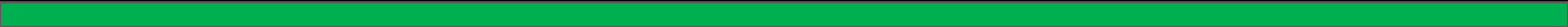


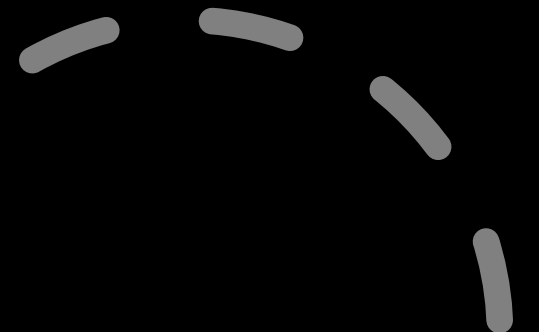


PROJECT ORION

Observation, Reconnaissance, Intelligence, and Operations Network



DEVELOPERS



ISAIAH R. HARVILLE

Data Scientist
Graduate Student

AIDAN W. NEEL

Full Stack
Non-Student

JACOB D. NEEL

M&S Engineer
Senior

CADEN S.L. HERREN

Software Engineer
Freshman



PROBLEM SET: BOTTS

- Visualization Experience
- Modeling and Sim Experience
- Data Science Experience



OVERVIEW

A versatile software platform for mission-critical applications.

Core Capabilities

- **Observation & Reconnaissance:**
Gathers real-time and historical data.
- **Intelligence & Operations:**
Processes information for strategic decision-making.

Potential Applications

- **Public Safety**
- **Security**
- **Environmental Monitoring**
- **Defense**

Technology Highlights

- **(WIP) Machine Learning Integration:**
Advanced data analysis
- **Multi-Source Data:**
Combines inputs from multiple APIs
- **Extreme Portability:**
Completely containerized, OS agnostic and served in a web app.



MACHINE LEARNING

Goal: Predict likelihood of Tornadoes in a given scan

Resources:

- Available literature is limited
- Identified paper from 2024 introducing an open-sourced dataset TorNet providing a series of NetCDF files from NEXRAD lv2 archives for training and inference
- NEXRAD AWS, provides recent radar data queryable by Radar ID

Limitations:

- Unable to finish streaming pipeline due to time constraints
- Unable to train custom DNN PyTorch model due to time constraints
- Dataset Quality

Accomplishments:

- Recreated paper results

arXiv:2401.16437v1 [physics.ao-ph] 26 Jan 2024

A Benchmark Dataset for Tornado Detection and Prediction using

Full-Resolution Polarimetric Weather Radar Data

Mark S. Veillette,^a James M. Kurdzo,^a Phillip M. Stepanian,^a John Y. N. Cho,^a Siddharth Samsi,^b Joseph McDonald^a

^a *Lincoln Laboratory, Massachusetts Institute of Technology, Lexington, Massachusetts*

^b *NVIDIA Corporation, Santa Clara, California*

M. S. Veillette, J. M. Kurdzo, P. M. Stepanian, J. Y. N. Cho, S. Samsi, and J. McDonald, Lincoln Laboratory, MIT, Lexington, MA, and NVIDIA Corporation, Santa Clara, CA, 2024.

