YAOKUN LI

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RESEARCH INTEREST

My research interests center around generalizable neural representations, 3D reconstruction, and face analysis/editing. In the long term, I strive to advance lightweight, generalizable representation learning for 3D objects/scenes, aiming to achieve effective 3D representations tailored for real-world applications. In the near term, I tend to do some work on generalizable 3D representation and 3D facial/body reconstruction.

BACKGROUND

Sun Yat-sen University

Successive master-doctor program in Control Science and Engineering Supervisor: Prof. Guang Tan & Assoc. Prof. Chao Gou Shenzhen, China Sep. 2021 – present

Wuhan University of Technology

B.Eng. in Vehicle Engineering Military service Wuhan, China Sep. 2015 – Sep. 2016 & Sep. 2018 – Jun. 2021 Sep.2016 – Sep. 2018

RESEARCH

Publications

- Yaokun Li, Guang Tan, and Chao Gou. "Cascaded Iterative Transformer for Jointly Predicting Facial Landmark, Occlusion Probability and Head Pose." International Journal of Computer Vision (IJCV).
 - We propose a task-dependent inspired cascaded iterative transformer multitasking framework for joint prediction of facial landmark, occlusion probability, and pose.
- Yuchen Zhou, Guang Tan, Rui Zhong, Yaokun Li, and Chao Gou. "PIT: Progressive Interaction Transformer for Pedestrian Crossing Intention Prediction." IEEE Transactions on Intelligent Transportation Systems (TITS).
 - We propose a progressive interaction transformer to capture the dynamic spatiotemporal interactions between humans, vehicles, and the environment more progressively as humans do.
- Yaokun Li, Yuezhao Yu, Yuliang Liu, and Chao Gou. "MS-GCN: Multi-Stream Graph Convolution Network for Driver Head Pose Estimation." (ITSC 2022)
 - We propose a multi-stream graph convolution network to incorporate topological, local, and global facial information for driver's head pose estimation.

Under review

- Yaokun Li, Chao Gou, Shuaixian Wang, and Guang Tan. "Taming Uncertainty in Generalizable NeRF with Sparse Inputs using Indirect Diffusion-Guided Latent Space." (ICRA 2024)
 - We propose ID-NeRF, a generalizable NeRF that leverages a pre-trained diffusion model to offer indirect guidance in resolving uncertainty from sparse inputs.

AWARDS

- 2023: Third Prize of 2023 "Huawei Cup" National Graduate Student Mathematical Modeling Competition
- 2022: Honorable mention in HACKPKU 2022
- 2019: China National Scholarship

SKILLS

- Programming Languages: Python, C.
- Framework: Pytorch, Tensorflow.
- Languages: Chinese (native), English (daily communication, academic reading and writing).