

# Some ideas for random forests with missing values

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# Regression Trees

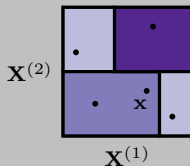
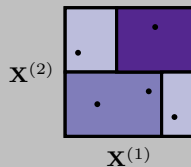
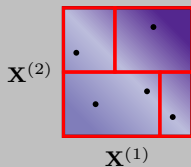
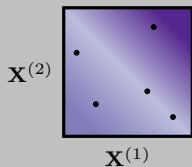
- ▶ Variable of interest  $Y \in \mathbb{R}$
- ▶ Vector of predictors  $\mathbf{X} \in \mathcal{X} \subseteq \mathbb{R}^p$

$$\mathbf{X} = (\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(p)})$$

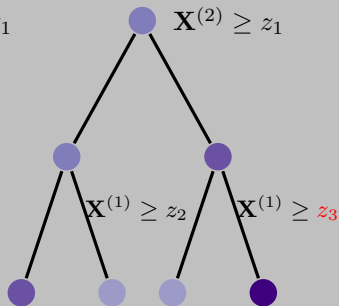
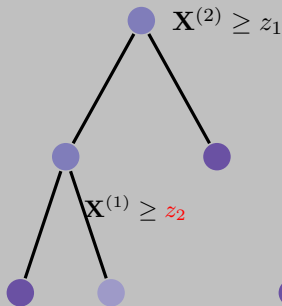
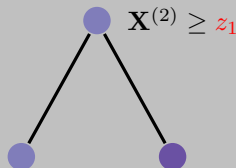
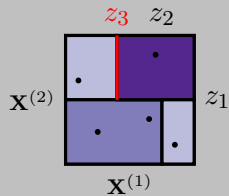
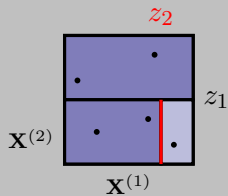
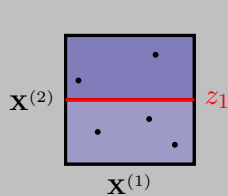
- ▶ training data set  $\mathcal{D}_n = ((\mathbf{X}_1, Y_1), \dots, (\mathbf{X}_n, Y_n))$

We want to estimate  $m(\cdot) \equiv \mathbb{E}[Y|\mathbf{X} = \cdot]$  using  $\mathcal{D}_n$

We can estimate  $m(\cdot) \equiv \mathbb{E}[Y|\mathbf{X} = \cdot]$  dividing (somehow)  $\mathcal{X}$  in disjoint regions and predicting with a constant in each region.



$$m_n(\mathbf{x}; \Theta, \mathcal{D}_n) = \bullet$$



## CART-split Criterion

$$\begin{aligned} L_{n,A}(h, z) &= \frac{1}{N_n(A)} \sum_{i=1}^n \left( Y_i - \bar{Y}_A \right)^2 \mathbb{1}_{\mathbf{X}_i \in A} \\ &\quad - \frac{1}{N_n(A)} \sum_{i=1}^n \left( Y_i - \bar{Y}_{A_L} \mathbb{1}_{\mathbf{X}_i^{(h)} < z} - \bar{Y}_{A_R} \mathbb{1}_{\mathbf{X}_i^{(h)} \geq z} \right)^2 \mathbb{1}_{\mathbf{X}_i \in A} \\ &\quad \vdots \\ &= \frac{N_n(A_L) N_n(A_R)}{N_n(A) N_n(A)} \left( \bar{Y}_{A_L} - \bar{Y}_{A_R} \right)^2 \end{aligned}$$

We construct the cells maximizing the CART criterion over all possible cuts in the cell  $\mathcal{C}_A$ .

$$(h_n^\star, z_n^\star) \in \arg \max_{(h, z) \in \mathcal{C}_A} L_n(h, z)$$

## Decision Trees

They are easy to be interpreted (not exactly true).

Shallow trees are easy to be interpreted.



They are unstable.



(Shallow) trees are inaccurate.



