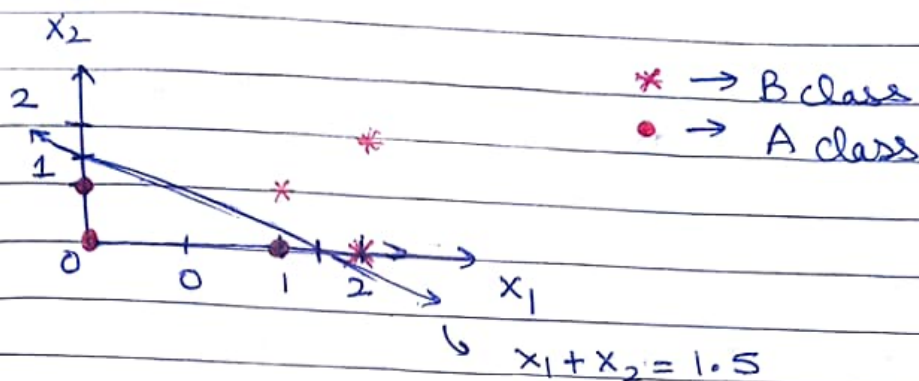


## ML-Assignment

Name - Ishit Bajpai

Roll. No - 2020380

## 1. Plotting the points



Yes, points are linearly separable as we can draw line  $x_1 + x_2 = 1.5$  separating both the classes completely.

~~Now showing~~

for class A

$$(x_1 + x_2 - 1.5)$$

| $x_1$ | $x_2$ | $x_1 + x_2 - 1.5$ |
|-------|-------|-------------------|
| 0     | 0     | -1.5              |
| 1     | 0     | -0.5              |
| 0     | 1     | -0.5              |

$x_1 + x_2 - 1.5 < 0$ , for all points in Class A  $\Rightarrow$  All points in Class A lies below  $x_1 + x_2 = 1.5$

Similarly, for class B

| $x_1$ | $x_2$ | $x_1 + x_2 - 1.5$ |
|-------|-------|-------------------|
| 1     | 1     | 0.5               |
| 2     | 2     | 2.5               |
| 2     | 0     | 0.5               |

$x_1 + x_2 - 1.5 > 0$ , for all points in Class B

$\Rightarrow$  All points in Class B lies above  $x_1 + x_2 = 1.5$

from ① and ② linearly separable  
 We can conclude that line ~~divides~~  
 class A and B.

2.0 As discussed in the lectures  
 our primal form  $\min \frac{1}{2} \|w\|^2$  st  
 $y_i (w^T x_i + b) \geq 1$  was converted

to dual where we are required to

$$\text{maximise } Q(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^T x_j$$

such that  $\alpha_i \geq 0, \forall i=0, \dots, n$   
 and  $\sum_{i=1}^n \alpha_i y_i = 0$

$n$  is the number of training examples

So, our optimisation problem is

$$\text{maximise } Q(\alpha) \text{ st } \alpha_i \geq 0 \forall i=0, 1, \dots, N$$

$$\sum_{i=1}^n \alpha_i y_i = 0.$$

Since optimal hyperplane has to be in between the points of class A and class B.

Therefore, ~~Only~~ ~~Supporting~~ Potential  
 Supporting Vectors can be  
 $(1, 0)$  and  $(0, 1)$  from class A

$(0,0)$  can not be a supporting vector as it lies below.

$(1,0)$   $(0,1)$   
 $\otimes_1$  in terms of  $x_1$  and  $\otimes_2$  in terms of  $x_2$ .

Similarly potential supporting vectors from class B can be  $\otimes_1 (1,1)$  and  $\otimes_2 (2,0)$

$(2,2)$  can not be a supporting vector as it lies ~~below~~ above  $\otimes_2 (1,1)$  in terms of  $\otimes_1 x_1$  and  $\otimes_2$  in terms  $x_2$ .  
 $(2,0)$



let us consider 3 SV to form optimal hyperplane.

$$S_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad S_2 = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \quad S_3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

One

We'll add bias to each of the vectors (augmenting) (later this will store our bias)

$$\tilde{S}_1 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \tilde{S}_2 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \quad \tilde{S}_3 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

Using Equation

$\sum_{i=1}^N \alpha_i \tilde{S}_i \tilde{S}_j$  → dot product.

