What is information?

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What is Information: session outcomes

- Ability to express ideas about information and relate that to uncertainty.
- Understand further fundamental measures of information theory including: mutual information, conditional mutual information.
- Ability to partially construct Matlab code to compute such measures, and apply that code to examples.

Primary references:

- Cover and Thomas, "Elements of Information Theory", Hoboken, New Jersey: John Wiley and Sons, Inc.,
 2006 (2nd ed.); section 2.2-2.5, 2.6, 2.8
- Mackay, "Information Theory, Inference, and Learning Algorithms", Cambridge: Cambridge University Press, 2003; sections 2.6, chapter 8.
- Bossomaier, Barnett, Harré, Lizier, "An Introduction to Transfer Entropy: Information Flow in Complex Systems", Springer, Cham, 2016; section 3.2.1-3.2.4.
- Lizier, "JIDT: An information-theoretic toolkit for studying the dynamics of complex systems", Frontiers in Robotics and Al, 1:11, 2014; Appendix A.1 and A.3

Cross entropy and Kullback-Leibler divergence

– Cross-entropy:

$$G(p||q) = \sum_{x \in A_r} p(x) \log_2 \frac{1}{q(x)}$$

- Average code length if using the PDF q(x) to optimally encode x, which has actual PDF p(x)
- Kullback-Leibler (KL) divergence:

$$D(p||q) = \sum_{x \in A_x} p(x) \log_2 \frac{p(x)}{q(x)}$$

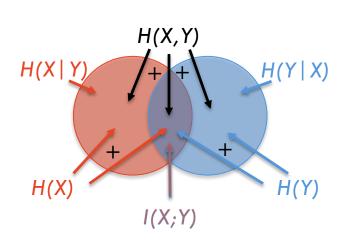
- Average coding penalty from using the PDF q(x) to optimally encode x, which has actual PDF p(x)
- $D(p||q) \ge 0$ with equality iff q=p
 - You always incur a cost for using incorrect PDF!

T. M. Cover and J. A. Thomas. Elements of Information Theory. Wiley-Interscience, New York, 1991. Section 2.3

Bossomaier, Barnett, Harré, Lizier, "An Introduction to Transfer Entropy: Information Flow in Complex Systems", Springer, Cham, 2016; section 3.2.4

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- Mutual information I(X;Y) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y
- Interpretation 1: from Venn diagrams –

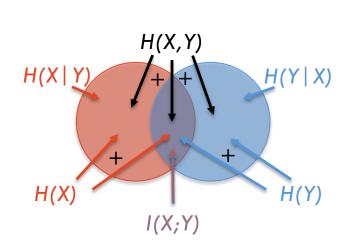


$$I(X; Y) = H(X) + H(Y) - H(X, Y)$$

 $I(X; Y) = H(X) - H(X|Y)$
 $I(X; Y) = H(Y) - H(Y|X)$
 $I(X; Y) = I(Y; X)$

- $0 \le I(X; Y) \le \min(H(X), H(Y))$
- Is symmetric in X and Y
- $I(X;Y) = H(X) \rightarrow H(X|Y) = 0$

- Mutual information I(X;Y) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y
- Interpretation 2: KL divergence / Bayesian view -

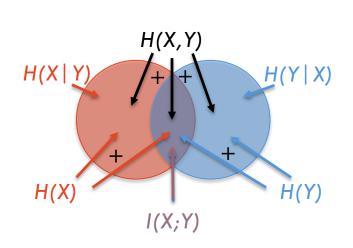


$$I(X;Y) = \sum_{x \in A_x, y \in A_y} p(x,y) \log_2 \frac{p(x,y)}{p(x)p(y)}$$

$$I(X;Y) = \sum_{x \in A_x, y \in A_y} p(x,y) \log_2 \frac{p(x|y)}{p(x)}$$

- I(X;Y) = D(p(x,y)||p(x)p(y))
- MI is code length penalty for coding $\{x,y\}$ assuming x and y are independent, or for coding x without using knowledge of y.

