

# Historical biogeography in RevBayes

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## 1 Introduction

Using RevBayes, this lab describes how to perform Bayesian inference of historical biogeography using RevBayes. The analysis jointly infers the posterior range evolution parameters and ancestral ranges using the data augmentation approach described in Landis et al. (2013). To generate hypotheses, we will explore the resulting posterior using Tracer, an MCMC analysis tool created by Andrew Rambaut, and Phylowood, a Javascript web service that animates and filters phylogenetic biogeography reconstructions (Landis and Bedford 2014). Finally, we will quantify and plot certain qualities of the inferred biogeographic posterior using R.

### Outline

- 1) Brief overview of model and method
- 2) Historical biogeography analysis
  - 2.a) Input
  - 2.b) MCMC inference
- 3) Review results.
  - 3.a) Parameter output
  - 3.b) Ancestral range output
  - 3.c) Visualize ancestral range reconstructions.

→ These little arrows indicate lines containing key information to progress through the lab. The rest of the text gives context for why we're taking these steps or what to make of results.

### 1.1 Handy links for this lab

Lab zip file	[ NESCent URL ]
RevBayes	<a href="https://github.com/revbayes/revbayes">https://github.com/revbayes/revbayes</a>
Phylowood software	<a href="http://mlandis.github.io/phylowood">http://mlandis.github.io/phylowood</a>
Phylowood manual	<a href="https://github.com/mlandis/phylowood/wiki">https://github.com/mlandis/phylowood/wiki</a>
Tracer	<a href="http://tree.bio.ed.ac.uk/software/tracer">http://tree.bio.ed.ac.uk/software/tracer</a>

## 1.2 Setting up your workspace

The practical part of the lab will analyze a small dataset of 19 taxa distributed over 4 biogeographic areas. Parts of the lab will require entering terminal commands, which will assume you are using the Unix shell `bash`. Just ask for help if the commands don't seem to work.

- Portions of this lab require `R` is installed, along with the `stringr` and `ggplot2` packages.
- This tutorial will assume you have successfully installed `RevBayes` and can be called from your current working directory.
- Download and unzip the lab zip file, `bayarea_lab.zip`, into `~/apps/bayarea_1.0.2`.
- Copy all files into `./examples/`

```
> ls bayarea_lab
my_data.txt           my_run.area_states.txt
my_geo.txt            my_run.nhx
my_lab_run.sh         my_run.parameters.txt
my_other_run.parameters.txt my_tree.txt
my_run.area_probs.txt pp_range.py

> cp bayarea_lab/* ./examples
```

- Move the shell script, `my_lab_run.sh`, into the main app directory, and set the file to be executable

```
> mv examples/my_lab_run.sh .
> chmod 766 my_lab_run.sh
```

## 2 Model and method

This section contains a brief description of the data, model, parameters, and method used in `BayArea`.

First, we define the range for taxon  $i$  as the bit vector  $X_i$ , where  $X_{i,j} = 1$  if the taxon is present in area  $j$  and  $X_{i,j} = 0$  if the taxon is absent. Each taxon range is a bit vector of length  $N$  areas. For example, if taxon  $B$  is present only in areas 2 and 3 out of  $N = 3$  areas, its range is represented as  $X_B = (0, 1, 1)$ , which is translated to the bit string  $X_B = 011$  for short. The data matrix,  $\mathbf{X}$ , is analogous to a multiple sequence alignment where each element in the data matrix reports a

discrete value for a homologous character shared by all taxa at column  $j$ . How to choose areas to define species ranges will not be covered in this tutorial.

Next, we need a model of range evolution. Since we have discrete characters we'll use the continuous-time Markov chain, which allows us to compute transition probability of a character changing from  $i$  to  $j$  in time  $t$  through matrix exponentiation

$$\mathbf{P}_{i,j}(t) = [\exp \{\mathbf{Q}t\}]_{i,j},$$

where  $\mathbf{Q}$  is the instantaneous rate matrix defining the rates of change between all pairs of characters, and  $\mathbf{P}$  is the transition probability rate matrix. This technique of matrix exponentiation is powerful because it integrates over all possible scenarios of character transitions that could occur during  $t$  so long as the chain begins in state  $i$  and ends in state  $j$ .

We can then encode range evolution events into the allowed character transitions of  $\mathbf{Q}$  and parameterize the events so that we may infer their relative importance to generating our observed ranges. We'll take a simple model of range expansion (e.g.  $011 \rightarrow 111$ ) and range contraction (e.g.  $011 \rightarrow 001$ ). (Range expansion may also be referred to as dispersal or area gain and range contraction as extirpation or area loss.) The rates in the transition matrix for three areas might appear as

$$\mathbf{Q} = \begin{array}{c|ccccccc} & 001 & 010 & 011 & 100 & 101 & 110 & 111 \\ \hline 001 & - & 0 & \lambda & 0 & \lambda & 0 & 0 \\ 010 & 0 & - & \lambda & 0 & 0 & \lambda & 0 \\ 011 & \lambda & \lambda & - & 0 & 0 & 0 & \lambda \\ 100 & 0 & 0 & 0 & - & \lambda & \lambda & 0 \\ 101 & \lambda & 0 & 0 & \lambda & - & 0 & \lambda \\ 110 & 0 & \lambda & 0 & \lambda & 0 & - & \lambda \\ 111 & 0 & 0 & 0 & \lambda & \lambda & \lambda & - \end{array},$$

