# FETHİYE IRMAK DOĞAN

Postdoctoral Researcher University of Cambridge, UK

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OBJECTIVE	Deploying autonomous robots in human environments to facilitate people's lives
AREAS OF INTEREST	Human-Robot Interaction, Artificial Intelligence, Machine Learning, Deep Learning
EDUCATION	Ph.D. in Computer Science, KTH Royal Institute of Technology 01.2018-03.202  — Thesis on Robots That Understand Natural Lang. Inst. and Resolve Ambiguities  M.Sc. in Computer Engineering, Middle East Technical University 09.2015-01.202  — Thesis on Hierarchical Incremental Context Modeling on Robots  — Graduated with High Honor degree - CGPA: 3.93/4.00  B.Sc. in Computer Engineering, Middle East Technical University 09.2010-06.202
	- Graduated with Honor degree - CGPA: 3.40/4.00
EMPLOYMENT, EXPERIENCE AND PROJECTS	Postdoctoral researcher at University of Cambridge, UK  - Human behavior analysis for socially appropriate and adaptive human-robe interaction with Prof. Hatice Gunes
	Postdoctoral researcher at KTH Royal Institute of Technology 03.2023-04.202  - Continual learning for robots in human environments leveraging explainability to he people with their daily tasks, working with Prof. Iolanda Leite
	Doctoral researcher at KTH Royal Institute of Technology 01.2018-03.202  - Follow-up clarification techniques (semantic or visual) for robots to resolve ambiguitie in user instructions, supervised by Prof. Iolanda Leite
	Visiting scholar at Georgia Institute of Technology, USA 11.2021-04.202  - Developing a semantically-driven disambiguation method to handle ambiguous us requests with clarifying questions, supervised by Prof. Sonia Chernova
	Participating in Oxford Machine Learning Summer School 07.2021-08.202 – Selected to participate in the highly selective summer school ( $\sim 15\%$ acceptance rat for best-in-class training on machine learning and deep learning
	Participating in Amazon Alexa Prize, KTH Fantom Team  O2.2018-08.201  - Selected as one of 8 teams among the applicants from leading 195 universities to create a social bot, supervised by Prof. Gabriel Skantze
	Researcher at Middle East Technical University, Turkey 09.2015-01.202  - Incremental context modeling for robots to make them capable of adapting challenging real-world environments, supervised by Prof. Sinan Kalkan
	Senior Design Project at Middle East Technical University 09.2014-06.2020 - 3D animation of fMRI data to visualize the cognitive processes in the brain, supervised by Prof. Fatos Tunay Yarman Vural
	Research intern at University of Southern Denmark 06.2014-09.202  - A plugin providing a graphical user interface for automated calibration of UR robo arms, supervised by Prof. Norbert Krueger
	Research intern at Middle East Technical University 06.2013-09.202  - Visualizing the 2D and 3D representations of the iCub robot's vision, supervised by Prof. Sinan Kalkan
	Part time software developer at Özgür Yazılım Company 02.2013-06.201
TEACHING	<ul> <li>Taking a role in the development of the Tekir Accounting Program</li> <li>Lecturer at KTH Royal Institute of Technology</li> <li>10.2023-01.202</li> </ul>
	<ul> <li>Master-level social robotics course</li> <li>Teaching Assistant at KTH Royal Institute of Technology</li> <li>Master-level machine learning course</li> </ul>

Teaching Assistant at Middle East Technical University

– C programming language course

 $02.2014 \hbox{-} 06.2014$ 

- MS Students: Hossein Rezaei
- BS Students: Umut Ozyurt, Gizem Çınar

#### KTH Royal Institute of Technology

01.2019-present

- PhD Students: Ermanno Bartoli, and Anna Deichler
- MS Students: Shipra Jain, Jiaming Huang, Amrita Panesar, Georgios Hadjiantonis, Aiman Shenawa, Francesca Cipelli, Beatriz Nogueira and Alexander Leszczynski
- Research Engineers: Shreya Kohli, Rasmus Rudling, and Alex Sleat
- High School Intern: Erik Eriksson