- Mutual information I(X;Y) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y
- Interpretation 3: statistical view -



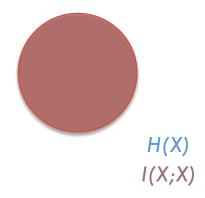
$$I(X;Y) = \sum_{x \in A_x, y \in A_y} p(x,y) \log_2 \frac{p(x|y)}{p(x)}$$

- $I(X;Y) = 0 \leftrightarrow X$ is independent of Y
- MI is a non-linear form of correlation

- Mutual information I(X;Y) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y
- Interpretation 4: self-information and uncertainty —

$$I(X;X) = H(X) + H(X) - H(X,X)$$

$$I(X;X) = H(X)$$



- Entropy H(X) (uncertainty) is equivalent to the self-information I(X;X) (uncertainty reduction) obtained from that variable about itself.
- Entropy and information are complementary quantities!

- Mutual information I(X;Y) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y
- Interpretation 5: Kelly Gambling -

$$I(X;Y) = \sum_{x \in A_x, y \in A_y} p(x,y) \log_2 \frac{p(x|y)}{p(x)}$$

- If we gamble on x, with fair odds (payout is 1/p(x) for each winner x), and invest all our capital on each race, over repeated races:
 - Best strategy is to spread investments as per p(x)
 - If we have side information y, best to invest as per p(x|y)
 - I(X;Y) as the average growth rate of investment return when investing as per p(x|y), with respect to gambling as per p(x).

T. M. Cover and J. A. Thomas. Elements of Information Theory. Wiley-Interscience, New York, 1991. Chapter 6

C. Finn and J.T. Lizier, "Pointwise Partial Information Decomposition Using the Specificity and Ambiguity Lattices", Entropy, 20, 297, 2018.

Pointwise or local Mutual information

- Mutual information i(x;y) is the reduction in uncertainty or surprise about one sample x of variable X that we obtain from one sample y of another variable Y

$$i(x; y) = h(x) + h(y) - h(x, y)$$

$$i(x; y) = h(x) - h(x|y)$$

$$i(x; y) = h(y) - h(y|x)$$

$$i(x; y) = \log_2 \frac{p(x|y)}{p(x)}$$

$$I(X; Y) = \langle i(x; y) \rangle$$

- i(x;y) > 0 means p(x|y) > p(x), so y increased our expectation that x would occur, positively informing us.
- i(x;y) < 0 means p(x|y) < p(x), so y reduced our expectation that x would occur, misinforming us.
 - e.g. when the weather report says 'sunshine' but it actually rains, we may have $p(rain | sunny_forecast) = 0.05$ whilst p(rain)=0.2.
 - But: on average over all samples Y provides $I(X;Y) \ge 0$.

Bossomaier, Barnett, Harré, Lizier, "An Introduction to Transfer Entropy: Information Flow in Complex Systems", Springer, Cham, 2016; section 3.2.2/3.2.2.1

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Pointwise or local Mutual information

- Mutual information i(x;y) is the reduction in uncertainty or surprise about one sample x of variable X that we obtain from one sample y of another variable Y
- Interpretation 6: information comes from effect of exclusions —

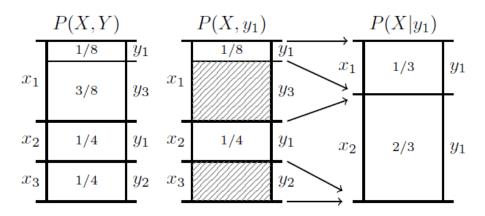
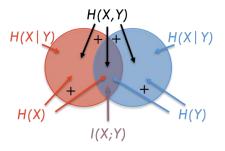


Fig. 1. Probability mass diagrams, which use length to represent the probability mass of each joint event (x,y) (summing to 1 over all (x,y) of course). These illustrate: a. (left) starting from the joint distribution P(X,Y); b. (middle) the occurrence of the event $Y=y_1$ leads to exclusions of $\overline{y}_1=\{\mathcal{Y}\setminus y_1\}=\{y_2,y_3\}$ to leave $P(X,y_1)$; c. (right) and the remaining space is then normalised into $P(X|y_1)$.

