FETHİYE IRMAK DOĞAN

Postdoctoral Research Associate University of Cambridge, UK

* irmakdogan.com ✓ fid21@cam.ac.uk **OBJECTIVE** Advancing autonomous robots to understand, interact, and collaborate with people Human-Robot Interaction, Robot Learning, Explainability, Deep Learning INTERESTS Ph.D. in Computer Science, KTH Royal Institute of Technology **EDUCATION** 01.2018 - 03.2023- Thesis on Robots That Understand Natural Lang. Inst. and Resolve Ambiguities - 61.0 ECTS credits in PhD-level courses (≈ one academic year; graded pass/fail basis) M.Sc. in Computer Engineering, Middle East Technical University 09.2015-01.2018 - Thesis on Hierarchical Incremental Context Modeling on Robots - Graduated with High Honor degree - CGPA: 3.93/4.00 B.Sc. in Computer Engineering, Middle East Technical University 09.2010-06.2015 Graduated with Honor degree - CGPA: 3.40/4.00

EMPLOYMENT AND RESEARCH EXPERIENCE

Postdoctoral researcher at University of Cambridge, UK

04.2024-present

- Generating socially appropriate and adaptive robot actions leveraging LLMs and explainability, working in the AFAR Lab with Prof. Hatice Gunes

Postdoctoral researcher at KTH Royal Institute of Technology 03.2023-04.2024

- Continual learning for robots in human environments to help people with their daily tasks, working with Prof. Iolanda Leite's research group

Doctoral researcher at KTH (employed for 80% research, 20% teaching) 01.2018-03.2023

- Follow-up clarification techniques (semantic or visual) for robots to resolve ambiguities in user instructions, supervised by Prof. Iolanda Leite

Visiting scholar at Georgia Institute of Technology, USA 11.2021-04.2022

 Developing a semantically-driven disambiguation method to handle ambiguous user requests with clarifying questions, supervised by Prof. Sonia Chernova

Participating in Oxford Machine Learning Summer School 07.2021-08.2021

- Selected to participate in the highly selective summer school ($\sim 15\%$ acceptance rate) for best-in-class training on machine learning and deep learning

Participating in Amazon Alexa Prize, KTH Fantom Team 02.2018-08.2018

 Selected as one of 8 teams among the applicants from leading 195 universities to create a social bot, supervised by Prof. Gabriel Skantze

Researcher at Middle East Technical University, Turkey

09.2015-01.2018

- Incremental context modeling for robots to make them capable of adapting to challenging real-world environments, supervised by Prof. Sinan Kalkan

Senior Design Project at Middle East Technical University

09.2014-06.2015

 3D animation of fMRI data to visualize the cognitive processes in the brain, supervised by Prof. Fatos Tunay Yarman Vural

Research intern at University of Southern Denmark

06.2014-09.2014

 A plugin providing a graphical user interface for automated calibration of UR robot arms, supervised by Prof. Norbert Krueger

Research intern at Middle East Technical University

06.2013-09.2013

 Visualizing the 2D and 3D representations of the iCub robot's vision, supervised by Prof. Sinan Kalkan

Part time software developer at Özgür Yazılım Company

02.2013-06.2013

- Taking a role in the development of the Tekir Accounting Program

TEACHING

Guest Lecture in the Affective AI Course, University of Cambridge
Teaching Assistant at Interaction Design, University of Cambridge
Lecturer at Master-level social robotics course, KTH
Teaching Assistant at Master-level machine learning course, KTH
Teaching Assistant at C programming language course, METU

11.2024
04.2024-06.2024
10.2023-01.2024
01.2019-03.2023
02.2014-06.2014

SUPERVISION

University of Cambridge

04.2024-present

- Mentoring PhDs: Wang Tang (Sichuan University, Publication J4)
- Master Thesis Supervision: Rafal Karpiński (Utrecht University)
- BS Student Projects (Cambridge): Lara Horne, Yuval Weiss, Yasaswi Malladi
- Google DeepMind Intern: Yifei Shi (King's College London)
- Senior Thesis Supervision: Rahma Elsheikh: 'Approaching Equalized Odds by Actively Forgetting in Deep-Learning Models' (Princeton University)
- Visiting MS Student: Jesher Joshua (Vellore Institute of Technology)
- Visiting BS Students: Umut Ozyurt (METU, Publication C13), Gizem Çınar (Bilkent University, Publication C13), Sujith Sai (Rourkela National Institute of Technology), Zeynep Altundal (Sabanci University), Kajal Patel (University of Illinois at Urbana-Champaign)

