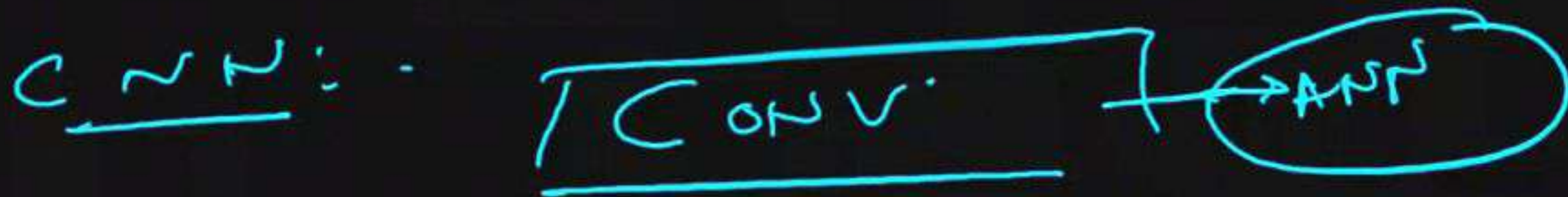
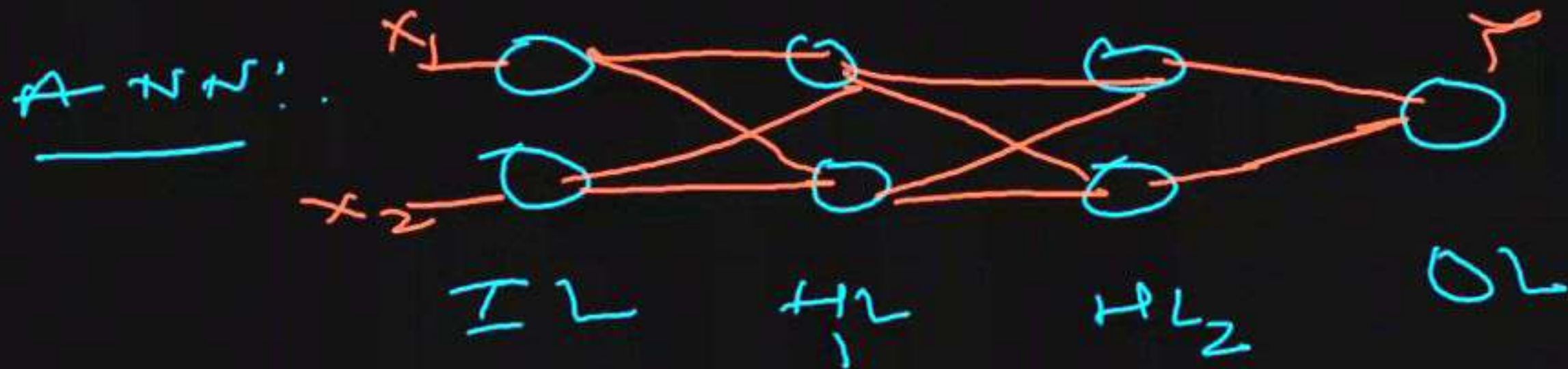
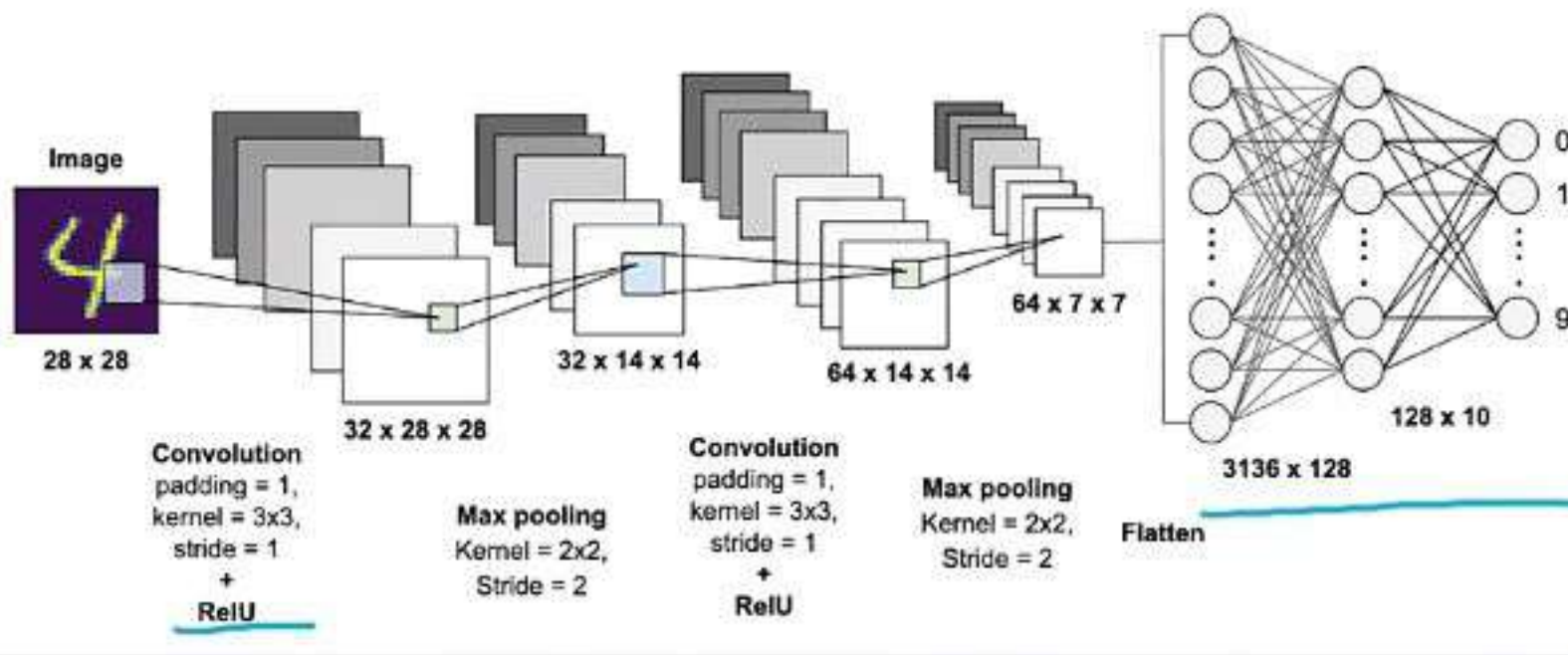