where  $\lambda$  is the rate of area gain or loss. This can also be represented compactly as the rate function

$$q_{\mathbf{y},\mathbf{z}}^{(a)} = \begin{cases} \lambda & \mathbf{y} \text{ and } \mathbf{z} \text{ differ in exactly one area} \\ 0 & \mathbf{y} \text{ and } \mathbf{z} \text{ differ in more than one area} \end{cases},$$

where  $\mathbf{y}$  and  $\mathbf{z}$  are the “from” and “to” ranges and  $a$  is the area that changes. For example,  $q_{011,111}^{(1)}$  is the rate of range expansion for  $011 \rightarrow 111$  to gain area 1. Note the rate of more than one event occurring simultaneously is zero, so a range must expand twice by one area in order to expand by two areas. This model is analogous to the Jukes-Cantor model, but uses binary characters instead of 4-state nucleotides.

There are several simple ways to extend this model. For example, the rate of area gain and area loss ( $\lambda_0$  and  $\lambda_1$ , resp.) may differ as

$$q_{\mathbf{y},\mathbf{z}}^{(a)} = \begin{cases} \lambda_0 & \text{if } z_a = 0 \\ \lambda_1 & \text{if } z_a = 1 \\ 0 & \mathbf{y} \text{ and } \mathbf{z} \text{ differ in more than one area} \end{cases}.$$

In addition, you may want to assign transition probabilities to entering the all-zero “extinction” state – an absorbing state that has a zero probability of being left (barring resurrection). In

addition, it may not be that any species is equally likely to be present or absent in any given area, i.e.  $\pi_0 \neq \pi_1$  but  $\pi_0 + \pi_1 = 1$ . This could be parameterized using state frequencies (much like as is done with base frequencies in the Felsenstein 84 model).

$$q_{\mathbf{y},\mathbf{z}}^{(a)} = \begin{cases} 2\pi_0\lambda_0 & \text{if } z_a = 0 \\ 2\pi_1\lambda_1 & \text{if } z_a = 1 \\ 0 & \mathbf{y} = 00\dots 0 \\ 0 & \mathbf{y} \text{ and } \mathbf{z} \text{ differ in more than one area} \end{cases}.$$

Finally, we may reasonably expect that a range expansion event into an area depends on which nearby areas are currently inhabited. The transition rate might then appear as

$$q_{\mathbf{y},\mathbf{z}}^{(a)} = \begin{cases} 2\pi_0\lambda_0 & \text{if } z_a = 0 \\ 2\pi_1\lambda_1\eta(\mathbf{y},\mathbf{z},a,\beta) & \text{if } z_a = 1 \\ 0 & \mathbf{y} = 00\dots 0 \\ 0 & \mathbf{y} \text{ and } \mathbf{z} \text{ differ in more than one area} \end{cases}.$$

For this tutorial, you can take  $\eta(\cdot)$  to adjust the rate of range expansion into area  $a$  by considering how close it is to the current range,  $\mathbf{y}$  relative to the closeness of all other areas unoccupied by the taxon. The  $\beta$  parameter rescales the importance of geographic distance between two areas by a power law. Importantly,  $\eta(\cdot) = 1$  when  $\beta = 0$ , meaning geographic distance between areas is irrelevant. Moreover, when  $\beta > 0$ ,  $\eta(\cdot) < 1$  when area  $a$  is relatively distant and  $\eta(\cdot) > 1$  when area  $a$  is relatively close.

Let's consider what happens to the size of  $\mathbf{Q}$  when the number of areas,  $N$ , becomes large. For three areas,  $\mathbf{Q}$  is size  $8 \times 8$ . For ten areas,  $\mathbf{Q}$  is size  $1024 \times 1024$ , which approaches the largest size matrix that can be exponentiated in a practical amount of time. This is problematic, meaning we need an alternative method to integrate over historical range evolution events.

You may wonder why matrix exponentiation works fine for molecular substitution models and large multiple sequence alignments. Because recombination degrades linkage disequilibrium over geological timescales, molecular substitution models typically assume each site in the multiple sequence alignment evolves independently. Conveniently, this keeps  $\mathbf{Q}$  small even for datasets with many sites.

Remember matrix exponentiation integrates over all *unobserved* transition events during time  $t$ . The likelihood of beginning in character  $i$  and ending in character  $j$  can be computed easily when the explicit series of event types and times are known. While we will never know the exact history of events, we can use stochastic mapping in conjunction with Markov chain Monte Carlo (MCMC) to repeatedly sample range evolution histories that are consistent with the ranges observed in the study taxa at the tips of the phylogeny.

This is the strategy used in BayArea to infer the posterior distribution approximated is  $\text{Prob}(\mathbf{X}_{aug}, \theta \mid \mathbf{X}_{obs}, T, M)$ , where  $\mathbf{X}_{obs}$  is the range data observed at the tips,  $\mathbf{X}_{aug}$  is the distribution of ancestral range reconstructions over the phylogeny,  $T$ , where  $\mathbf{X}_{aug}$  is inferred jointly with the parameters,  $\theta$ , assuming the range evolution model,  $M$ , that describes  $\mathbf{Q}$  above. Ancestral range reconstructions are often of primary interest in phylogenetic biogeographic analyses, which are generated with support values as a by-product of the MCMC analysis.

The rest of the tutorial will describe how to assemble the input, run the analysis, assess the output, and visualize the results.

