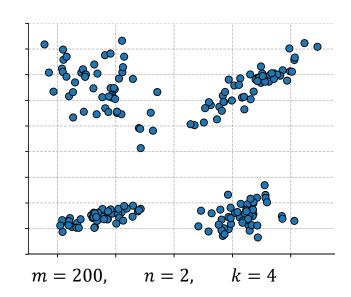
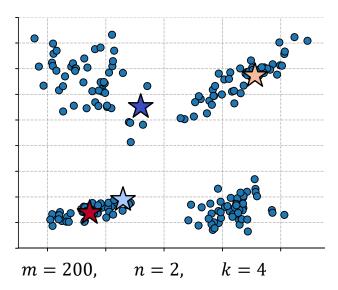
Implementing K-means in **Python** without **Sklearn**

Faculty of Mathematics and Computer Science, University of Bucharest and Sparktech Software

• $X = \{\vec{x}^{(1)}, \dots, \vec{x}^{(m)}\} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$



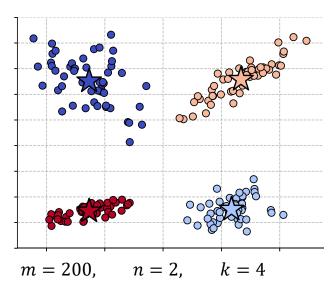
- $X = {\vec{x}^{(1)}, ..., \vec{x}^{(m)}} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$
- Initial cluster centers $M = \{\vec{\mu}^{(1)}, ..., \vec{\mu}^{(k)}\} \subset X$



- $X = {\vec{x}^{(1)}, \dots, \vec{x}^{(m)}} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$
- Initial cluster centers $M = \{\vec{\mu}^{(1)}, ..., \vec{\mu}^{(k)}\} \subset X$
- Expectation:

$$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = \operatorname{argmin}_{j} \|\vec{x}^{(i)} - \vec{\mu}^{(j)}\| \\ 0 & \text{otherwise} \end{cases}$$

$$\vec{\mu}^{(j)} \coloneqq \frac{1}{|C_j|} \sum_{\vec{x} \in C_j} \vec{x}$$

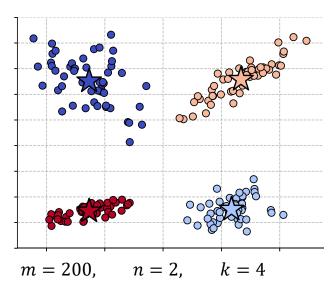


- $X = {\vec{x}^{(1)}, \dots, \vec{x}^{(m)}} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$
- Initial cluster centers $M = \{\vec{\mu}^{(1)}, ..., \vec{\mu}^{(k)}\} \subset X$
- Expectation:

$$y_i = \operatorname{argmin}_{\mathbf{i}} \|\vec{x}^{(i)} - \vec{\mu}^{(j)}\|$$

$$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$$

$$\vec{\mu}^{(j)} \coloneqq \frac{1}{|C_j|} \sum_{\vec{x} \in C_j} \vec{x}$$

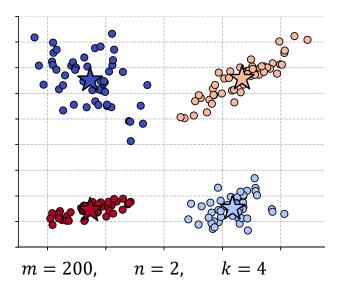


- $X = {\vec{x}^{(1)}, ..., \vec{x}^{(m)}} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$
- Initial cluster centers $M = \{\vec{\mu}^{(1)}, ..., \vec{\mu}^{(k)}\} \subset X$
- Expectation:

$$y_i = \operatorname{argmin}_{j} \sqrt{\langle \vec{x}^{(i)} - \vec{\mu}^{(j)}, \vec{x}^{(i)} - \vec{\mu}^{(j)} \rangle}$$

$$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$$

$$\vec{\mu}^{(j)} \coloneqq \frac{1}{|C_j|} \sum_{\vec{x} \in C_j} \vec{x}$$

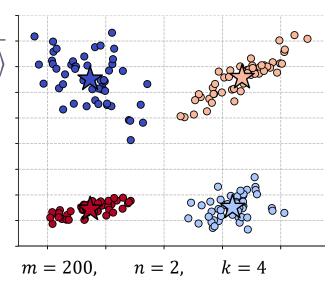


- $X = {\vec{x}^{(1)}, \dots, \vec{x}^{(m)}} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$
- Initial cluster centers $M = \{\vec{\mu}^{(1)}, ..., \vec{\mu}^{(k)}\} \subset X$
- Expectation:

