We choose k = 2 to be the new element that will be added to the basis. This is because $c_2 = 1 > 0$, and k is the smallest element that satisfies this constraint (Bland's rule)

$$t=min\{array([2.]),array([5.])\}=[2.]$$

$$x_B = b - tA_k = \begin{bmatrix} 2 \\ 5 \end{bmatrix} - [2.] \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0. \\ 3. \end{bmatrix}$$

This means that r = 1. This is the smallest 0-element index of the new x_B (by choosing this element, we are adhering to Bland's rule)

This means that our "better basis" is $B = \{13\}.$

The LP:
$$\max \begin{bmatrix} 0 & 1 & 3 & 0 \end{bmatrix} x + 0$$

$$\begin{bmatrix} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 1 \end{bmatrix} x = \begin{bmatrix} 2 \\ 5 \end{bmatrix}$$

Written in canonical form with the basis $B = \{13\}$ is:

$$\max \begin{bmatrix} -1. & 0. & 1. & 0. \end{bmatrix} x + 2.0$$

$$\begin{bmatrix} s.t. \\ 1. & 1. & 2. & 0. \\ -1. & 0. & -1. & 1. \end{bmatrix} x = \begin{bmatrix} 2. \\ 3. \end{bmatrix}$$

We choose k = 3 to be the new element that will be added to the basis. This is because $c_3 = 1. > 0$, and k is the smallest element that satisfies this constraint (Bland's rule)

$$t=min\{array([1.])\}=[1.]$$

$$x_B = b - tA_k = \begin{bmatrix} 2 \\ 3 \end{bmatrix} - \begin{bmatrix} 1 \\ \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 4 \end{bmatrix}$$

This means that r = 2. This is the smallest 0-element index of the new x_B (by choosing this element, we are adhering to Bland's rule)

This means that our "better basis" is $B = \{23\}$.

The LP:
$$\max \begin{bmatrix} -1. & 0. & 1. & 0. \end{bmatrix} x + 2.0$$

$$\begin{bmatrix} s.t. & 1. & 2. & 0. \\ -1. & 0. & -1. & 1. \end{bmatrix} x = \begin{bmatrix} 2. \\ 3. \end{bmatrix}$$

Written in canonical form with the basis $B = \{23\}$ is:

$$\max \begin{bmatrix} -1.5 & -0.5 & 0. & 0. \end{bmatrix} x + 3.0$$

$$\begin{bmatrix} \text{s.t.} \\ 0.5 & 0.5 & 1. & 0. \\ -0.5 & 0.5 & 0. & 1. \end{bmatrix} x = \begin{bmatrix} 1. \\ 4. \end{bmatrix}$$

$$x \ge \mathbb{O}$$

STOP!
$$c_N = \begin{bmatrix} -1.5 \\ -0.5 \end{bmatrix} \le 0$$
. The basic solution \bar{x} is optimal