### 3 Input

For this tutorial, we'll use a dataset for 19 species of *Psychotria* whose range spans the Hawaiian archipelago. The dataset was originally reported in Nepokroeff et al. (2003) and analyzed using the likelihood-based historical biogeography method, LAGRANGE, by Ree and Smith (2008). We'll use this dataset for three reasons. First, it is relatively small, meaning we can produce results quickly. Second, the Hawaiian archipelago can be broken into naturally discrete areas and has a well-characterized geographical history that is uncomplicated to model. Third, it has previously been analyzed, which provides some basis for comparison to other methods.

The model will assume presence-absence characters are recorded without error.

#### 3.1 Nexus file

The data file contains a matrix of binary characters corresponding to the observed ranges of the study taxa.

→ Open the file `examples/psychotria_range.txt`.

```
#NEXUS

begin data;
  dimensions ntax=19 nchar=4;
  format datatype=standard symbols = "01";
  matrix
    P_fauriei2          0100
    P_grandiflora_Kal2  1000
    ...
    P_wawraeDL7428      1000
  ;
end;

Begin trees;
  TREE tree1 = (((((((P_hawaiiensis_WaikamoiL1:1.0853
,P_mauiensis_Eke:1.0853)N2:0.7964,(P_fauriei2:1.3826,
P_hathewayi_1:1.3826)N5:0.4991)N6:0.1986,(
...
2.6568)N33:0.5204,P_hexandra_Oahu:3.1772)N35:2.6659)N36;
End;
```

Range data is stored in standard Nexus format. In the `data` block, the first line gives the dimensions of the data matrix and the second line indicates we will be using binary characters. The four characters correspond to areas defined by the geography file (next subsection). Rows in the `matrix` block correspond to taxa and their range data, while columns give in which areas each taxon is present (1) or absent (0). For example, taxon `P_fauriei2` is present only in area 2.

The `trees` block gives the tree describing the shared ancestry of the study species. Because range evolution occurs in units of geological time, the analysis in this tutorial requires a high-quality time-calibrated phylogeny. This typically requires a multiple sequence alignment over several loci plus fossils for calibration. Since this data availability is often the limiting factor for which taxa to include for your analysis, it is best to produce the phylogeny first. Only afterwards should you begin assembling data for your data matrix. If your phylogeny cannot be calibrated (e.g. it has no fossils) your best alternative is to proceed with a time tree resulting from a divergence time estimation analysis. For this tutorial, the phylogeny is assumed to contain no uncertainty.

## 3.2 Atlas file

Although the model will use discrete-state biogeographic ranges, geographical area is naturally continuous. This means we must impose some discretization upon the geography to designate a set of biogeographically meaningful characters called areas. Different methods use different criteria for this discretization, so it is best to perform the discretization yourself rather than blindly using the discretization given from a previous study or method (but do blindly use the dataset included in this tutorial). Some geographies have natural discretizations: for instance, the Hawaiian archipelago forms naturally discrete areas on the basis of islands. For many geographies, however, it may unclear how to perform this discretization. Much like morphological analyses, you might choose to choose areas based on expert opinion, based on some model, or using some “naive” uniform discretization. This procedure is not part of the tutorial, but you should be aware that area definitions are not always obvious or objective.

→ Open the file `examples/hawaii_dynamic.atlas.txt`.

```
{
  "name": "HawaiianArchipelago10my",
  "epochs":
  [{
    "name": "epoch1",
    "start_age": 10.0,
    "end_age": 3.7,
    "areas":
    [{ "name": "Kauai", "latitude": 22.08, "longitude": -159.50,
      "dispersalValues": [ 1, 0, 0, 0 ] },
      { "name": "Oahu", "latitude": 21.47, "longitude": -157.98, "
        dispersalValues": [ 0, 0, 0, 0 ] },
      { "name": "Maui", "latitude": 20.80, "longitude": -156.33, "
        dispersalValues": [ 0, 0, 0, 0 ] },
      { "name": "Hawaii", "latitude": 19.57, "longitude": -155.50, "
        dispersalValues": [ 0, 0, 0, 0 ] } ]
    },
    ... epoch2 and epoch3 omitted ...
  {
    "name": "epoch4",
    "start_age": 0.5,
    "end_age": 0.0,
    "areas":
    [{ "name": "Kauai", "latitude": 22.08, "longitude": -159.50,
      "dispersalValues": [ 1, 1, 1, 1 ] },
      { "name": "Oahu", "latitude": 21.47, "longitude": -157.98, "
        dispersalValues": [ 1, 1, 1, 1 ] },
      { "name": "Maui", "latitude": 20.80, "longitude": -156.33, "
        dispersalValues": [ 1, 1, 1, 1 ] },
      { "name": "Hawaii", "latitude": 19.57, "longitude": -155.50, "
        dispersalValues": [ 1, 1, 1, 1 ] } ] }
  ]
}
```

This is called the Atlas file, which uses a file format called JSON. JSON is a lightweight format used to assign values to variables in a hierarchical manner. There are three main tiers to the hierarchy in the Atlas file: the atlas, the epoch, and the area. In the lowest tier, each area corresponds to a character in the model and is assigned its own properties. In the middle tier, each epoch contains the set of homologous areas (characters) that may be part of a species' range, but importantly the properties of these areas may take on different values during different intervals of time, as given by the `start_age` and `end_age` variables. Because the tree and range evolution model also operate on units of geological time, the rates of area gain and loss can condition on



areas' properties as a function of time. Sometimes these models are called stratified models or epochal models. Finally, the atlas contains the array of epochs in the highest tier.