They can be used in regression or supervised classification problems.



They handle categorical or numerical variables, or a mix of both.



They can handle complex relations between variable.



# Regression Random Forests

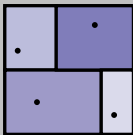


A random forest is an ensemble of many trees, i.e.

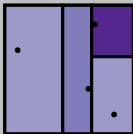
$$m_{M,n}(\mathbf{x}; \Theta_1, \dots, \Theta_M, \mathcal{D}_n) = \frac{1}{M} \sum_{k=1}^M m_n(\mathbf{x}; \Theta_k, \mathcal{D}_n)$$

We add two sources of randomness in each tree.

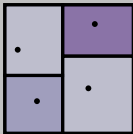
1. We select randomly  $a_n$  (with or without) replacement observations prior to the construction of each tree.
2. We select randomly `mtry` candidate directions to perform the cut.



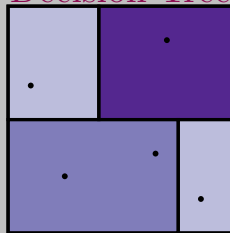
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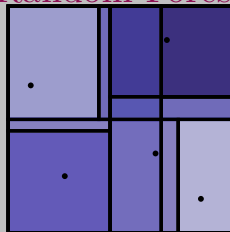
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Decision Tree



Random Forest



## Random Forests

They are difficult to be interpreted.



They are stable.



They are accurate.



They can be used in regression or supervised classification problems.



They handle categorical or numerical variables, or a mix of both.



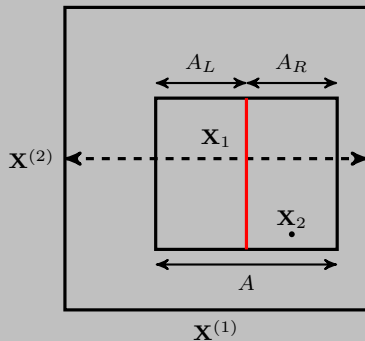
They can handle complex relations between variable.



They are easily parallelized.



# Decision Trees with Missing Values



$$\begin{aligned}
 L_{n,A}(h, z) = & \frac{1}{N_n(A)} \sum_{i=1}^n \left( Y_i - \bar{Y}_A \right)^2 \mathbb{1}_{\mathbf{X}_i \in A} \\
 & - \frac{1}{N_n(A)} \sum_{i=1}^n \left( Y_i - \bar{Y}_{A_L} \mathbb{1}_{\mathbf{X}_i^{(h)} < z} - \bar{Y}_{A_R} \mathbb{1}_{\mathbf{X}_i^{(h)} \geq z} \right)^2 \mathbb{1}_{\mathbf{X}_i \in A}
 \end{aligned}$$

