

Definition

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|------------------|--|
| Linear Functions | All terms are of degree 0 or 1. A solution of a system of linear equation is set of points that makes the equation system true. |
| Consistent | lin. systems is consistent if either 1 or ∞ solutions exist else inconsistent. |
| Conist | |

Coefficient Matrix

$$\begin{cases} A_1x_1 + A_2x_2 + A_3x_3 = \alpha \\ B_1x_1 + B_2x_2 + B_3x_3 = \beta \\ C_1x_1 + C_2x_2 + C_3x_3 = \gamma \end{cases} \Leftrightarrow \begin{bmatrix} A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \\ C_1 & C_2 & C_3 \end{bmatrix} \quad (1)$$

Augmented Matrix

$$\begin{cases} A_1x_1 + A_2x_2 + A_3x_3 = \alpha \\ B_1x_1 + B_2x_2 + B_3x_3 = \beta \\ C_1x_1 + C_2x_2 + C_3x_3 = \gamma \end{cases} \Leftrightarrow \left[\begin{array}{ccc|c} A_1 & A_2 & A_3 & \alpha \\ B_1 & B_2 & B_3 & \beta \\ C_1 & C_2 & C_3 & \gamma \end{array} \right] \quad (2)$$

Row-Equivalence

Two matrce are row-equivalent if there is a sequence of **EROS** that transforms one into the other.

Elementary Row Operations (EROS)

1. **[Replacement]** Replace one row by sum of itself.
2. **[Interchange]** Swap position of 2 rows.
3. **[Scaling]** Multiply all entries in row by non-zero constant.

Echelon Form (ef)

1. All non-zero rows are above any rows of all-zero.
2. Each leading entry of a row is in a column to the right of the roe above it.
3. All entries in a column below a leading entry are 0.

Reduced Row Echelon Form (rref)

1. As to be in echelon form.
2. Leading entry in each row is 1.
3. Each leading 1 is the only non-zero entry in its column.

Theorems



Theorem 1 Every matrix is row equivalent to a unique row echelon form.

Theorem 2 Every matrix is row equivalent to a unique row echelon form.

Orthogonality and Diagonalization

Definition

| | |
|---------------------|--|
| Inner Product | $\vec{v} \cdot \vec{u} = \vec{v}^T \vec{u} = u_1v_1 + \dots + u_nv_n$ (Also called dot product or scalar product) |
| Length of \vec{x} | $ \vec{x} = \sqrt{\vec{x} \cdot \vec{x}} = \sqrt{x_1^2 + \dots + x_n^2}$ (Also called Norm or Magnitude) |
| Unit vectore | A vector with $ \vec{x} = 1$ |
| Normalization | The formula $\vec{u} = \frac{\vec{x}}{ \vec{x} }$ creat a unit vector in the same direction as \vec{x} . |

| | |
|---------------|--|
| Distance | $dist(\vec{u}, \vec{v}) = \vec{u} - \vec{v}$  |
| Orthogonality | $\vec{u} \cdot \vec{v}$  |

Theorems

Properties 1 Let $\vec{u}, \vec{v}, \vec{w} \in \mathbb{R}^n$ and $c \in \mathbb{R}^n$ then:

- $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$
- $(\vec{u} + \vec{v}) \cdot \vec{w} = \vec{u} \cdot \vec{w} + \vec{v} \cdot \vec{w}$
- $(c\vec{u}) \cdot \vec{v} = c(\vec{u} \cdot \vec{v}) = (c\vec{v}) \cdot \vec{u}$
- $\vec{u} \cdot \vec{u} = u_1^2 + \dots + u_n^2 \geq 0$