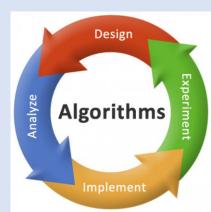
Divide and Conquer

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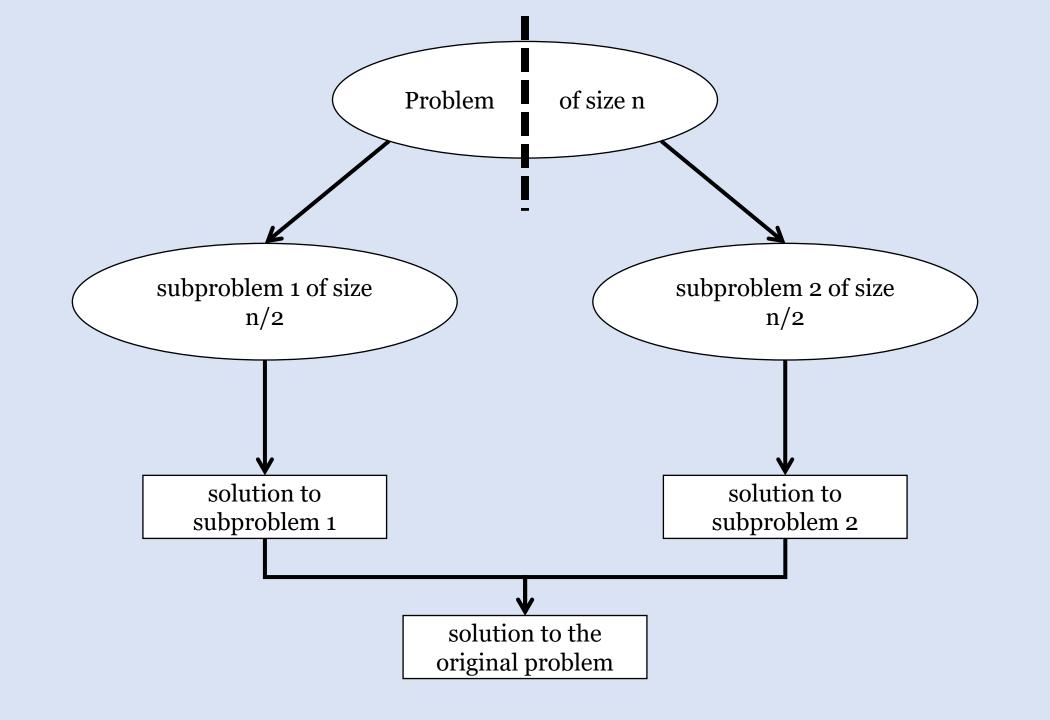


Introduction

- We just observed one of the first common approaches to designing algorithms
 - Brute Force
- While Brute Force yields correct results and is easy to implement, the algorithms have a high running time cost.
- There are multiple approaches to designing algorithms.
- Our goal in this lesson is to observe a technique that can help achieve a better running time.

Divide & Conquer

- A popular technique that used for general algorithm design
- Divide & Conquer Plan
 - A problem is divided into several subproblems of the same type, ideally about size.
 - The subproblems are solved (typically recursively, through sometimes a different algorithm is employed, especially when subproblems become small enough)
 - If necessary, the solutions to the subproblems are combined to get a solution to the original problem.
- Base Case: When the size of the problem is small enough, solve using Brute Force



How could we represent a divide and conquer using a recurrence?

- First we observe the input size of *n* for the algorithm
- Then number of instances b per subproblem
- This gives us $\frac{n}{b}$ subproblems
- We also need to consider how long the dividing takes for the algorithms. We can represent as f(n)
- Last we need to know how many problems are needed to be solved. This can be denoted as *a*
- Now if we put all of this together, we are going to recognize a certain recurrence.

The General Divide-and-Conquer

$$T(n) = aT\left(\frac{n}{b}\right) + f(n)$$

Remember The Sorting Problem Again?
Lets look at two of the solutions.
Merge-Sort and Quick-Sort
They both use Divide and Conquer

Remember Merge-Sort

```
\frac{\text{Merge-Sort}(A,p,q,r)}{\text{if } p < r}
q = \left\lfloor \frac{p+r}{2} \right\rfloor
\text{Merge-Sort}(A, p, q)
\text{Merge-Sort}(A, q + 1, r)
\text{Merge}(A, p, q, r)
```

```
\frac{\text{Merge}(A,p,q,r)}{n_1 = q - p + 1}
n_2 = r - q
//create two arrays
                                                          \Theta(1)
L[1...n_1+1] and R[1...n_2+1]
                                                      \Theta(n_1) = \Theta\left(\frac{n}{2}\right) = \Theta(n)
\Theta(n_2) = \Theta\left(\frac{n}{2}\right) = \Theta(n)
for i = 1 to n_1
 L[i] = A[p + i - 1]
for j = 1 to n_2
    R[j] = A[q + j]
L[n_1 + 1] = \infty
R[n_2 + 1] = \infty
                                                           \Theta(1)
i = 1
j = 1
for k = p to r
    if L[i] \leq R[j]
                                                           \Theta(n)
         A[k] = R[j]
        j = j + 1
```

Now why does Merge-Sort have that analysis?