$$y_i = \operatorname{argmin}_{j} \sqrt{\langle \vec{x}^{(i)}, \vec{x}^{(i)} \rangle - 2\langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \langle \vec{\mu}^{(j)}, \vec{\mu}^{(j)} \rangle}$$

$$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$$

$$\vec{\mu}^{(j)} \coloneqq \frac{1}{|C_j|} \sum_{\vec{x} \in C_j} \vec{x}$$

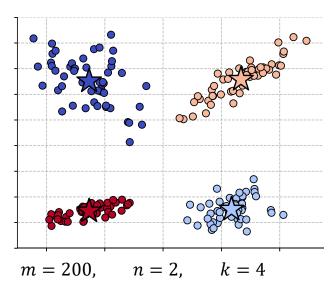


- $X = {\vec{x}^{(1)}, ..., \vec{x}^{(m)}} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$
- Initial cluster centers $M = \{\vec{\mu}^{(1)}, ..., \vec{\mu}^{(k)}\} \subset X$
- Expectation:

$$y_i = \operatorname{argmin}_{j} \left(-2 \langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \left\| \vec{\mu}^{(j)} \right\|^2 \right)$$

$$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$$

$$\vec{\mu}^{(j)} \coloneqq \frac{1}{|C_j|} \sum_{\vec{x} \in C_j} \vec{x}$$

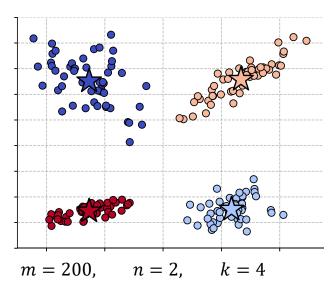


- $X = {\vec{x}^{(1)}, ..., \vec{x}^{(m)}} \subset \mathbb{R}^n \text{ and } k \in \mathbb{N}^+$
- Initial cluster centers $M = \{\vec{\mu}^{(1)}, ..., \vec{\mu}^{(k)}\} \subset X$
- Expectation:

$$y_i = \operatorname{argmin}_{j} \left(-2 \langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \left\| \vec{\mu}^{(j)} \right\|^2 \right)$$

$$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$$

$$\vec{\mu}^{(j)} \coloneqq \frac{1}{\sum_{i} z_{ij}} \sum_{i} z_{ij} \vec{x}^{(i)}$$



$$X = \begin{pmatrix} x_1^{(1)} & x_2^{(1)} & \cdots & x_n^{(1)} \\ x_1^{(2)} & x_2^{(2)} & \cdots & x_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(m)} & x_2^{(m)} & \cdots & x_n^{(m)} \end{pmatrix}_{m \times n}$$

$$M \in \mathbb{R}^{k \times n} = \begin{pmatrix} \mu_1^{(1)} & \mu_2^{(1)} & \cdots & \mu_n^{(1)} \\ \mu_1^{(2)} & \mu_2^{(2)} & \cdots & \mu_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ \mu_1^{(k)} & \mu_2^{(k)} & \cdots & \mu_n^{(k)} \end{pmatrix}_{k \times n}$$

$$X = \begin{pmatrix} x_1^{(1)} & x_2^{(1)} & \cdots & x_n^{(1)} \\ x_1^{(2)} & x_2^{(2)} & \cdots & x_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(m)} & x_2^{(m)} & \cdots & x_n^{(m)} \end{pmatrix}_{m \times n}$$

$$M \in \mathbb{R}^{k \times n} = \begin{pmatrix} \mu_1^{(1)} & \mu_2^{(1)} & \cdots & \mu_n^{(1)} \\ \mu_1^{(2)} & \mu_2^{(2)} & \cdots & \mu_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ \mu_n^{(k)} & \mu_2^{(k)} & \cdots & \mu_n^{(k)} \end{pmatrix}_{k \times n}$$

$$XM^T = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(1)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \langle \vec{x}^{(2)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(2)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(2)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(m)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}_{m \times n}$$

$$X = \begin{pmatrix} x_1^{(1)} & x_2^{(1)} & \cdots & x_n^{(1)} \\ x_1^{(2)} & x_2^{(2)} & \cdots & x_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(m)} & x_2^{(m)} & \cdots & x_n^{(m)} \end{pmatrix}_{m \times n}$$

