Contents

1	Der	ivation of Derivative wrt λ	2
	1.1	Derivative of REML	2
	1.2	Derivative of GCV	4
	1.3	Derivative of AIC	5
2	Der	ivation of the RFMI based Test Statistic	ŗ

1 Derivation of Derivative wrt λ

Corresponding to (2.2.3),

$$\mathbf{y} = \mathbf{\mu} + \mathbf{h} + \mathbf{\varepsilon}$$
 where $\mathbf{h} \sim N(\mathbf{0}, \tau \mathbf{K}_{\delta})$ $\mathbf{\varepsilon} \sim N(\mathbf{0}, \sigma^2 \mathbf{I})$

where \mathbf{K}_{δ} is the kernel matrix generated by $k_{\delta}(\mathbf{z}, \mathbf{z}')$. the general model may be expressed in matrix form as [1]:

$$\mathbf{v} = \mathbf{\mu} + \Phi(\mathbf{X})^{\mathsf{T}} \mathbf{\beta} + \mathbf{\varepsilon}$$
 where $\Phi(\mathbf{X})^{\mathsf{T}}$ is $\mathbf{n} \times \mathbf{p}$ (1.1)

where $\Phi(X)$ is the aggregation of columns $\phi(x)$ for all cases in the training set, and $\phi(x)$ is a function mapping a D-dimensional input vector x into an p-dimensional feature space. This model is fitted by penalized least squares, i.e., our estimate is

$$(\hat{\mu}, \hat{\beta}) = \underset{\mu, \beta}{\operatorname{argmin}} (\parallel \mathbf{y} - \boldsymbol{\mu} - \boldsymbol{\Phi}(\mathbf{X})^{\mathsf{T}} \boldsymbol{\beta} \parallel^{2} + \lambda \boldsymbol{\beta}^{\mathsf{T}} \boldsymbol{\beta})$$
(1.2)

The development that follows depends on the following Assumptions:

1.
$$\mathbf{1}^{\mathsf{T}}\Phi(\mathbf{X})^{\mathsf{T}} = \mathbf{0}$$
.

2. **y** is not in the column space of **1**.

where **1** is a $n \times 1$ vector.

1.1 Derivative of REML

As our choice of matrix notation suggests, model (1.1) can be seen as equivalent to a linear mixed model, in the following sense. The criterion in (1.2) is proportional to the log likelihood for the partly observed "data" (y, β) with respect to the unknowns μ and β , i.e., the best linear unbiased prediction (BLUP) criterion, for the mixed model

$$\mathbf{v}|\boldsymbol{\beta} \sim N(\boldsymbol{\mu} + \boldsymbol{\Phi}(\mathbf{X})^{\mathsf{T}}\boldsymbol{\beta}, \sigma^{2}\mathbf{I}), \quad \boldsymbol{\beta} \sim N(0, (\sigma^{2}/\lambda)\mathbf{I})$$

Under this model, $Var(y) = \sigma^2 V_{\lambda}$ where

$$\mathbf{V}_{\lambda} = \mathbf{I} + \lambda^{-1} \Phi(\mathbf{X})^{\mathsf{T}} \Phi(\mathbf{X}) = \mathbf{I} + \lambda^{-1} \mathbf{K}_{\delta}$$
(1.3)

The mixed model formulation motivates treating λ as a variance parameter to be estimated by maximizing the log likelihood

$$l(\mu, \lambda, \sigma^2 | \mathbf{y}) = -\frac{1}{2} \Big[log \mid \sigma^2 \mathbf{V}_{\lambda} \mid + (\mathbf{y} - \boldsymbol{\mu})^\mathsf{T} (\sigma^2 \mathbf{V}_{\lambda})^{-1} (\mathbf{y} - \boldsymbol{\mu}) \Big]$$

Maximizing this log likelihood results in estimating σ^2 with a downward bias, which is removed if we instead maximize the restricted log likelihood

$$l_{R}(\mu, \lambda, \sigma^{2} | \mathbf{y}) = -\frac{1}{2} \left[\log |\sigma^{2} \mathbf{V}_{\lambda}| + (\mathbf{y} - \mu)^{\mathsf{T}} (\sigma^{2} \mathbf{V}_{\lambda})^{-1} (\mathbf{y} - \mu) + \log |\sigma^{-2} \mathbf{1}^{\mathsf{T}} \mathbf{V}_{\lambda}^{-1} \mathbf{1}| \right]$$
(1.4)