• Lets represent this as a recurrence.

$$\begin{cases} \Theta(1) & n \leq c \text{ (base case)} \\ D(n) + aT(n/b) + C(n) & n > c \end{cases}$$
 Divide Step Conquer Step Combine Step

• The Combine Step (Merge) has a running time $\Theta(n)$

$$\bullet \begin{cases} \Theta(1) & n = 1 \\ \Theta(1) + 2T(n/2) + \Theta(n) & n > c \end{cases}$$

Master Theorem

- $T(n) = aT\left(\frac{n}{b}\right) + f(n)$
- $2T\left(\frac{n}{2}\right) + \Theta(n)$
- $f(n) vs n^{\log_2 2}$
- We can apply case 2 of Master Theorem
- Hence the running time analysis of Merge-Sort is $\Theta(n^{\log_2 2} lgn) = \Theta(nlgn)$

Merge-Sort Example

12	30	21	8	6	9	1	7
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Remember Quick-Sort

```
Quick-Sort(A,p,r)
if p < r
q = Partition (A, p, r)
Quick-Sort(A, p, q - 1)
Quick-Sort(A, q + 1, r)
```

```
\begin{array}{c|c} \underline{Partition(A,p,q,r)} \\ x = A[r] \\ i = p - 1 \\ \text{for } j = p \text{ to } r - 1 \\ \text{ if } A[j] \leq x \\ i = i + 1 \\ \text{ exchange } A[i] \text{ and } A[j] \\ \text{ exchange } A[i + 1] \text{ and } A[r] \\ \text{ return } i + 1 \end{array} \quad \Theta(1)
```

Worst Case for Quick-Sort

- Two subproblems are completely unbalanced:
 - One subproblem has (n 1) elements
 - The other subproblem has o elements
- Ex. Input Array is already sorted in increasing order
- $T(n) = T(n-1) + T(0) + \Theta(n)$
- T(n) = T(n-1) + cn
- $T(n) = cn + c(n-1) + c(n-2) + \dots + c2 + T(1)$
- $T(n) = c(n + (n-1) + (n-2)) + \dots + c2 + T(1)$
- $T(n) = c \left(n * \frac{(n+1)}{2} 1 \right) + \Theta(1) = \Theta(n^2)$

Best Case for Quick-Sort

- The two subproblems are balanced
- This means each subproblem has n/2 elements

•
$$T(n) = 2T\left(\frac{n}{2}\right) + \Theta(n)$$

•
$$T(n) = 2T\left(\frac{n}{2}\right) + cn$$

- We can apply case 2 of Master Theorem
- $T(n) = \Theta(n \lg n)$

Now wait a minute! Aren't we trying to design more efficient algorithms with various techniques? Why is quicksort running time in the worst case scenario quadratic? Doesn't divide and conquer guarantee better efficiency in running time and memory?

Lets move from sorting to the fake coin problem!

The Fake Coin Problem

- The problem is described as follows:
- You have n coins that are all supposed to be gold coins of the same weight, but you know that one coin is fake and weighs less than the others. You have a balance scale: you can put any number of coins on each side of the scale at one time, and it will tell you if the two sides weight the same, or which side is lighter if they don't weight the same.
- How many weightings will you do?

Two Common Solutions

- Brute Force
 - · Weigh each coin in sequential order until the fake one is found
- Divide and Conquer
 - Weigh two piles of coins and determine where the fake coin is
 - Discard heavier pile and divide pile into two sub piles
 - Repeat until fake coin found

Would you like to run the problem again?

