



Instituto Superior Técnico

Production Management

Laboratory Guide

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1 Introduction

To develop your group project, within Production Management course framework, a set of devices (sensors, boards, receivers, etc.) is provided. In order to have a proper functioning of these devices and to be able to gather data and analyse it, some code files to run in Arduino IDE will be necessary. A platform called ThingsBoard will be used to store and visualize the collected data.

During your first visit to Sustainable Production 4.0 Laboratory, you will have the opportunity to see 4 different demonstrations where the devices will be used with different purposes. Each demonstration aims to enlighten how the different devices can be helpful to gather relevant data in production management context.

In this document you will find important information and guidelines that will help you during your project development.

2 Devices

In the Sustainable Production 4.0 Laboratory there is a set of available devices that can be used to develop your projects. In this section of the guide, they are presented with a brief description.

2.1 Light Dependent Resistor (LDR)

A Light Dependent Resistor (LDR) (Figure 1) is an electronic component that is used to detect the presence or the level of light. As the light intensity increases, their resistance decreases (Figure 2). For example, in the dark, at low light levels, the resistance of a LDR is high, meaning there is few current flowing and a high voltage.

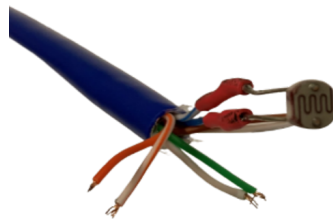


Figure 1: LDR

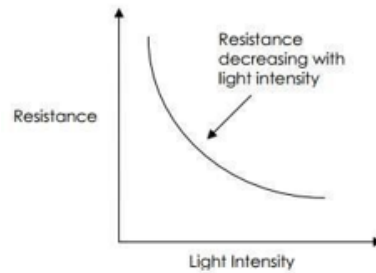


Figure 2: Resistance variation with light intensity

The analogic output of the LDR is a value between 0 and 1023. In the dark the output values will be higher than in brighter environments.

2.2 Buttons

This device (Figure 3) consists on a simple set of 5 buttons (and is also equipped with 3 LEDs). Every time a button is pressed, an output that indicates which of the 5 buttons was pressed is generated. It can be used for a wide variety of purposes, as it will be exemplified in different demonstrations.

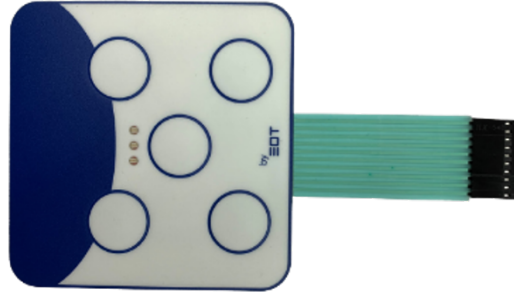


Figure 3: Buttons

2.3 Time of Flight (ToF)

The ToF sensor (Figure 4) allows to get the distance between itself and the closest object. Its working principle is simple (Figure 5). A light (infrared, invisible to human eyes) signal is emitted by the sensor. This signal will hit the first object in front of the sensor and will bounce back to it. Knowing the time it takes for the signal to travel that path, it is possible to know the distance between the sensor and the object.

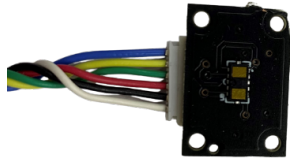


Figure 4: ToF

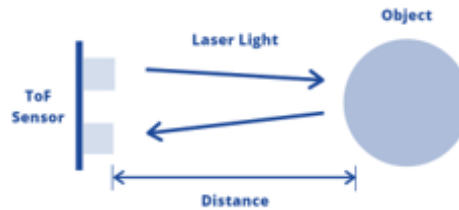


Figure 5: ToF working principle

2.4 Boards

The iStartLab V2.0 boards (Figure 6) were developed by IST iStartLab. The communication between the boards and ThingsBoard uses LoRa technology, which requires low power to send data. More information about this can be found in "IoT Technology" provided document. Among several relevant features, it should be noted that the boards are equipped with a buzzer, an USB port and a reset button.

Some of the previously mentioned devices should be connected to the iStartLab V2.0 board so that, after uploading the programs written in Arduino IDE, data from devices can be collected. These devices are: LDRs, buttons and ToF.



Figure 6: iStartLab V2.0 Board

2.5 Beacon + Receiver

An Arduino ESP32 board works as a receiver (Figure 7). It is placed in an interest point and will detect beacons (Figure 8) signals, making it easy to identify the beacons that were near the interest point. So, if the signal received from beacon A has higher intensity than the signal received from beacon B, you can conclude that beacon A was closer to the interest point.