We shall refer to the resulting estimate of λ as the REML choice of the parameter. For given μ and λ , the value of σ^2 maximizing the restricted log likelihood (1.4) is

$$\hat{\sigma}_{\mu,\lambda}^2 = (\mathbf{y} - \mathbf{\mu})^\mathsf{T} \mathbf{V}_{\lambda}^{-1} (\mathbf{y} - \mathbf{\mu}) / (n - 1) \tag{1.5}$$

substituting in this value and ignoring an additive constant leads to the profile restricted log likelihood

$$l_{R}(\mu, \lambda | \mathbf{y}) = -\frac{1}{2} \left[\log |\mathbf{V}_{\lambda}| + \log |\mathbf{1}^{\mathsf{T}} \mathbf{V}_{\lambda}^{-1} \mathbf{1}| + (n-1) \log \{(\mathbf{y} - \mu)^{\mathsf{T}} \mathbf{V}_{\lambda}^{-1} (\mathbf{y} - \mu)\} \right]$$
(1.6)

For given λ , the value of μ maximizing this last expression is the generalized least square fit $\hat{\mu}_{\lambda}=$ $(\mathbf{1}^\mathsf{T} \overset{\smile}{\mathbf{V}_{\lambda}}^{-1} \mathbf{1})^{-1} \mathbf{1}^\mathsf{T} \mathbf{V}_{\lambda}^{-1} \mathbf{y}.$

Using the readily verified equality $V_{\lambda}^{-1} = I - A_{\lambda}$, the following key facts about P_{λ} can be shown to hold under Assumptions 1-2:

$$\mathbf{P}_{\lambda} = \mathbf{I} - \mathbf{H}_{\lambda} \tag{1.7}$$

where \mathbf{H}_{λ} is the hat matrix defined by $\hat{\mathbf{y}} = \mathbf{H}_{\lambda}\mathbf{y}$ and given by

$$\mathbf{H}_{\lambda} = \mathbf{1}(\mathbf{1}^{\mathsf{T}}\mathbf{1})^{-1}\mathbf{1}^{\mathsf{T}} + \mathbf{A}_{\lambda} \tag{1.8}$$

$$\mathbf{V}_{\lambda}^{-1}\mathbf{1} = \mathbf{1} \tag{1.9}$$

$$\mathbf{V}_{\lambda}^{-1}\mathbf{1} = \mathbf{1}$$
 (1.9)
 $\mathbf{P}_{\lambda}^{k} = \mathbf{V}_{\lambda}^{-k} - \mathbf{1}(\mathbf{1}^{\mathsf{T}}\mathbf{1})^{-1}\mathbf{1}^{\mathsf{T}} \text{ for } k = 1, 2, ...$

Under Assumptions 1-2, repeated application of (1.9) gives $\mathbf{y} - \hat{\boldsymbol{\mu}}_{\lambda} = [\mathbf{I} - \mathbf{1} (\mathbf{1}^{\mathsf{T}} \mathbf{1})^{-1} \mathbf{1}^{\mathsf{T}}] \mathbf{y}$, and hence

$$(\mathbf{y} - \hat{\mathbf{\mu}}_{\lambda})^{\mathsf{T}} \mathbf{V}_{\lambda}^{-1} (\mathbf{y} - \hat{\mathbf{\mu}}_{\lambda}) = \mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda} \mathbf{y}$$
 (1.11)

Substituting (1.11) into (1.6) yields the profile restricted log likelihood for λ alone:

$$l_{R}(\lambda|\mathbf{y}) = -\frac{1}{2} \left[\log |\mathbf{V}_{\lambda}| + \log |\mathbf{1}^{\mathsf{T}}\mathbf{V}_{\lambda}^{-1}\mathbf{1}| + (n-1)\log(\mathbf{y}^{\mathsf{T}}\mathbf{P}_{\lambda}\mathbf{y}) \right]$$
(1.12)