Each area is assigned a `latitude` and `longitude` to represent its geographical coordinates, ideally the area's centroid. If a centroid does not represent the distance between areas, splitting the area into multiple smaller areas is reasonable. The data augmentation approach used in this analysis allows you to use more areas as desired, whereas matrix exponentiation methods are limited to approximately ten areas. The distance between any two areas' coordinates inform to distance-dependent dispersal parameter ( $\beta$  from the  $\eta(\cdot)$  function) for range expansion events, so coordinates roughly close to the center of the area suffice.

In addition, whether an area is habitable is

→ Open the file `examples/my_areas.txt`.

## 4 Analysis

### 4.1 Simulated data

The zip file contains a simulated dataset for 50 taxa over 33 terrestrial areas throughout Australia. The rate of range expansion, rate of range contraction, and distance power parameter were set as 0.1, 0.7, and 4.0 respectively. Additionally, the zip file contains the output from two completed MCMC analyses under the settings given below.

### 4.2 Settings

BayArea accepts command-line arguments to set input and output files, set MCMC sampling behavior, configure prior values, etc. To reduce the risk of typos, you can execute the command with arguments using a pre-defined shell script. For this lab, we'll be using `my_lab_run.sh`, which was used to produce the output files from the input files contained in `bayarea_lab.zip`. Before running our job, let's review the program settings by opening `my_lab_run.sh` using your favorite text editor.

→ Enter the following command.

```
> cat my_lab_run.sh
./bayarea -areaFileName=my_data.txt \
          -geoFileName=my_geo.txt \
          -treeFileName=my_tree.txt \
          -inputFilePath=./examples/ \
          -outputFilePath=./examples/ \
          -outputTimestamp=T \
          -outputPrefix=my_run \
          -parameterSampleFrequency=1000 \
          -historySampleFrequency=10000 \
```

```

-printFrequency=10000 \
-chainLength=50000000 \
-chainBurnIn=0 \
-probBurnIn=10000000 \
-modelType=3 \
-gainPrior=0.1 \
-lossPrior=0.1 \
-distancePowerPrior=0.1 \
-guessInitialRates=T \
-geoDistancePowerPositive=T \
-geoDistanceTruncate=F \
-areaProposalTuner=0.1

```

The first set of flags concerns file handling. `inputFilePath` indicates where to find the input files `areaFileName`, `geoFileName`, and `treeFileName`. `outputFilePath` indicates where output files will be stored, which may be prefixed with `outputPrefix` and timestamped with `outputTimestamp`, both useful for organizing output from many analyses.

The second set of flags concerns the MCMC analysis length, chain burn-in, and the sampling interval. MCMC starts at an arbitrary state (sampled from the prior) and takes some amount of time to converge to stationarity. Once at stationarity, independent samples of the MCMC state at regular intervals approximate the target posterior distribution. MCMC that relies on stochastic mapping for data augmentation takes a longer time to mix, because it takes many MCMC proposals to explore the space of stochastically mapped range evolution histories. Unfortunately, you typically do not know how long it takes to reach stationarity, so it's best to run MCMC analyses for an excessive length. `chainBurnIn` determines which cycle to begin recording the MCMC state, but generally you wish to save the entire chain and assess burn-in after the analysis.

In the next section, you'll see `my_run.area_probs.txt` and `my_run.nhx` report ancestral range reconstruction probabilities. The MCMC records the sampled histories every `historySampleFrequency` iteration to `my_run.area_states.txt`. However, this data is relatively "raw" and must be manipulated with scripts for immediate use (we will cover how to do so later). The probabilities in the files above are computed as part of the analysis for your convenience, disregarding the first `probBurnIn` iterations of the MCMC. (Here it is set to disregard the first quarter of the chain.)

Parameters are sampled every `parameterSampleFrequency` iterations. The current MCMC state is printed on-screen every `printFrequency` iterations.

The final set of flags concerns model parameters. The area gain rate ( $\lambda_1$ ), area loss rate ( $\lambda_0$ ), and distance power parameter ( $\beta$ ) are each assigned their own half-Cauchy prior distribution. The half-Cauchy distribution can be thought of as the absolute value of "fat-tailed" normal distributions, with scale parameters set by `gainPrior`, `lossPrior`, and `distancePowerPrior`. The flag `guessInitialRates` makes a very rough estimate of the initial values for  $\lambda_0$  and  $\lambda_1$  from the data and tree rather than sampling their values from the prior distribution. `areaProposalTuner` controls the expected proportion of areas to update during a range history proposal. Mixing suffers when this value is too large.

The distance power parameter,  $\beta$ , effectively rescales the distance between areas. When comput-

ing the probability of range expansion, the pairwise distances are computed between each occupied area in the starting range and each unoccupied area in the expanded range. For large numbers of areas ( $N > 100$ ), this computation can become slow. Assigning `geoDistanceTruncate` to `T` tells the software to skip computing pairwise distances for areas that are very distant given the current value of  $\beta$ , i.e. areas that have an exceedingly small chance of being gained. This speeds up computation but may introduce negligible amounts of error into computing the distance-dependent rate-modifier term,  $\eta$ .

Finally, there is nothing mathematically to prevent  $\beta$  from becoming negative, for which range expansion events would prefer distant areas to nearby areas. In some cases, BayArea will infer  $\beta < 0$  and generate implausible ancestral range reconstructions, particularly for globally distributed taxa. So, the flag `geoDistancePowerPositive` constrains  $\beta \geq 0$  when set to `T`.

