CSE410 - Computer Graphics Sessional OpenGL Assignment

Deadline: 02 May 2025, 11:59 PM

Overview

This assignment consists of the following tasks:

- **Task 1**: Implementing a fully controllable camera in 3D space.
- Task 2: Creating a real-time analog clock.
- **Task 3**: Simulating a bouncing ball in a cube with gravity, collisions, and rolling behavior.

You must recreate the behavior demonstrated in the provided reference output files.

Task 1: Camera Movement

Implement a camera that can **translate** and **rotate** freely in 3D space.

Translation Controls

• **Up arrow**: Move forward

• Down arrow: Move backward

• Left arrow: Move left

• **Right arrow**: Move right

• Page Up: Move upward

• Page Down: Move downward

Rotation Controls

- 1: Look left (Yaw)
- 2: Look right (Yaw)
- 3: Look up (Pitch)
- 4: Look down (Pitch)
- **5**: Tilt clockwise (Roll)
- **6**: Tilt counterclockwise (Roll)
- w: Move upward without changing reference point
- **s**: Move downward without changing reference point

Demo

Check the **balldemo** executable from "Demo Executables" folder on Moodle for reference.

Task 2: Real-Time Analog Clock

Implement a real-time analog clock showing hour, minute, and second hands.

Description

- Draw a circular clock face with hour and minute markers.
- Draw three hands: Hour (short, thick), Minute (long, medium), Second (thin, long).
- Animate the clock hands based on system time.
- Clock should update in real-time.

Demo

Check the **clockdemo** executable from "Demo Executables" folder on Moodle for reference.

Task 3: 3D Bouncing Ball Simulation

Simulate a ball bouncing inside a cube under gravity, with realistic rolling and collision handling.

Visual Elements

- 3D Ball
- Checkered floor
- Colored cube walls (sides and ceiling)
- Velocity direction arrow (toggleable)

Physics Simulation

- Gravity acting downward (9.8 m/s²)
- Bounce on collisions with restitution coefficient (0.7~0.8) for damping effect
- Ball comes to rest if vertical velocity is too low
- Rolling rotation based on displacement
- Proper spinning behavior for the ball
- You do not necessarily need to implement friction mechanism for the rolling ball

Simulation Controls

- **Space**: Toggle simulation on/off
- **r**: Reset ball position and velocity (randomly, but the velocity direction should be upward)
- +/-: Increase or decrease initial speed (only applicable after reset and before release)
- v: Toggle velocity arrow

Demo

Check the **balldemo** executable from "Demo Executables" folder on Moodle for reference.

Submission Instructions

Important Submission Guidelines

- 1. Create a directory named with your 7-digit student ID.
- 2. Add all relevant source files.
- 3. Zip the directory (.zip format only).
- 4. Upload to Moodle before the deadline.

Special Instructions

• No plagiarism: Strictly enforced.

• Use variables: Avoid hardcoding.

• Clean code: Structure your program properly.

• Incremental workflow: Keep adding components gradually.

Mark Distribution

Task	Subtask Description	Subtask Mark	Task Mark
Task 1	Camera Movement	20	20
Task 2	Drawing clock face (markers) Drawing and updating hands correctly Smooth animation using system time	10 10 10	30
Task 3	Scene rendering (cube, floor, ball visuals) Resetting and control functionality Proper gravity and collision handling Ball realistic rolling and bouncing	10 10 15 15	50

Total: 100 Marks