Setting the derivative of (1.12) with respect of λ to zero will yield an equation for the REML estimate of λ . By (1.9) again, $\log |\mathbf{1}^T \mathbf{V}_{\lambda}^{-1} \mathbf{1}| = \log |\mathbf{1}^T \mathbf{1}|$, which does not depend on λ , so the differentiation reduces to finding the derivatives of $\log |\mathbf{V}_{\lambda}|$ and $\log(\mathbf{y}^{\mathsf{T}}\mathbf{P}_{\lambda}\mathbf{y})$. To that end we shall need the (component-wise) derivatives of V_{λ} and P_{λ} with respect to λ ; these can be shown to be:

$$\frac{\partial \mathbf{V}_{\lambda}}{\partial \lambda} = \lambda^{-1} (\mathbf{I} - \mathbf{V}_{\lambda}) \tag{1.13}$$

$$\frac{\partial \mathbf{P}_{\lambda}}{\partial \lambda} = \lambda^{-1} (\mathbf{P}_{\lambda} - \mathbf{P}_{\lambda}^{2}) \tag{1.14}$$

A formula in [2](p. 1016), together with (1.13), leads to

$$\frac{\partial}{\partial \lambda} \text{log} \mid \mathbf{V}_{\lambda} \mid = \lambda^{-1} \text{tr}(\mathbf{V}_{\lambda}^{-1} - \mathbf{I})$$

By (1.10), $\operatorname{tr}(\mathbf{V}_{\lambda}^{-1}) = \operatorname{tr}(\mathbf{P}_{\lambda}) + \operatorname{tr}[\mathbf{I} - \mathbf{1}(\mathbf{1}^{\mathsf{T}}\mathbf{1})^{-1}\mathbf{1}^{\mathsf{T}}] = \operatorname{tr}(\mathbf{P}_{\lambda}) + 1$, so we conclude that

$$\frac{\partial}{\partial \lambda} \log |\mathbf{V}_{\lambda}| = \lambda^{-1} [\operatorname{tr}(\mathbf{P}_{\lambda}) - (n-1)] \tag{1.15}$$

By Assumption 2, $\mathbf{y}^{\mathsf{T}}\mathbf{P}_{\lambda}\mathbf{y} > 0$. Thus, using (1.14), we obtain

$$\frac{\partial}{\partial \lambda} \log(\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda} \mathbf{y}) = \lambda^{-1} \left[1 - \frac{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda}^{2} \mathbf{y}}{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda} \mathbf{y}} \right]$$
(1.16)

Under our Assumptions, the matrix

$$\boldsymbol{P}_{\lambda} = \boldsymbol{V}_{\lambda}^{-1} - \boldsymbol{V}_{\lambda}^{-1} \boldsymbol{1} (\boldsymbol{1}^{\mathsf{T}} \boldsymbol{V}_{\lambda}^{-1} \boldsymbol{1})^{-1} \boldsymbol{1}^{\mathsf{T}} \boldsymbol{V}_{\lambda}^{-1}$$

which plays a role in some treatments of mixed model theory, turns out to be important for both the REML and the GCV approach to choosing λ . By (1.12), (1.16) and (??), we obtain

$$\frac{\partial l_{R}(\lambda | \mathbf{y})}{\partial \lambda} = \frac{1}{2\lambda} \left[(n-1) \frac{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda}^{2} \mathbf{y}}{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda} \mathbf{y}} - \operatorname{tr}(\mathbf{P}_{\lambda}) \right]$$
(1.17)

Thus by (1.7), (1.11) and (1.17), $\frac{\partial l_R(\lambda|y)}{\partial \lambda} = 0$ implies

$$\frac{(\mathbf{y} - \hat{\mathbf{\mu}}_{\lambda})^{\mathsf{T}} \mathbf{V}_{\lambda}^{-1} (\mathbf{y} - \hat{\mathbf{\mu}}_{\lambda})}{n - 1} = \frac{\mathbf{y}^{\mathsf{T}} (\mathbf{I} - \mathbf{H}_{\lambda})^{2} \mathbf{y}}{\mathsf{tr}(\mathbf{I} - \mathbf{H}_{\lambda})}$$
(1.18)

which is also

$$\frac{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda} \mathbf{y}}{\mathsf{n} - 1} = \frac{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda}^{2} \mathbf{y}}{\mathsf{tr}(\mathbf{P}_{\lambda})} \quad \text{or} \quad \frac{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda} \mathbf{y}}{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda}^{2} \mathbf{y}} = \frac{\mathsf{n} - 1}{\mathsf{tr}(\mathbf{P}_{\lambda})}$$
(1.19)

