# Solar Tracking System Integrated with Geomagnetism

INSTITUTION: NATIONAL INSTITUTE OF TECHNOLOGY, AGARTALA

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# **INTRODUCTION**

A solar tracking system enhances the efficiency of solar panels by continuously adjusting their orientation to follow the Sun's movement across the sky. This dynamic positioning increases solar energy capture by up to 25–35% compared to fixed panels.

To improve tracking precision, geomagnetism—the Earth's natural magnetic field—is integrated into the system using magnetometers. These sensors detect the panel's orientation relative to magnetic north, allowing the tracker to adjust more accurately without relying solely on GPS or light sensors.

By using geomagnetic input, the system becomes more stable, weather-independent, and energy-efficient, especially under cloudy conditions where traditional light-dependent sensors may fail. This makes the solution ideal for both urban and remote solar applications, offering improved reliability and reduced

operational costs.

# PROBLEM STATEMENT

- Solar panels waste sunlight during non-peak hours.
- Manual adjustment is inefficient.
- Lack of low-cost automated tracking solutions.
- No orientation awareness in basic trackers → we solve this with geomagnetism.

# **OBJECTIVE**

- To calculate Azimuth angle, elevation angle, Zenith angle and magnetic inclination angle.
- Reduce manual intervention.
- Integrate geomagnetic sensing for better orientation.
- Use affordable hardware (Arduino) and open-source software (Python).

# **SOLAR TRACKING SYSTEM**

A **solar tracking system** is a smart mechanism designed to **orient solar panels** towards the sun as it moves across the sky during the day. Unlike fixed-position panels, which remain stationary, tracking systems continuously **adjust the panel's angle** to ensure it always faces the sun at the most optimal angle.

### This dynamic positioning helps in:

- Maximizing solar irradiance capture
- Increasing the overall energy output by 25–35%
- Improving efficiency during mornings, evenings, and seasonal shifts

### There are mainly two types of trackers:

- Single-axis trackers: Rotate east to west to follow the sun's daily movement.
- Dual-axis trackers: Follow both east—west and north—south (elevation) movements to track the sun year-round.

### Solar tracking is particularly useful in:

- Large-scale solar farms,
- Remote off-grid systems,
- And smart energy setups where every watt counts.

Objective: To ensure maximum solar energy harvesting by keeping panels aligned with the sun's real-time position throughout the day.

### 1. Measure the Sun's Angles

Use a sun tracker or basic camera goniometer to measure:

- Elevation angle  $(\alpha)$  vertical angle from horizon
- Azimuth (Az) compass direction from true North  $(0^{\circ}-360^{\circ})$

### 2. Why Solar Tracking is Important?

- Increases solar panel output by 20% to 40% compared to fixed panels.
- Especially useful in locations with long daylight hours or varying sun angles.
- Ideal for large solar farms and standalone solar installations.

### 3. Core Components in a Basic Solar Tracker

- Arduino Microcontroller: Brain of the system.
- LDR Sensors: Detect the direction of sunlight.
- Servo/Motor Drivers: Physically rotate the panel.
- Solar Panel: The energy-harvesting component.
- Power Supply: Battery or solar-powered source.

### 4. Benefits of Using Arduino and LDR

- Cost-effective and beginner-friendly setup.
- Allows for real-time adjustment to sun position.
- Easy to upgrade with IoT or data logging (using Python).
- Can be integrated with geomagnetic sensors for better orientation.

# **How Geomagnetism Helps?**

- Earth's magnetic field gives directional orientation.
- Helps panel face true East in the morning.
- Geomagnetic sensor (e.g., HMC5883L or QMC5883L) aligns system relative to magnetic north.
- Geomagnetism refers to the Earth's magnetic field, which surrounds the planet and points roughly from the magnetic south to the magnetic north pole. Just like a compass uses the Earth's magnetic field to determine direction, electronic systems can use magnetic sensors to find orientation.

