Results of ILS trials

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1. Introduction

Comparison of ILS, with different implementations, applied to some symmetric TSP instances (available in TSPLIB [TspLib]). For 1, the first column gives the instance name and its size. The next columns give the best cost, taken over 1000 iterations, using: (i) a sequential **2-opt** ILS with one **double-bridge** perturbation; (ii) a Parallel, multi-processing, using OpenMP with 16 threads, for (i); (iii) a **3-opt** ILS get from [Helena R. Lorenço and STUTZLE]. The best results are taken over 5 trials on each instance.

For $\ref{eq:column}$, the first column gives the instance name and its size. The next columns give the best elapsed time, in seconds, taken over 1000 iterations, using: (i) a sequential **2-opt** ILS with one **double-bridge** perturbation; (ii) a Parallel, multi-processing, using OpenMP with 12 threads, for (i); (iii) a **3-opt** ILS get from [Helena R. Lorenço and STUTZLE]. The best results are taken over 30 trials on each instance.

2. Trials results

2.1. Costs

Table 1. Solution of each symmetric TSP instance for Sequential and Parallel ILS.

| Instance | Sequential Distance | Parallel Distance | Sequential Time | Parallel Time |
|----------|-----------------------|-----------------------|-----------------------|-----------------------|
| | | | | |
| d198 | 1.628×10^4 | 1.721×10^4 | 6.114×10^{1} | 8.649 |
| a280 | 2.643×10^{3} | 2.729×10^{3} | 1.755×10^2 | 2.411×10^{1} |
| lin318 | 4.382×10^4 | 4.763×10^4 | 2.775×10^2 | 3.941×10^{1} |
| pcb442 | 5.172×10^4 | 5.348×10^4 | 7.463×10^2 | 1.018×10^2 |
| rat783 | 9.271×10^{3} | 9.659×10^{3} | 4.620×10^{3} | 5.999×10^{2} |
| u1060 | 2.317×10^5 | 2.416×10^5 | 1.217×10^4 | 5.062×10^3 |

3. Títulos

- \rightarrow Traveling Salesman Problem of optimal debris removal sequence using non-population gradient search.
- → A hybrid and adaptive evolutionary approach for multitask optimization of postdisaster traveling salesman and repairman problems
- → A comprehensive survey on the generalized traveling salesman problem
- → A novel hybrid swarm intelligence algorithm for solving TSP and desired-path-based online obstacle avoidance strategy for AUV

- → Time-reliability optimization for the stochastic traveling salesman problem
- → Unmanned Aerial Vehicle-enabled grassland restoration with energy-sensitive of trajectory design and restoration areas allocation via a cooperative memetic algorithm
- → New features for customer classification in the Flying Sidekick Traveling Salesman Problem
- \rightarrow A new evolutionary optimization algorithm with hybrid guidance mechanism for truck-multi drone delivery system
- → An effective memetic algorithm for the close-enough traveling salesman problem
- → On the Application of Heuristics of the TSP for the Task of Restoring the DNA Matrix
- → Estimating optimal objective values for the TSP, VRP, and other combinatorial problems using randomization
- → Solving Traveling Salesman Problem Using Parallel River Formation Dynamics Optimization Algorithm on Multi-core Architecture Using Apache Spark
- → Genetic algorithm to the bi-objective multiple travelling salesman problem
- \rightarrow The Discrete Carnivorous Plant Algorithm with Similarity Elimination Applied to the Traveling Salesman Problem
- → The parallel drone scheduling problem with multiple drones and vehicles
- → New mixed integer linear programming models and an iterated local search for the clustered traveling salesman problem with relaxed priority rule
- → Multi-objectivization inspired metaheuristics for the sum-of-the-parts combinatorial optimization problems

References

Helena R. Lorenço, O. M. and STUTZLE, T. Iterated local search.

TspLib. Disponível em: http://comopt.ifi.uni-heidelberg.de/software/TSPLIB95/. Acesso em: 11 de setembo 2023.