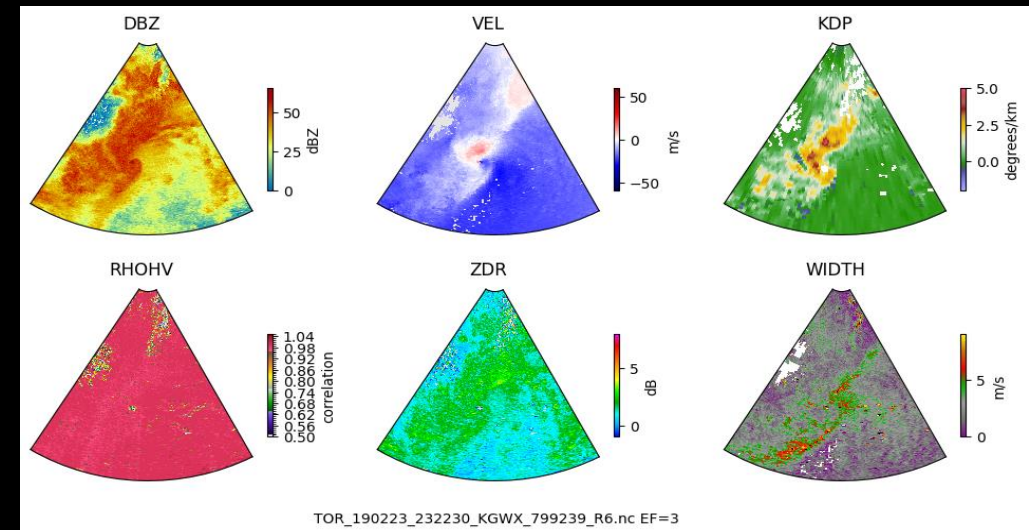
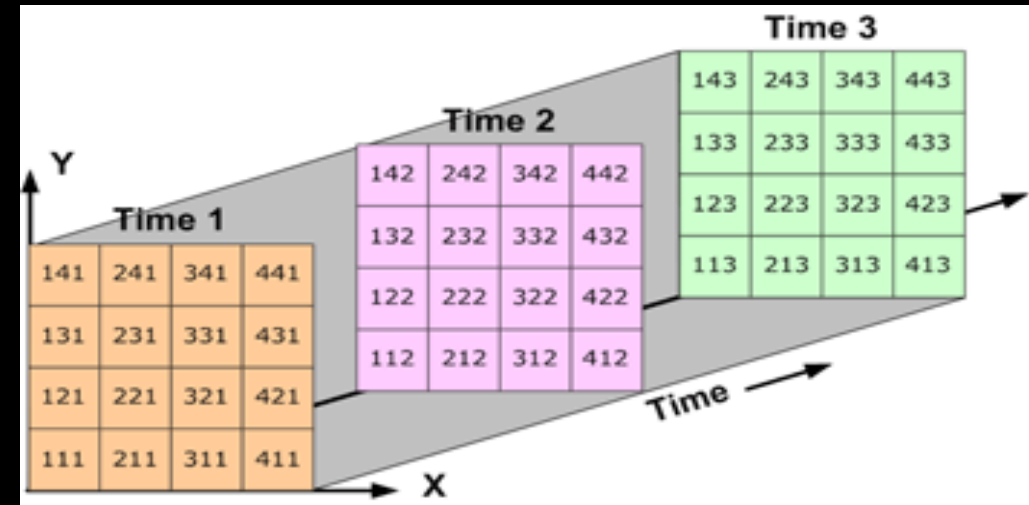
WEATHER DATA

- **Model Data:**

- NetCDF, self describing, multi-dimensional binary format
- NexradL2 data, converted to expected input shape of Neural Network in the NetCDF format utilizing pyart.
- Inference data sourced from Nexrad II AWS service