where $\hat{\mu}_{\lambda}$ and \mathbf{H}_{λ} are the parameter estimate and hat matrix, respectively, obtained with smoothing parameter value λ . The left side of (1.18) is the REML estimate of σ^2 [3]. The right side equals $\|\mathbf{y} - \hat{\mathbf{y}}\|^2 / [\mathbf{n} - \mathrm{tr}(\mathbf{H}_{\lambda})]$, an estimate of σ^2 based on viewing $\mathrm{tr}(\mathbf{H}_{\lambda})$ as the degrees of freedom of the smoother [4](p. 487) and [5](p. 279). In other words, when λ is estimated by REML, the REML error variance estimate agrees with the "smoothing-theoretic" variance estimate.

1.2 Derivative of GCV

The GCV criterion is given by

$$GCV(\lambda) = \frac{\parallel \mathbf{y} - \hat{\mathbf{y}} \parallel^2}{[1 - \operatorname{tr}(\mathbf{H}_{\lambda})/n]^2} = \frac{\mathbf{y}^{\mathsf{T}}(\mathbf{I} - \mathbf{H}_{\lambda})^2 \mathbf{y}}{[\operatorname{tr}(\mathbf{I} - \mathbf{H}_{\lambda})]^2} = \frac{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda}^2 \mathbf{y}}{[\operatorname{tr}(\mathbf{P}_{\lambda})]^2}$$

with the last equality following from (1.7). This criterion, originally proposed by [6], is an approximation to $\frac{1}{n}\sum_{i=1}^{n}\frac{(y_i-\hat{y}_i)^2}{(1-h_{\lambda[ii]})^2}$, where $h_{\lambda[11]},...,h_{\lambda[nn]}$ are the diagonal elements of \mathbf{H}_{λ} . The latter expression can be shown (at least in some smoothing problems) to be equal to the leave-one-out cross-validation criterion, but lacks an invariance-under-reparametrization property that is gained by instead using GCV [3](pp. 52-53). Using (1.14), we can obtain

$$\frac{\partial GCV(\lambda)}{\partial \lambda} = \frac{2}{\lambda [tr(\mathbf{P}_{\lambda})]^3} \left[tr(\mathbf{P}_{\lambda}^2) \mathbf{y}^{\mathsf{T}} P_{\lambda}^2 \mathbf{y} - tr(\mathbf{P}_{\lambda}) \mathbf{y}^{\mathsf{T}} P_{\lambda}^3 \mathbf{y} \right]$$
(1.20)

Thus at the GCV-minimizing λ we have

$$\frac{\mathbf{y}^\mathsf{T} \mathbf{P}_\lambda^3 \mathbf{y}}{\mathsf{tr}(\mathbf{P}_\lambda^2)} = \frac{\mathbf{y}^\mathsf{T} \mathbf{P}_\lambda^2 \mathbf{y}}{\mathsf{tr}(\mathbf{P}_\lambda)} \quad \text{or} \quad \frac{\mathbf{y}^\mathsf{T} \mathbf{P}_\lambda^3 \mathbf{y}}{\mathbf{y}^\mathsf{T} \mathbf{P}_\lambda^2 \mathbf{y}} = \frac{\mathsf{tr}(\mathbf{P}_\lambda^2)}{\mathsf{tr}(\mathbf{P}_\lambda)}$$

1.3 Derivative of AIC

The AIC criterion is given by

$$AIC(\lambda) = log(\parallel \mathbf{y} - \hat{\mathbf{y}} \parallel^2) + \frac{2}{n}[tr(\mathbf{H}_{\lambda}) + 1] = log(\mathbf{y}^{\mathsf{T}}\mathbf{P}_{\lambda}^2\mathbf{y}) + \frac{2}{n}tr(\mathbf{I} - \mathbf{P}_{\lambda}) + \frac{2$$

Using (1.14), we can obtain

$$\frac{\partial AIC(\lambda)}{\partial \lambda} = \frac{2}{\lambda} \left[1 - \frac{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda}^{3} \mathbf{y}}{\mathbf{y}^{\mathsf{T}} \mathbf{P}_{\lambda}^{2} \mathbf{y}} - \frac{1}{n} tr(\mathbf{P}_{\lambda} - \mathbf{P}_{\lambda}^{2}) \right]$$
(1.21)

Thus at the AIC-minimizing λ we have

$$\frac{\boldsymbol{y}^T\boldsymbol{P}_{\lambda}^3\boldsymbol{y}}{\boldsymbol{y}^T\boldsymbol{P}_{\lambda}^2\boldsymbol{y}} = \frac{\text{tr}(\boldsymbol{I} - \boldsymbol{P}_{\lambda} + \boldsymbol{P}_{\lambda}^2)}{n}$$

2 Derivation of the REML based Test Statistic

In this section, we derive the score test statistic based on REML [7].

