

Introduction to multigrid

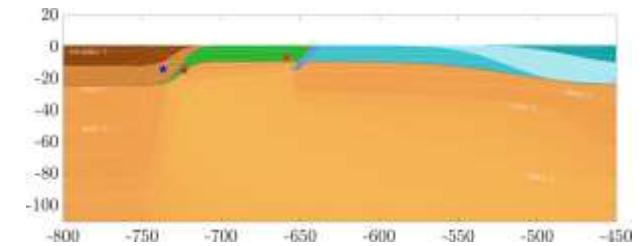
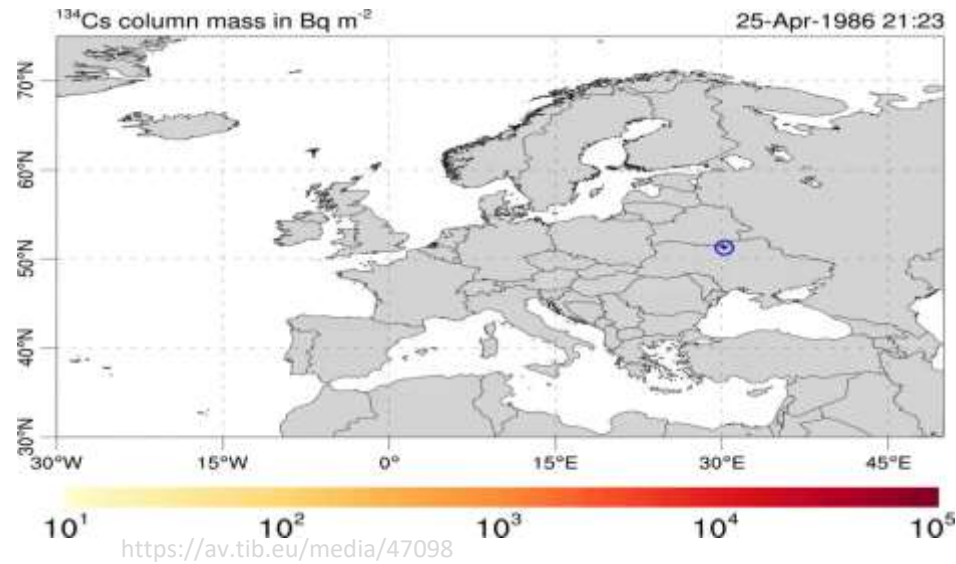
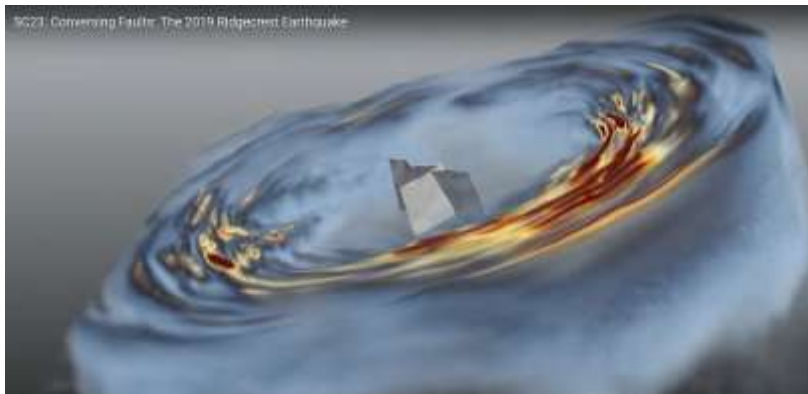
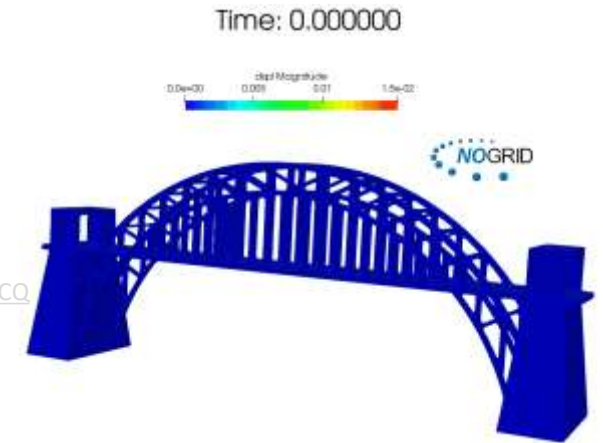
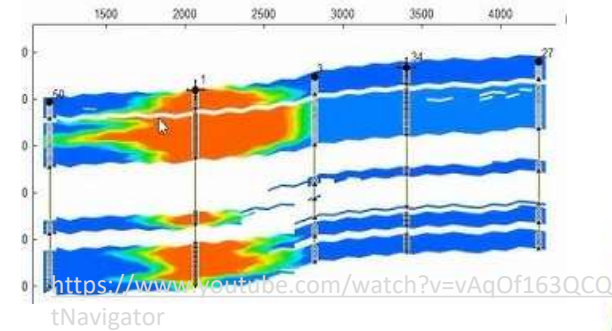
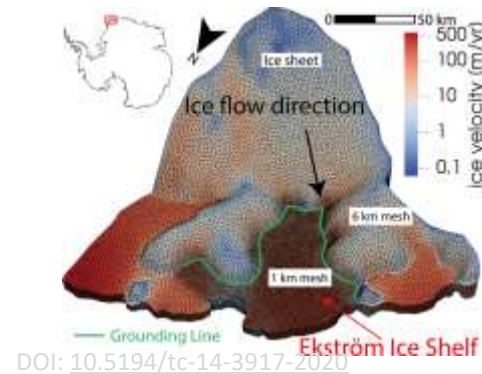
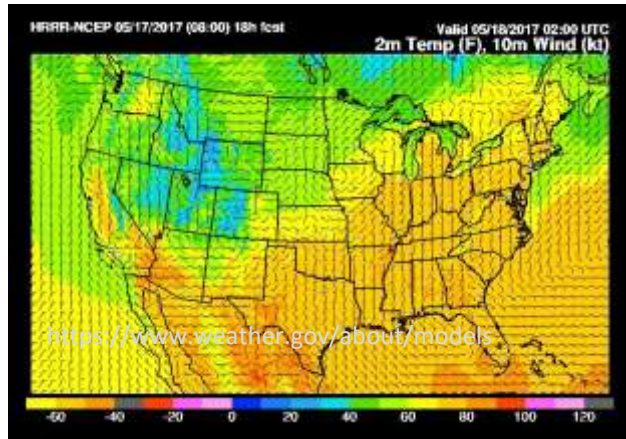
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Mainz 4 December 2024