See Section 4.1 of the BayArea v1.0.2 manual to learn about additional input, output, and analysis settings.

### 4.3 Running a job

Executing the shell script will run our job. Bombs away!

→ Enter the following command.

```
> ./my_lab_run.sh
```

## 5 Output

Instead of waiting for the MCMC to finish, we'll use the output from a completed analysis on the same data.

→ Press `ctrl-C` to kill the job.

### 5.1 Screen

There are three types of MCMC proposals, the first being parameter proposals that act upon the model parameters,  $\lambda_0$ ,  $\lambda_1$ , and  $\beta$ . The second type of proposals act upon our sampling parameters,  $\lambda_0^*$  and  $\lambda_1^*$ , which we use to sample range histories but do not directly affect our model likelihood. The last type, ancestral range history updates, occur in very high proportion to all other updates.

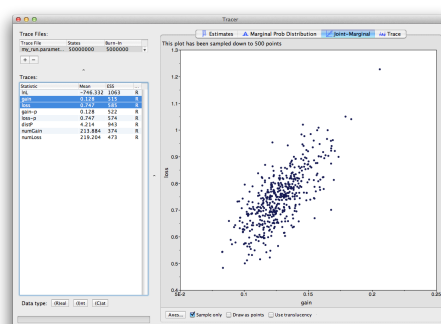
Recall from the Introduction that this is necessary to effectively integrate over all ancestral ranges of moderate to high posterior probability. The screen output reports whether the proposal for that iteration was accepted or rejected. If you notice the MCMC is rejecting most proposals, it will probably not produce an accurate approximation of the posterior. Pay particular attention to range history proposals. Range history proposals tend to introduce very small differences to the

likelihood so they are generally accepted easily. If you notice very few range history proposals are accepted, you will improve the acceptance probability by reducing the `areaProposalTuner` value.

## 5.2 Sampled parameters (`my_run.parameters.txt`)

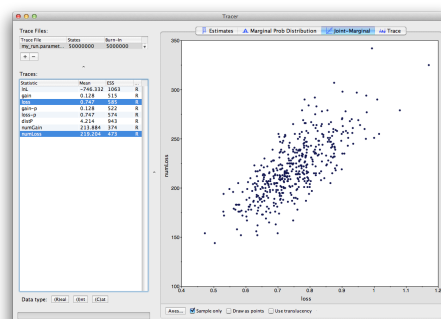
This tab-delimited file contains the parameters sampled at regular intervals from the MCMC (set by `parameterSampleFrequency`). Open the `my_run.parameters.txt` in Tracer. First, we see the effective sample size is only moderate for  $50 \times 10^6$  cycles when sampling every 1000 cycles. This is because the vast majority of MCMC updates are range history updates.

→ Highlight the “gain” and “loss” parameters then click Joint-Marginal.



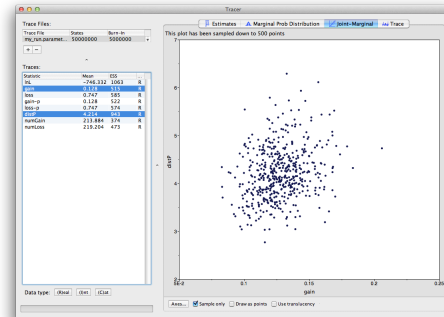
The Joint-Marginal of rate of area gain and loss parameters shows strong positive correlation. This correlation arises partly because the proportion of occupied areas is greatly influenced by the ratio of rate of area gain to rate of area loss. For example, when the rates of area gain and loss are equal, range sizes tend to equal half the total number of areas.

→ Highlight the “loss” and “numLoss” parameters then click Joint-Marginal. Do the same for “gain” and “numGain”.



Again, we see strong positive correlation. This is reassuring, since we expect to see many sampled range gain and loss events when the corresponding rates are high.

- Highlight the “gain” and “distP” parameters then click Joint-Marginal. Do the same for “loss” and “distP”.



For the simulated data we don’t see any strong correlation between either rate of loss or gain and the distance power parameter, but this is not always the case. Large distance power parameters sometimes results in rates of area gain and loss being underestimated in value, resulting in a mild negative correlation.

- Highlight all parameters and click Estimates.

Estimates			
Summary Statistic	gain	loss	distP
mean	0.1277	0.7471	4.2138
stderr of mean	7.583E-4	4.0847E-3	0.0181
stddev	0.0172	0.0988	0.5562
variance	2.9608E-4	9.7536E-3	0.3093
median	0.1265	0.742	4.1667
mode	n/a	n/a	n/a
geometric mean	0.1266	0.7407	4.178
95% HPD Interval	[0.0952, 0.1615]	[0.5623, 0.9435]	[3.1846, 5.3318]
auto-correlation time (ACT)	87395.6134	76980.238	47721.5092
effective sample size (ESS)	514.9	584.5656	942.971

This gives you a handy selection of summary statistics. Of course we typically don’t know the true parameter values, but we should be reassured to learn the true parameter values for gain, loss, and distP (0.1, 0.7, and 4.0, respectively) reside within their corresponding 95% HPD Intervals. It’s also interesting to note that the distance power parameter has a much wider interval than the rate parameters, suggesting there is less information in the data for this parameter.

