FETHİYE IRMAK DOĞAN

OBJECTIVE Deploying autonomous robots in human environments to facilitate people's lives AREAS OF Human-Robot Interaction, Machine Learning, Deep Learning, Computer Vision INTEREST **EDUCATION** Ph.D. in Computer Science, KTH Royal Institute of Technology 01.2018-03.2023 - Thesis on Robots That Understand Natural Language Instructions and Resolve *Ambiguities* M.Sc. in Computer Engineering, Middle East Technical University 09.2015-01.2018 Thesis on Hierarchical Incremental Context Modeling on Robots Graduated with High Honor degree - CGPA: 3.93/4.00 B.Sc. in Computer Engineering, Middle East Technical University 09.2010-06.2015 - Graduated with Honor degree - CGPA: 3.40/4.00 EMPLOYMENT, Postdoctoral researcher at the Division of Robotics, Perception and Learning, KTH **EXPERIENCE** Royal Institute of Technology, SWEDEN 03.2023-present AND PROJECTS - Focusing on continual learning for robots in human environments leveraging explainability to help them with their daily tasks Doctoral researcher at the Division of Robotics, Perception and Learning, KTH Royal Institute of Technology, SWEDEN 01.2018-03.2023 Working on different follow-up clarification techniques (semantic or visual) for robots to resolve ambiguities in user instructions, supervised by Iolanda Leite Visiting scholar at the Robot Autonomy and Interactive Learning (RAIL) Lab, Georgia Institute of Technology, USA 11.2021-04.2022 Developing a semantically-driven disambiguation method to handle ambiguous user requests with clarifying questions, supervised by Sonia Chernova

Participating in Oxford Machine Learning Summer School 2021 07.2021-08.2021

– Selected to participate in the highly selective summer school ($\sim 15\%$ acceptance rate) for best-in-class training on machine learning and deep learning

Participating in Amazon Alexa Prize, Fantom Social Bot 02.2018-08.2018

 Selected as one of 8 teams among the applicants from leading 195 universities to create a social bot, supervised by Gabriel Skantze

 $Researcher \ at \ KOVAN \ Robotics \ Research \ Lab, \ Department \ of \ Computer \ Engineering, \\ Middle \ East \ Technical \ University, \ TURKEY \\ 09.2015-01.2018$

 Incremental context modeling for robots to make them capable of adapting to challenging real-world environments, supervised by Sinan Kalkan

Senior Design Project at Department of Computer Engineering, Middle East Technical University, TURKEY 09.2014-06.2015

 3D animation of fMRI data to visualize the cognitive processes in the brain, supervised by Fatos Tunay Yarman Vural

Internship at The Maersk Mc-Kinney Moller Institute, University of Southern Denmark, DENMARK 06.2014-09.2014

 A plugin providing a graphical user interface for automated calibration of UR robot arms, supervised by Norbert Krueger

Internship at KOVAN Robotics Research Lab, Department of Computer Engineering, Middle East Technical University, TURKEY 06.2013-09.2013

 Visualizing the 2D and 3D representations of the iCub robot's vision, supervised by Sinan Kalkan

Part time software developer at Özgür Yazılım Company, TURKEY 02.2013-06.2013

- Taking a role in the development of the Tekir Accounting Program

TEACHING

Lecturer at KTH Royal Institute of Technology, SWEDEN

10.2023-present

Master-level social robotics course

 $Teaching\ Assistant\ at\ KTH\ Royal\ Institute\ of\ Technology,\ SWEDEN\ 01.2019-03.2023$

- Master-level machine learning course

Teaching Assistant at Middle East Technical University, TURKEY 02.2014-06.2014

- C programming language course

MENTORING

KTH Royal Institute of Technology, SWEDEN

01.2019-present

- PhD Students: Ermanno Bartoli, and Anna Deichler
- Master Students: Shipra Jain, Jiaming Huang, Amrita Panesar, and Georgios Hadjiantonis
- Research Engineers: Shreya Kohli, Rasmus Rudling, and Alex Sleat
- High School Intern: Erik Eriksson

Georgia Institute of Technology, USA

11.2021 - 04.2022

- Master Student: Aswin Gururaj Prakash

Frontiers in Robotics and AI, 2023.