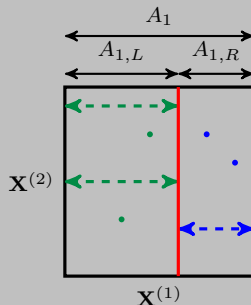
Let be

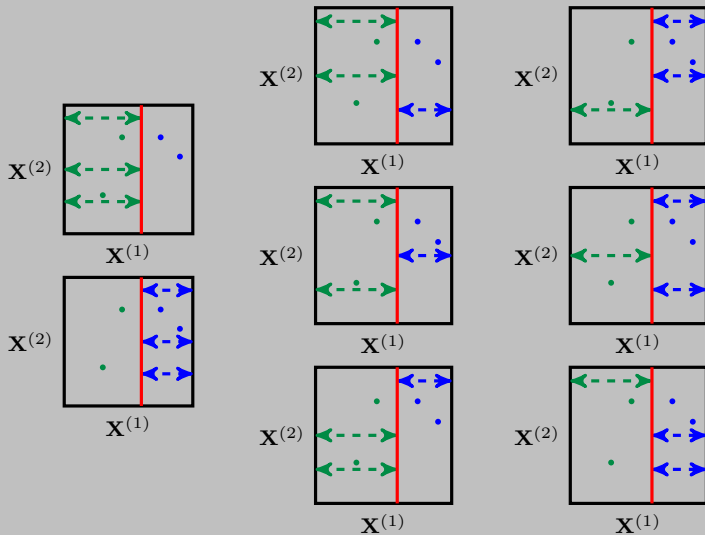
$$A_1 = \mathcal{X}$$

and

$$\mathbf{X}_{i,1}^{(h)} = \begin{cases} \mathbf{X}_i^{(h)} & \text{si } \mathbf{M}_i^{(h)} = 0 \\ \mathcal{X}^{(h)} & \text{si } \mathbf{M}_i^{(h)} = 1 \end{cases}, \quad 1 \leq h \leq p$$

$$\begin{aligned}
L_{n,A_1} \left( h, z, \mathbf{X}_{miss}^{(h)} \right) &= \frac{1}{N_n(A_1)} \sum_{i=1}^n \left( Y_i - \bar{Y}_{A_1} \right)^2 \mathbb{1}_{\mathbf{X}_{i,1} \in A_1} \\
&\quad - \frac{1}{N_n(A_1)} \sum_{i=1}^n \left( Y_i - \bar{Y}_{A_{1,L}} \right)^2 \mathbb{1}_{\mathbf{X}_{i,1} \in A_1, \mathbf{X}_i^{(h)} < z} \\
&\quad - \frac{1}{N_n(A_1)} \sum_{i=1}^n \left( Y_i - \bar{Y}_{A_{1,R}} \right)^2 \mathbb{1}_{\mathbf{X}_{i,1} \in A_1, \mathbf{X}_i^{(h)} \geq z}
\end{aligned}$$







1. For each candidate cut we calculate the CART criterion with all possibilities for the missing values.
2. We select the combination that maximizes the CART criterion between  $\mathcal{M}_{try}$ ,  $\mathcal{C}_{A_1}$  and  $\mathbf{X}_{miss}^{(h_{n,1})}$

$$\left( h_{n,1}^*, z_{n,1}^*, \mathbf{X}_{miss}^{\star(h_{n,1}^*)} \right) \in \arg \max_{\substack{h \in \mathcal{M}_{try} \\ (h,z) \in \mathcal{C}_{A_1} \\ \mathbf{X}_{miss}^{(h)} \in [a_1^{(h)}, b_1^{(h)}]}} L_{n,A_1} \left( h, z, \mathbf{X}_{miss}^{(h)} \right)$$

3. We move to  $A_2$  taking  $\mathbf{X}_{i,2}$ .

# Mechanisms of Missingness<sup>1</sup>

- ▶ **Missing Completely at Random (MCAR)** A variable is missing completely at random if the probability of missingness is the same for all units.
- ▶ **Missing at Random (MAR)** A variable is missing at random if the probability of missingness just depends on observed information.
- ▶ **Not Missing at Random (NMAR)** If the probability of missingness depends on unobserved information, it is called not missing at random.

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<sup>1</sup>Roderick JA Little and Donald B Rubin. *Statistical analysis with missing data*. 2nd ed. John Wiley & Sons, 2002.

## Simulation<sup>2</sup>

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<sup>2</sup>Anna Rieger, Torsten Hothorn, and Carolin Strobl. “Random forests with missing values in the covariates”. In: (2010).

- ▶ We take the regression function “friedman1”:

$$m(\mathbf{x}) = 10 \sin \left( \pi \mathbf{x}^{(1)} \mathbf{x}^{(2)} \right) + 20 \left( \mathbf{x}^{(3)} - 0.5 \right)^2 + 10 \mathbf{x}^{(4)} + 5 \mathbf{x}^{(5)}$$

### Training data sets

- ▶ We created 100 training data sets.
- ▶ We simulated 200 observations from  $\mathbf{X} \sim \mathcal{U}[0, 1]^5$ .

### Test data set

- ▶ We create 1 data set.
- ▶ We simulated 2000 observations from  $\mathbf{X} \sim \mathcal{U}[0, 1]^5$ .
- ▶ All values are observed.