Overview

- Direct solvers
- Iterative solvers
 - Exercises
 - Advantages of iterative solver vs direct
- Steady-state diffusion equation
- Multigrid solver
 - Exercises

What is common?



<https://www.youtube.com/watch?v=JvMuQN4FuvU>
<https://seissol.org/>

System of linear equations

$$\mathbf{Ax} = \mathbf{b}$$

How to solve?

$$\mathbf{x} = \mathbf{A} \backslash \mathbf{b}$$

Thank you for your attention!



System of linear equations

$$101x + 12y - 13z = 14$$

$$21x + 201y + 23z = 24$$

$$-31x + 32y + 301z = 34$$

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix} b = \begin{bmatrix} 14 \\ 24 \\ 34 \end{bmatrix}$$

System of linear equations

$$101x_1 + 12x_2 - 13x_3 = 14$$

$$21x_1 + 201x_2 + 23x_3 = 24$$

$$-31x_1 + 32x_2 + 301x_3 = 34$$

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix} \quad b = \begin{bmatrix} 14 \\ 24 \\ 34 \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Direct solve

Solve system of linear equations in code

$$\mathbf{x} = \mathbf{A} \backslash \mathbf{b}$$

OR

$$\mathbf{x} = \mathbf{A}^{-1} \mathbf{b}$$

Direct solve

Solve system of linear equations in code

$$\mathbf{x} = \mathbf{A} \backslash \mathbf{b}$$

$$\mathbf{x} = \mathbf{A}^{-1} * \mathbf{b}$$

$$\mathbf{x} = \text{inv}(\mathbf{A}) * \mathbf{b}$$

$$\mathbf{x} = \text{linsolve}(\mathbf{A}, \mathbf{b})$$

Iterative solvers

Iterative solvers

$$101x_1 + 12x_2 - 13x_3 = 14$$

$$21x_1 + 201x_2 + 23x_3 = 24$$

$$-31x_1 + 32x_2 + 301x_3 = 34$$

Guess x !

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix} \quad b = \begin{bmatrix} 14 \\ 24 \\ 34 \end{bmatrix} \quad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

Iterative solvers

$$\mathbf{r} = \mathbf{b} - \mathbf{A}\mathbf{x}_{\text{guess}}$$

Iterative solvers

$$\mathbf{r} = \mathbf{b} - \mathbf{A}\mathbf{x}$$

$$\mathbf{x} = \mathbf{x} + \mathbf{r}$$



Iterative solvers

$$\mathbf{r} = \mathbf{b} - \mathbf{A}\mathbf{x}$$

$$\mathbf{x} = \mathbf{x} + \mathbf{r}$$

Check if norm of $(\mathbf{x} - \mathbf{x}_{old})$ is small



Go exercise

Iterative solvers

Richardson method

$$\mathbf{r} = \mathbf{w}(\mathbf{b} - \mathbf{Ax})$$

Iterative solvers

Richardson method

$$\mathbf{r} = \mathbf{w}(\mathbf{b} - \mathbf{Ax})$$

$$w = 2 / (\min(\text{eig}(\mathbf{A})) + \max(\text{eig}(\mathbf{A})))$$

Iterative solvers

Jacobi method

$$\mathbf{r} = \mathbf{D}^{-1}(\mathbf{b} - (\mathbf{L} + \mathbf{U})\mathbf{x})$$

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix}$$

$$D = \begin{bmatrix} 101 & & \\ & 201 & \\ & & 301 \end{bmatrix}$$

$$U = \begin{bmatrix} & 12 & -13 \\ & & 23 \\ & & \end{bmatrix}$$

$$L = \begin{bmatrix} & & \\ 21 & & \\ -31 & 32 & \end{bmatrix}$$

Iterative solvers

Dampened Jacobi method

$$\mathbf{r} = \mathbf{w}\mathbf{D}^{-1}(\mathbf{b} - (\mathbf{L} + \mathbf{U})\mathbf{x}) + (\mathbf{1} - \mathbf{w})\mathbf{x}$$

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix}$$

$$D = \begin{bmatrix} 101 & & \\ & 201 & \\ & & 301 \end{bmatrix}$$

$$U = \begin{bmatrix} & 12 & -13 \\ & & 23 \\ & & \end{bmatrix}$$

$$L = \begin{bmatrix} & & \\ 21 & & \\ -31 & 32 & \end{bmatrix}$$

Iterative solvers

Gauss-Seidel method

$$\mathbf{r} = \mathbf{L}^{-1}(\mathbf{b} - \mathbf{U}\mathbf{x})$$

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix}$$

$$D = \begin{bmatrix} 101 & & \\ & 201 & \\ & & 301 \end{bmatrix}$$

$$U = \begin{bmatrix} & 12 & -13 \\ & & 23 \\ & & \end{bmatrix}$$

$$L = \begin{bmatrix} & & \\ 21 & & \\ -31 & 32 & \end{bmatrix}$$

Iterative solvers

Successive over-relaxation method

$$\mathbf{r} = (\mathbf{1} - \mathbf{w})\mathbf{x} + \mathbf{w}\mathbf{D}^{-1}(\mathbf{b} - \mathbf{U}\mathbf{x} - \mathbf{L}\mathbf{x})$$