Denote $V(\theta) = \sigma^2 V_{\lambda} = \sigma^2 I + \tau K_{\delta}$, where $\theta = (\delta, \lambda, \sigma^2)$. The REML given in (1.4) can be rewritten as

$$l_{R} = -\frac{1}{2} \left[\log |\mathbf{V}(\boldsymbol{\theta})| + \log |\mathbf{1}^{\mathsf{T}} \mathbf{V}(\boldsymbol{\theta})^{-1} \mathbf{1}| + (\mathbf{y} - \boldsymbol{\mu})^{\mathsf{T}} \mathbf{V}(\boldsymbol{\theta})^{-1} (\mathbf{y} - \boldsymbol{\mu}) \right]$$
(2.1)

Under H_0 : $\delta = 0$ (2.2.2), we set $\theta_0 = (0, \lambda, \sigma^2)$ and

$$\boldsymbol{P}_0(\boldsymbol{\theta}_0) = \boldsymbol{V}(\boldsymbol{\theta}_0)^{-1} - \boldsymbol{V}(\boldsymbol{\theta}_0)^{-1} \mathbf{1} [\mathbf{1}^\mathsf{T} \boldsymbol{V}(\boldsymbol{\theta}_0)^{-1} \mathbf{1}]^{-1} \mathbf{1}^\mathsf{T} \boldsymbol{V}(\boldsymbol{\theta}_0)^{-1}$$

Take the derivative of (2.1) with respect to δ ,

$$\begin{split} \frac{\partial l_R}{\partial \delta} &= -\frac{1}{2} \Big[\frac{\partial log \mid \mathbf{V}(\boldsymbol{\theta}) \mid}{\partial \delta} + \frac{\partial log \mid \mathbf{1}^T \mathbf{V}(\boldsymbol{\theta})^{-1} \mathbf{1} \mid}{\partial \delta} + \frac{\partial (\mathbf{y} - \boldsymbol{\mu})^T \mathbf{V}(\boldsymbol{\theta})^{-1} (\mathbf{y} - \boldsymbol{\mu})}{\partial \delta} \Big] \\ &= -\frac{1}{2} \Big[tr \big(\mathbf{V}(\boldsymbol{\theta})^{-1} \frac{\partial \mathbf{V}(\boldsymbol{\theta})}{\partial \delta} \big) + tr \big([\mathbf{1}^T \mathbf{V}(\boldsymbol{\theta})^{-1} \mathbf{1}]^{-1} \mathbf{1}^T \frac{\partial \mathbf{V}(\boldsymbol{\theta})^{-1}}{\partial \delta} \mathbf{1} \big) \\ &\quad + (\mathbf{y} - \boldsymbol{\mu})^T \frac{\partial \mathbf{V}(\boldsymbol{\theta})^{-1}}{\partial \delta} (\mathbf{y} - \boldsymbol{\mu}) \Big] \\ &= -\frac{1}{2} \Big[tr \big(\mathbf{V}(\boldsymbol{\theta})^{-1} \tau (\partial \mathbf{K}_{\delta}) \big) - tr \big(\tau (\partial \mathbf{K}_{\delta}) \mathbf{V}(\boldsymbol{\theta})^{-1} \mathbf{1} [\mathbf{1}^T \mathbf{V}(\boldsymbol{\theta})^{-1} \mathbf{1}^T \mathbf{V}(\boldsymbol{\theta})^{-1} \big) \\ &\quad - (\mathbf{y} - \boldsymbol{\mu})^T \mathbf{V}(\boldsymbol{\theta})^{-1} \tau (\partial \mathbf{K}_{\delta}) \mathbf{V}(\boldsymbol{\theta})^{-1} (\mathbf{y} - \boldsymbol{\mu}) \Big] \\ &= \frac{1}{2} (\mathbf{y} - \boldsymbol{\mu})^T \mathbf{V}(\boldsymbol{\theta})^{-1} \tau (\partial \mathbf{K}_{\delta}) \mathbf{V}(\boldsymbol{\theta})^{-1} (\mathbf{y} - \boldsymbol{\mu}) \\ &\quad - \frac{1}{2} tr \Big[\tau (\partial \mathbf{K}_{\delta}) \big[\mathbf{V}(\boldsymbol{\theta})^{-1} - \mathbf{V}(\boldsymbol{\theta})^{-1} \mathbf{1} [\mathbf{1}^T \mathbf{V}(\boldsymbol{\theta})^{-1} \mathbf{1}]^{-1} \mathbf{1}^T \mathbf{V}(\boldsymbol{\theta})^{-1} \big] \Big] \end{split}$$