- For the missing values we create 7 different mechanisms of missingness:
  - 1 Missing Completely At Random (MCAR).
  - 5 Missing At Random (MAR1, MAR2, MAR3, MAR4, Depy).
  - 1 Not Missing At Random (LOG).

Determinant Variable	Missing Variable	% Missing Data
$\mathbf{X}^{(2)}, Y$	$\mathbf{X}^{(1)}$	20%
$\mathbf{X}^{(5)}, Y$	$\mathbf{X}^{(3)}$	10%
	$\mathbf{X}^{(4)}$	20%

- **MAR1** The probability of NA is

$$\frac{2 \times \text{rango}(\text{var.det.})}{n(n+1)}$$

- **MAR2** We create two groups in the det. var. An observation belongs to the first group if it is bigger to the the median, otherwise it belongs to the second group. The probability of NA for each group is

$$0.9/\#(\text{obs. in 1st group}) \quad 0.1/\#(\text{obs. in 2nd group})$$

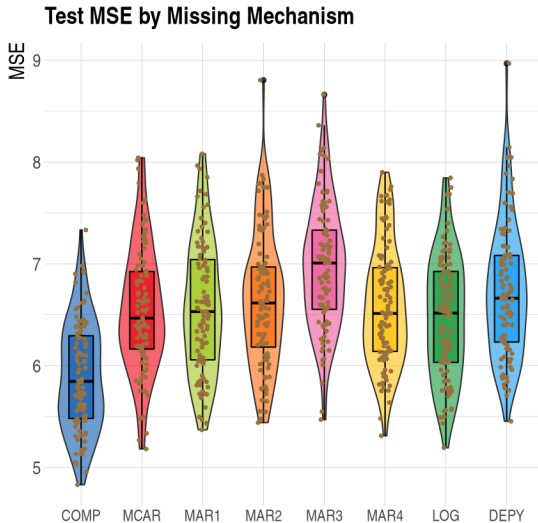
- ▶ **MAR3** The biggest values in det. var. are NA in missing var.
- ▶ **MAR4** The biggest and smallest values in det. var. are NA in missing var.
- ▶ **Depy** Probability of NA is 0.1 if  $Y \geq 13$ , otherwise is 0.4
- ▶ **LOG**

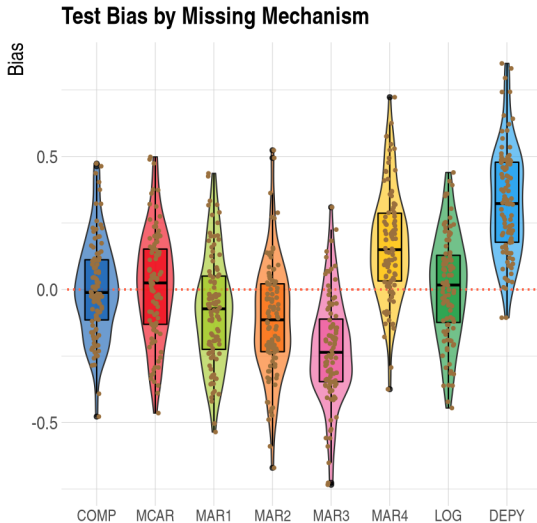
$$\text{logit}(\mathbb{P}[\mathbf{M}^{(h)} = 1]) = -0.5 + \sum_{\substack{k=1 \\ k \neq h}}^5 \mathbf{X}^{(h)}$$

## Random Forests

- ▶ For each data set and each mechanism of missingness (including complete data) we create 1 random forest.
- ▶ Each forest is built with the parameters:
  - ▶  $M = 50$  trees.
  - ▶ `mtry` = 1 variable selected at random to perform the cut.
  - ▶  $a_n = 127$  observations selected at random and without replacement for each tree.
  - ▶ `nodesize` = 5, maximum number of observations of the final nodes.