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix}$$

$$D = \begin{bmatrix} 101 & & \\ & 201 & \\ & & 301 \end{bmatrix}$$

$$U = \begin{bmatrix} & 12 & -13 \\ & & 23 \\ & & \end{bmatrix}$$

$$L = \begin{bmatrix} & & \\ 21 & & \\ -31 & 32 & \end{bmatrix}$$

$$\mathbf{w} = 0.52$$

Iterative solvers

Dampened Jacobi method simplified

$$\mathbf{r} = \mathbf{w}\mathbf{D}^{-1}(\mathbf{b} - (\mathbf{L} + \mathbf{U})\mathbf{x}) + (\mathbf{1} - \mathbf{w})\mathbf{x}$$

Dampened Jacobi method



$$\mathbf{r} = \mathbf{w}\mathbf{D}^{-1}(\mathbf{b} - \mathbf{A}\mathbf{x})$$

Simplified dampened Jacobi method

$$\mathbf{w} = 2/3$$

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix}$$

$$D = \begin{bmatrix} 101 & & \\ & 201 & \\ & & 301 \end{bmatrix}$$

$$U = \begin{bmatrix} & 12 & -13 \\ & & 23 \\ & & \end{bmatrix}$$

$$L = \begin{bmatrix} & & \\ 21 & & \\ -31 & 32 & \end{bmatrix}$$

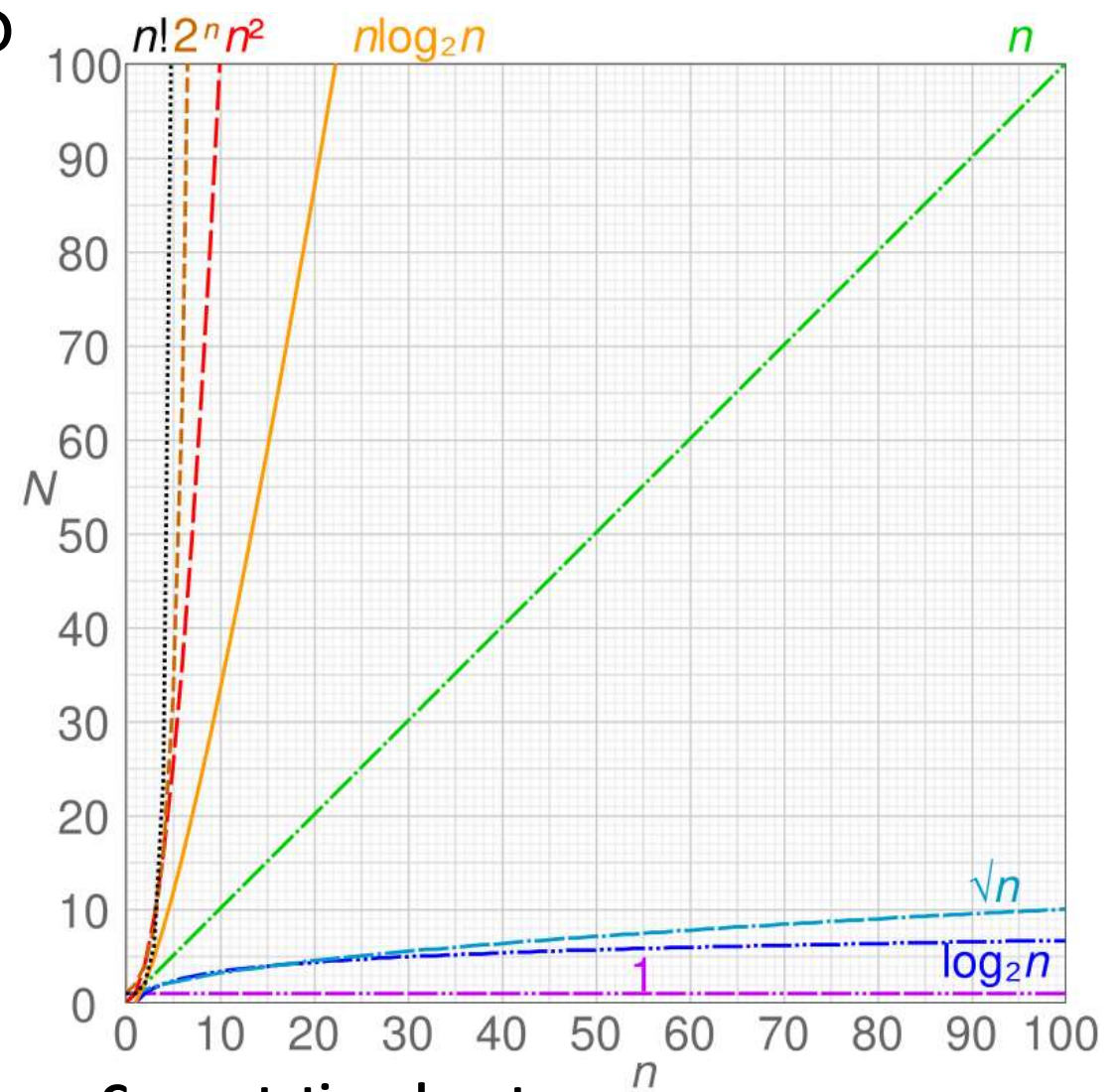
Disclaimer for iterative methods:

A Needs to be positive definite to converge =
diagonally dominant

$$A = \begin{bmatrix} 101 & 12 & -13 \\ 21 & 201 & 23 \\ -31 & 32 & 301 \end{bmatrix}$$

Why use iterative solvers?