SCIENTIFIC

Journal Articles

CONTRIBUTIONS J1 F. I. Doğan, W. Liu, I. Leite, and S. Chernova, 'Semantically-Driven Disambiguation for Human-Robot Interaction,' ACM Transactions on

Human-Robot Interaction (THRI). (in preparation)

J2 F. I. Doğan, G. I. Melsión, and I. Leite, 'Leveraging Explainability for

Understanding Object Descriptions in Ambiguous 3D Environments,

J3 F. I. Doğan, S. Gillet, E. J. Carter, and I. Leite, 'The Impact of Adding Perspective-Taking to Spatial Referencing during Human-Robot Interaction,' Robotics and Autonomous Systems (RAS), 2020.

Refereed Conference Publications

- C1 E. Bartoli, F. I. Doğan, and I. Leite 'Streaming Network for Continual Learning of Object Relocations under Household Context Drifts', ICRA, 2024. (under review)
- C2 F. I. Doğan, I. Torre, and I. Leite, 'Asking Follow-Up Clarifications to Resolve Ambiguities in Human-Robot Conversation,' HRI, 2022.
- C3 M. Iovino, F. I. Doğan, I. Leite, and C. Smith, 'Interactive Disambiguation for Behavior Tree Execution,' *Humanoids*, 2022.
- C4 A Panesar, F. I. Doğan, and I. Leite, 'Improving Visual Question Answering by Leveraging Depth and Adapting Explainability' RO-MAN, 2022.
- C5 F. I. Doğan, S. Kalkan, and I. Leite, 'Learning to Generate Unambiguous Spatial Referring Expressions for Real-World Environments,' *IROS*, 2019.
- C6 P. Jonell, P. Fallgren, F. I. Doğan, J. Lopes, U. Wennberg, and G. Skantze, 'Crowdsourcing a self-evolving dialog graph,' *International Conference on Conversational User Interfaces (CUI)*, 2019.
- C7 F. I. Doğan*, İ. Bozcan*, M. Celik, and S. Kalkan, 'Cinet: A learning based approach to incremental context modeling in robots,' *IROS*, 2018.
- C8 F. I. Doğan, H. Çelikkanat, and S. Kalkan, 'A Deep Incremental Boltzmann Machine for Modeling Context in Robots,' ICRA, 2018.
- C9 F. I. Doğan, H. Çelikkanat, and S. Kalkan, 'Robotlarda Bağlamın Derin Artırımlı Boltzmann Makineleri ile Modellenmesi,' *Turkey Robotics Conference (ToRK)*, 2018. (written in Turkish)
- C10 F. I. Doğan, S. Kalkan, 'Bağlamın Hiyerarşik Doğası,' Turkey Robotics Conference (ToRK), 2016. (written in Turkish)

^{*} Equal Contribution

C11 O. Yıldız, F. I. Doğan, İ. Öztekin, E. Mızrak, and F. T. Y. Vural, 'A robust normalization method for fMRI data for brain decoding,' Signal Processing and Communication Application Conference (SIU), 2016.

Workshop Proposals

- P1 E. Yadollahi, M. Romeo, F. I. Doğan, W. Johal, M. D. Graaf, S. Levy-Tzedek and I. Leite, 'Explainability for Human-Robot Collaboration,' HRI, 2024.
- P2 M. Pattel*, F. I. Doğan*, Z. Zeng, K. Baraka, and S. Chernova, 'Semantic Scene Understanding for Human-Robot Interaction,' HRI, 2023.
- P3 W. Johal, L. Phaijit, F. I. Doğan, A. Tabrez, and M. Graaf, 'HRI for Explainable Robotics,' RO-MAN, 2023.

Refereed Workshop Publications

- W1 E. Bartoli, F. I. Doğan, and I. Leite, 'Contextualized Knowledge Graph Embeddings for Activity Prediction in Service Robotics,' Workshop on Semantic Scene Understanding for Human-Robot Interaction, HRI, 2023.
- W2 F. I. Doğan, 'Social Robots That Understand Natural Language Instructions and Resolve Ambiguities,' RSS Pioneers Workshop, RSS, 2021.
- W3 I. Torre, **F. I. Doğan**, and D. Kontogiorgos, 'Voice, Embodiment, and Autonomy as Identity Affordances,' Workshop on Robo-Identity: Exploring Artificial Identity and Multi-Embodiment, HRI, 2021.
- W4 F. I. Doğan, and I. Leite, 'Open Challenges on Generating Referring Expressions for Human-Robot Interaction,' Workshop on Natural Language Generation for Human-Robot Interaction, INLG, 2020.
- W5 F. I. Doğan, H. Çelikkanat, I. Bozcan, and S. Kalkan, 'Learning to Increment A Contextual Model,' Workshop on Continual Learning, NeurIPS, 2018.