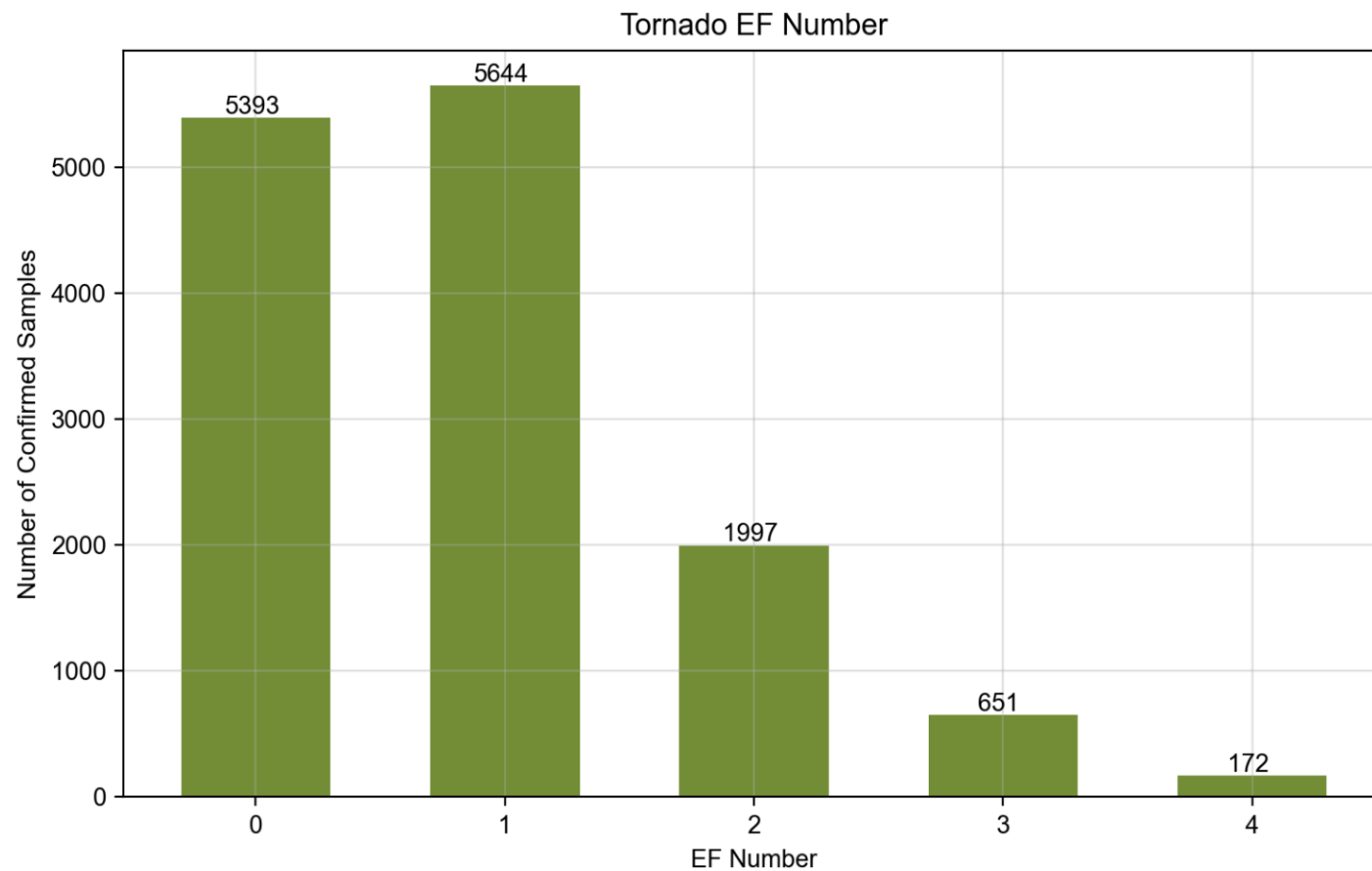
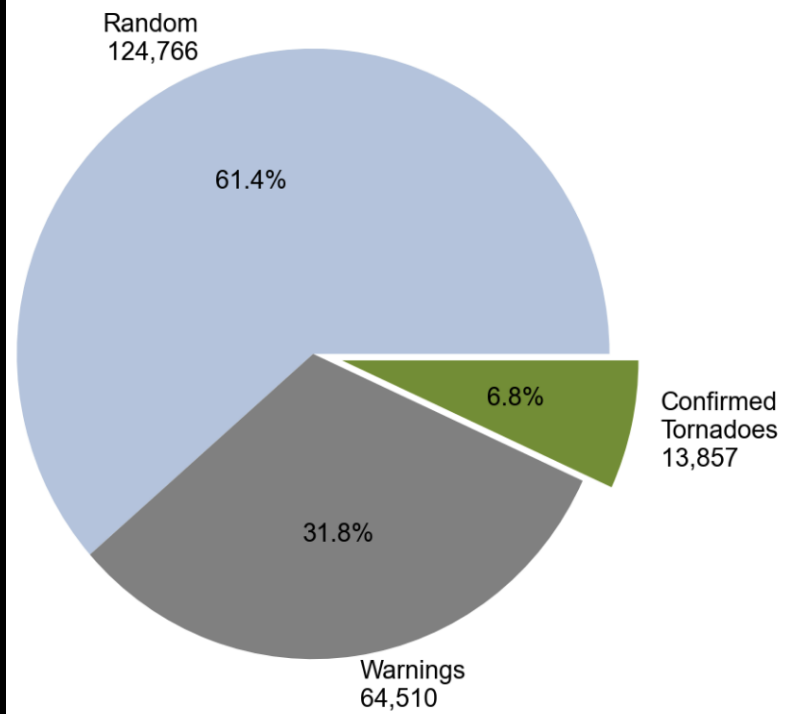
- **Map Data (GUI):**