0: No 1: Yes Selection:

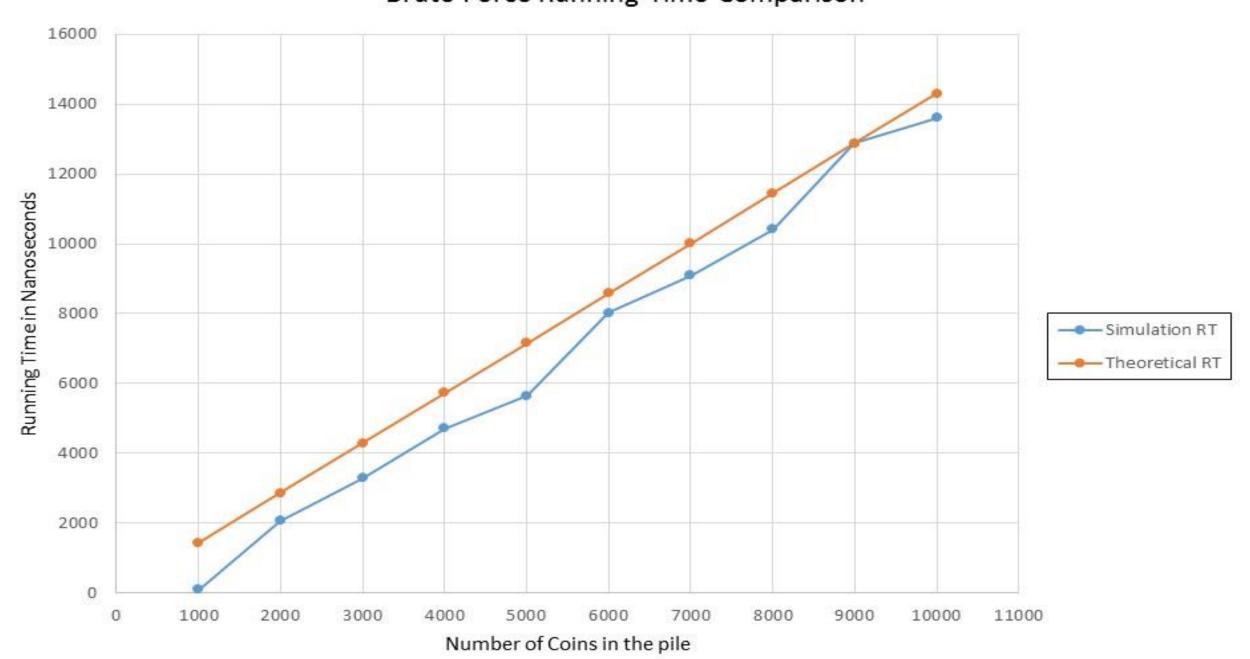
Brute Force

n	Simulation RT	Theoretical RT	Hidden Constant	
1000	96.6	1000	0.09660	
2000	2056.2	2000	1.02810	
3000	3288.4	3000	1.09613	
4000	4714.4	4000	1.17860	
5000	5641	5000	1.12820	
6000	8031	6000	1.33850	
7000	9088.6	7000	1.29837	
8000	10420.8	8000	1.30260	
9000	12882.4	9000	1.43138	
10000	10000 13606.4		1.36064	
	C _{max}	1.4	13138	

Brute Force

n	Simulation RT	Theoretical RT	% Difference	
1000	96.6	1431.4	93.25	
2000	2056.2	2862.8	28.17	
3000	3288.4	4294.1	23.42	
4000	4714.4	5725.5	17.66	
5000	5641	7156.9	21.18	
6000	8031	8588.3	6.49	
7000	9088.6	10019.6	9.29	
8000	10420.8	11451.0	9.00	
9000	12882.4	12882.4	0.00	
10000	13606.4	14313.8 4.94		
	C _{max}	1.43138		
Average % Difference		21.34		