- 1. Learning the value $Y=y_1$ leads to exclusions in the joint space $P(X,y_1)$. The potential "value" of the exclusions is $h(y_1)$.
- 2. Renormalise the probability space to get $P(X|y_1)$.
- 3. Compare $P(x_1)$ and $P(x_1|y_1)$ for the event x_1 which occurred.
- Consider how exclusions in Guess Who provide information in this way ...

C. Finn & J.T. Lizier, "Decomposing Local Information into Directed Positive and Negative Components", arXiv:1801.09223, 2018.

Mutual information (MI) - code



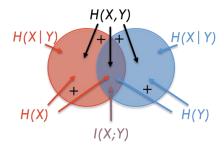
The reduction in uncertainty or surprise about one variable
 X that we obtain from another variable Y

$$i(x; y) = h(x) + h(y) - h(x, y)$$

 $I(X; Y) = H(X) + H(Y) - H(X, Y)$

- Exercise: Let's code it!
 - 1. Edit the Matlab function mutualinformation (p) to return the MI between X and Y for the joint probability p.
 - a. You can assume p is 2D (p (x, y)); this is the input.
 - b. Trick: can we use our existing entropy() and jointentropy()?
 - c. Test: mutualinformation ([0.5, 0; 0, 0.5]) = 1
 - **d.** Test: mutualinformation ([0.25, 0.25; 0.25, 0.25]) = 0
 - e. Guess Who? I(sex; earings)? Construct p(sex, earings) first. Why is there MI here?

Mutual information (MI) - code



The reduction in uncertainty or surprise about one variable
 X that we obtain from another variable Y

$$i(x; y) = h(x) + h(y) - h(x, y)$$

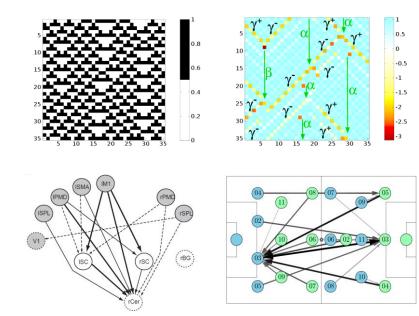
 $I(X; Y) = H(X) + H(Y) - H(X, Y)$

- Exercise: Let's code it!
 - 1. Edit the Matlab function mutualinformationempirical (xn, yn) to return the MI between X and Y from empirical samples x_n, y_n :
 - a. Input is samples x_n, y_n .
 - b. Trick: can we use our existing jointentropyempirical()?
 - c. Test: mutualinformationempirical([0,0,1,1], [0,1,0,1]) =0
 - d. Test: mutualinformationempirical([0,0,1,1], [0,0,1,1]) =1

- Is a great model-free tool to:
 - detect relationships between variables;
 - reveal patterns;
 - show how such relationships and patterns fluctuate in time.

Example uses:

- Feature selection in machine learning
- Space-time characterisation of information processing in complex systems – see later!
- Inferring relationships (i.e. networks) in multivariate time-series data (e.g. brain imaging) – see later!



J. T. Lizier. "Measuring the dynamics of information processing on a local scale in time and space". In M. Wibral, R. Vicente, and J. T. Lizier, editors, "Directed Information Measures in Neuroscience", Springer, Berlin/Heidelberg, 2014; pp. 161–193.

J. T. Lizier, J. Heinzle, A. Horstmann, J.-D. Haynes, & M. Prokopenko. "Multivariate information-theoretic measures reveal directed information structure and task relevant changes in fMRI connectivity". J. Computational Neuroscience, 30 (1):85–107, 2011.

O.M. Cliff, J.T. Lizier, P. Wang, X.R. Wang, O. Obst, M. Prokopenko, "Quantifying Long-Range Interactions and Coherent Structure in Multi-Agent Dynamics", Artificial Life, vol. 23, no. 1, pp. 34-57, 2017.

- I(X;Y|Z) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y, given the value of another variable Z.
- Interpretation 1: in the context of Z —

$$I(X;Y|Z) = H(X|Z) + H(Y|Z) - H(X,Y|Z)$$

$$I(X;Y|Z) = H(X|Z) - H(X|Y,Z)$$

$$I(X;Y|Z) = H(Y|Z) - H(Y|X,Z)$$

$$I(X;Y|Z) = I(Y;X|Z)$$

$$I(X;Y|Z) = I(X;Y,Z) - I(X;Z)$$
Ok this one is new!