The beacons use Bluetooth Low Energy (BLE) technology, which requires a considerably lower power consumption than classic Bluetooth. But the receiver must be plugged because it is constantly trying to find beacons and receive their signals, requiring more energy. It communicates via Wi-Fi to send the collected data to ThingsBoard.

A specific program written in Arduino IDE must be uploaded to the receiver board, so data can be collected. For further explanation, see section 3 of this document.



Figure 7: Beacon

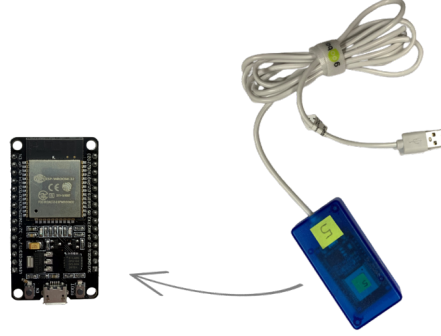


Figure 8: Receiver board (on the left) and receiver inside its box, with cable (on the right)

2.6 Vibration sensor

It is possible to identify a machine state, working or stopped, by detecting its vibration. For that, an Arduino Nano RP2040 Connect (Figure 9) is used, which has an onboard accelerometer. Since vibration in all directions is relevant, accelerometer values in x, y and z axis are considered. Also, to ignore the offset of the acceleration, the variation values are used instead of the acceleration value itself. The obtained output is F , computed according to equation 1, where N represents the number of samples used ($N=128$).

$$F = \sum_{n=2}^N [|accX_n - accX_{n-1}| + |accY_n - accY_{n-1}| + |accZ_n - accZ_{n-1}|] \quad (1)$$

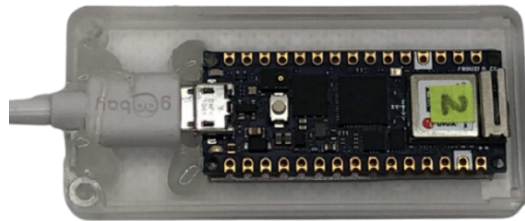


Figure 9: Arduino Nano RP2040 Connect inside its box



A specific program written in Arduino IDE must be uploaded to this board, so data can be collected. For further explanation, see section 3 of this document.

3 Arduino IDE sketches

As explained before, for the devices to properly work, specific sketches must be uploaded to the iStartLab board (in case the devices being used are LDRs, buttons or ToF), vibration sensor board and receiver board.

Table 1 shows the folder where you will find the required sketch to upload when using each device.

Table 1: Organisation of the code folders

Folder name	Upload when using
LDR	LDR
Buttons_Counter	Buttons
ToF	ToF
BLE_receiver	Beacon + Receiver
Vibration_Sensor	Vibration sensor

These sketches will be provided in the beginning of your project development. You are free to adapt and change it according to your project specifications.

4 Tips and Important Guidelines

To develop your group project, different software will be required. Each has its own characteristics and some might need to be changed. In this section you can find tips and important guidelines, with step-by-step explanations.

4.1 General

4.1.1 Wi-Fi

Whenever you are working with any of the devices previously mentioned, it is required to connect to a specific Wi-Fi network:



- **Name:** Production Management
- **Password:** ist_1911

4.1.2 Arduino IDE

If you don't have it yet, install **Arduino IDE** software. It can be done through this [link](#). Note that you will need to be using **version 1.8 or higher** for this project.

4.2 LDR and Buttons

4.2.1 Choose Board

To be able to upload sketches into iStartLab boards, you must select the board “Adafruit Feather M0”, which requires the installation of “Adafruit SAMD Board” in Boards Manager. For that, follow the next steps:

- On the top left **Menu**, select **File** and then **Preferences**.
- In the **Additional Boards Manager URLs** option (Figure 10), write the link: `https://adafruit.github.io/arduino-board-index/package_adafruit_index.json`