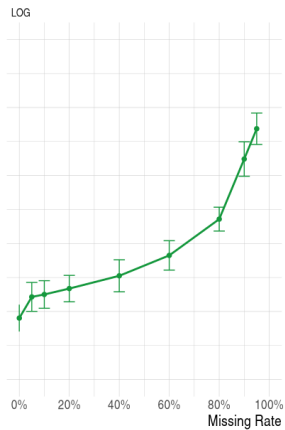
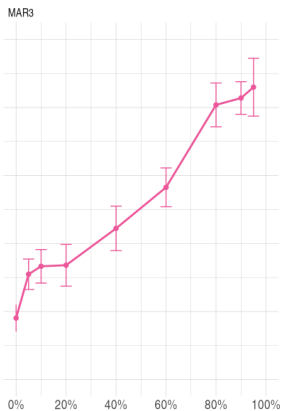
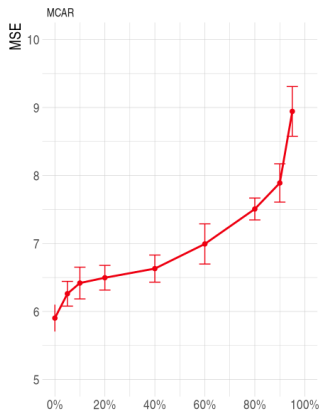
We also change the percentage of missingness of each variable, without changing the percentage of the other variables.

$\mathbf{X}^{(1)}$	$\mathbf{X}^{(3)}$	$\mathbf{X}^{(4)}$
20%	10%	5%, 10%, 20%, 40%, 60%, 80%, 90%, 95%

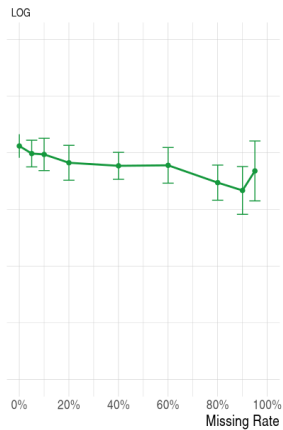
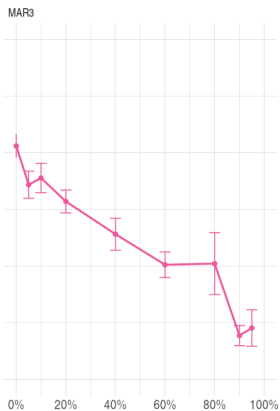
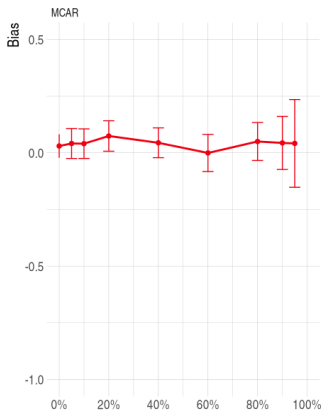
$\mathbf{X}^{(4)}$	$\mathbf{X}^{(3)}$	$\mathbf{X}^{(1)}$
20%	10%	5%, 10%, 20%, 40%, 60%, 80%, 90%, 95%

$\mathbf{X}^{(1)}$	$\mathbf{X}^{(4)}$	$\mathbf{X}^{(3)}$
20%	20%	5%, 10%, 20%, 40%, 60%, 80%, 90%, 95%

Test MSE by Missing Rate in X4



### Test Bias by Missing Rate in X4



Consistency

$$\lim_{n \rightarrow \infty} \mathbb{E}_{\mathbf{X}, \mathcal{D}_n} [m_n(\mathbf{X}) - m(\mathbf{X})]^2 = 0$$

$$\mathbb{E}_{Y, \mathbf{X} | \mathcal{D}_n} [m_n(\mathbf{X}) - m(\mathbf{X})]^2 = \text{Estimation Error} \\ + \text{Approximation Error}$$

## Estimation Error

$$\mathbb{E}_{Y, \mathbf{X} | \mathcal{D}_n} [m_n(\mathbf{X}) - Y]^2 - \inf_{f \in \mathcal{F}_n} \mathbb{E}_{Y, \mathbf{X}} [f(\mathbf{X}) - Y]^2$$