ANN:- 3 layers

i/p layer hidden layer output layer

CNN:- Convolutional N.N.





Stride = 1

1	2	3	4	5
2	10	3	4	5
3	255	2	4	5
4	1	2	3	5
5	1	2	3	4

① Kernel / filter
feature detector

② Stride

③ Padding

④ Pooling

⑤ Flatten

• kernel! - 3x3 =

1	1	1
2	1	2
3	1	3

$$1 \times 1 + 2 \times 1 + 3 \times 1 \\ + 2 \times 2 + 1 \times 1 + 3 \times 2 \\ + 3 \times 3 + 1 \times 1 + 2 \times 3$$

feature/Convolutional map

3	x	x

$$\textcircled{1} \quad \begin{array}{l} n \times n \\ m \times m \\ s = 1 \end{array}$$

Size of feature map

$$= n - m + 1$$

$$= 5 - 3 + 1 = 3$$

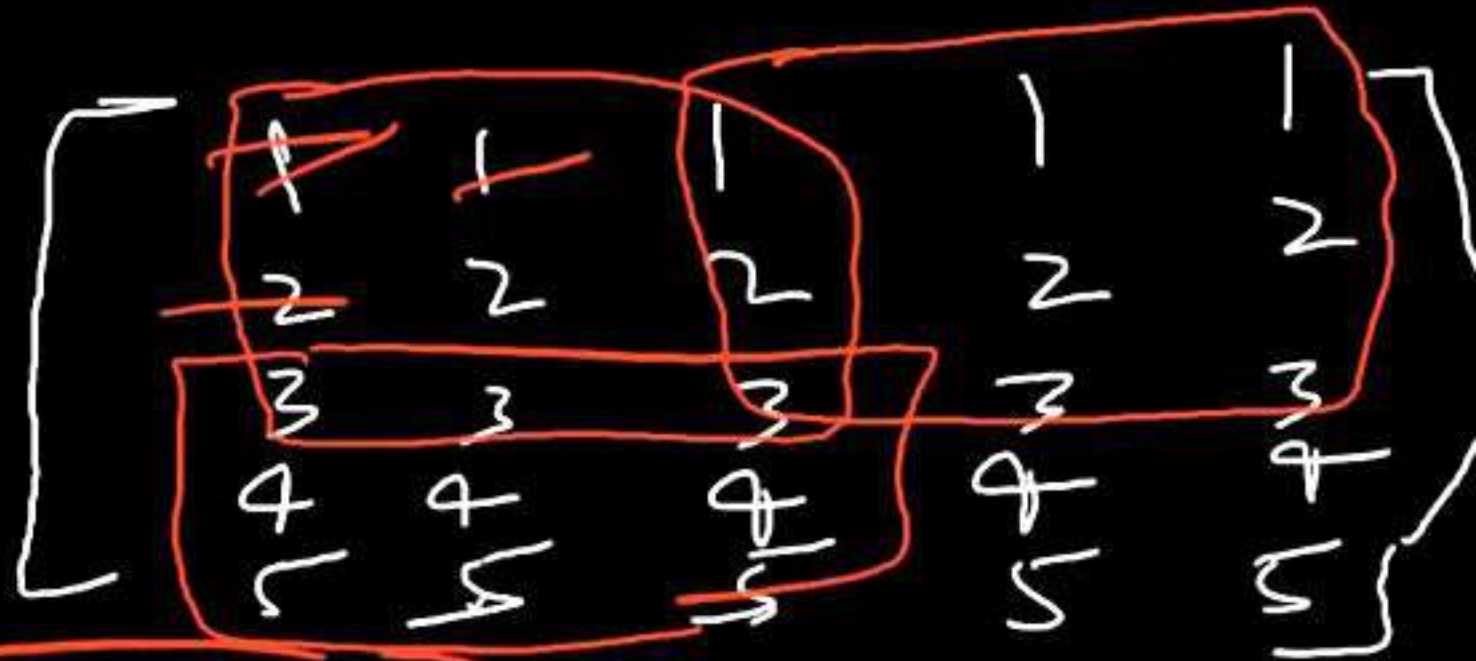
$$= 3 - 3 + 1 = 1$$

$\textcircled{2}$

$$n \times n = 5 \times 5$$

$$m \times m = 3 \times 3$$

$$s = 2 \times 2 = 2 \times 2$$

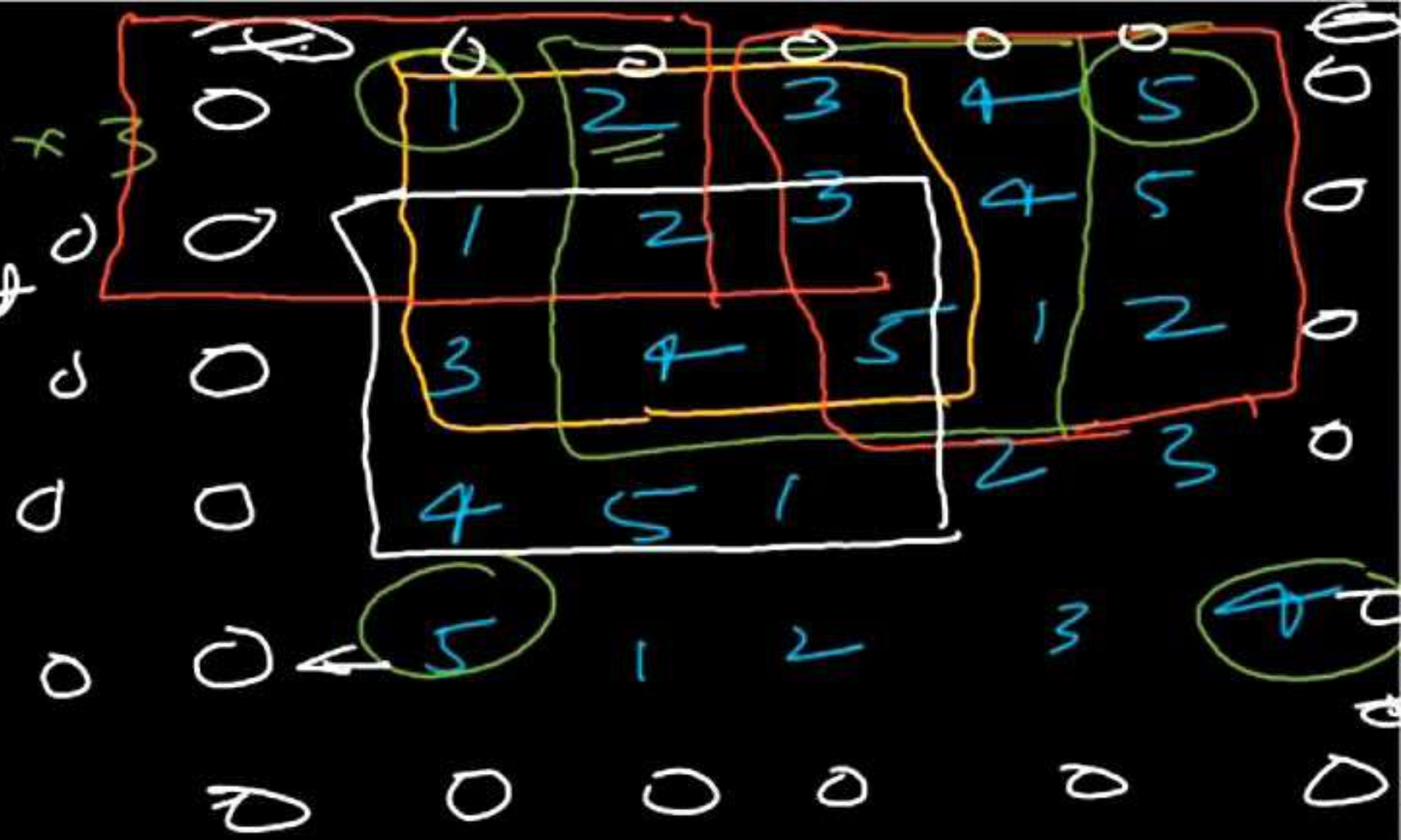


$$2 \times 2$$