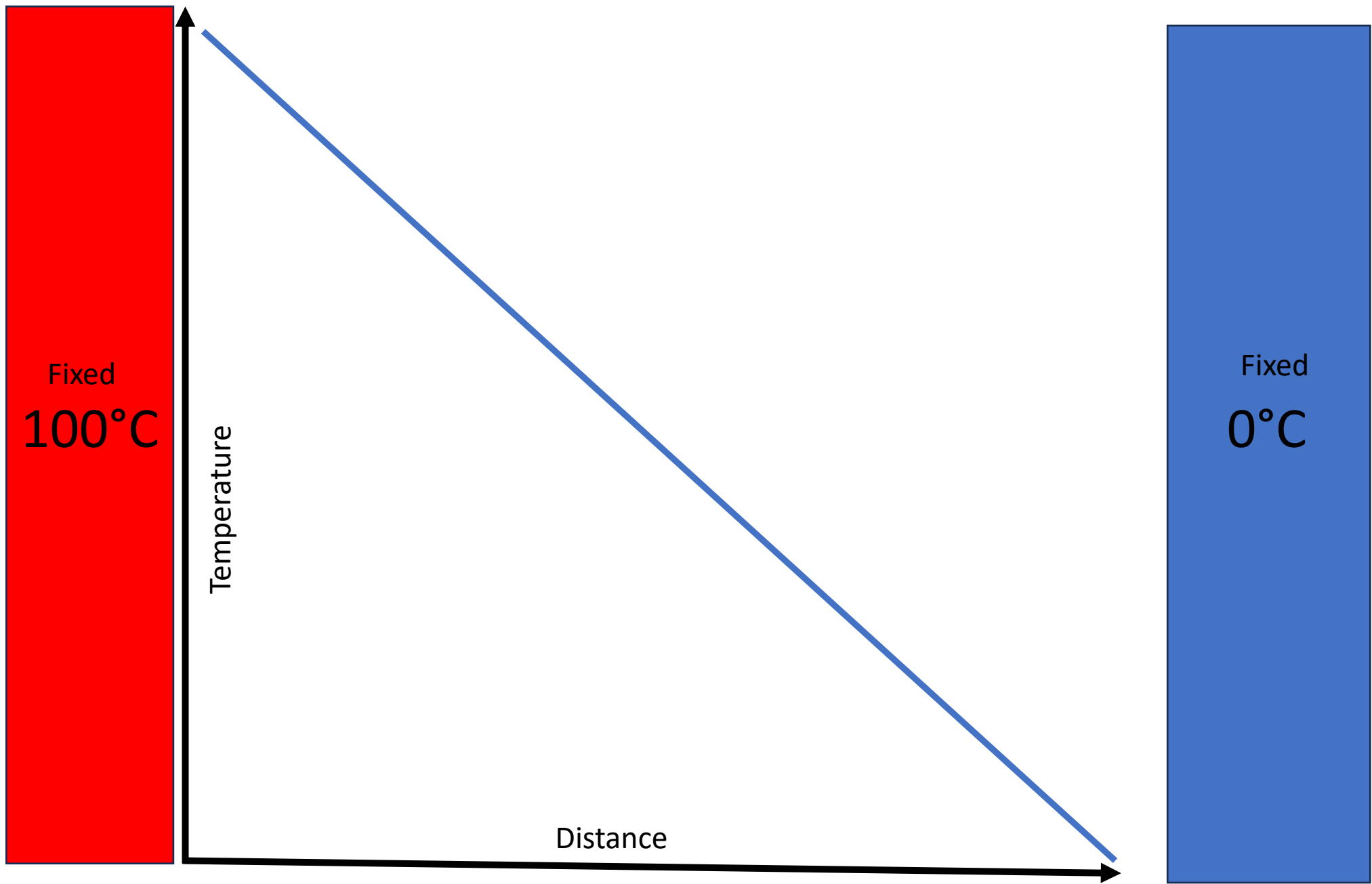
- Only matrix-vector multiplication
- Most of our systems has zeros in matrix A
- Do not need to store additional matrices for factorization
- More scalable
- Much better to parallelize
- Can use preconditioners



Computational cost:

Direct solver: $O(n^3)$

Iterative solvers (sparse): $\approx O(n^2)$



Temperature equation

(When internal heat production is negligible and there is no advection of material)

$$\kappa \nabla^2 T = \frac{\partial T}{\partial t}$$
$$\kappa \frac{\partial^2 T}{\partial x^2} = \frac{\partial T}{\partial t}$$

where $\kappa = \frac{k}{\rho C_p}$

T – temperature

t – time

κ – diffusivity constant

Steady-state

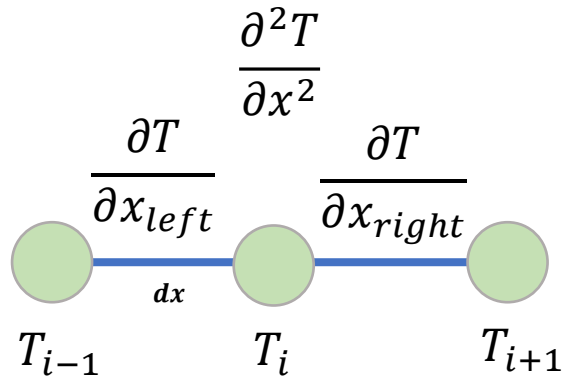
$$\frac{\partial T}{\partial t} = 0$$

$$\kappa \frac{\partial^2 T}{\partial x^2} = 0$$

- Temperature does not change in time

Finite-Difference Discretization

$$\kappa \frac{\partial^2 T}{\partial x^2} = 0$$



$$\frac{\partial T}{\partial x_{right}} = \frac{T_{i+1} - T_i}{dx}$$

$$\frac{\partial T}{\partial x_{left}} = \frac{T_i - T_{i-1}}{dx}$$

$$\frac{\partial^2 T_i}{\partial x^2} = \frac{\partial}{\partial x} \left(\frac{\partial T}{\partial x} \right) = \frac{\frac{\partial T}{\partial x_R} - \frac{\partial T}{\partial x_L}}{dx} = \frac{1}{dx} \left(\frac{T_{i+1} - T_i}{dx} - \frac{T_i - T_{i-1}}{dx} \right)$$