# Why Use Geomagnetism in Solar Tracking?

• Most solar tracking systems rely on mechanical sensors like LDRs (Light Dependent Resistors) or astronomical calculations. However, geomagnetic sensors (magnetometers) offer the benefit of providing real-time directional awareness, allowing for precise azimuth angle alignment of the solar panel.

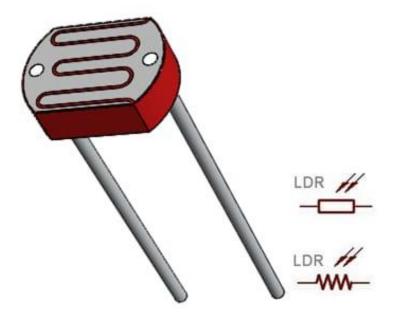
# How its helps:

• It helps in- Accurate orientation Improved tracking accuracy Stabilizing movement

# **SENSOR TECHNOLOGY**

- The goal of a solar tracking system is to maximize solar panel exposure to sunlight.
- Sensors detect the sun's position to adjust the panel in real time.
- The most common sensor used in basic solar tracking is the LDR (Light Dependent Resistor).

LDR (Light Dependent Resistor) is a passive electronic sensor that detects light intensity. It is made of a semiconductor material that becomes more conductive as light intensity increases.



# How LDR is Used in Solar Tracking?

### **Working Principle of LDR- Based Tracking**

- Two or more LDRs are placed on opposite sides of a panel (e.g., East–West or North–South).
- When sunlight falls unevenly, difference in light intensity is detected.
- The microcontroller (Arduino) reads this difference and rotates the panel toward the brighter side using a servo/motor.

### **Advantages of Using LDR Sensors in Solar Tracking Systems**

- •Cost-effective: LDRs (Light Dependent Resistors) are very cheap and easily available, making the system affordable.
- •Simple to use: Easy to interface with microcontrollers like Arduino, using just analog pins.
- •Real-time sunlight detection: Responds to actual light intensity—helps dynamically adjust the panel toward the brightest direction.
- •Low power consumption: Requires minimal electrical power, making it ideal for solar projects.
- •Effective in clear weather: LDR-based tracking works well under direct sunlight conditions for quick realignment.

# **⚠** Limitations of LDR Sensors in Solar Tracking

- •Affected by weather: LDRs may give inaccurate readings during cloudy or diffused light conditions.
- •No absolute direction: Cannot detect the actual position of the sun—only relative brightness.
- •False triggers: Shadows, reflections, or nearby light sources can confuse the sensor.

# **Circuit Setup:**

Each LDR is connected in a voltage divider circuit with a resistor.

Output of the divider is connected to Arduino analog pins (A0, A1, etc.).

Arduino reads light intensity on both sides.

Arduino controls the servo motor via PWM pins to rotate the panel.

# Working Mechanism:

- 1. When one LDR receives more light than the other, its resistance drops, and the voltage output to the Arduino increases.
- 2. Arduino compares values:

If LDR1 > LDR2  $\rightarrow$  rotate toward LDR1

If LDR2 > LDR1  $\rightarrow$  rotate toward LDR23.

Motor adjusts the panel until both LDRs receive similar light  $\rightarrow$  system balanced.

### **LDR Placement:**

LDRs are mounted at an angle on opposite sides of a small shadow-casting divider.

This setup enhances detection of light direction more accurately.

### **Software & Tech Stack**

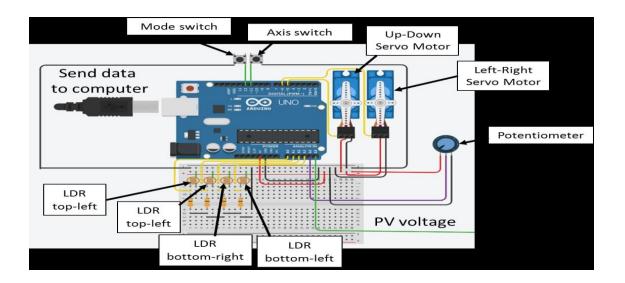
Arduino IDE: To code and flash microcontroller logic.