$$\left[\frac{n - m}{s} \right] + 1 = \textcircled{2}$$

Padding:- $s=1, k=3 \times 3$

To fix border effect
problem:-



$$n \times n = 5 \times 5$$

$$m \times m = 3 \times 3$$

$$s \times s = 1 \times 1$$

$$p=1$$

Size of feature map

$$= \left\lfloor \frac{n-m+2p}{s} \right\rfloor + 1 =$$

$$\frac{5-3+2}{1} + 1 = 5 \times 5$$

Pooling:-

2×2 , 3×3

\rightarrow max, Avg, Sum
 $3 \times 2 \times 2$

1	2	3	4
2	3	4	5
3	4	5	1
4	5	1	2
5	1	2	3

5
1
2
3
4

\Rightarrow

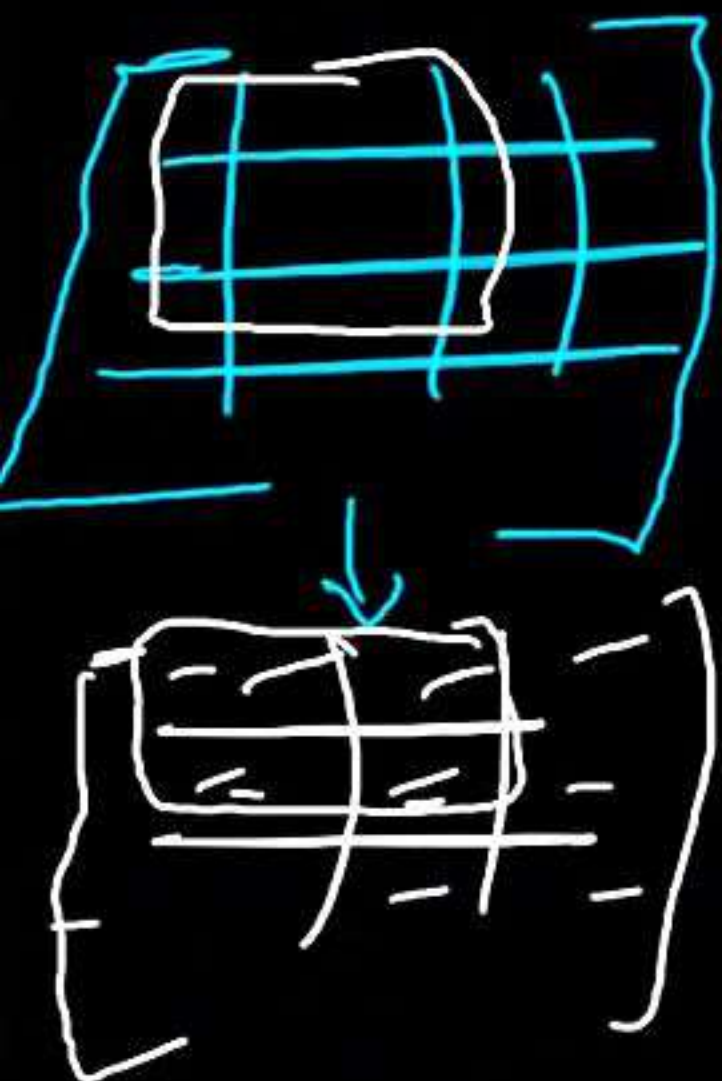
[

2x2

5×5

3×3

img = $n \times n$



Conv. Op

↳ kernel $m \times n$

↳ padding

↳ stride

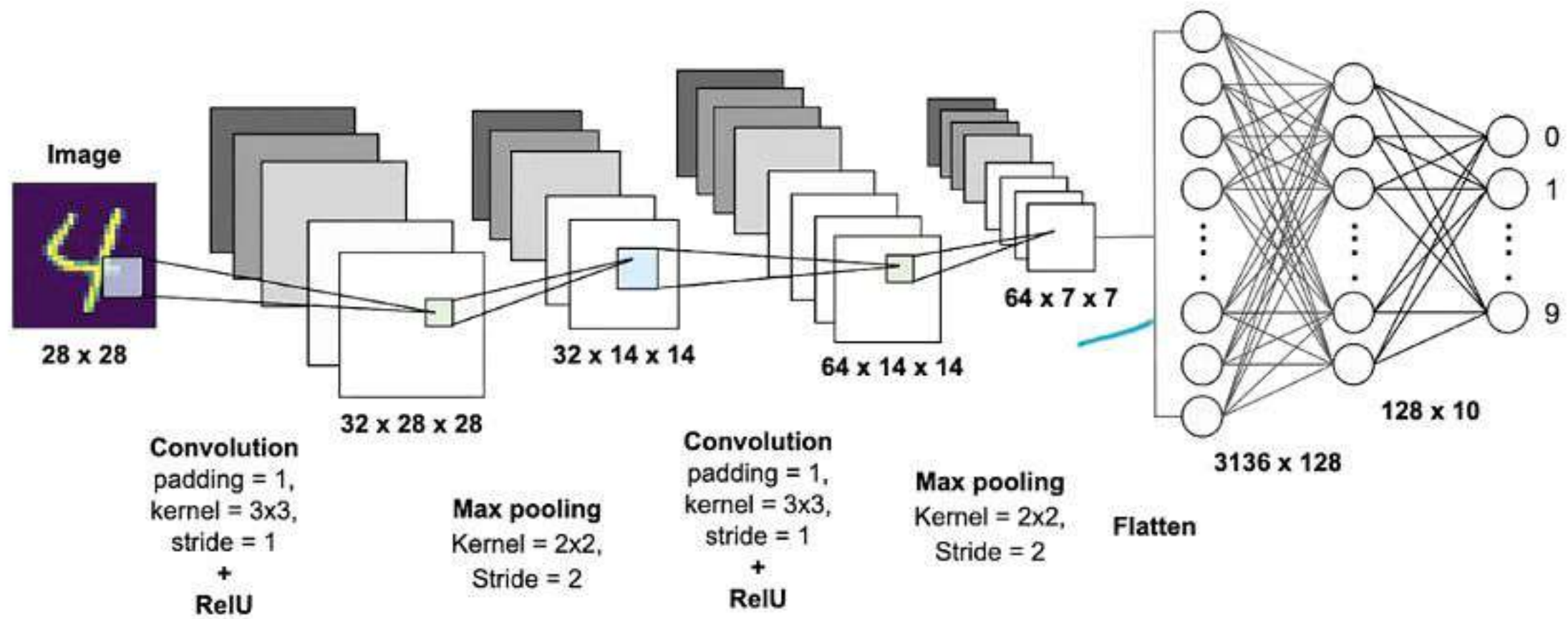
↓
feature map

↓
pooling



$K = 32 \times 3 \times 3$





$$14 - 3 + 2 + 1$$

$$= 14$$

$$C + P \rightarrow$$

$$C + P$$

$$\begin{matrix} n \times n \\ m \times m \\ s \times s \\ p \end{matrix} \Rightarrow$$