## Georgia Institute of Technology

11.2021-04.2022

- MS Student: Aswin Gururaj Prakash

## SCIENTIFIC

### Journal Articles

#### CONTRIBUTIONS

- J1 F. I. Doğan, W. Liu, I. Leite, and S. Chernova, 'Semantically-Driven Disambiguation for Human-Robot Interaction,' RAS. (in preparation)
- J2 E. Bartoli, F. I. Doğan, and I. Leite 'Streaming Network for Continual Learning of Object Relocations under Household Context Drifts', RA-L. (in preparation)
- J3 F. I. Doğan, G. I. Melsión, and I. Leite, 'Leveraging Explainability for Understanding Object Desc. in Ambiguous 3D Environments,' Frontiers in Robotics and AI, 2023.
- J4 F. I. Doğan, S. Gillet, E. J. Carter, and I. Leite, 'The Impact of Adding Perspective-Taking to Spatial Referencing during Human-Robot Interaction,' RAS, 2020.

#### Refereed Conference Publications

- C1 G. Hadjiantonis, S. Gillet, M. Vázquez, I. Leite, and F. I. Doğan, 'Let's move on: Topic Change in Robot-Facilitated Group Discussions', RO-MAN. (under review)
- C2 F. I. Doğan, I. Torre, and I. Leite, 'Asking Follow-Up Clarifications to Resolve Ambiguities in Human-Robot Conversation,' HRI, 2022.
- C3 M. Iovino, F. I. Doğan, I. Leite, and C. Smith, 'Interactive Disambiguation for Behavior Tree Execution,' *Humanoids*, 2022.
- C4 A Panesar, F. I. Doğan, and I. Leite, 'Improving Visual Question Answering by Leveraging Depth and Adapting Explainability' RO-MAN, 2022.
- C5 F. I. Doğan, S. Kalkan, and I. Leite, 'Learning to Generate Unambiguous Spatial Referring Expressions for Real-World Environments,' IROS, 2019.
- C6 P. Jonell, P. Fallgren, F. I. Doğan, J. Lopes, U. Wennberg, and G. Skantze, 'Crowdsourcing a self-evolving dialog graph,' CUI, 2019.
- C7 F. I. Doğan\*, İ. Bozcan\*, M. Celik, and S. Kalkan, 'Cinet: A learning based approach to incremental context modeling in robots,' *IROS*, 2018.
- C8 F. I. Doğan, H. Çelikkanat, and S. Kalkan, 'A Deep Incremental Boltzmann Machine for Modeling Context in Robots,' ICRA, 2018.
- C9 F. I. Doğan, H. Çelikkanat, and S. Kalkan, 'Robotlarda Bağlamın Derin Artırımlı Boltzmann Makineleri ile Modellenmesi,' Turkey Robotics Conference (ToRK), 2018.
- C10 F. I. Doğan, S. Kalkan, 'Bağlamın Hiyerarşik Doğası,' Turkey Robotics Conference (ToRK), 2016.
- C11 O. Yıldız, F. I. Doğan, İ. Öztekin, E. Mızrak, and F. T. Y. Vural, 'A robust normalization method for fMRI data for brain decoding,' SIU, 2016.

## Workshop Proposals

- P1 E. Yadollahi, M. Romeo, F. I. Doğan, W. Johal, M. D. Graaf, S. Levy-Tzedek and I. Leite, 'Explainability for Human-Robot Collaboration,' HRI, 2024.
- P2 M. Pattel\*, F. I. Doğan\*, Z. Zeng, K. Baraka, and S. Chernova, 'Semantic Scene Understanding for Human-Robot Interaction,' HRI, 2023.
- P3 W. Johal, L. Phaijit, **F. I. Doğan**, A. Tabrez, and M. Graaf, 'HRI for Explainable Robotics,' RO-MAN, 2023.

<sup>\*</sup> Equal Contribution

### Refereed Workshop Publications

- W1 E. Bartoli, F. I. Doğan, and I. Leite, 'Contextualized Knowledge Graph Embeddings for Activity Prediction in Service Robotics,' Workshop on SSU for HRI, HRI 2023.
- W2 F. I. Doğan, 'Social Robots That Understand Natural Language Instructions and Resolve Ambiguities,' RSS Pioneers Workshop, RSS 2021.
- W3 I. Torre, F. I. Doğan, and D. Kontogiorgos, 'Voice, Embodiment, and Autonomy as Identity Affordances,' Workshop on Robo-Identity, HRI 2021.
- W4 F. I. Doğan, and I. Leite, 'Open Challenges on Generating Referring Expressions for Human-Robot Interaction,' Workshop on NLG for HRI, INLG 2020.
- W5 F. I. Doğan, H. Çelikkanat, I. Bozcan, and S. Kalkan, 'Learning to Increment A Contextual Model,' Workshop on Continual Learning, NeurIPS 2018.