Python: For data logging, visualization, or remote control via serial.

**Serial Communication**: Python ↔ Arduino

Libraries Used: pyserial (Python)Wire.h, Servo.h (Arduino)

Adafruit Sensor, QMC5883L/HMC5883L (I2C libraries)



System Architecture Diagram

Sensor input  $\rightarrow$  Arduino  $\rightarrow$  Decision Logic  $\rightarrow$  Motor Control  $\rightarrow$  Solar Panel Movement

Feedback loop with geomagnetic alignment

# SOFTWARE AND HARDWARE INTEGRATION

Integration of Software (Arduino & Python) with Hardware

Our solar tracking system combines hardware components like sensors and motors with software control using Arduino and Python.

Here's how they work together:

# **Arduino (Embedded Control Layer)**

Arduino Uno acts as the central controller for hardware.

Reads sensor data from:

LDRs (light levels – analog pins)Magnetometer (heading – I<sup>2</sup>C)IMU (pitch/tilt – I<sup>2</sup>C)

Runs control logic:

Compares current vs desired panel position.

Calculates error using PID algorithm. Sends PWM signals to servo/direction motors to move panel.

```
Wire.h // For I2C communication (magnetometer, IMU)
Adafruit_Sensor.h // Unified sensor functions
PID_v1.h // PID control logic
Servo.h // To control servos
```

# 2. Python (Monitoring & Data Logging Layer)

Python script runs on a PC or Raspberry Pi.

Communicates with Arduino via USB serial port using PySerial.

Reads real-time tracking data (azimuth, tilt, light intensity).

Stores values into CSV / SQLite database for analysis.

Generates live plots and dashboards using:matplotlib, pandas, tkinter or streamlit

pyserial # Communicate with Arduino over COM port

pandas # Data handling and analysis

matplotlib # Graphing solar tracking performance

tkinter # Simple GUI for live monitoring

# **How They Work Together:**

Flow Description

Hardware → Arduino Sensors give real-time input

Arduino → Motors Arduino processes input and controls movement

Arduino → Python Arduino sends status data via serial port

Python → User Python visualizes & logs data for reports

# CHALLENGES FACED

### **Technical Challenges**

### **Sensor Calibration:**

LDRs and magnetometers required precise calibration to ensure accurate readings.

Noisy Data from Sensors:

External light interference and magnetic noise sometimes led to unstable sensor values.

Servo Motor Alignment Issues:

Ensuring smooth and precise rotation without overshooting or jitter was difficult during initial testing.

### **Integration Challenges**

### **Synchronizing Arduino & Python:**

Establishing reliable serial communication and handling real-time data transfer required debugging.

Power Supply Management:

Ensuring consistent power to both the motor and sensors without voltage drops.

### **Team & Coordination Challenges**

Dividing hardware, coding, and testing tasks efficiently across teams.

Managing cross-team dependencies and aligning work pace during development

# **FUTURE SCOPE**

- IoT Integration Enable remote monitoring and control via cloud platforms.
- AI/ML Optimization Use machine learning to predict sunlight patterns and optimize tracking
- Dual-Axis Tracking Improve efficiency with two-axis rotation for precise sun alignment
- Battery Storage Support Store excess energy for off-grid or backup use.
- Scalable Applications Deploy in solar farms, agriculture, or smart greenhouse environments.

# **CONCLUSION**

- Our project successfully implements a solar tracking system that uses both light sensors (LDRs) and geomagnetic sensing to optimize solar panel orientation.
- The integration of Arduino and Python enables real-time control, monitoring, and data logging, making the system intelligent and adaptable.
- This hybrid approach ensures maximum solar energy capture by accurately tracking the sun's movement while also maintaining correct directional alignment.
- The system is cost-effective, scalable, and energy-efficient, making it a valuable solution for enhancing the performance of solar energy setups.
- With further improvements like weather adaptation, machine learning, or IoT integration, the system can evolve into a fully autonomous smart solar tracker.