Finite-Difference Discretization

$$\kappa \frac{\partial^2 T}{\partial x^2} = 0$$

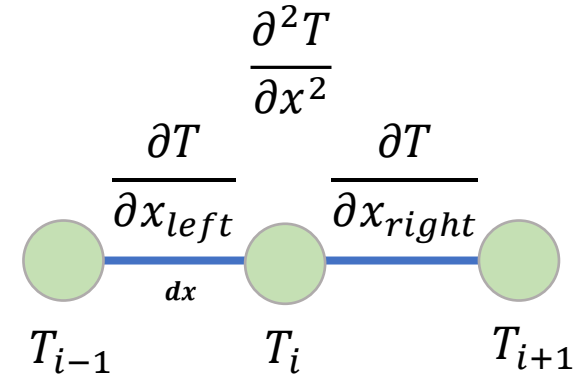
Finite-difference
approximation

$$k \frac{T_{i+1} - 2T_i + T_{i-1}}{dx^2} = 0$$

$$\frac{k}{dx^2} T_{i+1} - 2 \frac{k}{dx^2} T_i + \frac{k}{dx^2} T_{i-1} = 0$$

$$S = \frac{k}{dx^2} \text{ --- Constant}$$

$$ST_{i+1} - 2ST_i + ST_{i-1} = 0$$



$$\frac{\partial T}{\partial x_{right}} = \frac{T_{i+1} - T_i}{dx}$$

$$\frac{\partial T}{\partial x_{left}} = \frac{T_i - T_{i-1}}{dx}$$

$$\frac{\partial^2 T_i}{\partial x^2} = \frac{1}{dx} \left(\frac{T_{i+1} - T_i}{dx} - \frac{T_i - T_{i-1}}{dx} \right)$$

Fill up matrix A and RHS

$$ST_{i+1} - 2ST_i + ST_{i-1} = 0$$

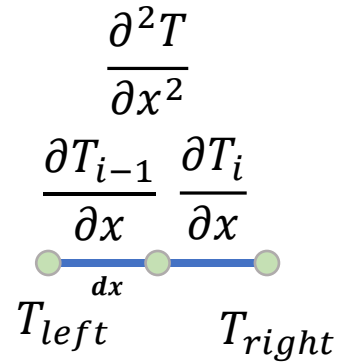
$$A = \begin{bmatrix} -2S & 0 & 0 \\ 1 & -2S & 1 \\ 0 & 0 & -2S \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

New T

$$b = \begin{bmatrix} T_{guess} \\ T_{guess} \\ T_{guess} \end{bmatrix}$$

Old T/Initial Guess T

Boundary Conditions

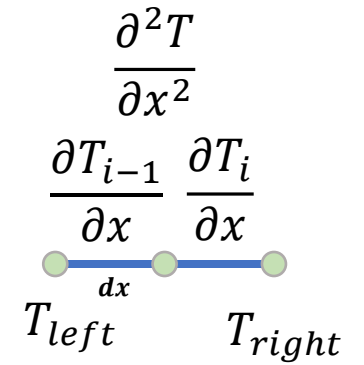
$$\frac{\partial^2 T}{\partial x^2}$$


The diagram shows a horizontal line with three green dots representing nodes. The middle node is labeled with the second derivative of temperature, $\frac{\partial^2 T}{\partial x^2}$. The two outer nodes are labeled with the first derivative of temperature, $\frac{\partial T_{i-1}}{\partial x}$ on the left and $\frac{\partial T_i}{\partial x}$ on the right. The distance between the middle and right nodes is labeled dx . The left node is labeled T_{left} and the right node is labeled T_{right} .

$$A = \begin{bmatrix} -2S & 0 & 0 \\ 1 & -2S & 1 \\ 0 & 0 & -2S \end{bmatrix} \quad x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$b = \begin{bmatrix} T_{guess} \\ T_{guess} \\ T_{guess} \end{bmatrix}$$

Boundary Conditions



A diagram illustrating a 1D domain with three nodes (green dots) and boundary conditions. The domain is represented by a horizontal line with a blue segment between the first and second nodes, and a black segment between the second and third nodes. The distance between the first and second nodes is labeled dx . The boundary conditions are T_{left} at the first node and T_{right} at the third node. The second-order derivative $\frac{\partial^2 T}{\partial x^2}$ is shown above the first segment, and the first-order derivatives $\frac{\partial T_{i-1}}{\partial x}$ and $\frac{\partial T_i}{\partial x}$ are shown above the first and second segments, respectively.

