



This thesis was submitted to the Institute of Mechanism Theory, Machine Dynamics and Robotics

Cross-Compiling ROS2 Humble to WebAssembly

Master Thesis

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Aachen, 31 March 2023

Issue

Master Thesis

by Isabel Paredes B.Sc. Student number: 415723

Cross-Compiling ROS2 Humble to WebAssembly

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Formula symbols and indices				
Lower case latin letters as formula symbols				
a	$\frac{\mathrm{m}}{\mathrm{s}^2}$	acceleration		
Upper case latin letters as formula symbols				
A	m^2	surface		
Lower case	greek let	ters as formula symbols		
α	_	Weighting factor		
Upper case	greek let	ters as formula symbols		
Ω	$\frac{\mathrm{rad}}{\mathrm{m}}$	Angular frequency		

Indices

a Amplitude

List of abbreviations

General abbreviations

FFT Fast-Fourier-Transformation

WASM Web Assembly

1. Introduction

Motivation for work

- 2. Literature Review
- 2.1. ROS on Web
- 2.2. Web Tools
- 2.3. Unreal WASM??

3. Concept Realization

Ideal scenario: - click on a link and run ${\rm ROS}$ - connect to a robot via bluetooth - share simulations and algorithms

- 4. Technical Levels
- 4.1. User Levels of Interaction
- 4.2. Technical Levels of Implementation

5. Scope of Tasks

- Middleware replacement (why sockets don't work)
- JavaScript "ROS master"

6. Methodology

- Development environment - Building tools - Testing tools (chrome, firefox)

7. Middleware Implementation

- What does the middleware do? - ROS supported middleware implementations - Why it needs to be replaced - Minimal implementation (minimal set of functions) - Design of middleware packages (tree diagram or something)

8. Package Building Process

- Emscripten - Colcon - Toolchains

9. Design of Web Elements

- Web workers, what are they? why are they needed? - Communication channels - Registry of topics/subs/pubs - Message handling

10. Package Management and Distribution

- Automating package building - robostack?

11. Concept Assessment

- Survey - Performance measures - Limitations

12. Summary

13. Outlook

- Compiling on the browser - Packaging Gazebo - WASI

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