$\tilde{S}_j$  = Sign of Class to which  $\tilde{S}_j$  belongs.

$\alpha_i$ 's → Lagrangian multipliers

for  $S_1$

$$\alpha_1 \tilde{S}_1 \tilde{S}_1 + \alpha_2 \tilde{S}_1 \tilde{S}_2 + \alpha_3 \tilde{S}_1 \tilde{S}_3 = +1$$

$$\alpha_1 (1+1+1) + \alpha_2 (2+0+1) + \alpha_3 (1+0+1) = +1$$

$$3\alpha_1 + 3\alpha_2 + 2\alpha_3 = +1 \quad \text{--- (1)}$$

$$\text{for } S_2 \quad \alpha_1 \tilde{S}_1 \tilde{S}_2 + \alpha_2 \tilde{S}_2 \tilde{S}_2 + \alpha_3 \tilde{S}_3 \tilde{S}_2 = +1$$

$$\alpha_1 (2+0+1) + \alpha_2 (4+0+1) + \alpha_3 (2+0+1) = 1$$

$$3\alpha_1 + 5\alpha_2 + 3\alpha_3 = 1 \quad \text{--- (2)}$$

$\sim$  for  $S_3$

$$\alpha_1 S_1 S_3 + \alpha_2 S_2 S_3 + \alpha_3 S_3 S_3 = 1 - 1$$

$$2\alpha_1 + 3\alpha_3 + 2\alpha_3 = -1 \quad \text{--- (3)}$$

Solving  $\alpha_1, \alpha_2, \alpha_3$ , we get (~~corrected~~)

$$\alpha_1 = 2, \alpha_2 = 5, \alpha_3 = -10$$

$$w = \sum_{i=1}^n \alpha_i^o s_i$$

$$= 2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 5 \begin{pmatrix} 2 \\ 0 \end{pmatrix} - 10 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2+10-10 \\ 2+0-0 \\ 2+5-10 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \\ -3 \end{pmatrix}$$

from previous argument

$$w = \begin{pmatrix} 2 \\ 2 \end{pmatrix} \quad \text{bias} = -3$$

Eq<sup>n</sup> of ~~optimal~~ hyperplane (maximum margin)

$$w^T x + b = 0$$

$$\begin{bmatrix} 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - 3 = 0 \Rightarrow 2x_1 + 2x_2 = 3$$

$$\Rightarrow \boxed{x_1 + x_2 = 1.5}$$

Calculating distance of points from ~~hyp~~

~~(0,0)~~

Class A

$$(i) (0,0) \quad \frac{|0+0-1.5|}{\sqrt{2}} = \frac{3}{2\sqrt{2}}$$

$S_3$

$$(ii) (1,0) \quad \frac{|1+0-1.5|}{\sqrt{2}} = \frac{1}{2\sqrt{2}}$$

$$(iii) (0,1) = \frac{|0+1-1.5|}{\sqrt{2}} = \frac{1}{2\sqrt{2}}$$

• Since it is at same distance from  $x_1 + x_2 = 1.5$  as  $S_3 \Rightarrow (0,1)$  is also a Support Vector.  
Let  $S_4 = (0,1)^T$

Class B

$S_1$

$$(i) (1,1) \rightarrow \frac{|1+1-1.5|}{\sqrt{2}} = \frac{1}{2\sqrt{2}}$$

$$(ii) S_2 (2,0) \rightarrow \frac{|2+0-1.5|}{\sqrt{2}} = \frac{1}{2\sqrt{2}}$$

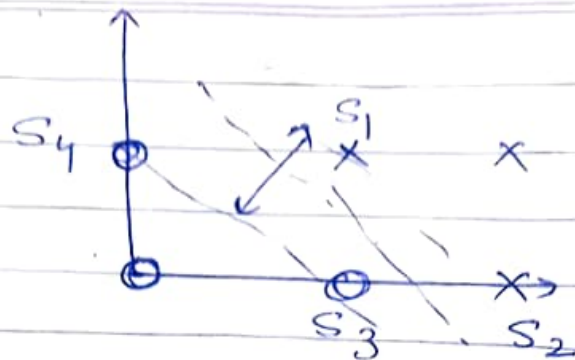
$$(iii) (2,2) \rightarrow \frac{|2+2-1.5|}{\sqrt{2}} = \frac{5}{2\sqrt{2}}$$