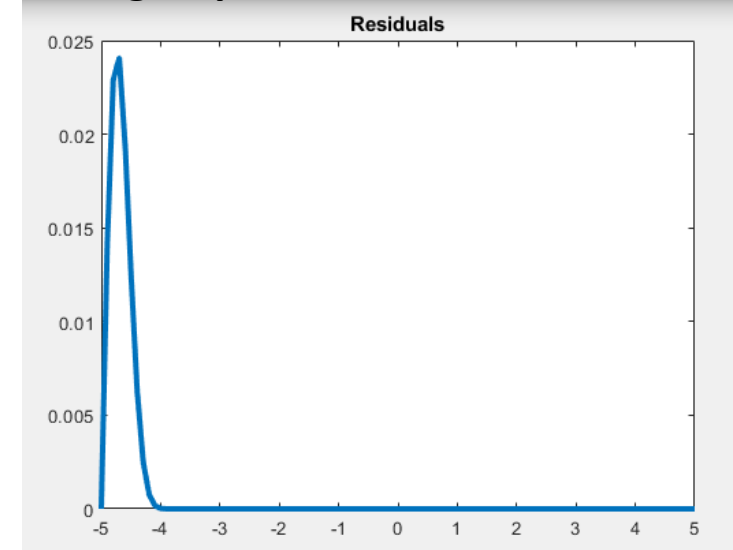
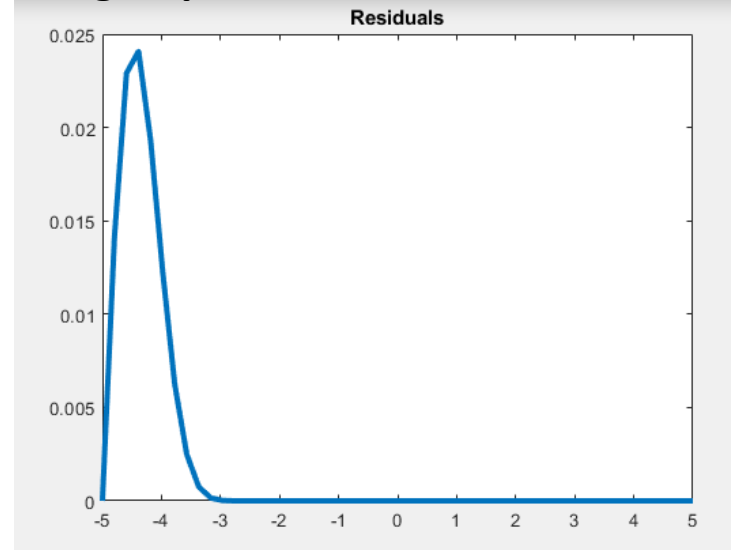
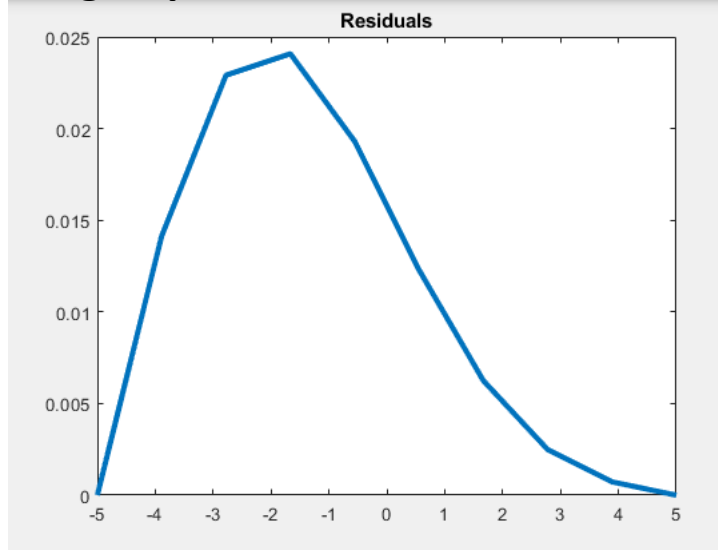
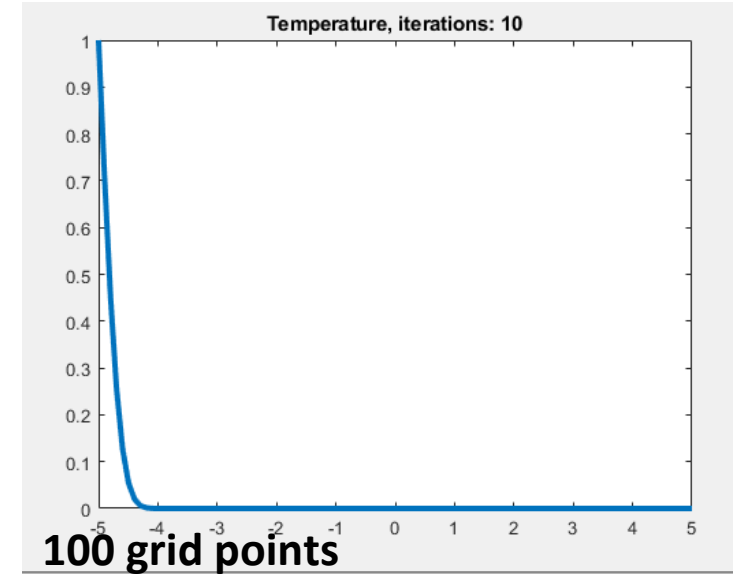
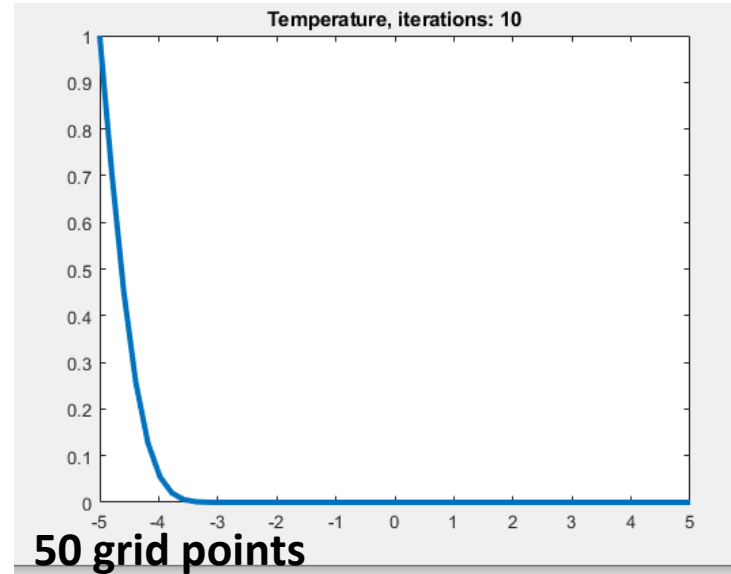
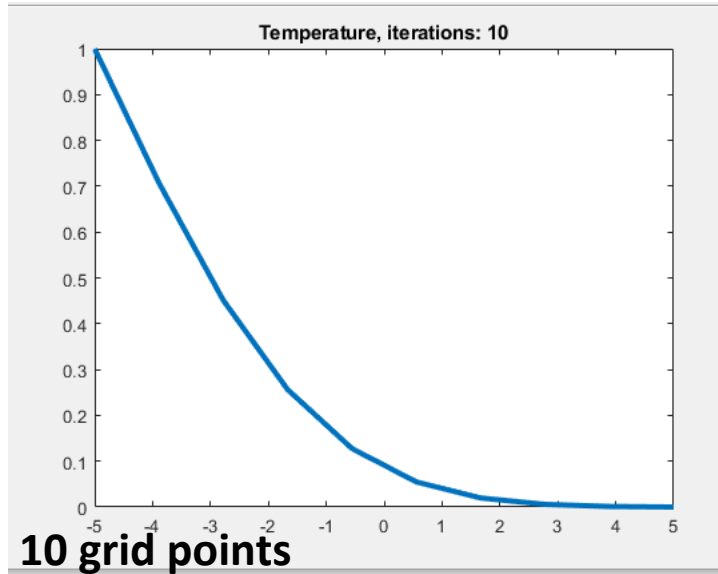
$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & -2S & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$b = \begin{bmatrix} T_{left} \\ T_{guess} \\ T_{right} \end{bmatrix}$$