where $\partial \mathbf{K}_{\delta}$ is the derivative kernel matrix whose $(i,j)^{\text{th}}$ entry is $\frac{\partial k_{\delta}(\mathbf{x},\mathbf{x}')}{\partial \delta}$. If we further denote $\mathbf{K}_0 = \mathbf{K}_{\delta} \mid_{\delta=0}$ and $\partial \mathbf{K}_0 = (\partial \mathbf{K}_{\delta}) \mid_{\delta=0}$, we get the REML based score function of δ evaluated at H_0

$$S_{\delta=0} = \frac{1}{2}(\boldsymbol{y} - \boldsymbol{\mu})^{\mathsf{T}} \mathbf{V}(\boldsymbol{\theta}_0)^{-1} \tau(\boldsymbol{\partial} \boldsymbol{K}_0) \mathbf{V}(\boldsymbol{\theta}_0)^{-1} (\boldsymbol{y} - \boldsymbol{\mu}) - \frac{1}{2} tr[\tau(\boldsymbol{\partial} \boldsymbol{K}_0) \boldsymbol{P}_0]$$

To test for H_0 : $\delta = 0$, we propose to use the sroce-based test statistic

$$\boldsymbol{\hat{T}}_0 = \boldsymbol{\hat{\tau}}(\boldsymbol{y} - \boldsymbol{\hat{\mu}})^{\mathsf{T}} \boldsymbol{V}_0^{-1} (\boldsymbol{\partial} \boldsymbol{K}_0) \boldsymbol{V}_0^{-1} (\boldsymbol{y} - \boldsymbol{\hat{\mu}})$$

where $\mathbf{V}_0 = \hat{\sigma}^2 \mathbf{I} + \hat{\tau} \mathbf{K}_0$.

References

- [1] Philip T. Reiss and R. Todd Ogden. Smoothing Parameter Selection for a Class of Semiparametric Linear Models. *JRSS-B*, 71(2), 2009.
- Bates. Newton—Raphson and EM [2] Mary J. Lindstrom and Douglas M. Algorithms Mixed-Effects Models Repeated-Measures Data. for Linear for Statistical Journal the American Association, 83(404):1014–1022, Decem-ISSN 0162-1459. 10.1080/01621459.1988.10478693. ber 1988. doi: URL https://doi.org/10.1080/01621459.1988.10478693.
- [3] G. Wahba. Spline Models for Observational Data. CBMS-NSF Regional Conference Series in Applied Mathematics. Society for Industrial and Applied Mathematics, January 1990. ISBN 978-0-89871-244-5. doi: 10.1137/1.9781611970128. URL https://epubs.siam.org/doi/book/10.1137/1.9781611970128.
- [4] Pawitan. *In All Likelihood: Statistical Modelling and Inference Using Likelihood*. Oxford University Press, Oxford, New York, August 2001. ISBN 978-0-19-850765-9.
- [5] Lee, Nelder, and Pawitan. Generalized Linear Models with Random Effects: Unified Analysis via H-likelihood, July 2006.
- [6] P. Craven and G. Wahba. Smoothing noisy data with spline functions | SpringerLink, 1979. URL https://link.springer.com/article/10.1007/BF01404567.
- [7] Arnab Maity and Xihong Lin. Powerful tests for detecting a gene effect in the presence of possible gene-gene interactions using garrote kernel machines. *Biometrics*, 67(4):1271–1284, December 2011. ISSN 1541-0420. doi: 10.1111/j.1541-0420.2011.01598.x.