## Technical Reports

- T1 P. Jonell, M. Bystedt, **F. I. Doğan**, P. Fallgren, J. Ivarsson, M. Slukova, U. Wennberg, J. Lopes, J. Boye, and G. Skantze, 'Fantom: A crowdsourced social chatbot using an evolving dialog graph,' *Proceedings of Alexa Prize*, 2018.
- T2 F. I. Doğan, and S. Kalkan, 'Hierarchical Context Modeling Using Incremental Deep Boltzmann Machines,' *Technical Report, Dept. of Computer Eng., METU*, 2017.

# POSTERS AND DEMOS

- AI-CARING Symposium 2022
- Invited demo on SIGDIAL Conference 2019
- SpLU-RoboNLP Workshop at the NAACL-HLT Conference 2019
- SoRos Workshop 2018 and 2019
- Amazon Alexa Prize Summit 2018

#### INVITED TALKS

- Talking Robotics, 2021
- Oxford Machine Learning Summer School, Unconference Track, 2021
- RAIL Research Lab, Georgia Institute of Technology, 2021
- Image Lab, Middle East Technical University, 2021

#### HONORS AND AWARDS

- Fellowship from the Postdoc-NeT-AI in AI and Robotics (2022) which brings together outstanding early-career researchers with leading German institutions
- RSS Pioneer 2021, selected to participate in the Robotics: Science and Systems (RSS) Pioneers, which brings together the world's top early-career researchers
- Honourable mention award in CUI 2019
- High honor certificates (Spring 2014-2015, Fall 2014-2015, Spring 2013-2014, Fall 2013-2014), and honor certificate (Spring 2012-2013) from Middle East Technical University

## GRANTS

- Travel grant from Annual Conference of NAACL-HLT 2019
- Travel grant from International Conf. on Robotics and Automation (ICRA) 2018
- Travel grant International Conf. on Intelligent Robots and Systems (IROS) 2018

# SERVICES AND VOLUNTEERING

### Organization Committee

- Workshop on Explainability for Human-Robot Collaboration, HRI 2024
- Workshop on Semantic Scene Understanding for Human-Robot Interaction, HRI 2023
- Workshop on HRI for Explainable Robotics, RO-MAN 2023
- RSS Pioneers Workshop, Robotics: Science and Systems (RSS), 2022

## Program Committee

- International Conference on Multimodal Interaction (ICMI), 2024
- Affective Computing and Intelligent Interaction Conference (ACII), 2024
- Towards Autonomous Robotic Systems Conference (TAROS), 2021
- SpLU-RoboNLP Workshop, 2021 and 2023

## Journal Article Referee

- Frontiers in Robotics and AI
- IEEE Robotics and Automation Letters (RA-L)
- Autonomous Robots (AURO)
- User Modeling and User-Adapted Interaction (UMUAI)

#### Conference Paper Referee

- Robotics: Science and Systems (RSS)
- Conference on Robot Learning (CoRL)
- International Conference on Robotics and Automation (ICRA)
- International Conference on Human-Robot Interaction (HRI)
- International Conference on Intelligent Robots and Systems (IROS)
- International Conf. on Robot & Human Interactive Communication (RO-MAN)
- Signal Processing and Communication Application Conference (SIU)
- Turkey Robotics Conference (ToRK)

#### Student Volunteer

- ACM/IEEE International Conference on Human-Robot Interaction (HRI), 2022
- Int. Conf. on Autonomous Agents and Multiagent Systems (AAMAS), 2018

## SELECTED OUTREACH

- Swedish Foundation for Strategic Research (SSF), 2023
- KTH School of Electrical Engineering and Computer Science Lab Tours, 2023
- Atlanta Science Festival, Georgia Tech Science and Engineering Day, 2022
- Sveriges Television (SVT), 2020
- The Minister for Higher Education and Research (Matilda Ernkrans), 2019
- Robots Exhibition at the Swedish Tekniska Museum, 2019
- Giants event for female and non-binary high school students, 2018
- European Researchers' Night event for high school students, 2016