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(1)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \langle \vec{x}^{(2)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(2)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(2)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(m)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}$$

$$M_* = \begin{pmatrix} 1 & 1 & \cdots & 1 \\ 1 & 1 & \cdots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \cdots & 1 \end{pmatrix}_{m \times n} \cdot (M^T)^2$$
Point-wise squaring

$$M \in \mathbb{R}^{k \times n} = \begin{pmatrix} \mu_1^{(1)} & \mu_2^{(1)} & \cdots & \mu_n^{(1)} \\ \mu_1^{(2)} & \mu_2^{(2)} & \cdots & \mu_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ \mu_1^{(k)} & \mu_2^{(k)} & \cdots & \mu_n^{(k)} \end{pmatrix}_{k \times n}$$

Point-wise squaring

$$X = \begin{pmatrix} x_{1}^{(1)} & x_{2}^{(1)} & \cdots & x_{n}^{(1)} \\ x_{1}^{(2)} & x_{2}^{(2)} & \cdots & x_{n}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1}^{(m)} & x_{2}^{(m)} & \cdots & x_{n}^{(m)} \end{pmatrix}_{m \times n}$$

$$M \in \mathbb{R}^{k \times n} = \begin{pmatrix} \mu_{1}^{(1)} & \mu_{2}^{(1)} & \cdots & \mu_{n}^{(1)} \\ \mu_{1}^{(2)} & \mu_{2}^{(2)} & \cdots & \mu_{n}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ \mu_{1}^{(k)} & \mu_{2}^{(k)} & \cdots & \mu_{n}^{(k)} \end{pmatrix}_{k \times n}$$

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(1)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \langle \vec{x}^{(2)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(2)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(2)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(m)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}_{m \times k}$$

$$M_{*} = \begin{pmatrix} 1 & 1 & \cdots & 1 \\ 1 & 1 & \cdots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \cdots & 1 \end{pmatrix}_{m \times n} \cdot (M^{T})_{k}^{2} = 1_{m \times n} \cdot \begin{pmatrix} \mu_{1}^{(1)^{2}} & \cdots & \mu_{1}^{(k)^{2}} \\ \mu_{2}^{(1)^{2}} & \cdots & \mu_{n}^{(k)^{2}} \\ \vdots & \ddots & \vdots \\ \mu_{n}^{(1)^{2}} & \cdots & \mu_{n}^{(k)^{2}} \end{pmatrix} = \begin{pmatrix} \|\vec{\mu}^{(1)}\|^{2} \\ \end{pmatrix}_{m \times k}$$

$$X = \begin{pmatrix} x_1^{(1)} & x_2^{(1)} & \cdots & x_n^{(1)} \\ x_1^{(2)} & x_2^{(2)} & \cdots & x_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{(m)} & x_2^{(m)} & \cdots & x_n^{(m)} \end{pmatrix}_{m \times n}$$

$$M \in \mathbb{R}^{k \times n} = \begin{pmatrix} \mu_1^{(1)} & \mu_2^{(1)} & \cdots & \mu_n^{(1)} \\ \mu_1^{(2)} & \mu_2^{(2)} & \cdots & \mu_n^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ \mu_1^{(k)} & \mu_2^{(k)} & \cdots & \mu_n^{(k)} \end{pmatrix}_{k \times n}$$

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(1)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \langle \vec{x}^{(2)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(2)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(2)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \langle \vec{x}^{(m)}, \vec{\mu}^{(2)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}_{m \times k}$$

$$M_{*} = \begin{pmatrix} 1 & 1 & \cdots & 1 \\ 1 & 1 & \cdots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \cdots & 1 \end{pmatrix}_{m \times n} \cdot (M^{T})_{*}^{2} = 1_{m \times n} \cdot \begin{pmatrix} \mu_{1}^{(1)^{2}} & \cdots & \mu_{1}^{(k)^{2}} \\ \mu_{2}^{(1)^{2}} & \cdots & \mu_{2}^{(k)^{2}} \\ \vdots & \ddots & \vdots \\ \mu_{n}^{(1)^{2}} & \cdots & \mu_{n}^{(k)^{2}} \end{pmatrix} = \begin{pmatrix} \left\|\vec{\mu}^{(1)}\right\|^{2} & \left\|\vec{\mu}^{(2)}\right\|^{2} & \cdots & \left\|\vec{\mu}^{(k)}\right\|^{2} \\ \left\|\vec{\mu}^{(1)}\right\|^{2} & \left\|\vec{\mu}^{(2)}\right\|^{2} & \cdots & \left\|\vec{\mu}^{(k)}\right\|^{2} \\ \vdots & \vdots & \ddots & \vdots \\ \left\|\vec{\mu}^{(1)}\right\|^{2} & \left\|\vec{\mu}^{(2)}\right\|^{2} & \cdots & \left\|\vec{\mu}^{(k)}\right\|^{2} \end{pmatrix}_{m \times k}$$