## Approximation Error

$$\inf_{f \in \mathcal{F}_n} \mathbb{E}_{Y, \mathbf{X}} [f(\mathbf{X}) - Y]^2 - \mathbb{E}_{Y, \mathbf{X}} [m(\mathbf{X}) - Y]^2$$

# Estimation Error

$$\begin{aligned} & \mathbb{E}_{Y, \mathbf{X} | \mathcal{D}_n} [m_n(\mathbf{X}) - Y]^2 - \inf_{f \in \mathcal{F}_n} \mathbb{E}_{Y, \mathbf{X}} [f(\mathbf{X}) - Y]^2 \\ & \leq 2 \sup_{f \in \mathcal{F}_n} \left| \frac{1}{n} \sum_{i=1}^n [f(\mathbf{X}_i) - Y_i]^2 - \mathbb{E}_{Y, \mathbf{X}} [f(\mathbf{X}) - Y]^2 \right| \end{aligned}$$

We use concentration inequalities for empirical processes.

If  $g : \mathbb{R}^{d+1} \rightarrow [0, B]$ , by Hoeffding's Inequality

$$\mathbb{P} \left\{ \left| \frac{1}{n} \sum g(Z_i) - \mathbb{E}g(Z) \right| > \varepsilon \right\} \leq 2e^{-\frac{2n\varepsilon^2}{B^2}}$$



Using Boole's Inequality

$$\mathbb{P} \left\{ \sup_{g \in \mathcal{G}_n} \left| \frac{1}{n} \sum g(Z_i) - \mathbb{E}g(Z) \right| > \varepsilon \right\} \leq 2|\mathcal{G}_n| e^{-\frac{2n\varepsilon^2}{B^2}}$$

By Lemma of Borel-Cantelli, if

$$\sum_{n=1}^{\infty} |\mathcal{G}_n| e^{-\frac{2n\varepsilon^2}{B^2}} < \infty$$

then

$$\sup_{g \in \mathcal{G}_n} \left| \frac{1}{n} \sum g(Z_i) - \mathbb{E}g(Z) \right| \xrightarrow[n \rightarrow \infty]{a.s.} 0$$

# Approximation Error

$$\begin{aligned} & \inf_{f \in \mathcal{F}_n} \mathbb{E}_{Y, \mathbf{X}} [f(\mathbf{X}) - Y]^2 - \mathbb{E}_{Y, \mathbf{X}} [m(\mathbf{X}) - Y]^2 \\ &= \inf_{f \in \mathcal{F}_n} \mathbb{E}_{\mathbf{X}} [f(\mathbf{X}) - m(\mathbf{X})]^2 \end{aligned}$$

$$\begin{aligned} &\leq \mathbb{E} [\Delta(m, A_n(\mathbf{X}, \Theta))]^2 \\ &\leq \xi^2 + 4\|m\|_\infty^2 \mathbb{P} [\Delta(m, A_n(\mathbf{X}, \Theta)) > \xi] \end{aligned}$$

$$\Delta(m, A) = \sup_{x, x' \in A} |m(x) - m(x')|$$

(H1) *the response  $Y$  follows*

$$Y = \sum_{j=1}^p m_j \left( \mathbf{X}^{(j)} \right) + \varepsilon$$

*where  $\mathbf{X}$  is uniformly distributed over  $[0, 1]^p$ , there is a MCAR mechanism for all input variables,  $\varepsilon$  is an independent centered Gaussian noise with finite variance  $\sigma^2 > 0$  and each component  $m_j$  is continuous.*<sup>3</sup>

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<sup>3</sup>Erwan Scornet, Gérard Biau, and Jean-Philippe Vert. “Consistency of random forests”. In: *The Annals of Statistics* 43.4 (2015), pp. 1716–1741.