Technical Reports

- T1 P. Jonell, M. Bystedt, **F. I. Doğan**, P. Fallgren, J. Ivarsson, M. Slukova, U. Wennberg, J. Lopes, J. Boye, and G. Skantze, 'Fantom: A crowdsourced social chatbot using an evolving dialog graph,' *Proceedings of Alexa Prize*, 2018.
- T2 F. I. Doğan, and S. Kalkan, 'Hierarchical Context Modeling Using Incremental Deep Boltzmann Machines,' Technical Report, Dept. of Computer Engineering, Middle East Technical University, 2017.

TALKS, DEMOS AND POSTERS

Seminar Talks

- Talking Robotics (a series of seminars about Robotics and its interaction with other relevant fields, such as AI and HRI), 2021
- Oxford Machine Learning Summer School, Unconference Track, 2021
- The Robot Autonomy and Interactive Learning (RAIL) Research Lab, School of Interactive Computing, Georgia Institute of Technology, 2021
- Image Lab, Department of Computer Engineering, Middle East Technical University, 2021

System Demonstration

- Invited demo on SIGDIAL Conference 2019

Poster presentations

- AI-CARING Symposium 2022
- SpLU-RoboNLP Workshop at the Conference of the North American Chapter of the Association for Computational Linguistics (NAACL-HLT 2019)
- SoRos Workshop 2018 and 2019
- Amazon Alexa Prize Summit 2018

HONORS, AWARDS AND GRANTS

- Fellowship from the Postdoc-NeT-AI in AI and Robotics (2022) which brings together outstanding early-career researchers with leading German institutions
- RSS Pioneer 2021, selected to participate in the Robotics: Science and Systems (RSS) Pioneers, which brings together the world's top early-career researchers
- Student travel grant from ICRA 2018, IROS 2018, NAACL-HLT 2019

- Honourable mention award in CUI 2019
- High honor certificates from Middle East Technical University (Spring 2014-2015, Fall 2014-2015, Spring 2013-2014, Fall 2013-2014)
- Honor certificate from Middle East Technical University (Spring 2012-2013)

SERVICES AND VOLUNTEERING

Organization Committee

- Workshop on Explainability for Human-Robot Collaboration, International Conference on Human-Robot Interaction (HRI), 2024
- Workshop on Semantic Scene Understanding for Human-Robot Interaction, International Conference on Human-Robot Interaction (HRI), 2023
- Workshop on HRI for Explainable Robotics, International Conference on Robot & Human Interactive Communication (RO-MAN), 2023
- RSS Pioneers Workshop, Robotics: Science and Systems (RSS), 2022

Program Committee

- Towards Autonomous Robotic Systems Conference, (TAROS) 2021
- Workshop on Spatial Language Understanding and Grounded Communication for Robotics (SpLU-RoboNLP), 2021 and 2023

Journal Article Referee

- Frontiers in Robotics and AI
- IEEE Robotics and Automation Letters (RA-L)
- Autonomous Robots (AURO)
- User Modeling and User-Adapted Interaction (UMUAI)

Conference Paper Referee

- Robotics: Science and Systems (RSS)
- Conference on Robot Learning (CoRL)
- International Conference on Robotics and Automation (ICRA)
- ACM/IEEE Conference on Human-Robot Interaction (HRI)
- International Conference on Intelligent Robots and Systems (IROS)
- Signal Processing and Communication Application Conference (SIU)
- Turkey Robotics Conference (ToRK)

Student Volunteer

- ACM/IEEE International Conference on Human-Robot Interaction (HRI 2022)
- International Conference on Autonomous Agents and Multiagent Systems (AAMAS 2018)

SELECTED OUTREACH

$Robotics\ demonstrations\ and\ presentations\ of\ current\ research$

- Swedish Foundation for Strategic Research (SSF), 2023
- KTH School of Electrical Engineering and Computer Science Lab Tours, 2023
- Atlanta Science Festival, Georgia Tech Science and Engineering Day, 2022
- Sveriges Television (SVT), 2020
- The Minister for Higher Education and Research (Matilda Ernkrans), 2019
- Robots Exhibition at the Tekniska Museum, 2019
- Giants event for female and non-binary high school students, 2018
- European Researchers' Night event for high school students, 2016

EXTRA-CURRICULAR ACTIVITIES

- Theater (played in private theaters for 8 years and 5 plays)
- Computer Engineers' Association (a sub-unit of Turkish Engineers' and Architects' Association) board member, 2016-2018
- Student Delegate Committee member at Middle East Technical University, 2010-2011