### 5.3 Sampled range histories (my\_run.area\_states.txt)

This file reports the stochastically mapped range histories sampled every `historySampleFrequency` iterations. From this we can compute the *marginal* posterior probability of any given area being occupied simply by finding the frequency the area was marked present (1), which we’ll call the *marginal area posterior probability*. You may be interested in not only the marginal posterior of area occupancy, but the marginal posterior of the joint distribution of areas, which we’ll call the *marginal range posterior probability*. For example, say your range contains 4 areas, and taxon A is present only in areas 1 and 2 for half of all MCMC samples and only present in areas 3 and 4 for the remaining half. The marginal area posterior range would report a 0.5 probability of any given area being occupied. The marginal range posterior would give you richer information, that

the range was either composed of areas 1 and 2 or of 3 and 4, but never 1 and 3, 1 and 4, 2 and 3, or 2 and 4.

Here we will use Python to report the marginal range probability for the range belonging to the most recent common ancestor (MRCA) shared by the species named **t1** and **t2** ordered by their posterior probabilities. We'll call this node MRCA(t1,t5).

→ Change directories to examples.

```
> cd examples
```

→ Open the Python console and enter the following commands.

```
>>> from pp_range import *
>>> range_dict = make_range_dict('my_run.area_states.txt', fburn
    =0.25)
>>> area_coords = get_area_coords('my_geo.txt')
>>> idx_list = get_node_idx_list('my_run.area_states.txt')
>>> node_key = get_node_key('my_tree.txt', 't1', 't5', idx_list)
>>> best_ranges = get_best_ranges(range_dict, node_key)
>>> prob_area_pairs = make_posterior_area_pairs(range_dict, node_key
    )
>>> best_area_pairs = get_best_area_pairs(prob_area_pairs)
>>> best_areas = get_best_area_pairs(prob_area_pairs, show_marginal=
    True)
```

→ To list the five most probable ranges for MRCA(t1,t5), type

[illegible]

The second column gives the probability of the entire MRCA(t1,t5) range shown in the first

column. There's a fair deal of uncertainty the MRCA(t1,t5) range reconstruction, since these best five ranges only account for about 0.08 of the probability.

→ To list the five most probable area co-occurrences in the MRCA(t1,t5) range, type

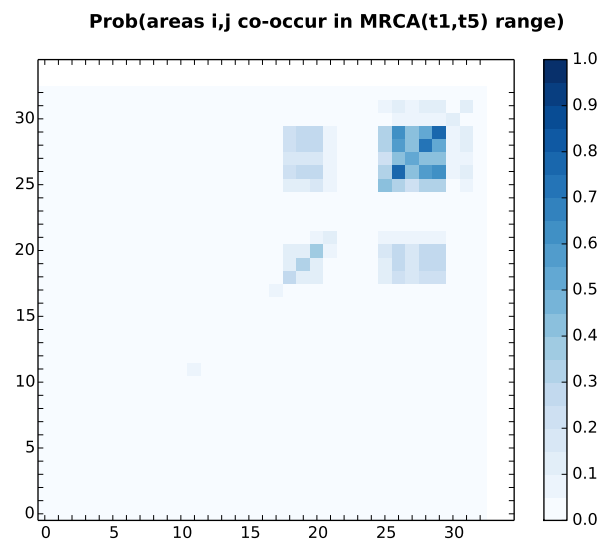
```
>>> best_area_pairs[0:5]
[(26, 29), 0.60650493201812505),
 (26, 28), 0.57717941882164425),
 (28, 29), 0.54385497200746136),
 (26, 27), 0.42282058117834981),
 (27, 28), 0.41242335377232475)]

>>> best_areas[0:5]
[(26, 26), 0.78459077579311998),
 (29, 29), 0.77179418821647394),
 (28, 28), 0.74193548387096575),
 (26, 29), 0.60650493201812505),
 (26, 28), 0.57717941882164425)]
```

Note the values in **best\_areas** are the marginal area probabilities. These correspond to the diagonal entries in the heatmap below and to the values in `my_run.area_probs.txt` and `my_run.nhx`.

→ To visualize these probabilities as a heatmap, type

```
>>> title_str = 'Prob(areas i,j co-occur in MRCA(t1,t5) range) '
>>> plot_posterior_area_pair(prob_area_pairs, title_str)
```



As indicated from the list produced by `get_best_area_pairs()`, we see the inference gives moderate support for areas 26, 28, and 29 being co-occupied by MRCA(t1,t5). Referring to `my_geo.txt`, we see these areas are geographically close and located in south-eastern Australia. You can also retrieve the coordinates through the `area_coords` dictionary.

→ To query the geographical coordinates for an area, type

```
>>> area_coords[26]
{'lat': -32.5, 'lon': 137.5}

>>> area_coords[28]
{'lat': -32.5, 'lon': 147.5}

>>> area_coords[29]
{'lat': -32.5, 'lon': 152.5}
```

## 5.4 Posterior probabilities of range histories (`my_run.area_probs.txt`)

Each row of this tab-delimited file contains information about that node's range. The rows are ordered in postorder traversal (aka pruningwise). The first column gives the taxon name. The remaining columns correspond to areas, maintaining the same order as all other files (e.g. the second column is the first area, the  $n$ th column is the  $(n-1)$ th area). These entries report the marginal area probability of the taxon (row) occupying the area (column). These probabilities are computed the frequency that the area was marked present from the data contained in `my_run.area_probs.txt`, a quantity that cannot be computed until the MCMC analysis completes. Because MCMC does not accurately sample from posterior during burn-in, some number of initial cycles are discarded as specified by the `probBurnIn` flag.