**Theorem 1**

Assume that (H1) is satisfied. Then, if  $a_n \rightarrow \infty$ ,  $t_n \rightarrow \infty$  and  $t_n (\log a_n)^9 / a_n \rightarrow 0$ , the random forest is consistent, i.e.

$$\lim_{n \rightarrow \infty} \mathbb{E}_{\mathbf{X}, \mathcal{D}_n} [m_n(\mathbf{X}) - m(\mathbf{X})]^2 = 0$$

### Lemma 1

Assume that (H1) is satisfied. Then,  $\forall \mathbf{x} \in [0, 1]^p$ ,

$$\Delta(m, A_k^*(\mathbf{x}, \Theta)) \rightarrow 0 \quad \text{casi seguro, con } k \rightarrow \infty$$

### Ideas of the Proof

$$\begin{aligned} L_{A_\ell}^* \left( h, z, \mathbb{P}_{A_{\ell,L}^*, \text{obs}}, \mathbb{P}_{A_{\ell,L}^*, \text{miss}} \right) &= L_{1, A_\ell}^* \left( h, z, \mathbb{P}_{A_{\ell,L}^*, \text{obs}} \right) \\ &\quad + L_{2, A_\ell}^* \left( h, z, \mathbb{P}_{A_{\ell,L}^*, \text{miss}} \right) \\ &\quad + L_{3, A_\ell}^* \left( h, z, \mathbb{P}_{A_{\ell,L}^*, \text{obs}}, \mathbb{P}_{A_{\ell,L}^*, \text{miss}} \right) \\ &\quad + L_{4, A_\ell}^* \left( h, z, \mathbb{P}_{A_{\ell,L}^*, \text{obs}}, \mathbb{P}_{A_{\ell,L}^*, \text{miss}} \right) \end{aligned}$$

$$L_{1,A_\ell^\star}^\star(h, z, \mathbb{P}_{A_{\ell,L}^\star, obs}) =$$

$$\mathbb{P}[\mathbf{M}^{(h)} = 0 | \mathbf{X} \in A_\ell^\star] \mathbb{P}_{A_{\ell,L}^\star, obs} \left(1 - \mathbb{P}_{A_{\ell,L}^\star, obs}\right) \left(\mu_{A_{\ell,L}^\star, obs} - \mu_{A_{\ell,R}^\star, obs}\right)^2$$

$$L_{3,A_\ell^\star}^\star(h, z, \mathbb{P}_{A_{\ell,L}^\star, obs}, \mathbb{P}_{A_{\ell,L}^\star, miss}) =$$

$$\left(\mu_{A_{\ell}^\star, obs} - \mu_{A_\ell^\star}\right)^2 \mathbb{P}[\mathbf{M}^{(h)} = 0 | \mathbf{X} \in A_\ell^\star]$$

$$- \left(\mu_{A_{\ell,L}^\star, obs} - \mu_{A_{\ell,L}^\star}\right)^2 \mathbb{P}[\mathbf{M}^{(h)} = 0, a_\ell^{\star(h)} \leq \mathbf{X}^{(h)} < z | \mathbf{X} \in A_\ell^\star]$$

$$- \left(\mu_{A_{\ell,R}^\star, obs} - \mu_{A_{\ell,R}^\star}\right)^2 \mathbb{P}[\mathbf{M}^{(h)} = 0, z \leq \mathbf{X}^{(h)} \leq b_\ell^{\star(h)} | \mathbf{X} \in A_\ell^\star]$$

Because of the MCAR mechanism:

- $L_{3,A_\ell^\star}^\star = 0$  and  $L_{4,A_\ell^\star}^\star = 0$

- $L_{A_\ell^\star}^\star(h, z) =$

$$\mathbb{P} \left[ a_\ell^\star \leq \mathbf{X}^{(h)} < z | \mathbf{X} \in A_\ell^\star \right] \mathbb{P} \left[ z \leq \mathbf{X}^{(h)} \leq b_\ell^\star | \mathbf{X} \in A_\ell^\star \right] \left( \mu_{A_{\ell,L}^\star} - \mu_{A_{\ell,R}^\star} \right)^2$$

Because  $\mathbf{X} \sim U[0, 1]^p$ :

$$L_{A_\ell^\star}^\star(h, z) = \frac{1}{(z - a_\ell^{\star(h)})(b_\ell^{\star(h)} - z)} \left( M_h(z) - \frac{z - a_\ell^{\star(h)}}{b_\ell^{\star(h)} - a_\ell^{\star(h)}} C_h \right)^2$$

If  $L_{A_\ell^\star}^\star(h, z) \equiv 0$  then  $m$  is constant.