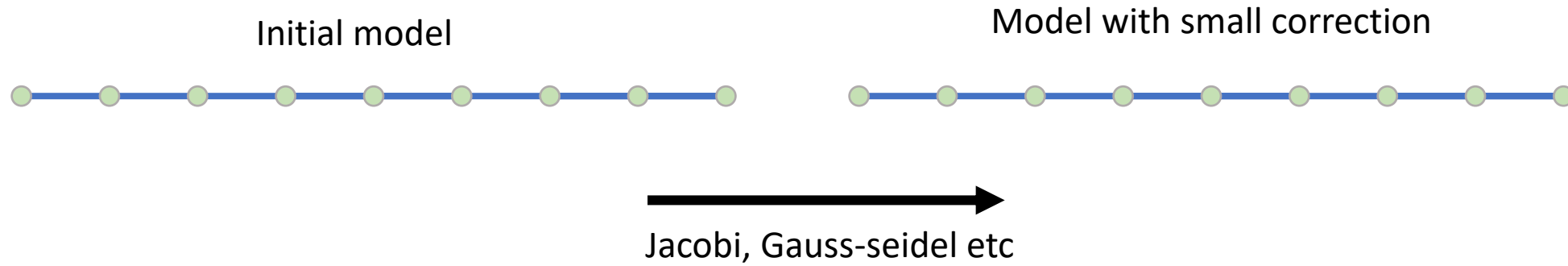
Correction propagation

Go exercise



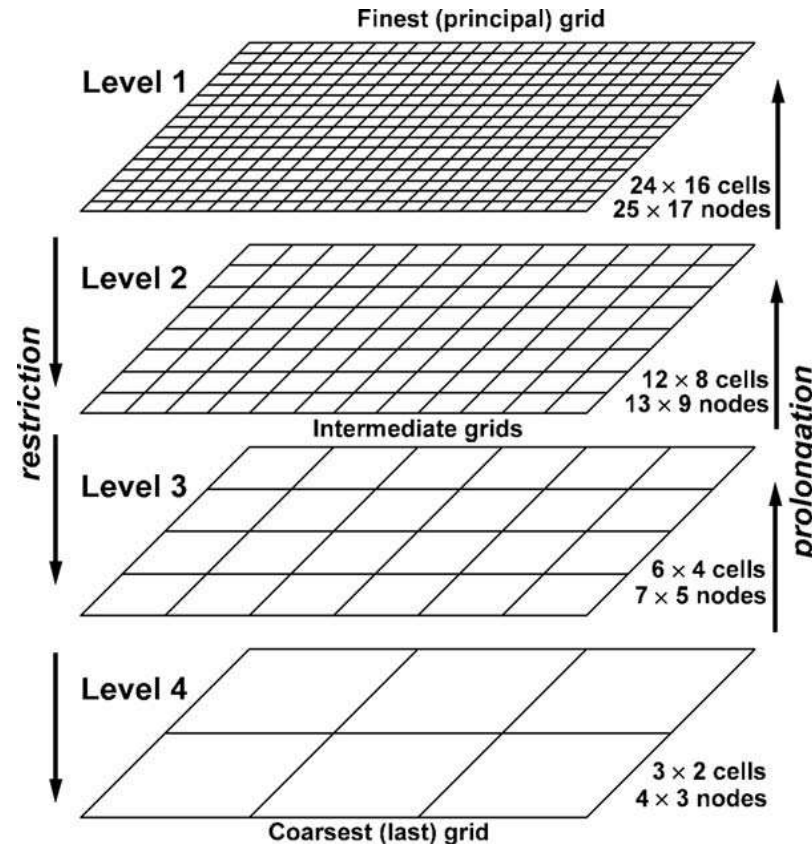
Iteration cycle

Courant–Friedrichs–Lewy (CFL) condition is dependent on spatial increment