Brute Force Running Time Comparison



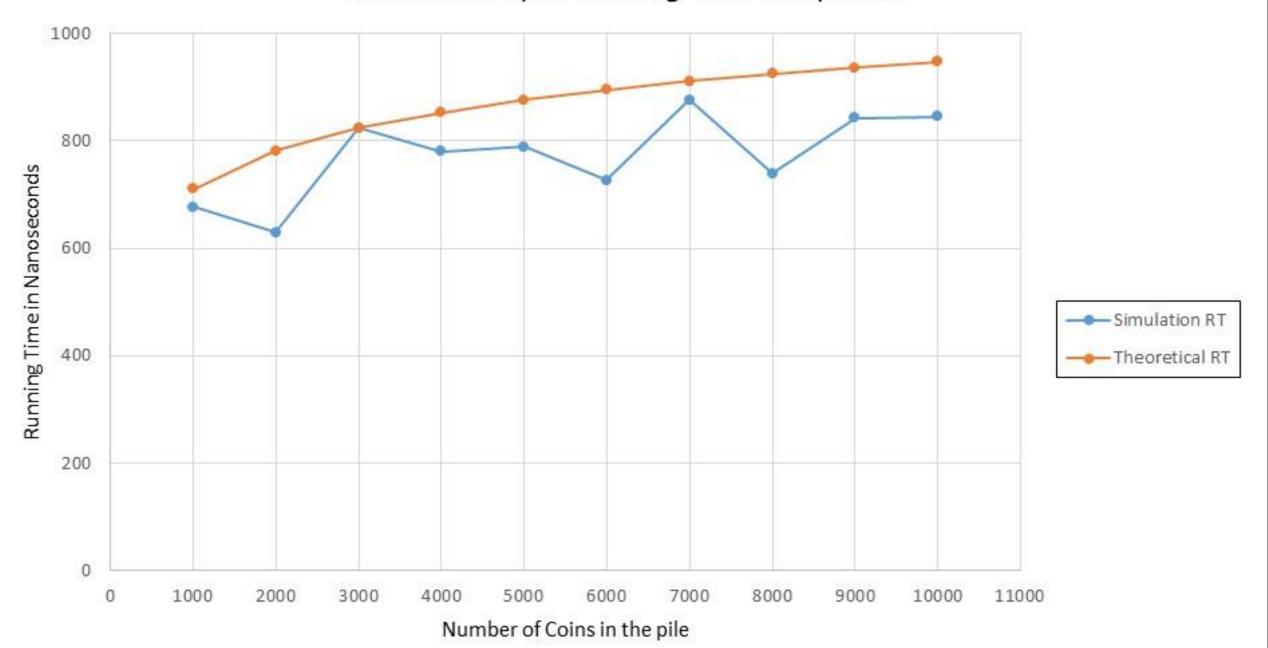
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n	Simulation RT	Theoretical RT	Hidden Constant	
1000	677.2	996.6	0.67953	
2000	630.2	1096.6	0.57470	
3000	823.6	1155.1	0.71303	
4000	780	1196.6	0.65186	
5000	789.4	1228.8	0.64243	
6000	727	1255.1	0.57925	
7000	876.8	1277.3	0.68644	
8000	739.4	1296.6	0.57027	
9000	842.4	1313.6	0.64131	
10000	845.6	1328.8	0.63638	
C _{max}		0.71303		

