# ISHAN DESHMUK

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**ABOUT** 

Postal address: B/102, Nisarg Nirmiti, Pimple Saudagar, Pune, Maharashtra, India, 411027

Deep-seated passion for Robotics, driven by my extensive expertise and skillset. My determination is focused on catalyzing innovation and advancing the frontiers of the robotics industry to shape a transformative future.

#### **EXPERIENCE**

• Team Robomanipal [�]

AUG 2023 - FEB 2025

Electronics Subsystem Member

Manipal, India

• Fabricated, prototyped, and assembled 5+ competition-grade robots, implementing advanced robotics and electronics principles. Programmed microcontrollers and PWM control algorithms, enhancing actuation precision. Integrated 7+ sensors (IMU, proximity, encoders, color, depth, line, limit switches) and 10+ motors/controllers for optimized performance. Competed in DD Robocon 2024, securing AIR 22 nationally. Proficient in KiCAD, SolidWorks, Arduino IDE, and MATLAB, improving circuit design efficiency and mechanical simulations.

#### **EDUCATION**

## Manipal Institute of Technology

2022 - 2026

Bachelor of technology, Mechatronics Engineering

Karnataka, India

o GPA: 7.50/10.00

# Shubhamraje Junior College

2022

Higher Secondary Education

Maharashtra, India

o Grade: 79.3%

• D.A.V. Public School

2019

Secondary Education o Grade: 91.3%

### Maharashtra, India

## ACADEMIC PROJECTS

- 3D Printed Robotic Manipulator: Manufactured a 3 DOF manipulator using NEMA-17 and Servos.
- Signal Filtering of a Heart Rate Monitoring System: Implemented a real-time Butterworth filter in MATLAB to process and smooth heart rate signals, reducing noise by 10%.
- Mathematical Modelling of a DC motor: Designed and simulated a shunt DC motor model in MATLAB, analyzing speed-torque characteristics and transient response. Applied system modeling techniques to optimize motor control strategies.
- Smart Water Level Indicator for Plants: Developed an IIoT-based water level monitoring system, integrating real-time sensor data for optimized irrigation. Utilized embedded systems to enhance plant hydration efficiency and reduce water waste by 40%
- Simulation for DC-DC Buck-Boost Converter with Closed Loop PI Controller: Simulation of the Buck-Boost converter on MATLAB.
- Simulation of Maze Solving Bot: Simulated the movement of a robot in Gazebo using ROS2.
- Automated Temperature Regulator: Simulated a closed-loop temperature regulation system using PLC programming, ensuring precise environmental control.
- Net Throwing Pneumatic Gun to catch Drones: Developed and tested a pneumatic net-launching system using Festo FluidSim, achieving 55% effectiveness in capturing UAVs within 50 meters.

#### EXTRACURRICULAR ACTIVITIES

• Head of Robotics IE India Mechatronics Student's Chapter, Manipal OCT 2023 - FEB 2025

Managed a club of 200 people and conducted several events and robotics related workshops.

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- Inspired and mentored 50+ students across various engineering disciplines, fostering interest in robotics through
- hands-on workshops and projects. Provided technical guidance on robotic concepts, sensor integration, and control systems, while also assisting in technical report writing and documentation.

# • Core Committee Member for Tech Tatva 2024 (Technical Fest)

SEP 2024 - OCT 2024

IE India Mechatronics Student's Chapter, Manipal o Organized Mechatron, overseeing event logistics and coordinating a team of 15.

## • Organizing Committee Member for Tech Tatva 2023 (Technical Fest)

SEP 2023 - OCT 2023

IE India Mechatronics Student's Chapter, Manipal

• Designed and built 3 RC cars using L293D motor drivers and ESP32 with Bluetooth for remote control. Focused on optimizing circuit layout and motor control for reliable performance during the event.

#### OTHER DETAILS

- Date of Birth: 12/04/2004
- Languages Known: English, Hindi, and Marathi.