Support Vectors are

$(1,0), (0,1), (1,1), (2,0)$



(3)



(margin)

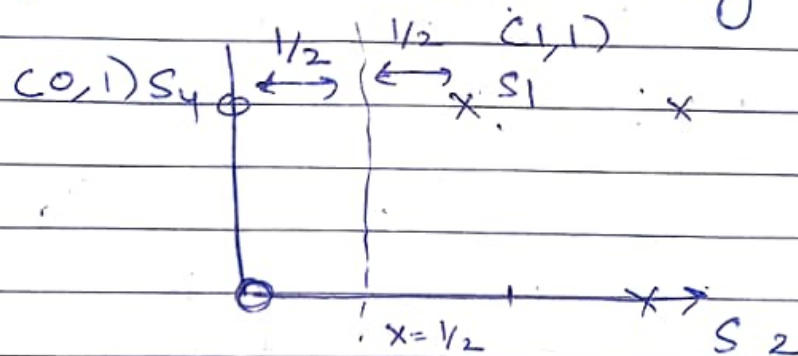
$$M = \frac{1}{\sqrt{2}}$$

$$S_1 = (1, 1)^T \quad S_2 = (2, 0)^T \quad S_3 = (1, 0)^T$$

$$S_4 = (0, 1)^T$$

- \* Since we constructed the optimal margin using  $S_1, S_2, S_3$ , removing  $S_4$  will have no effect on optimal margin.  $\left(\frac{1}{2\sqrt{2}} \times 2\right)$   
(discussed previous)

- if we remove  $S_3$ , then by

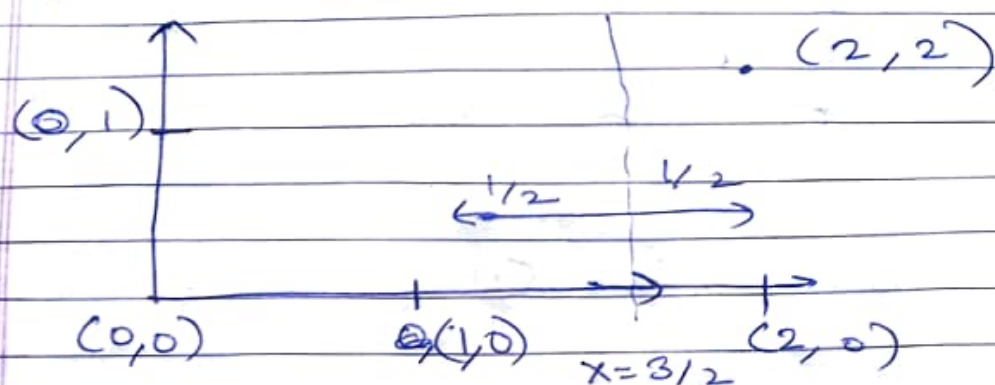


by visual inspection we can see that  $S_2$  no longer remains a support vector and  $(0,0), (0,1), (1,1)$  becomes the new support vectors.

The new optimal hyperplane became  $x = \frac{1}{2}$ . (all support vectors are at equal distance from  $x = \frac{1}{2}$ )

- \* new margin = 1, Thus margin  $\uparrow$  if we remove  $(1,0)$ .

if we remove  $S_1 (1,1)$



$(2,2), (1,0), (2,0)$  ~~are~~ becomes the new Support Vectors

and  $x = 1.5$  is optimal hyperplane as it is at equal distance from all the support vectors.

new margin becomes 1

$\Rightarrow$  Margin  $\uparrow$  if we remove  $(1,1)$ .