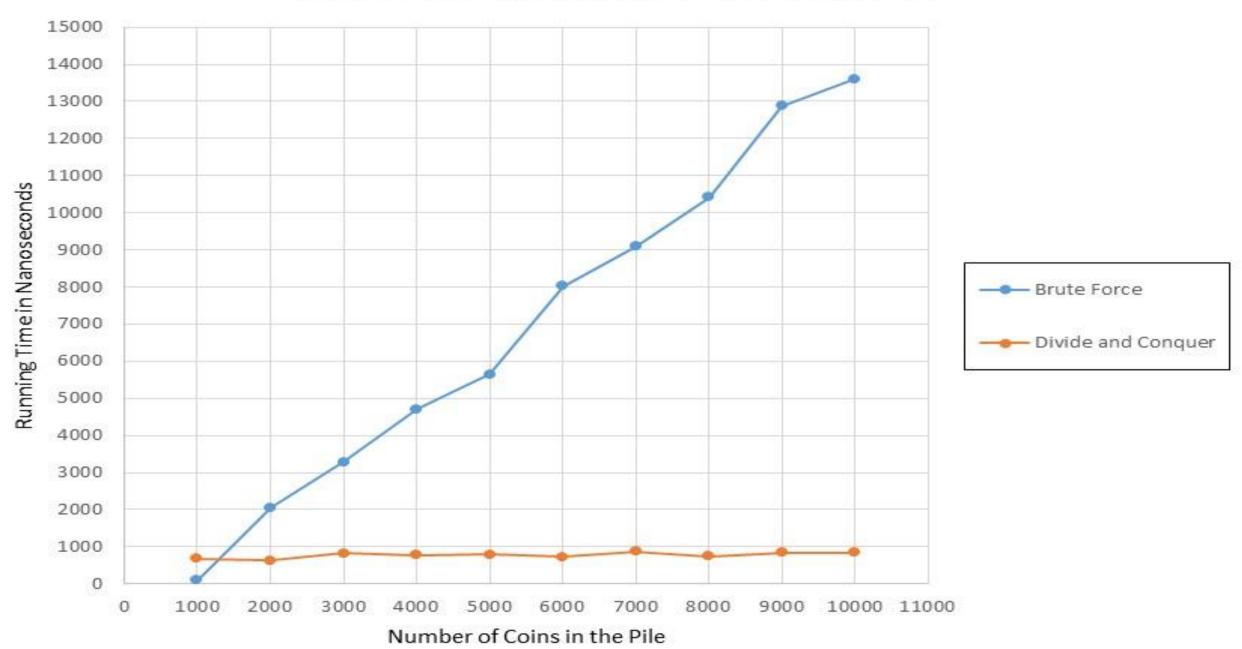
Divide & Conquer

n	Simulation RT	Theoretical RT	% Difference	
1000	677.2	710.6	4.70	
2000	630.2	781.9	19.40	
3000	823.6	823.6	0.00	
4000	780	853.2	8.58	
5000	789.4	876.1	9.90	
6000	727	894.9	18.76	
7000	876.8	910.8	3.73	
8000	739.4	924.5	20.02	
9000	842.4	936.6	10.06	
10000	845.6	947.5	10.75	
C _{max}		0.71303		
Average % D	ifference	10.59		

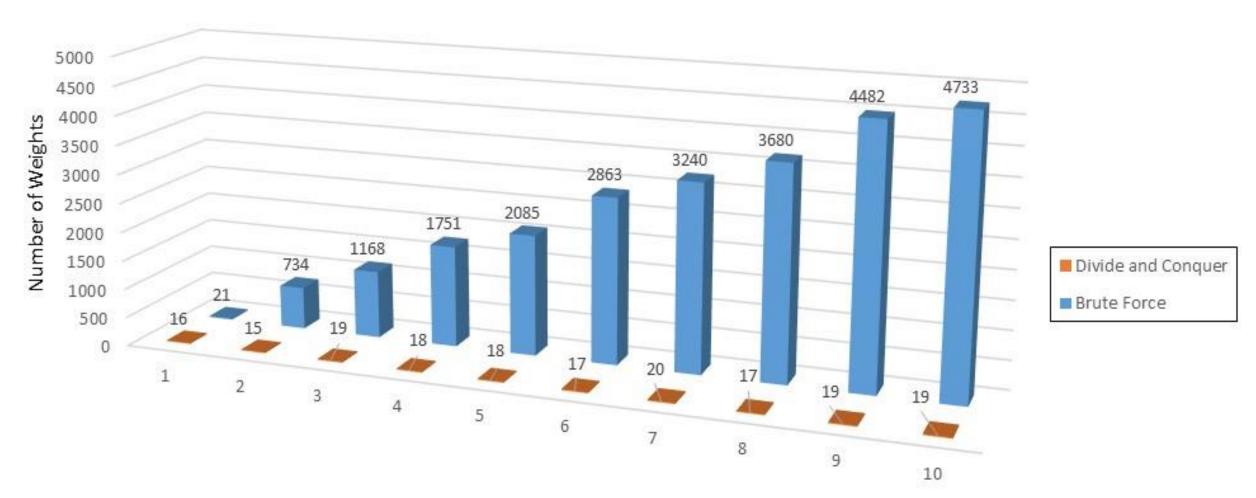
Divide & Conquer Running Time Comparison



Running Time Comparison of Both Algorithms



Number of Weights Comparison based on the Algorithm



Pile Number

Binary Search

- Given a sorted array A of n numbers, determine whether a given number x belongs to the array.
- We want to search an array A[p...r] and check to see if a certain element exists.
- Divide the array into two halves.
 - $q = \left\lfloor \frac{p+r}{2} \right\rfloor$
- Compare the middle element with the value x. If x smaller than middle element, then we discard the right half of the array and look at the left half. If not, we look at the right half. Repeat the same step until the size of array is 1 element.
 - If x < A[q], then search x into A[p...q-1]
 - If x > A[q], then search x into A[q+1...r]

Binary Search Algorithm

```
BinarySearch(A,p,r,x)
if p == r
  if x==A[p] then return p
  else return -1 //not found
if x == A[q] then return q
else if x < A[q]
  BinarySearch(A, p, q - 1, x)
else
  BinarySerach(A, q+1, r, x)
```

Example of Applying Binary Search for element 13

2	7	13	32	71	77	80	84	99	101
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Binary Search Running Time Analysis

•
$$T(n) = aT\left(\frac{n}{b}\right) + f(n)$$

- Combine Step: Constant $\Theta(1)$
- 1 Problem (a = 1)
- Subproblems created (b = 2)

•
$$T(n) = T\left(\frac{n}{2}\right) + \Theta(1)$$

- We can apply Case 2 of Master Theorem
- This results in the running time analysis to be $\Theta(\log n)$
- Significant Improvement compared to a linear search!

Growth of Functions for Search

