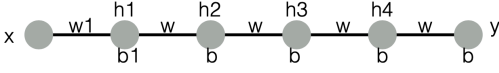


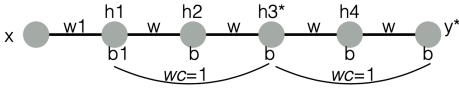
Question 1:



$$\begin{aligned}\frac{\partial y}{\partial w_1} &= \frac{\partial y}{\partial z_y} \cdot \frac{\partial z_y}{\partial h_4} \cdot \frac{\partial h_4}{\partial z_4} \cdot \frac{\partial z_4}{\partial h_3} \cdot \frac{\partial h_3}{\partial z_3} \cdot \frac{\partial z_3}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} \\ &= \sigma'(z_y) \cdot w \cdot \sigma'(z_4) \cdot w \cdot \sigma'(z_3) \cdot w \cdot \sigma'(z_2) \cdot w \cdot \sigma'(z_1) \cdot x \\ &= w^4 \cdot \sigma'(z_y) \cdot \sigma'(z_4) \cdot \sigma'(z_3) \cdot \sigma'(z_2) \cdot \sigma'(z_1) \cdot x\end{aligned}$$

$$\begin{aligned}h_1 &= \sigma(z_1) = \sigma(w_1 x + b_1) \\ h_2 &= \sigma(z_2) = \sigma(w h_1 + b) \\ h_3 &= \sigma(z_3) = \sigma(w h_2 + b) \\ h_4 &= \sigma(z_4) = \sigma(w h_3 + b) \\ y &= \sigma(z_y) = \sigma(w h_4 + b)\end{aligned}$$

$$\begin{aligned}\frac{\partial y}{\partial b_1} &= \frac{\partial y}{\partial z_y} \cdot \frac{\partial z_y}{\partial h_4} \cdot \frac{\partial h_4}{\partial z_4} \cdot \frac{\partial z_4}{\partial h_3} \cdot \frac{\partial h_3}{\partial z_3} \cdot \frac{\partial z_3}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} \\ &= \sigma'(z_y) \cdot w \cdot \sigma'(z_4) \cdot w \cdot \sigma'(z_3) \cdot w \cdot \sigma'(z_2) \cdot w \cdot \sigma'(z_1) \cdot 1 \\ &= w^4 \cdot \sigma'(z_y) \cdot \sigma'(z_4) \cdot \sigma'(z_3) \cdot \sigma'(z_2) \cdot \sigma'(z_1)\end{aligned}$$



$$\begin{aligned}h_1 &= \sigma(z_1) = \sigma(w_1 x + b_1) & z_1 &= w_1 x + b_1 \\ h_2 &= \sigma(z_2) = \sigma(w h_1 + b) & z_2 &= w h_1 + b \\ h_3^* &= \sigma(z_3^*) = \sigma(w h_2 + h_1 + b) & z_3^* &= w h_2 + h_1 + b \\ h_4 &= \sigma(z_4) = \sigma(w h_3^* + b) & z_4 &= w h_3^* + b \\ y^* &= \sigma(z_{y^*}) = \sigma(w h_4 + h_3^* + b) & z_{y^*} &= w h_4 + h_3^* + b\end{aligned}$$

$$\begin{aligned}\frac{\partial y^*}{\partial w_1} &= \frac{\partial y^*}{\partial z_{y^*}} \cdot \left[\frac{\partial z_{y^*}}{\partial h_4} \cdot \frac{\partial h_4}{\partial z_4} \cdot \frac{\partial z_4}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} \cdot \left(\frac{\partial z_3^*}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} + \frac{\partial z_3^*}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} \right) \right. \\ &\quad \left. + \frac{\partial z_{y^*}}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} \cdot \left(\frac{\partial z_3^*}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} + \frac{\partial z_3^*}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} \right) \right] \\ &= \frac{\partial y^*}{\partial z_{y^*}} \cdot \left(\frac{\partial z_{y^*}}{\partial h_4} \cdot \frac{\partial h_4}{\partial z_4} \cdot \frac{\partial z_4}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} + \frac{\partial z_{y^*}}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} \right) \cdot \left(\frac{\partial z_3^*}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} + \frac{\partial z_3^*}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} \right) \\ &= \sigma'(z_{y^*}) (w \cdot \sigma'(z_4) \cdot w \cdot \sigma'(z_3^*) + 1 \cdot \sigma'(z_3^*)) \cdot (w \cdot \sigma'(z_2) \cdot w \cdot \sigma'(z_1) \cdot x + 1 \cdot \sigma'(z_1) \cdot x) \\ &= w^4 \cdot \sigma'(z_{y^*}) \cdot \sigma'(z_4) \cdot \sigma'(z_3^*) \cdot \sigma'(z_2) \cdot \sigma'(z_1) \cdot x + w^2 \cdot \sigma'(z_{y^*}) \cdot \sigma'(z_4) \cdot \sigma'(z_3^*) \cdot \sigma'(z_1) \cdot x + \\ &\quad w^2 \cdot \sigma'(z_{y^*}) \cdot \sigma'(z_3^*) \cdot \sigma'(z_2) \cdot \sigma'(z_1) \cdot x + \sigma'(z_{y^*}) \cdot \sigma'(z_3^*) \cdot \sigma'(z_1) \cdot x\end{aligned}$$