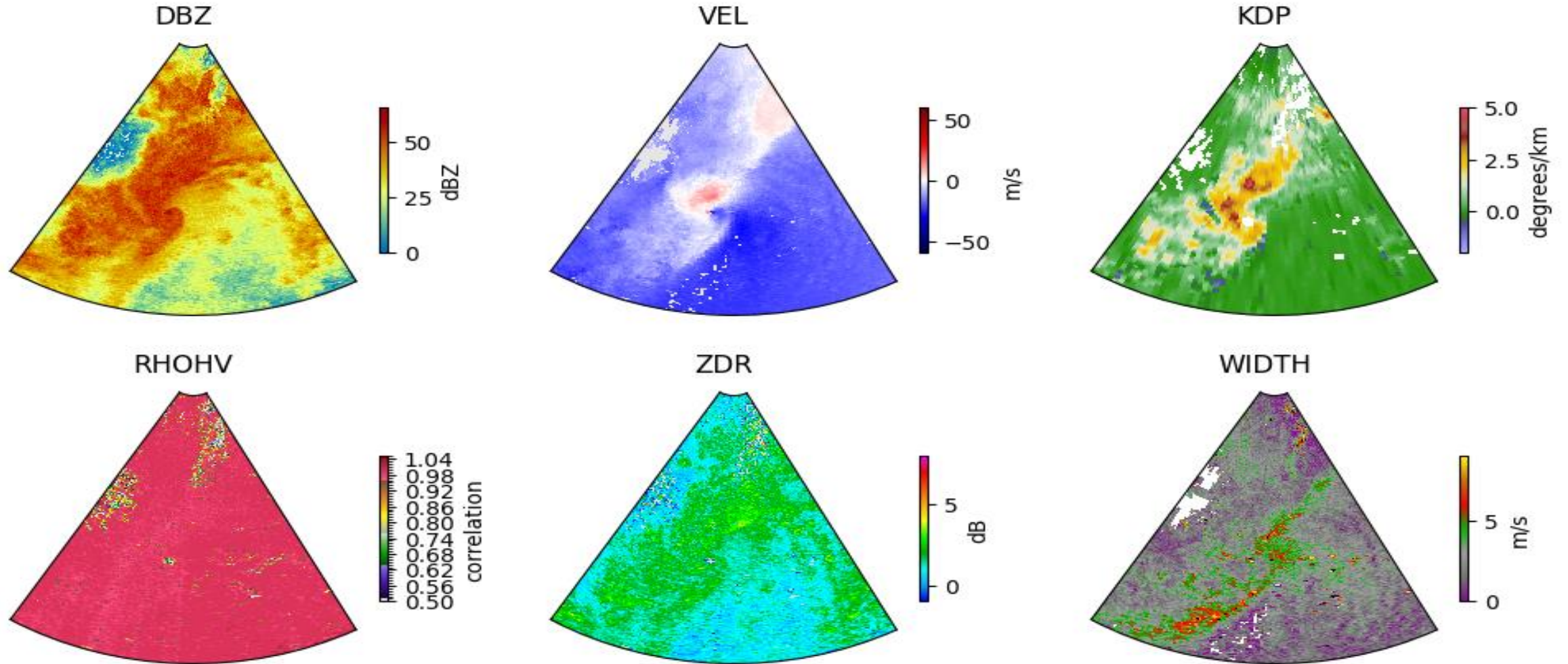
- Real-time weather data sourced from RainViewer
- Contains precipitation information