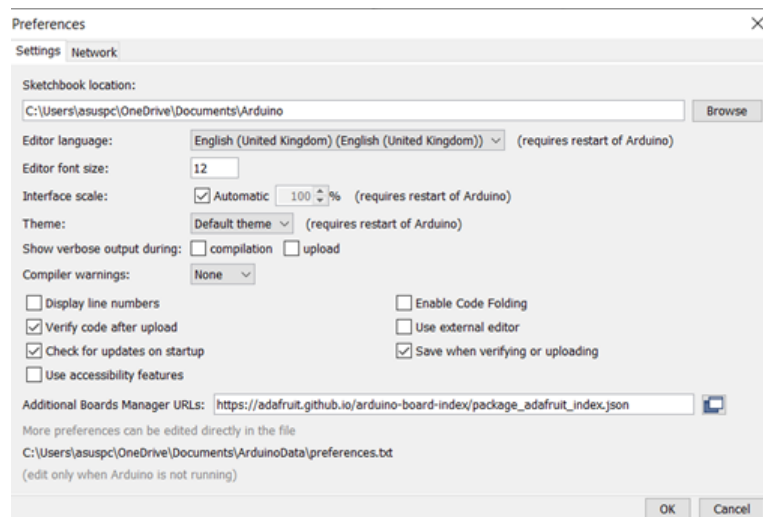


Figure 10: Preferenes tab

- Back to the top left **Menu**, select **Tools**, then **Board** and finally **Boards Manager**.
- Use the search bar to find “**Adafruit SAMD Boards**” and **install** it (Figure 11).



Figure 11: Boards Manager with “Adafruit SAMD Boards” installed

- Having the required package installed, go to **Menu**, **Tools**, **Board** and select the board “**Adafruit Feather M0**” (Figure 12).

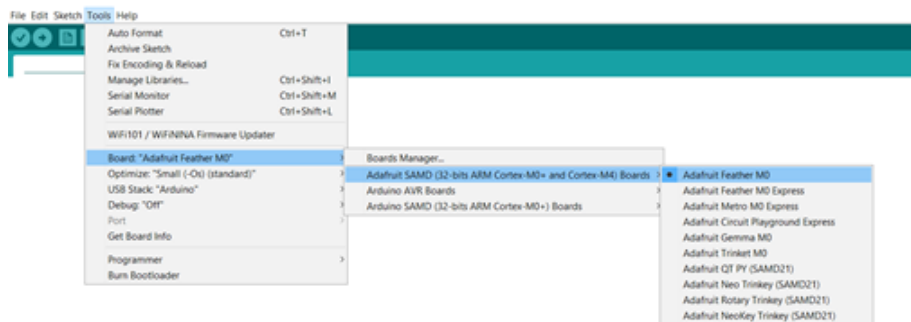


Figure 12: “Adafruit Feather M0” board selected

4.2.2 Install libraries

For the sketch code to be compiled without any error message, some libraries must be installed. That can be done following the next steps:

- On the top left **Menu**, select **Sketch**, then **Include Library** and finally **Manage Libraries**.
- Use the search bar to find “**ArduinoJson**” and **install** it (Figure 13).



Figure 13: “ArduinoJson” library installed

4.3 ToF

4.3.1 Choose Board

To be able to upload sketches into iStartLab boards, you must select the board “**Adafruit Feather M0**” (Figure 12), which requires the installation of “Adafruit SAMD Board” in Boards Manager. If you haven’t done it yet, follow the steps described in section 4.2.1 of this document.

4.3.2 Install libraries

For the sketch code to be compiled without any error message, some libraries must be installed. That can be done following the next steps:

- On the top left **Menu**, select **Sketch**, then **Include Library** and finally **Manage Libraries**.
- Use the search bar to find “**CayenneLPP.h**” and “**RTCZero.h**” and **install** it (Figures 14 and 15).

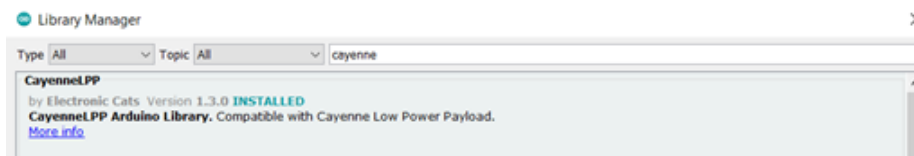


Figure 14: “CayenneLPP” library installed



Figure 15: “RTCZero” library installed

4.4 Beacon + Receiver

4.4.1 Choose Board

To be able to upload sketches into receiver boards, you must select the board “**ESP32 Dev Module**”, which requires the installation of “**esp32**” in Boards Manager. The procedure (Figures 16 to 18) is similar to the one described in section 4.2.1, being necessary to do the following changes:

- The link to write in Additional Boards Manager URLs field is:
https://dl.espressif.com/dl/package_esp32_index.json
 Note that, if other links are written in this field, they must be separated by comma.