Point-wise squaring

Point-wise operations	Matrix operations
$y_i = \operatorname{argmin}_{j} \left(-2\langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \ \vec{\mu}^{(j)}\ ^2 \right)$	
$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$	
$\vec{\mu}^{(j)} \coloneqq \frac{1}{\sum_{i} z_{ij}} \sum_{i} z_{ij} \vec{x}^{(i)}$	

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}$$

$$M_{*} = \begin{pmatrix} \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \\ \vdots & \ddots & \vdots \\ \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \end{pmatrix}$$

Point-wise operations	Matrix operations
$y_i = \operatorname{argmin}_{j} \left(-2\langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \ \vec{\mu}^{(j)}\ ^2 \right)$	$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix} = \text{rowwise_argmin}(-2XM^T + M_*)$
$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$	
$\vec{\mu}^{(j)} \coloneqq \frac{1}{\sum_{i} z_{ij}} \sum_{i} z_{ij} \vec{x}^{(i)}$	

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}$$

$$M_{*} = \begin{pmatrix} \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \\ \vdots & \ddots & \vdots \\ \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \end{pmatrix}$$

Point-wise operations	Matrix operations
$y_i = \operatorname{argmin}_{j} \left(-2\langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \ \vec{\mu}^{(j)}\ ^2 \right)$	$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix} = \text{rowwise_argmin}(-2XM^T + M_*)$
$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$	$Z = \begin{pmatrix} z_{11} & \cdots & z_{1k} \\ \vdots & z_{ij} & \vdots \\ z_{m1} & \cdots & z_{mk} \end{pmatrix} = \begin{pmatrix} \text{one_hot}(y_1) \\ \vdots \\ \text{one_hot}(y_m) \end{pmatrix}$
$\vec{\mu}^{(j)} \coloneqq \frac{1}{\sum_{i} z_{ij}} \sum_{i} z_{ij} \vec{x}^{(i)}$	

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}$$

$$M_{*} = \begin{pmatrix} \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \\ \vdots & \ddots & \vdots \\ \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \end{pmatrix}$$

Point-wise operations	Matrix operations
$y_i = \operatorname{argmin}_{j} \left(-2\langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \ \vec{\mu}^{(j)}\ ^2 \right)$	$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix} = \text{rowwise_argmin}(-2XM^T + M_*)$
$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$	$Z = \begin{pmatrix} z_{11} & \cdots & z_{1k} \\ \vdots & z_{ij} & \vdots \\ z_{m1} & \cdots & z_{mk} \end{pmatrix} = \begin{pmatrix} \text{one_hot}(y_1) \\ \vdots \\ \text{one_hot}(y_m) \end{pmatrix}$
$\vec{\mu}^{(j)} \coloneqq \frac{1}{\sum_{i} z_{ij}} \sum_{i} z_{ij} \vec{x}^{(i)}$	

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}$$

$$M_{*} = \begin{pmatrix} \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \\ \vdots & \ddots & \vdots \\ \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \end{pmatrix}$$

One-hot encoding of y_i basically means row y_i of I_k (identity matrix of size $k \times k$):

$$I_{4} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$0 + 4 \implies 0$$

$$0 + 0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0$$

$$0 + 0 + 0$$

$$0 + 0 + 0$$

$$0 + 0$$

$$0 + 0$$

$$0 + 0$$

$$0 +$$

Point-wise operations	Matrix operations
$y_i = \operatorname{argmin}_{j} \left(-2\langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \ \vec{\mu}^{(j)}\ ^2 \right)$	$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix} = \text{rowwise_argmin}(-2XM^T + M_*)$
$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$	$Z = \begin{pmatrix} z_{11} & \cdots & z_{1k} \\ \vdots & z_{ij} & \vdots \\ z_{m1} & \cdots & z_{mk} \end{pmatrix} = \begin{pmatrix} \text{one_hot}(y_1) \\ \vdots \\ \text{one_hot}(y_m) \end{pmatrix}$
$\vec{\mu}^{(j)} \coloneqq \frac{1}{\sum_{i} z_{ij}} \sum_{i} z_{ij} \vec{x}^{(i)}$	

• The matrix Z is a permutation (with replacement) of I_k with rows selected according to Y.