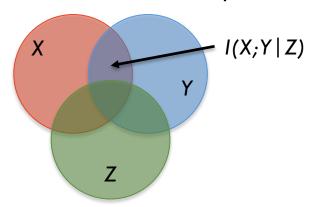
Ok this one is new!

Properties:

- $-0 \le I(X;Y|Z) \le \min(H(X|Z),H(Y|Z))$ - e.g. if Z explains X (H(X|Z)=0), then I(X;Y|Z)=0
- Is symmetric in X and Y
- $I(X; Y|Z) = H(X|Z) \rightarrow H(X|Y,Z) = 0$

T. M. Cover and J. A. Thomas. Elements of Information Theory. Wiley-Interscience, New York, 1991. Section 2.5

- I(X;Y|Z) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y, given the value of another variable Z.
- Be warned against using Venn diagrams to interpret 3-term entropies!
 - Areas in the diagram add up correctly <u>but</u> the diagram gives the misleading impression that all areas are positive! (They aren't!)



Mackay emphasises that there are no other well-defined "3-term entropies"

T. M. Cover and J. A. Thomas. Elements of Information Theory. Wiley-Interscience, New York, 1991. Problem 2.25

D. J. C. MacKay. Information Theory, Inference, and Learning Algorithms. Cambridge University Press, Cambridge, 2003. Exercise 8.8 (sol'n p. 143) & p. 139
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- I(X;Y|Z) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y, given the value of another variable Z.
- Interpretation 2: KL divergence / Bayesian view -

$$I(X;Y|Z) = \sum_{x \in A_{x}, y \in A_{y}, z \in A_{z}} p(x,y,z) \log_{2} \frac{p(x,y|z)}{p(x|z)p(y|z)}$$

$$I(X;Y|Z) = \sum_{x \in A_{x}, y \in A_{y}, z \in A_{z}} p(x,y,z) \log_{2} \frac{p(x|y,z)}{p(x|z)}$$

Properties:

- I(X; Y|Z) = D(p(x, y|z)||p(x|z)p(y|z))
- CMI is code length penalty for coding $\{x,y\}$ assuming x and y are conditionally independent (on z), or for coding x without using knowledge of y in addition to knowledge of z.

- I(X;Y|Z) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y, given the value of another variable Z.
- Interpretation 3: statistical view -

$$I(X;Y|Z) = \sum_{x \in A_x, y \in A_y, z \in A_z} p(x,y,z) \log_2 \frac{p(x|y,z)}{p(x|z)}$$

- $I(X;Y|Z) = 0 \leftrightarrow X$, conditional on Z, is independent of Y
- CMI is a non-linear form of partial correlation

Local or pointwise Conditional Mutual information

- i(x;y|z) is the reduction in uncertainty or surprise about one sample x of variable X that we obtain from one sample y another variable Y, given the sample z of another variable Z.

$$i(x; y|z) = h(x|z) + h(y|z) - h(x, y|z)$$

$$i(x; y|z) = h(x|z) - h(x|y, z)$$

$$i(x; y|z) = h(y|z) - h(y|x, z)$$

$$i(x; y|z) = \log_2 \frac{p(x|y, z)}{p(x|z)}$$

$$I(X; Y|Z) = \langle i(x; y|z) \rangle$$

- i(x;y|z) may be positive or negative (as per i(x;y))

Bossomaier, Barnett, Harré, Lizier, "An Introduction to Transfer Entropy: Information Flow in Complex Systems", Springer, Cham, 2016; section 3.2.3

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Conditional Mutual information (CMI) - code

- I(X;Y|Z) is the reduction in uncertainty or surprise about one variable X that we obtain from another variable Y, given the value of another variable Z.

$$i(x; y|z) = h(x|z) + h(y|z) - h(x, y|z)$$

 $I(X; Y|Z) = H(X|Z) + H(Y|Z) - H(X, Y|Z)$

- Exercise: Let's code it! (empirical only)
 - 1. Edit the Matlab function conditional mutual information empirical (xn, yn, zn) to return the CMI between X and Y given Z from empirical samples x_n, y_n, z_n :
 - a. Input is samples x_n, y_n, z_n .
 - b. Trick: can we use our existing conditionalentropyempirical()?
 - c. Test: CMI([0,0,1,1], [0,1,0,1], [0,1,0,1]) = 0
 - d. Test: CMI([0,0,1,1], [0,0,1,1], [0,1,1,0]) = 1
 - e. Challenge: compute using I(X;Y|Z) = I(X;Y,Z) I(X;Z)
 - f. Challenge: write conditional mutual information (p) (p is a 3D matrix!)

