

EE 511 Simulation Methods for Stochastic Systems

Project #5: Optimization & Sampling via MCMC

[Due 3-May-2019]

[MCMC for Sampling]

The random variable X has a mixture distribution: 60% in a Beta(1,8) distribution and 40% in a Beta(9,1) distribution.

- Implement a Metropolis-Hastings algorithm to generate samples from this distribution.
- Run the algorithm multiple times from different initial points. Plot sample paths for the algorithm. Can you tell if/when the algorithm converges to its equilibrium distribution?

Plot sample paths for the algorithm using different proposal pdfs. Comment on the effect of low-variance vs high-variance proposal pdfs on the behavior of your algorithm.

[MCMC for Optimization]

The n -dimensional Schwefel function

$$f(\vec{x}) = 418.9829n - \sum_{i=1}^n x_i \sin \sqrt{|x_i|}$$
$$x_i \in [-500, 500]$$

is a very bumpy surface with many local critical points and one global minimum. We will explore the surface for the case $n=2$ dimensions.

- Plot a contour plot of the surface for the 2-D surface
- Implement a simulated annealing procedure to find the global minimum of this surface
- Explore the behavior of the procedure starting from the origin with an exponential, a polynomial, and a logarithmic cooling schedule. Run the procedure for $t=\{20, 50, 100, 1000\}$ iterations for $k=100$ runs each. Plot a histogram of the function minima your procedure converges to.
- Choose your best run and overlay your 2-D sample path on the contour plot of the Schwefel function to visualize the locations your optimization routine explored.

[Optimal Paths]

The famous Traveling Salesman Problem (TSP) is an NP-hard routing problem. The time to find optimal solutions to TSPs grows exponentially with the size of the problem (number of cities). A statement of the TSP goes thus:

“A salesman needs to visit each of N cities exactly once and in any order. Each city is connected to other cities via an air transportation network. Find a minimum length path on the network that goes through all N cities exactly once (an optimal Hamiltonian cycle).”

A TSP solution $\vec{c} = (c_1, \dots, c_N)$ is just an ordered list of the N cities with minimum path length. We will be exploring MCMC solutions to small and larger scale versions of the problem.

- Pick $N=10$ 2-D points in the $[0,1000] \times [0,1000]$ rectangle. These 2-D samples will represent the locations of $N=10$ cities.

- Write a function to capture the objective function of the TSP problem:

$$D(\vec{c}) = \sum_{i=1}^{N-1} \|c_{i+1} - c_i\|$$

- Start with a random path through all N cities \vec{c}_0 (a random permutation of the cities), an initial high temperature T_0 , and a cooling schedule $T_k = f(T_0, k)$.
 - Randomly pick any two cities in your current path. Swap them. Use the difference between the new and old path length to calculate a Gibbs acceptance probability. Update the path accordingly.
 - Update your annealing temperature and repeat the previous city swap step. Run the simulated annealing procedure “to convergence.”
 - Plot the values of your objective function from each step. Plot your final TSP city tour.
- Run the Simulated Annealing TSP solver you just developed for $N = \{40, 400, 1000\}$ cities. Explore the speed and convergence properties at these different problem sizes. You might want to play with the cooling schedules.