M. S. Veillette, J. M. Kurdzo, P. M. Stepanian, J. Y. N. Cho, S. Samsi, and J. McDonald, Lincoln Laboratory, MIT, Lexington, MA, and NVIDIA Corporation, Santa Clara, CA, 2024.

Number of samples: 203,133





TOR_190223_232230_KGWX_799239_R6.nc EF=3

UAV / AIS DATA

- Historical & Simulated Real Time Data
- Track Friendly/Enemy, lat/lon/alt, and more
- Open Sensor Hub API

[/ systems /](#) [View as JSON](#)

All Connected Systems

<< Previous Next >>

Predator UAV (MISB simulated RT)

UID: urn:osh:sensor:uas:predator001-RT
System Type: System [↗](#)

Validity Period:
2023-05-14T15:22:00Z
2025-03-23T18:05:00Z (Now)

Geometry: None

Properties:

[Spec Sheet](#) [Sampling Features](#) [Datastreams](#)

Predator UAS (data loader)

UID: urn:osh:system:uas:predator001
System Type: System [↗](#)

Validity Period:
2022-06-08T21:00:00Z
2025-03-23T18:05:00Z (Now)

Geometry: None

Properties:

[Spec Sheet](#) [Subsystems](#) [Sampling Features](#) [Datastreams](#)

GPS Vehicle Network

Simulated vehicle network reporting GPS measurements along random itineraries obtained using Google Direction API


UID: urn:osh:sensor:simgps:cd6fdaa2
System Type: Sensor [↗](#)

Validity Period:
2023-05-23T13:10:37Z
2025-03-23T18:05:00Z (Now)

Geometry: None

Properties:

[Spec Sheet](#) [Sampling Features](#) [Datastreams](#)



A map showing the African continent and surrounding regions, including parts of Europe, the Middle East, and South America. The map is displayed on a web interface with a zoom control on the left. The map shows various countries and their names in both Arabic and English. The map is credited to Leaflet and OpenStreetMap contributors.

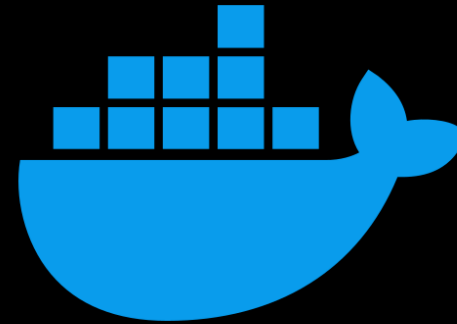
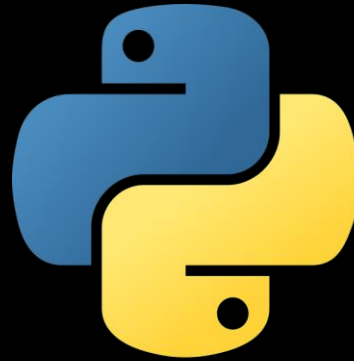
TECH STACK

- **Frontend:**

- Svelte Kit
- Tailwind
- RainViewer API
- Open Sensor Hub API

- **Backend:**

- PyTorch & Keras
- FastAPI
- Docker
- Python



PROJECT ORION

Observation, Reconnaissance, Intelligence, and Operations Network

DEMONSTRATION