## 5.5 New Hampshire extended format file (`my_run.nhx`)

This file summarizes the input and output from a BayArea analysis using NEXUS format containing a New Hampshire eXtended (NHX) tree string. NHX allows you to annotate nodes in a Newick string with meta-information, which BayArea uses to report the probabilities in the `my_run.area_probs.txt` file. The `geo` block gives the geographical latitudes and longitudes for the areas in the order they are reported as probabilities. Like the `my_run.area_probs.txt` file, this file is not written until the analysis is complete. This annotation is used for the two visualization programs covered in the next section, Phylowood and BayArea-Fig. The anatomy of the Phylowood and BayArea-Fig settings blocks will also be explained there.

# 6 Visualization

Here we'll explore two options for visualizing ancestral range reconstructions. I'll walk you through some of the basic functionality, but feel free to play around as you like.

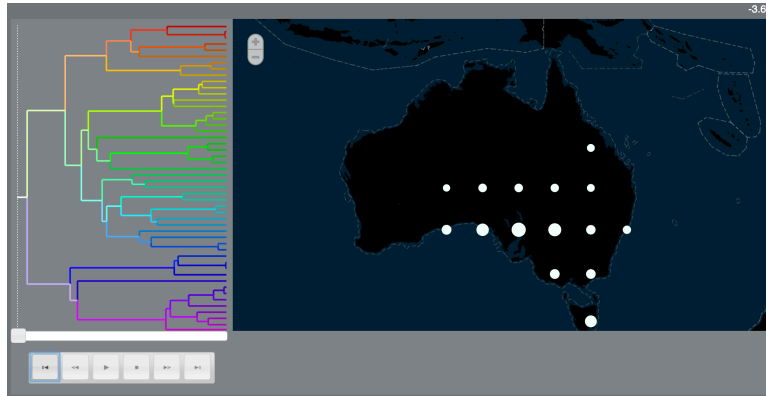


## 6.1 Phylowood

Phylowood generates interactive animations to explore biogeographic reconstructions.

→ Open <http://mlandis.github.io/phylowood>.

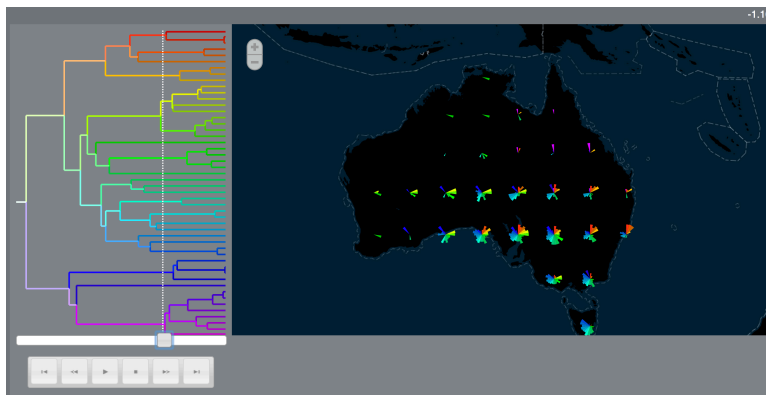
→ Drag and drop `my_run.nhx` into the text field.



→ Click the Play button to view the animation.

There are three control panels to help you filter data: the media panel, the map panel, and the phylogeny panel. The media buttons correspond to Beginning, Slow/Rewind, Play, Stop, Fast Forward, Ending (from left to right). The animation will play the timeframe corresponding to the slider.

→ Drag the slider to the time marked “-1.1” in the upper right corner.



→ Pan and zoom around the map.

Marker colors correspond to the phylogenetic lineages in the phylogeny panel. Markers are split into slices and (loosely) sorted phylogenetically, so nearby slices are generally closely related. At divergence events, a marker's radius is proportional to the marginal posterior probability the node was present in the area at that time. Between divergence events, marker's radius is simply an interpolation of the values at the two endpoints.

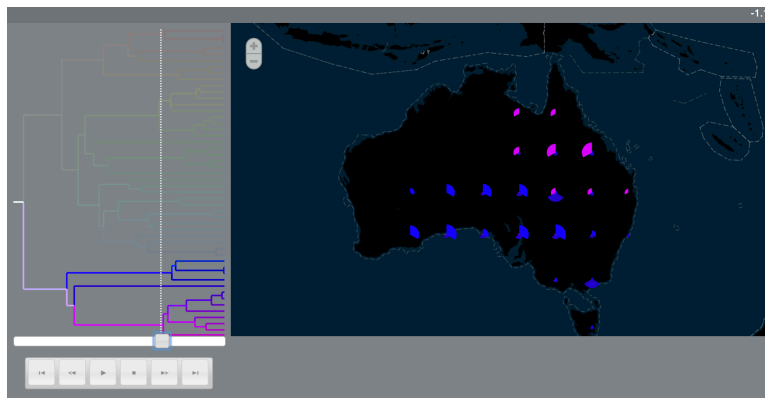
- Mouseover an area to learn which lineage it belongs to and its presence probability.

Since it's difficult to see how specific clades evolve with so many taxa, Phylowood offers two ways to filter taxa from the animation. We call the set of a lineage, all its ancestral lineages towards the root, and all descendant lineages a phylogenetic heritage. The root's heritage is the entire clade. A leaf node's heritage is a path from the tip to the root.