$$\begin{aligned}\frac{\partial y^*}{\partial b_1} &= \frac{\partial y^*}{\partial z_{y^*}} \cdot \left[\frac{\partial z_{y^*}}{\partial h_4} \cdot \frac{\partial h_4}{\partial z_4} \cdot \frac{\partial z_4}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} \cdot \left(\frac{\partial z_3^*}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} + \frac{\partial z_3^*}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} \right) \right. \\ &\quad \left. + \frac{\partial z_{y^*}}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} \cdot \left(\frac{\partial z_3^*}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} + \frac{\partial z_3^*}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} \right) \right] \\ &= \frac{\partial y^*}{\partial z_{y^*}} \cdot \left(\frac{\partial z_{y^*}}{\partial h_4} \cdot \frac{\partial h_4}{\partial z_4} \cdot \frac{\partial z_4}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} + \frac{\partial z_{y^*}}{\partial h_3^*} \cdot \frac{\partial h_3^*}{\partial z_3^*} \right) \cdot \left(\frac{\partial z_3^*}{\partial h_2} \cdot \frac{\partial h_2}{\partial z_2} \cdot \frac{\partial z_2}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} + \frac{\partial z_3^*}{\partial h_1} \cdot \frac{\partial h_1}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} \right) \\ &= \sigma'(z_{y^*}) (w \cdot \sigma'(z_4) \cdot w \cdot \sigma'(z_3^*) + 1 \cdot \sigma'(z_3^*)) \cdot (w \cdot \sigma'(z_2) \cdot w \cdot \sigma'(z_1) \cdot 1 + 1 \cdot \sigma'(z_1) \cdot 1) \\ &= w^4 \cdot \sigma'(z_{y^*}) \cdot \sigma'(z_4) \cdot \sigma'(z_3^*) \cdot \sigma'(z_2) \cdot \sigma'(z_1) + w^2 \cdot \sigma'(z_{y^*}) \cdot \sigma'(z_4) \cdot \sigma'(z_3^*) \cdot \sigma'(z_1) + \\ &\quad w^2 \cdot \sigma'(z_{y^*}) \cdot \sigma'(z_3^*) \cdot \sigma'(z_2) \cdot \sigma'(z_1) + \sigma'(z_{y^*}) \cdot \sigma'(z_3^*) \cdot \sigma'(z_1)\end{aligned}$$

So far the derivation is as shown above.

Question 2:

1) Standard gradient descent:

$$Loss(x) = \begin{cases} -x+1 & (x < 1) \\ x-1-h & (1 < x < 1+h) \\ -x+1+h & (1+h < x < 1+2h) \\ -0.3x + \frac{(1+2h)}{0.3} & (x > 1+2h) \end{cases} \quad \frac{\partial Loss}{\partial x} = \begin{cases} -1 & (x < 1) \\ 1 & (1 < x < 1+h) \\ -1 & (1+h < x < 1+2h) \\ -0.3 & (x > 1+2h) \end{cases}$$

$x_0 = 0$
 $x_1 = x_0 - a \times \frac{\partial Loss}{\partial x_0} = 0 - 0.3 \times (-1) = 0.3$
 $x_2 = x_1 - a \times \frac{\partial Loss}{\partial x_1} = 0.3 - 0.3 \times (-1) = 0.6$
 $x_3 = x_2 - a \times \frac{\partial Loss}{\partial x_2} = 0.6 - 0.3 \times (-1) = 0.9$
 $x_4 = x_3 - a \times \frac{\partial Loss}{\partial x_3} = 0.9 - 0.3 \times (-1) = 1.2$
 $x_5 = x_4 - a \times \frac{\partial Loss}{\partial x_4} = 1.2 - 0.3 \times (1) = 0.9$
 $x_6 = x_5 - a \times \frac{\partial Loss}{\partial x_5} = 0.9 - 0.3 \times (-1) = 1.2$

repeating

2) Adam Optimizer:

Within 9999 iterations, if the x can escape the bump, which means $x > (1+h)$, the height h is not large enough

After 9999 iterations, if the x cannot escape the bump, we believe the height h is too large to escape

```

1  def de_function(x, h):
2      if x<1:
3          return -1
4      elif 1<x< (1+h):
5          return 1
6      elif (1+h)< x<(1+2*h):
7          return -1
8      else:
9          return -0.3
10
11 def find_h( derivative, n_iter, alpha, betal, beta2, eps=0):
12     for h in np.arange(0.3,1,0.0001):
13         x = 0
14         m = 0.0
15         v = 0.0
16         for t in range(1,n_iter):
17             g = de_function(x,h)
18             m = betal * m + (1 - betal) * g
19             v = beta2 * v + (1 - beta2) * g**2
20             mhat = m / (1.0 - betal**t)
21             vhat = v / (1.0 - beta2**t)
22             x = x - alpha * mhat / (vhat**0.5 )
23             if x>(1+h):
24                 break
25             if x<(1+h):
26                 print("The maximum height of the bump h=", h)
27                 break
28
29 n_iter = 10000
30 alpha = 0.3
31 betal = 0.9
32 beta2 = 0.999
33 find_h( de_function, n_iter, alpha, betal, beta2)
    
```

Gradient with Adam Optimizer:

The maximum height of the bump h= 0.4101999999999998785

Question 3:

