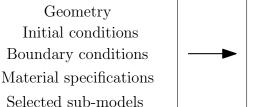
Simulator



Input Deck

Other controllable inputs

Conservation Equations $b(\mathbf{u}, \mathbf{x}_c, \{\mathcal{M}_i(\mathbf{x}_c, \mathbf{x}_m, \mathbf{u})\}) = 0$

Closure Laws, sub-models, etc.

 $\{\mathcal{M}_i(\mathbf{x}_c,\mathbf{x}_m,\mathbf{u}); i>0\}$

TH System Code