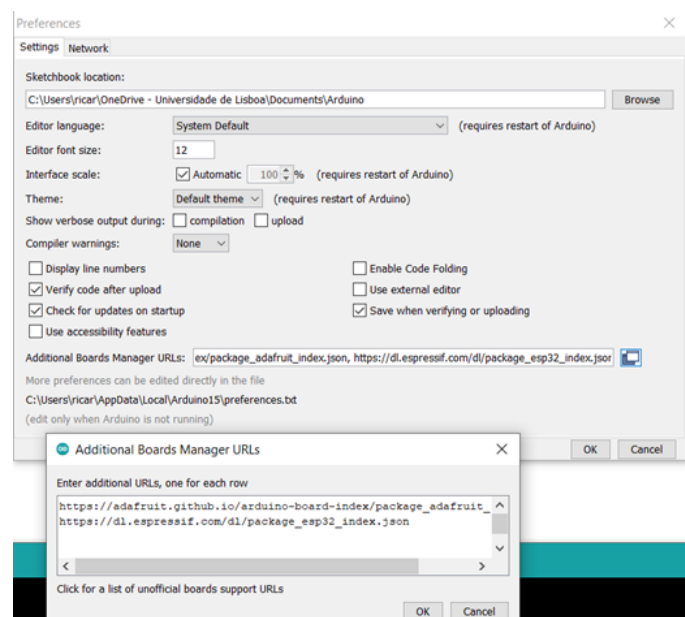


Figure 16: Preferences tab

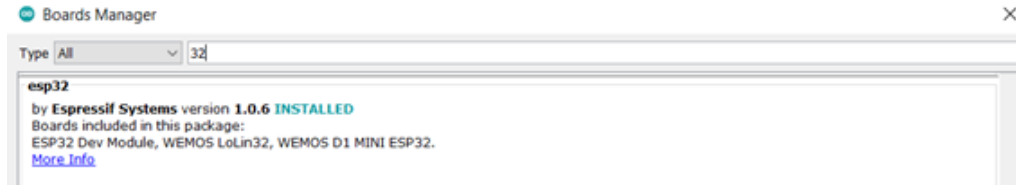


Figure 17: Boards Manager with “esp32” installed

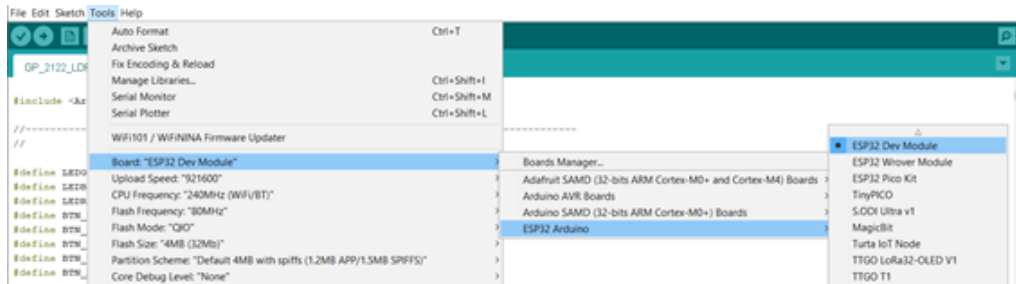


Figure 18: “ESP32 Dev Module” board selected

4.4.2 Install libraries

For the sketch code to be compiled without any error message, some libraries must be installed. That can be done following the next steps:

- On the top left **Menu**, select **Sketch**, then **Include Library** and finally **Manage Libraries**.
- Use the search bar to find “**ESP32 BLE Arduino**”, “**PubSubClient**”, “**ThingsBoard**” and **install** them (Figure 19 to 21).



Figure 19: “ESP 32 BLE Arduino” library installed



Figure 20: “PubSubClient” library installed

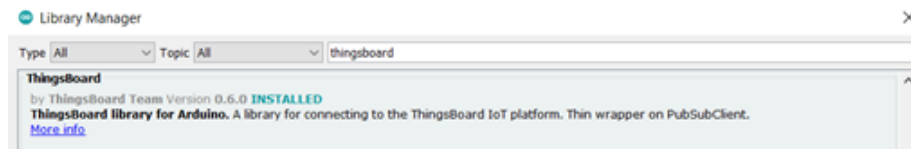


Figure 21: “ThingsBoard” library installed

4.4.3 Access token

Each receiver has a unique access token that allows to have access and view the collected data in ThingsBoard platform. You can find the access token on ThingsBoard. On the left side menu choose **Devices**, then select the receiver you are working with and click on **Copy access token** (Figure 22).