$$\frac{n - m + 2p}{s} + 1$$

$$\frac{28 - 3 + 2}{1} + 1$$

$$= 28$$

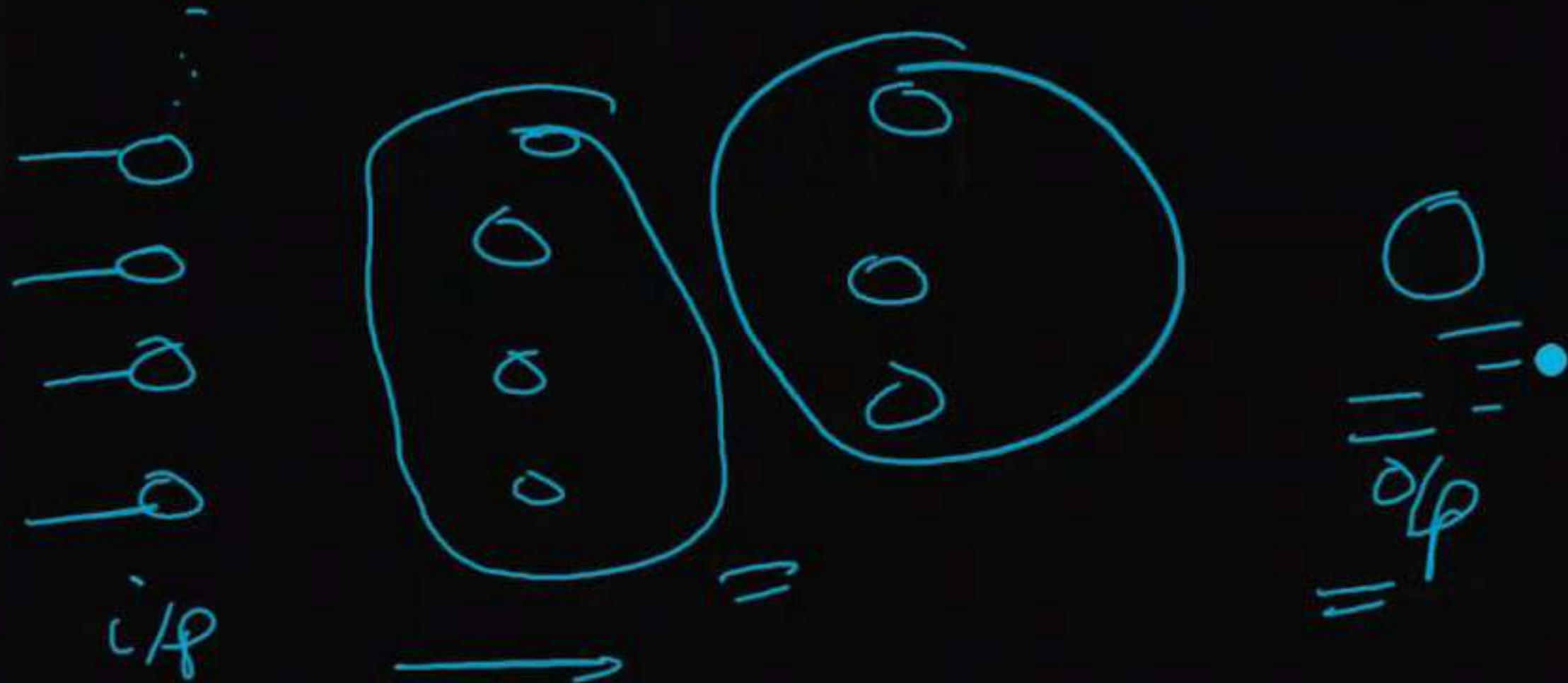
$$28 \times 28 \quad n = 32$$

$$K = 3$$

$$C \otimes$$

$$\frac{n - m + 2p}{s} + 1$$

chg - C P - $64 \times \overset{7}{\cancel{A}} \times \overset{7}{\cancel{A}}$ = []



$$64 \times 49 = 3136$$

final feature map:-

64 \Rightarrow 49

$$64 \times 4 = 3136$$



32 -

⊙
⊙
⊙
⊙
⊙
⊙

•

flat
⊙

{ [[[]],
[[]],
[[]],
[[]] }