KTH Royal Institute of Technology

01.2019 - 02.2025

- Mentoring PhDs: Ermanno Bartoli (Publication C14 and W6), and Anna Deichler
- Master Thesis Supervision:
 - (i) Alexander Leszczynski: 'LLMs and BTs for User Instructions' (Publication C15),
 - (ii) Aiman Shenawa: 'Task specific evaluation of Large Language Models',
 - (iii) Georgios Hadji.: 'Topic change in robot-mod. group diss.' (Publication C12),
 - (iv) Amrita Panesar: 'VQA with Depth and Adap. Expl.' (Publication C9)
- MS Project Supervision: Shipra Jain, Jiaming Huang
- Research Engineers: Shreya Kohli, Rasmus Rudling, and Alex Sleat
- High School Intern: Erik Eriksson

Georgia Institute of Technology

11.2021 - 04.2022

- MS Student: Aswin Gururaj Prakash

HONORS AND AWARDS

- Finalist for Outstanding Women in Robotics & Automation Paper Awards,
 IEEE Int. Conf. on Robotics & Automation (ICRA) 2025
- Seal of Excellence Award granted by the European Commission after a rigorous international expert project proposal evaluation (2025)
- Special Recognition for Outstanding Reviews, ACM/IEEE HRI 2024
- Research Associate at Darwin College, University of Cambridge, awarded through a competitive process for research excellence and academic merit (2024)
- Fellowship from Postdoc-NeT-AI (2022), which brings together outstanding early-career researchers in the field of artificial intelligence and robotics
- **RSS Pioneer 2021**, selected to participate in the Robotics: Science and Systems (RSS) Pioneers, which brings together the world's top early-career researchers
- Honourable mention award from ACM CUI 2019
- High honour certificates (Spring 2014-2015, Fall 2014-2015, Spring 2013-2014, Fall 2013-2014), and honour certificate (Spring 2012-2013) from METU

GRANTS AND FUNDS

- Contributor to the **Seed Fund Grant** ($\approx 10.000 \, \text{\pounds}$), University of Cambridge, 2024
- Travel grant from ACL Annual Conference of NAACL-HLT 2019
- Travel grant from IEEE Int. Conf. on Robotics and Automation (ICRA) 2018
- Travel grant from IEEE Int. Conf. on Intelligent Robots and Systems (IROS) 2018

INVITED TALKS

- Keynote speaker on Robo-Identity Workshop, IEEE RO-MAN 2025
- Keynote speaker on Collective Gen. Futures, CHIA Early Career Conf., 2025
- Science seminar, Darwin College, University of Cambridge, 2025
- Google DeepMind Research Ready Program, University of Cambridge, 2024
- Talking Robotics, a series of seminars about Robotics and AI, 2021
- Oxford Machine Learning Summer School, Unconference Track, 2021
- RAIL Research Lab seminar, Georgia Institute of Technology, 2021
- Image Lab seminar, Middle East Technical University, 2021

SCIENTIFIC CONTRIBUTIONS

Journal Articles

- J5 E. Yadollahi*, F. I. Doğan*, Y. Zhang, B. Nogueira, T. Guerreiro, S. Levy-Tzedek, and I. Leite, 'Expectations, Explanations, and Embodiment: Attempts at Robot Failure Recovery'. (under review for Int. Journal of Human-Computer Studies)
- J4 W. Tang, F. I. Dogan, L. Qing, H. Gunes, 'AsyReC: A Multimodal Graph-based Framework for Spatio-Temporal Asymmetric Dyadic Relationship Classification'. (under review for IEEE Transactions on Circuits and Systems for Video Technology)
- J3 N. Churamani, S. Checker, F. I. Doğan, H. L. Chiang, and H. Gunes 'Feature Aggregation with Latent Generative Replay for Federated Continual Learning of Socially Appr. Robot Behaviours'. (in prep. for IEEE Transactions on Robotics)
- J2 F. I. Doğan, G. I. Melsión, and I. Leite, 'Leveraging Explainability for Understanding Object Desc. in Ambiguous 3D Environments', Frontiers in Robotics and AI, 2023.
- J1 F. I. Doğan, S. Gillet, E. J. Carter, and I. Leite, 'The Impact of Adding Perspective-Taking to Spatial Referencing during Human-Robot Interaction', Robotics and Autonomous Systems (RAS), 2020.

Refereed Conference Publications

- C16 F. I. Doğan, U. Ozturk, G. Cinar, and H. Gunes, 'GRACE: Generating Socially Appr. Robot Actions Leveraging LLMs and Human Explanations', IEEE ICRA, 2025.
- C15 F. I. Doğan, M. Patel, W. Liu, I. Leite, and S. Chernova, 'A Model-Agnostic Appr. for Semantically-Driven Disamb. in HRI', IEEE RO-MAN, 2025.
- C14 N. I. Abbasi*, **F. I. Dogan***, G. Laban*, J. Anderson, T. Ford, P. B. Jones, H. Gunes, 'Robot-Led VLM Wellbeing Assess. of Children', *IEEE RO-MAN*, 2025.
- C13 A. Leszczynski, S.Gillet, I. Leite, and F. I. Dogan, 'A Test-Driven Appr. for Modular Unders. of User Instr. Leveraging BTs and LLMs', IEEE RO-MAN, 2025.
- C12 E. Bartoli, F. I. Doğan, and I. Leite 'Streaming Netw. for Cont. Learning of Object Reloc. under Household Context Drifts', IEEE RO-MAN, 2025.
- C11 G. Hadjiantonis, S. Gillet, M. Vázquez, I. Leite, and **F. I. Doğan**, 'Let's move on: Topic Change in Robot-Facilitated Group Discussions', *IEEE RO-MAN*, 2024.
- C10 F. I. Doğan, I. Torre, and I. Leite, 'Asking Follow-Up Clarifications to Resolve Ambiguities in Human-Robot Conversation', ACM/IEEE HRI, 2022.
- C9 M. Iovino, F. I. Doğan, I. Leite, and C. Smith, 'Interactive Disambiguation for Behavior Tree Execution', *IEEE Humanoids*, 2022.
- C8 A Panesar, F. I. Doğan, and I. Leite, 'Improving Visual Question Answering by Leveraging Depth and Adapting Explainability', IEEE RO-MAN, 2022.
- C7 F. I. Doğan, S. Kalkan, and I. Leite, 'Learning to Generate Unambiguous Spatial Referring Expressions for Real-World Environments', *IEEE IROS*, 2019.
- C6 P. Jonell, P. Fallgren, F. I. Doğan, J. Lopes, U. Wennberg, and G. Skantze, 'Crowdsourcing a self-evolving dialog graph', ACM CUI, 2019.
- C5 F. I. Doğan*, I. Bozcan*, M. Celik, and S. Kalkan, 'Cinet: A learning based approach to incremental context modeling in robots', *IEEE IROS*, 2018.

^{*} Equal Contribution

- C4 F. I. Doğan, H. Çelikkanat, and S. Kalkan, 'A Deep Incremental Boltzmann Machine for Modeling Context in Robots', IEEE ICRA, 2018.
- C3 P. Jonell, M. Bystedt, F. I. Doğan, P. Fallgren, J. Ivarsson, M. Slukova, U. Wennberg, J. Lopes, J. Boye, and G. Skantze, 'Fantom: A crowdsourced social chatbot using an evolving dialog graph', Proceedings of Alexa Prize SocialBot Grand Challenge, 2018.
- C2 O. Yıldız, F. I. Doğan, İ. Öztekin, E. Mızrak, and F. T. Y. Vural, 'A robust normalization method for fMRI data for brain decoding', *IEEE SIU*, 2016.
- C1 F. I. Doğan, S. Kalkan, 'The Hierarchical Nature of Context', Turkey Robotics Conference (ToRK), 2016. (written in Turkish)

Workshop Proposals

- P4 E. Yadollahi, F. I. Doğan, M. Romeo, D. Kontogiorgos, P. Qian, and Y. Zhang, 'Exp. in Human-Robot Collob.: Real-World Concerns', In Proc. of ACM/IEEE HRI, 2025.
- P3 E. Yadollahi, M. Romeo, F. I. Doğan, W. Johal, M. D. Graaf, S. Levy-Tzedek and I. Leite, 'Exp. for Human-Robot Collaboration', In Comp. of ACM/IEEE HRI, 2024.
- P2 M. Pattel*, F. I. Doğan*, Z. Zeng, K. Baraka, and S. Chernova, 'Semantic Scene Understanding for Human-Robot Interaction', In Comp. of ACM/IEEE HRI, 2023.
- P1 W. Johal, L. Phaijit, F. I. Doğan, A. Tabrez, and M. Graaf, 'HRI for Explainable Robotics', IEEE RO-MAN, 2023.

Refereed Workshop Contributions

- W6 E. Bartoli, F. I. Doğan, and I. Leite, 'Contextualized Knowledge Graph Embeddings for Activity Prediction in Service Robotics', Workshop on SSU for HRI, HRI 2023.
- W5 F. I. Doğan, 'Social Robots That Understand Natural Language Instructions and Resolve Ambiguities', RSS Pioneers Workshop, RSS 2021.
- W4 I. Torre, F. I. Doğan, and D. Kontogiorgos, 'Voice, Embodiment, and Autonomy as Identity Affordances', Workshop on Robo-Identity, HRI 2021.
- W3 F. I. Doğan, and I. Leite, 'Open Challenges on Generating Referring Expressions for Human-Robot Interaction', Workshop on NLG for HRI, INLG 2020.
- W2 F. I. Doğan, S. Kalkan, and I. Leite, 'Learning to Gen. Unambiguous Spatial Ref. Expressions for Real-World Env.', SpLU-RoboNLP Workshop, NAACL-HLT 2019.
- W1 F. I. Doğan, H. Çelikkanat, I. Bozcan, and S. Kalkan, 'Learning to Increment A Contextual Model', Workshop on Continual Learning, NeurIPS 2018.

Technical Reports

T1 F. I. Doğan, and S. Kalkan, 'Hierarchical Context Modeling Using Incremental Deep Boltzmann Machines', Technical Report, Dept. of Computer Eng., METU, 2017.

POSTERS AND DEMOS

- AI-CARING Symposium 2022
- Invited demo on SIGDIAL Conference 2019
- SpLU-RoboNLP Workshop at the NAACL-HLT Conference 2019
- SoRos Workshop 2018 and 2019
- Amazon Alexa Prize Summit 2018

COMMUNITY EVENTS AND SERVICES

Organization Committee

- Robotics and Embodied Intelligence Workshop, CHIA, University of Cambridge, 2025
- Workshop on Expl. in Human-Robot Collaboration: Real-World Concerns, HRI 2025
- Workshop on Explainability for Human-Robot Collaboration, HRI 2024
- Workshop on Semantic Scene Understanding for Human-Robot Interaction, HRI 2023
- Workshop on HRI for Explainable Robotics, RO-MAN 2023
- RSS Pioneers Workshop, Robotics: Science and Systems (RSS), 2022

^{*} Equal Contribution

Conference Session Chairing

- Chair of Human-Robot Interaction Session at IEEE ICRA 2025

Program Committee

- International Conference on Multimodal Interaction (ICMI), 2024
- Affective Computing and Intelligent Interaction Conference (ACII), 2024
- Towards Autonomous Robotic Systems Conference (TAROS), 2021
- SpLU-RoboNLP Workshop, 2021 and 2023

Journal Article Referee

- Frontiers in Robotics and AI
- IEEE Robotics and Automation Letters (RA-L)
- Autonomous Robots (AURO)
- User Modeling and User-Adapted Interaction (UMUAI)

Conference Paper Referee

- Robotics: Science and Systems (RSS)
- Conference on Robot Learning (CoRL)
- International Conference on Robotics and Automation (ICRA)
- International Conference on Human-Robot Interaction (HRI)
- International Conference on Intelligent Robots and Systems (IROS)
- ACM International Conference on Multimedia
- International Conference on Multimodal Interaction (ICMI)
- International Conf. on Robot & Human Interactive Communication (RO-MAN)
- Signal Processing and Communication Application Conference (SIU)
- Turkey Robotics Conference (ToRK)

Student Volunteer

- ACM/IEEE International Conference on Human-Robot Interaction (HRI), 2022
- Int. Conf. on Autonomous Agents and Multiagent Systems (AAMAS), 2018

SELECTED OUTREACH

- Featured in BBC Click by Spencer Kelly for his 1000th and final episode, 2025
- HE+ Hampshire Lecture, Trinity Hall, University of Cambridge 2025
- Trinity Hall Science Open Day, University of Cambridge 2025
- Human Machine Interaction Showcase, University of Cambridge, 2025
- Swedish Foundation for Strategic Research (SSF), 2023
- KTH School of Electrical Engineering and Computer Science Lab Tours, 2023
- Atlanta Science Festival, Georgia Tech Science and Engineering Day, 2022
- Featured in a documentary on Sveriges Television (SVT), 2020
- Sweden's Minister for Higher Education and Research (Matilda Ernkrans), 2019
- Robots Exhibition at the Swedish Tekniska Museum, 2019
- Giants event for female and non-binary high school students, 2018
- Live broadcast on national Turkish TV (Kanal B) on image processing and AI, 2017
- European Researchers' Night event for high school students, 2016

EXTRA-CURRICULAR

- Member of the Dept. Research Staff Forum, University of Cambridge (2024-present)
- Theater (played in private theatres for 8 years and 5 plays)
- Computer Engineers' Association board member, 2016-2018
- Student Delegate Committee member at Middle East Technical University, 2010-2011