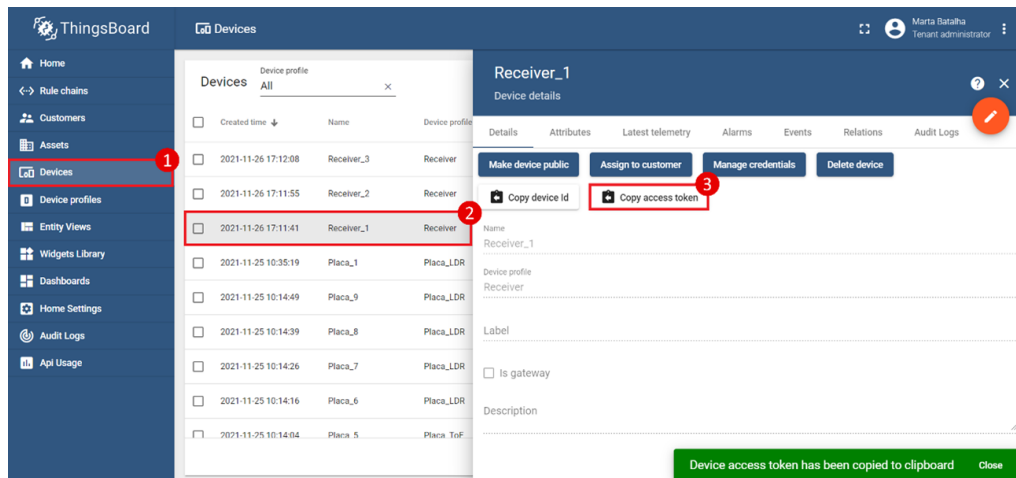


Figure 22: ThingsBoard interface with steps to get access token

Finally, you need to change the access token in the proper section (Fig-



ure 23) of file “secrets.h”, which is in the folder “BLE_receiver”. The code should be uploaded to the receiver board only after completing this step.



```
BLE_receiver secrets.h
/**** Wi-Fi Credentials *****/
#define STA_SSID "Vodafone-0E5D6"
#define STA_PASS "E8vM5BhC3"

/**** The ThingsBoard parameters *****/

// if cloud/professional edition
#define THINGSBOARD_SERVER "iot.istartlab.technico.ulisboa.pt"

// if community edition live demo
// #define THINGSBOARD_SERVER "demo.thingsboard.io"

//BLE Receiver Device Token
#define TOKEN "Cqhw4DeOmj3Y3yez2hhh"

/**** BLE System UUID *****/
// same for all beacons and all BLE Receivers
uint8_t uuid_system[16] = { 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00 };
```

Figure 23: “secrets.h” code for BLE receiver

In this same file it is essential to confirm that in define STA_SSID “name” and define STA_PASS “password” the name and password are those of the Wi-Fi network to which one is connected.

4.4.4 Compiling error troubleshooting

If the error message below shows up when you try to compile the code, you will have to change the Partition Scheme, according to Figure 24.

Error Message:

*“Sketch uses 1496186 bytes (114%) of program storage space. Maximum is 1310720 bytes.text section exceeds available space in board.
Global variables use 55568 bytes (16%) of dynamic memory, leaving 272112 bytes for local variables. Maximum is 327680 bytes.
Sketch too big; see <https://support.arduino.cc/hc/en-us/articles/360013825179> for tips on reducing it.
Error compiling for board ESP32 Dev Module.”*

4.5 Vibration Sensor

4.5.1 Choose Board

To be able to upload sketches into the vibration sensor, you must select the board “**Arduino Nano RP2040 Connect**”, which requires the instal-

