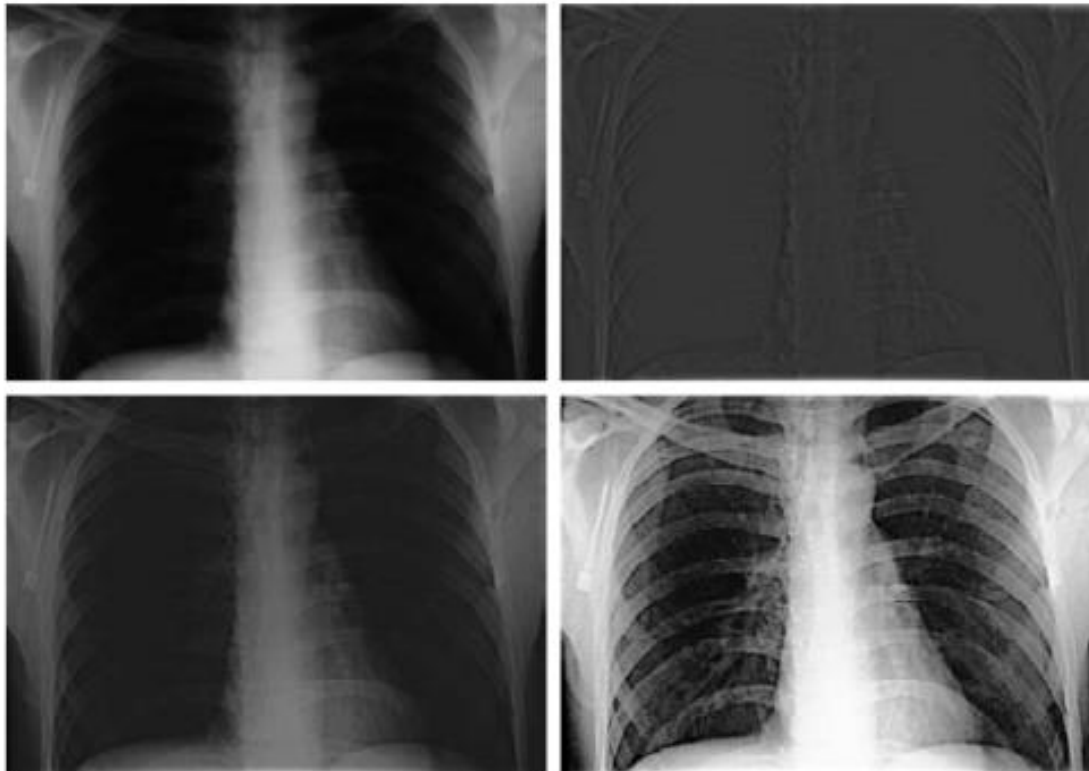
- Gaussian High Pass Filter results with  $D_0 = 30, 60, \text{ and } 160$





# Potential Applications

- Medical Field
  - HPF, HPF emphasis, and histogram equalization



# More on High Pass Filtering

- Laplacian Filtering
- Homomorphic Filtering
- Potential Applications
  - PET Scans
  - Satellite Imagery of Space

# Other Topics

- Selective Filtering (Band Reject Filters)