Use uniform continuity of  $m$  and contradiction.

## Lemma 2

Assume that Hypothesis 1 is satisfied. Fix  $\mathbf{x} \in [0, 1]^p$ ,  $k \in \mathbb{N}$ , and let  $\xi > 0$ . Then for all  $\alpha, \rho > 0$  there exists  $\delta > 0$  such that

$$\lim_{n \rightarrow \infty} \mathbb{P} \left\{ \sup_{args} |L_{n,k}(\mathbf{x}, \mathbf{d}_k, \mathbb{X}_{miss,k}) - L_{n,k}(\mathbf{x}, \mathbf{d}'_k, \mathbb{X}'_{miss,k})| > \alpha \right\} \leq \rho$$

$$args = \begin{array}{l} \|\mathbf{d}_k - \mathbf{d}'_k\|_\infty \leq \delta \\ \mathbf{d}_k, \mathbf{d}'_k \in \bar{\mathcal{A}}_k^\xi(\mathbf{x}) \\ d(\mathbb{X}_{miss,k}, \mathbb{X}'_{miss,k}) \leq \delta \end{array}$$



$$\|\mathbf{d}_k - \mathbf{d}'_k\|_\infty = \max_{1 \leq j \leq k} \max\{|d_j^{(1)} - d_j'^{(1)}|, |d_j^{(2)} - d_j'^{(2)}|\}$$

$$\begin{aligned} d\left(\mathbf{X}_{miss,j}^{(h)}, \mathbf{X}_{miss,j}'^{(h')}\right) &= |h - h'| \mathbb{1}_{h \neq h'} \\ &\quad + \frac{1}{N_{n,miss}^{(h)}} d_H\left(\mathbf{X}_{miss,j}^{(h)}, \mathbf{X}_{miss,j}'^{(h')}\right) \mathbb{1}_{h=h'} \end{aligned}$$

where  $d_H$  is the Hamming distance with the alphabet  $\Sigma = \{o, n, l, r\}$ .

## Ideas of the Proof

Control the number of points in the cells, control the Gaussian noise

- ▶ Many points in the cell: use strong law of large numbers
- ▶ Few points in the cell: use concentration inequalities

Make induction.

**Lemma 3**

Assume that (H1) is satisfied. Fix  $\xi, \rho > 0$  and  $k \in \mathbb{N}^*$ ,  
 $\exists N \in \mathbb{N}^*$  s.t.  $\forall n \geq N$

$$\mathbb{P}[d_\infty(\hat{\mathbf{d}}_{k,n}(\mathbf{X}, \Theta), \mathcal{A}_k^*(\mathbf{X}, \Theta)) \leq \xi] \geq 1 - \rho$$

**Ideas of the Proof**

- ▶ Compare empirical and theoretical CART criteria.
- ▶ Add and subtract empirical and theoretical splits.
- ▶ Use triangle inequality.
- ▶ Make induction.


- ▶ Lemma 1 studies the theoretical random forests.
- ▶ Lemma 3 Proves (via Lemma 2) that theoretical cuts and empirical cuts are close.
- ▶ Finally,


$$\mathbb{P} [\Delta (m, A_n(\mathbf{X}, \Theta)) > \xi] \xrightarrow{n \rightarrow \infty} 0$$


as consequence of Lemmas 1 and 3.


## Conclusions

The proposed algorithm:

Does not “explode” even with a high percentage of missingness. 

Does not required the proximity matrix and just build one forest. 

Does not require a previous processing of the data. 

The assignation of the missing values can be done in parallel. 

Uses extensive computer power. 

Does not answer how to predict. 

Thank you!

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