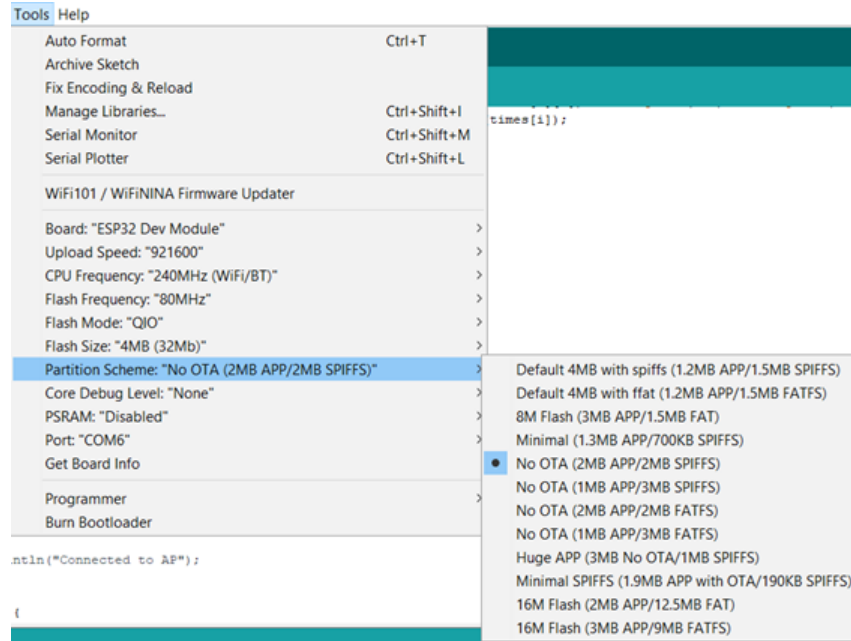


Figure 24: Partition Scheme selection

lation of **“Arduino Mbed OS Nano Boards”** in Boards Manager. This procedure (Figures 25 and 26) is similar to the one described in section 4.2.1 of this document.



Figure 25: Boards Manager with “Arduino Mbed OS Nano Boards” installed

4.5.2 Install libraries

For the sketch code to be compiled without any error message, some libraries must be installed. That can be done following the next steps:

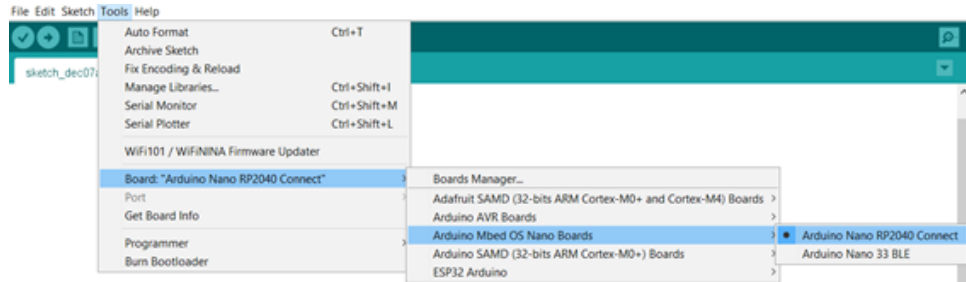


Figure 26: “Arduino Nano RP2040 Connect” board selected

- On the top left **Menu**, select **Sketch**, then **Include Library** and finally **Manage Libraries**.
- Use the search bar to find “**Arduino_LSM6DSOX**”, “**ArduinoMqttClient**” and “**WiFiNINA**” and **install** it (Figures 27 to 29).



Figure 27: “Arduino_LSM6DSOX” library installed



Figure 28: “ArduinoMqttClient” library installed

4.5.3 Access token

Each vibration sensor has a unique access token that allows to have access and view the collected data in ThingsBoard platform.

You can find the access token on Thingsboard, following a similar procedure to the one explained in section 4.4.3 of this document. On the left

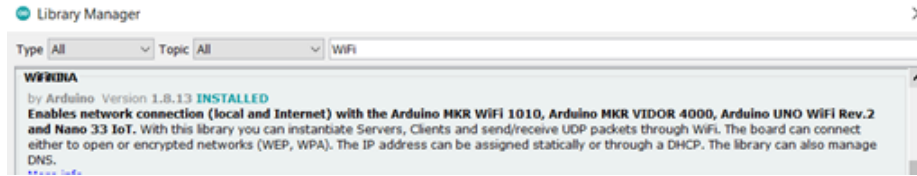


Figure 29: “WiFiNINA” library installed

side menu choose **Devices**, then select the receiver you are working with and click on **Copy access token**.

Finally, you need to change the access token in the proper section (Figure 30) of file “secrets.h”, which is in the folder “Vibration.Sensor”. The code should be uploaded to the vibration sensor board only after completing this step.



Figure 30: “secrets.h” code for vibration sensor

In this same file it is essential to confirm that in define STA_SSID “name” and define STA_PASS “password” the name and password are those of the Wi-Fi network to which one is connected.

4.6 Changing boards keys

Each iStartLab board has 3 unique keys – network session key (NSK), application session key (ASK) and device address (DA). More than one board can be in use at the same time. However, the platform used to gather data is the same for every board. This means that these keys are essential to identify



the board from where a certain message was sent. For this to be possible, it is mandatory to **change the board keys to the ones of the board being used before uploading the sketch to the board**. These keys, in the appropriate format, can be found in Appendix A.