• Removing  $S_2 (2,0)$

$S_1 (1,1)$   $S_2 (2,0)$   $S_4 (0,1)$

• Using  $\sum \alpha_i^* \tilde{S}_i^* \tilde{S}_j = \text{Sign of class to which } S_j \text{ belongs}$

$$\alpha_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 2 \\ 0 \end{pmatrix} + \alpha_4 \begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 1$$

$$3\alpha_1 + 3\alpha_2 + 2\alpha_4 = 1 \quad \text{--- (1)}$$



$$\alpha_1 \tilde{s}_1 \tilde{s}_2 + \alpha_2 \tilde{s}_2 \tilde{s}_2 + \alpha_4 \tilde{s}_4 \tilde{s}_2 = +1$$

$$3\alpha_1 + 5\alpha_2 + \alpha_4 = 1 \quad \text{--- (2)}$$

$$\alpha_1 \tilde{s}_1 \tilde{s}_4 + \alpha_2 \tilde{s}_2 \tilde{s}_4 + \alpha_4 \tilde{s}_4 \tilde{s}_4 = -1$$

$$2\alpha_1 + \alpha_2 + 2\alpha_4 = -1 \quad \text{--- (3)}$$

$$\alpha_4 = -10, \alpha_2 = -5, \alpha_1 = 12$$

$$\tilde{w} = \sum \alpha_i \tilde{s}_i$$

$$\tilde{w} = 12 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} - 5 \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} - 10 \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 12 - 10 \\ 12 - 10 \\ 12 - 5 - 10 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \\ -3 \end{pmatrix}$$

$$w = [2 \ 2]^T \quad \text{bias} = -3$$

$$w^T x + b = 0 \Rightarrow 2x_1 + 2x_2 - 3 = 0$$

Thus we get the same optimal hyperplane as we would get with  $s_1, s_2, s_3, s_4$ .

$\Rightarrow$  On removing  $(2, 0)$  margin remains same.

Q4 ~~In~~ SVM, we are maximising the margin when

+

(Q4) In general, for any dataset if we remove Support Vectors then optimal margin can increase or remain same (as shown in previous questions ~~it~~ it remains same).

~~In~~

• We can expect an increase because on removing support vector distance between the nearest points of opposite classes <sup>can</sup> increase, as a result margin can also increase (as

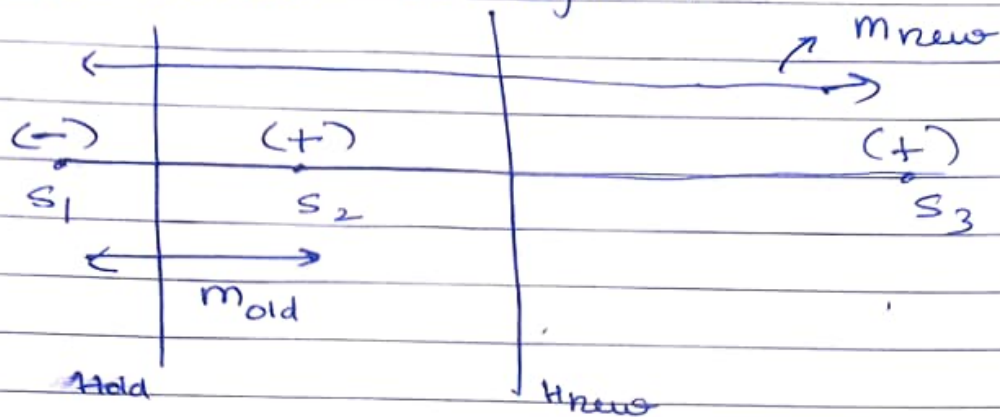
optimal hyperplane is made  $s^+d^+ = d^-$ ) \* (Illustration <sup>shown</sup> at last)

However it is not ~~need~~ necessary that margin will  $\uparrow$  as in previous question even on dropping  $S_1, S_2$  margin remained same.

Mathematical Approach: SVM is maximisation problem in which constraints are made because of support vectors. On dropping support vectors, in a way constraints are somewhat relaxed. This may result in more maximisation than before.

\* As

Case when margin  $\uparrow$ .



def  $H_{old}$  is maximum margin hyperplane between  $(-)$  and  $(+)$ .

~~def~~  $m_{old}$  is the margin length, Suppose we now drop  $s_2$  and  $s_3$  is now closest point of  $+$  class to  $- (s_1)$ . New optimal hyperplane becomes  $H_{new}$  and clearly  $m_{new} > m_{old}$ .

Thus margin  $\uparrow$ .