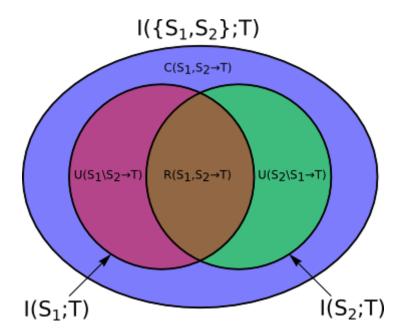
Conditional and unconditional mutual information

Conditioning on Z in I(X;Y|Z), as compared to I(X;Y) can:

- Have no effect (if all variables are independent)
- Serve to decrease I(X;Y|Z) compared to I(X;Y)
 - Y and Z carry redundant information about X.
 - Z explained away some of what could be detected by Y
 - e.g. If X=Y=Z are iid random bits, I(X;Y|Z)=0 although I(X;Y)=1
- Serve to increase I(X;Y|Z) compared to I(X;Y)
 - Y and Z together provide synergistic information about X, which cannot be detected by examining either alone.
 - e.g. If $X=Y \times C \times Z$, iid random bits, I(X;Y|Z)=1 although I(X;Y)=0.
- I(X;Y|Z) I(X;Y) being positive implies presence of synergy, or being negative implies presence of redundancy.
- But you can have both redundancy and synergy at once!

Synergy and redundancy: Information decomposition

- Cannot measure redundancy and synergy with traditional info
 theory ...
 - Need a new measure for redundancy (out of scope)



Williams and Beer, "Nonnegative decomposition of multivariate information". arXiv:1004.2515, 2010.

J.T. Lizier, N. Bertschinger, J. Jost, M. Wibral, "Information Decomposition of Target Effects from Multi-Source Interactions: Perspectives on Previous, Current and Future Work", Entropy, 20(4), 307, 2018

C. Finn and J.T. Lizier, "Pointwise Information Decomposition Using the Specificity and Ambiguity Lattices", Entropy, 20(4), 297, 2018
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Chain rule for mutual information

Chain rule for information:

$$- I(X; Y, Z) = I(X; Y) + I(X; Z|Y)$$

$$- I(X; Y, Z) = I(X; Z) + I(X; Y|Z)$$

$$I(X_1, X_2, \dots, X_n; Y) = \sum_{i=1}^n I(X_i; Y | X_1 \dots X_{i-1})$$

- This is an information regression!
- Same applies for i(x,y), I(X,Y|Z) and i(x,y|z).

Aside: Mutual information – derivation

Pointwise mutual information between X and Y:

$$i(x; y) = \log_2 \frac{p(x|y)}{p(x)}$$

and by implication $I(X;Y) = \langle i(x;y) \rangle$

- Is a unique form that satisfies four axioms:
 - Once-differentiability w.r.t. p(x) and p(x|y)
 - Conditional form i(x;y|z) matches i(x;y) but with all PDFs conditioned on z
 - Additivity i(x;y,z) = i(x;z) + i(x;y|z)
 - Separation for independent ensembles:
 - $p(x, y, u, v) = p(x, y)p(u, v) \rightarrow i(x, u; y, v) = i(x; y) + i(u, v)$

Fano, R.M.: Transmission of information: a statistical theory of communications. M.I.T. Press, Cambridge, MA, USA (1961)

What is information: summary

- We've been introduced to the ideas of uncertainty and surprise.
- Understand the meaning of information as uncertainty reduction
- Know how to calculate fundamental measures of information theory, from PDFs and empirically from data.
- Coming up: Move onto using a more advanced toolkit, and dealing with continuous-valued variables using a number of different estimators.

Questions