If you are using “LDR”, change the keys in the section shown in Figure 31. If you are using “Buttons_Counter”, change the keys in the section shown in Figure 32. If you are using “ToF”, change the keys in the section shown in Figure 33.

```
GP_2122_LDRs_100  CayenneLPP.cpp  CayenneLPP.h  TinyLoRa.cpp  TinyLoRa.h
#include "TinyLoRa.h"
#include <SPI.h>

TinyLoRa lora = TinyLoRa(RFM_DIO0, RFM_CS, RFM_RST);

// Network Session Key (MSB)
uint8_t NwkSkey[16] = { 0x3b, 0x9e, 0x90, 0x4f, 0x59, 0x28, 0x4e, 0x02, 0x65, 0xf5, 0xb3, 0x1b, 0x9b, 0xfe, 0x54, 0xe1 };
// Application Session Key (MSB)
uint8_t AppSkey[16] = { 0x09, 0xec, 0xcf, 0x02, 0x2d, 0x57, 0x34, 0x0b, 0x96, 0x97, 0x6f, 0xae, 0xa7, 0xf2, 0xca, 0x84 };
// Device Address (MSB)
uint8_t DevAddr[4] = { 0x01, 0x40, 0xe5, 0x20 };

// These 3 keys change from
// board to board. Go to the
// guide provided, copy the
// correct keys and paste
// them in this code.
```

Figure 31: Keys in LDR code

```
GP_2122_Buttons  CayenneLPP.cpp  CayenneLPP.h  TinyLoRa.cpp  TinyLoRa.h
#include "TinyLoRa.h"
#include <SPI.h>

TinyLoRa lora = TinyLoRa(RFM_DIO0, RFM_CS, RFM_RST);

// Network Session Key (MSB)
uint8_t NwkSkey[16] = { 0x3b, 0x9e, 0x90, 0x4f, 0x59, 0x28, 0x4e, 0x02, 0x65, 0xf5, 0xb3, 0x1b, 0x9b, 0xfe, 0x54, 0xe1 };
// Application Session Key (MSB)
uint8_t AppSkey[16] = { 0x09, 0xec, 0xcf, 0x02, 0x2d, 0x57, 0x34, 0x0b, 0x96, 0x97, 0x6f, 0xae, 0xa7, 0xf2, 0xca, 0x84 };
// Device Address (MSB)
uint8_t DevAddr[4] = { 0x01, 0x40, 0xe5, 0x20 };

// These 3 keys change from
// board to board. Go to the
// guide provided, copy the
// correct keys and paste
// them in this code.
```

Figure 32: Keys in buttons code



```

ToF      ComponentObject.h  RangeSensor.h  SparkFun_VL53L1X.cpp  SparkFun_VL53L1X.h  TinyLoRa.cpp  TinyLoRa.h  secrets.h$  v53l1_error_codes.h  v53l1x_class.cpp  v53l1x_class.h

/***** The Things Network Keys *****/

// Network Session Key (MSB)
uint8_t NwkSKey[16] = { 0x38,0x43,0xf2,0x3d,0x5e,0xf1,0x63,0xe0,0xf0,0x91,0x44,0x42,0x39,0x13,0x68,0x3e};

// Application Session Key (MSB)
uint8_t AppSKey[16] = { 0xfe,0xc3,0xde,0x18,0x4d,0x2f,0x75,0xbc,0xce,0x10,0xe8,0xab,0x9c,0x04,0xcc,0x94};

// Device Address (MSB)
uint8_t DevAddr[4] = { 0x01,0x89,0xe4,0xd0} ;

// These 3 keys change from
// device to device. After
// adding a new device to
// Chirpstack, a set of keys
// is assigned. Copy them
// and change this code
// accordingly.
```

Figure 33: Keys in ToF code

A Boards keys

Keys for BOARD 1

```
// Network Session Key (MSB)
uint8_t NwkSKey[16] =
{ 0x3b,0x9e,0x90,0x4f,0x59,0x28,0x4e,0x02,0x65,0xf5,0xb3,0x1b,0x9b,0xfe,0x54,0xe1};
// Application Session Key (MSB)
uint8_t AppSKey[16] =
{ 0x09,0xec,0xcf,0x02,0x2d,0x57,0x34,0x0b,0x96,0x97,0x6f,0xae,0xa7,0xf2,0xca,0x84};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x01,0x40,0xe5,0x20} ;
```

Keys for BOARD 2

```
// Network Session Key (MSB)
uint8_t NwkSKey[16] =
{ 0x6b,0xb4,0x08,0x41,0xe7,0x7c,0x43,0x39,0xf8,0x1d,0xfe,0x36,0x2d,0x10,0xb0,0x43};
// Application Session Key (MSB)
uint8_t AppSKey[16] =
{ 0x89,0x93,0xe2,0x78,0xc3,0xf4,0xb1,0xfc,0xbb,0x16,0xf2,0x63,0x58,0x6c,0x8b,0x35};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x00,0x11,0x31,0xe6} ;
```