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}$$

$$M_{*} = \begin{pmatrix} \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \\ \vdots & \ddots & \vdots \\ \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \end{pmatrix}$$

One-hot encoding of y_i basically means row y_i of I_k (identity matrix of size $k \times k$):

$$I_{4} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$x = 4 \implies$$

$$one_hot(3) = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$one_hot(1) = \begin{bmatrix} 1 & 0 & 0 & 0 \end{bmatrix}$$

Point-wise operations	Matrix operations
$y_i = \operatorname{argmin}_{j} \left(-2\langle \vec{x}^{(i)}, \vec{\mu}^{(j)} \rangle + \ \vec{\mu}^{(j)}\ ^2 \right)$	$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix} = \text{rowwise_argmin}(-2XM^T + M_*)$
$z_{ij^*} \coloneqq \begin{cases} 1 & \text{if } j^* = y_i \\ 0 & \text{otherwise} \end{cases}$	$Z = \begin{pmatrix} z_{11} & \cdots & z_{1k} \\ \vdots & z_{ij} & \vdots \\ z_{m1} & \cdots & z_{mk} \end{pmatrix} = \begin{pmatrix} \text{one_hot}(y_1) \\ \vdots \\ \text{one_hot}(y_m) \end{pmatrix}$
$\vec{\mu}^{(j)} \coloneqq \frac{1}{\sum_{i} z_{ij}} \sum_{i} z_{ij} \vec{x}^{(i)}$	$M = \frac{Z^T X}{Z^T 1_{m \times n}}$

• The matrix Z is a permutation (with replacement) of I_k with rows selected according to Y.

$$XM^{T} = \begin{pmatrix} \langle \vec{x}^{(1)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(1)}, \vec{\mu}^{(k)} \rangle \\ \vdots & \ddots & \vdots \\ \langle \vec{x}^{(m)}, \vec{\mu}^{(1)} \rangle & \cdots & \langle \vec{x}^{(m)}, \vec{\mu}^{(k)} \rangle \end{pmatrix}$$

$$M_{*} = \begin{pmatrix} \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \\ \vdots & \ddots & \vdots \\ \|\vec{\mu}^{(1)}\|^{2} & \cdots & \|\vec{\mu}^{(k)}\|^{2} \end{pmatrix}$$

One-hot encoding of y_i basically means row y_i of I_k (identity matrix of size $k \times k$):

$$I_4 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$k = 4 \implies$$

$$one_hot(3) = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

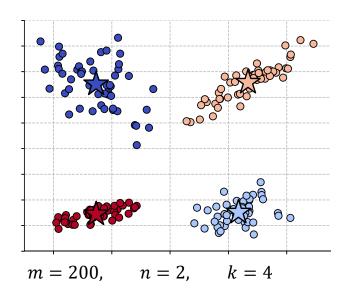
$$one_hot(1) = \begin{bmatrix} 1 & 0 & 0 & 0 \end{bmatrix}$$

- $X \in \mathbb{R}^{m \times n}$ and $k \in \mathbb{N}^+$
- Initial cluster centers $M \in \mathbb{R}^{k \times n}$
- Expectation:

$$M_* = 1_{m \times n} (M^T)^2$$

 $Y = \text{rowwise_argmin}(-2XM^T + M_*)$
 $Z = \text{rowwise_onehot}(Y) = I_k[Y]$

$$M = \frac{Z^T X}{Z^T 1_{m \times n}}$$



K-means in Python without Sklearn

```
import numpy as np
     m , n = X.shape # (200, 2)
     k = 4
     indices = np.arange(m) # indices = np.array([0, 1, 2, ..., 199])
     np.random.suffle(indices) # shuffles the indices in place
     M = X[indices[:k]] # select the point of the first k indices (after shuffling)
     n_{steps} = 50
     for _ in range(n_steps):
11
         M_{star} = np.ones((m, n)).dot(M.T**2) # M_star.shape == (200, 4)
12
         y = np.argmin(-2*X.dot(M.T) + M_star, axis = 1) # y.shape == (200,)
         Z = np.eye(k)[y] # Expectation
         M = Z.T.dot(X) / Z.T.dot(np.ones((m, n))) # Maximization
```

K-means in Python with some Sklearn

```
import numpy as np
     from sklearn.metrics.pairwise import euclidean distances
     from sklearn.utils import resample
     m, n = X.shape # (200, 2)
     k = 4
     M = resample(X, n_samples = k)
     n \text{ steps} = 50
     for _ in range(n_steps):
         y = np.argmin(euclidean_distances(X, M), axis = 1) # y.shape == (200,)
11
         Z = np.eye(k)[y]
12
         M = Z.T.dot(X) / Z.sum(axis = 0).reshape(-1, 1) # reshape turns shape (4,) into (4, 1)
13
```