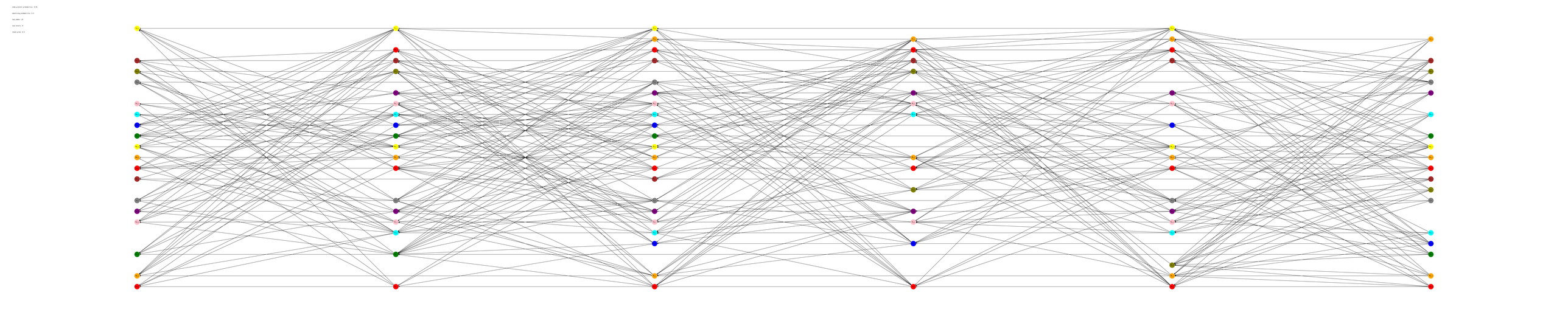

node_present_probability: 0.45
observing_probability: 0.4
bad_radius: 25
red_radius: 0
mean_prob: 0.2