Keys for **BOARD 3**

```
// Network Session Key (MSB)
uint8_t NwkSkey[16] =
{ 0x38,0x43,0xf2,0x3d,0x5e,0xf1,0x63,0xe0,0xf0,0x91,0x44,0x42,0x39,0x13,0x68,0x3e};
// Application Session Key (MSB)
uint8_t AppSkey[16] =
{ 0xfe,0xc3,0xde,0x18,0x4d,0x2f,0x75,0xbc,0xce,0x10,0xe8,0xab,0x9c,0x04,0xcc,0x94};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x01,0x89,0x64,0xd0} ;
```

Keys for **BOARD 4**

```
// Network Session Key (MSB)
uint8_t NwkSkey[16] =
{ 0xd1,0xce,0x66,0x65,0x33,0x44,0x74,0x25,0x09,0x34,0x43,0x24,0x58,0x15,0x03,0x06};
// Application Session Key (MSB)
uint8_t AppSkey[16] =
{ 0xfb,0x0b,0x69,0xc5,0x1d,0xea,0x61,0x6c,0x18,0x44,0xfe,0x00,0x0b,0x2c,0xa4,0xde};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x01,0x1e,0x70,0x8d} ;
```

Keys for **BOARD 5**

```
// Network Session Key (MSB)
uint8_t NwkSkey[16] =
{ 0x21,0xc9,0xbe,0x10,0x89,0xa5,0x1f,0x46,0xdc,0x31,0x98,0x74,0x65,0x9f,0x7f,0x95};
// Application Session Key (MSB)
uint8_t AppSkey[16] =
{ 0xdb,0xb7,0x2b,0x42,0xe0,0xe2,0x3b,0xcb,0xb6,0xbf,0x80,0x52,0x52,0x65,0xbe,0x2e};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x00,0xdb,0xc8,0x81} ;
```



Keys for **BOARD 6**

```
// Network Session Key (MSB)
uint8_t NwkSkey[16] =
{ 0xfb,0x71,0x16,0x1c,0xde,0x4a,0x43,0x23,0x63,0x17,0xee,0xf2,0xe7,0xa1,0xf6,0x90};
// Application Session Key (MSB)
uint8_t AppSkey[16] =
{ 0x31,0x71,0x3e,0xfc,0xcc,0x75,0xfb,0xec,0xf7,0x63,0xb8,0x1c,0xbb,0xdf,0x56,0xe0};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x01,0x84,0x60,0xea} ;
```

Keys for **BOARD 7**

```
// Network Session Key (MSB)
uint8_t NwkSkey[16] =
{ 0x3f,0x30,0x64,0x02,0x62,0xe5,0x42,0xb3,0xef,0xe7,0xb4,0x4b,0x7a,0x28,0xd9,0x15};
// Application Session Key (MSB)
uint8_t AppSkey[16] =
{ 0x73,0x72,0x85,0x6d,0x85,0x42,0xad,0x5c,0x01,0x08,0xaa,0xda,0x82,0xf6,0xf5,0xac};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x01,0x7f,0xfb,0x22} ;
```

Keys for **BOARD 8**

```
// Network Session Key (MSB)
uint8_t NwkSkey[16] =
{ 0xc6,0x90,0xbe,0x33,0x65,0xaa,0xe7,0xe8,0x69,0x4b,0xca,0x29,0xc2,0xaa,0xfc,0xa2};
// Application Session Key (MSB)
uint8_t AppSkey[16] =
{ 0xbc,0x6a,0x65,0xf2,0xaa,0xa3,0xf9,0xa7,0x0c,0x63,0x1c,0xf4,0x4d,0xf6,0x0c,0x38};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x01,0x6d,0x0c,0x4d} ;
```



Keys for **BOARD 9**

```
// Network Session Key (MSB)
uint8_t NwkSkey[16] =
{ 0xd5,0x97,0xaa,0xd5,0x30,0x4e,0x31,0xa6,0xa1,0x5f,0xc2,0xfc,0xef,0xb9,0x39,0x87};
// Application Session Key (MSB)
uint8_t AppSkey[16] =
{ 0xb9,0x08,0x6a,0x81,0x93,0x88,0x67,0x0d,0x69,0x69,0x4f,0xaa,0x86,0x2e,0x94,0x3c};
// Device Address (MSB)
uint8_t DevAddr[4] =
{ 0x00,0x2f,0x57,0x35} ;
```