- Mouseover a lineage to temporarily highlight the lineage's heritage. Remove the mouseover to remove the highlight effect.

The highlight effect is temporary and quickly allows you to single out lineages of interest during animation. Phylowood also offers a masking effect that persists until an unmask command is issued.

- Double-click the white root branch to mask the root node's heritage (all lineages). Single click a lineage to unmask that lineage's heritage.



Now that the masking effects are in place, you're free to interact with other map components. In addition, the area of marker sizes is only distributed among unmasked lineages.

- Visit <https://github.com/mlandis/phylowood/wiki> to learn more about Phylowood.

## 6.2 BayArea-Fig

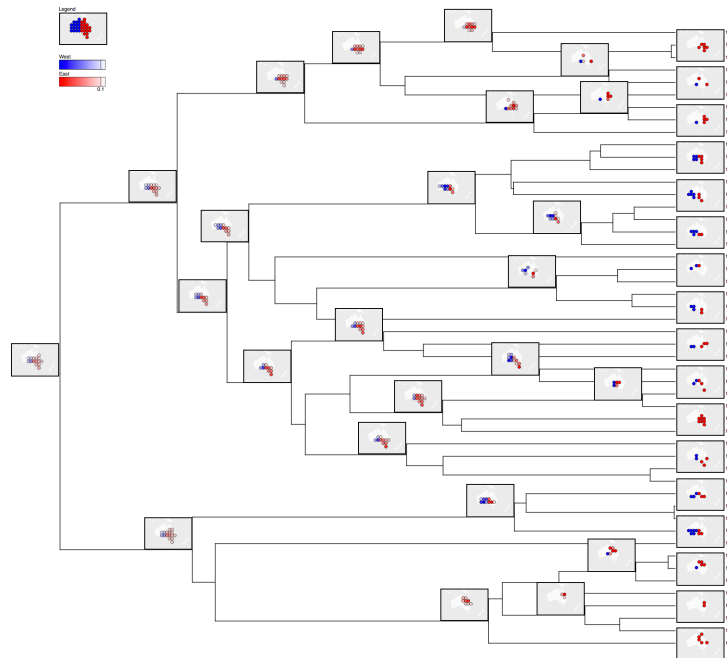
BayArea-Fig is a simple Javascript utility to help generate ancestral range reconstruction figures for publications. BayArea 1.0.2 does not automatically generate the NEXUS settings block for

BayArea-Fig, so I added the following block to `my_run.nhx`.

```
Begin bayarea-fig;  
  mapheight 100  
  mapwidth 150  
  canvasheight 2000  
  canvaswidth 2000  
  minareaval 0.1  
  areacolors blue red  
  areatypes 0 1 0 0 0 1 1 0 0 0 0 1 1 1 0 0 0 0 1 1 1 1 0 0 0  
            0 1 1 1 1 1 1  
  areanames West East  
End;
```

→ Open <http://mlandis.github.io/bayarea-fig> in a web browser.

→ Drag and drop `my_run.nhx` into the text field.



The generated figure reports the marginal area probabilities for each node in the phylogeny with a miniature map. Because of the limited real estate in the figure, you may only wish to show a subset of ancestral ranges.

→ Click unwanted ancestral ranges to delete them.

Depending on the purpose for the figure, you may wish to alter its size. The `mapheight`, `mapwidth`, `canvasheight`, and `canvaswidth` settings give the height and widths for the node-maps and the entire figure, respectively.

If you would like to differentiate areas (e.g. East from West, as above), give an ordered list of colors using the `areacolors` setting. Next, in the order areas appear in the `GEO` block, provide `areatypes` a list of assignments to area types. In the above example “0” corresponds to the 0th `areacolors` group, “blue”, and “1” corresponds to the 1st group, “red”.

- Add a new color as the third `areacolors` entry. Add “Tasmania” as a third entry to `areanames`. Change the last area in `areatypes` to equal 2.

We’ve seen that ancestral range reconstructions contain a great deal of uncertainty. Filtering out low probability ranges may make your figure easier to interpret. If the marginal probability of presence for a node-area pair is less than `minareaval`, it is not shown. The probabilities and the threshold value are shown in the upper left corner.

After arranging your figure, you’ll want to save it to file. How to accomplish this varies across operating systems and web browsers. Generally, the figure is most easily saved from the browser by printing the file to pdf. In this case the image size is equal to the paper size. If the standard  $8.5 \times 11$  inch image is too small, you will need to create and apply a sufficiently large custom paper size.

## References

- Landis, M. J. and T. Bedford. 2014. Phylowood: interactive web-based animations of biogeographic and phylogeographic histories. *Bioinformatics* 30:123–124.
- Landis, M. J., N. J. Matzke, B. R. Moore, and J. P. Huelsenbeck. 2013. Bayesian analysis of biogeography when the number of areas is large. *Systematic biology* 62:789–804.
- Nepokroeff, M., K. J. Sytsma, W. L. Wagner, and E. A. Zimmer. 2003. Reconstructing ancestral patterns of colonization and dispersal in the hawaiian understory tree genus *psychotria* (rubiacaceae): a comparison of parsimony and likelihood approaches. *Systematic Biology* 52:820–838.
- Ree, R. H. and S. A. Smith. 2008. Maximum likelihood inference of geographic range evolution by dispersal, local extinction, and cladogenesis. *Systematic Biology* 57:4–14.