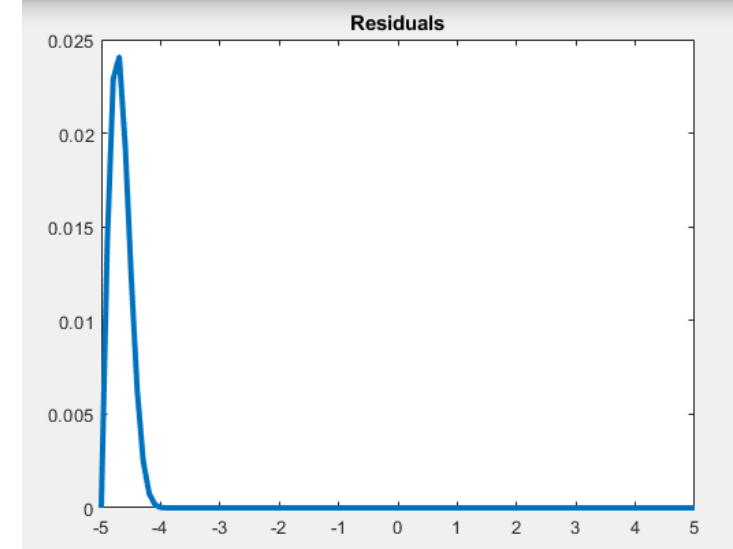
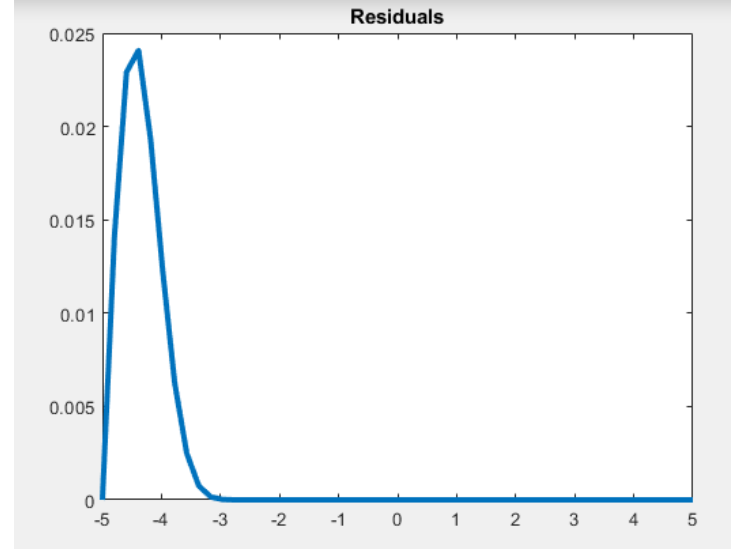
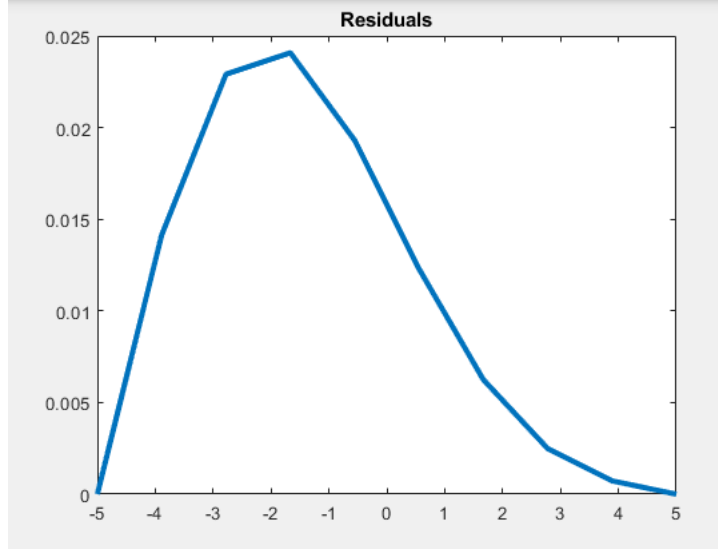
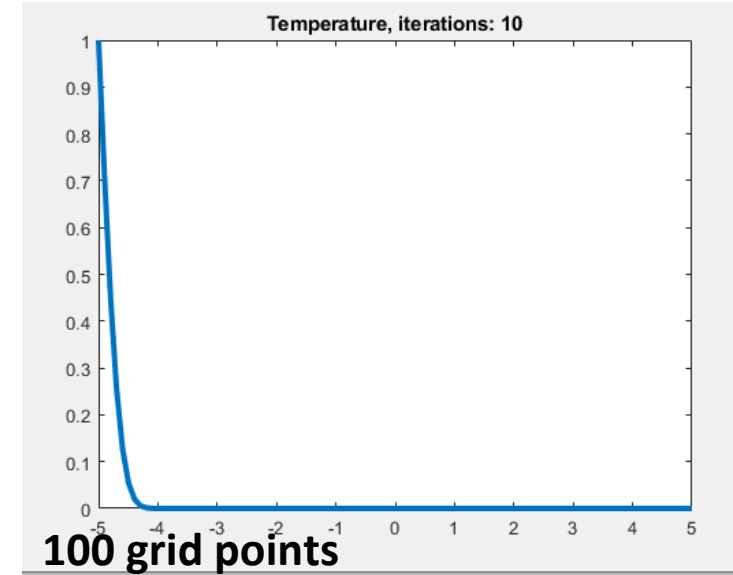
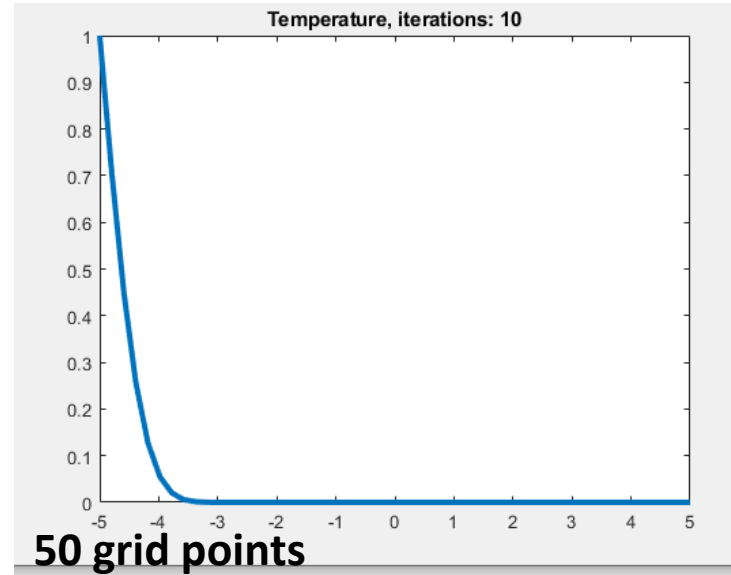
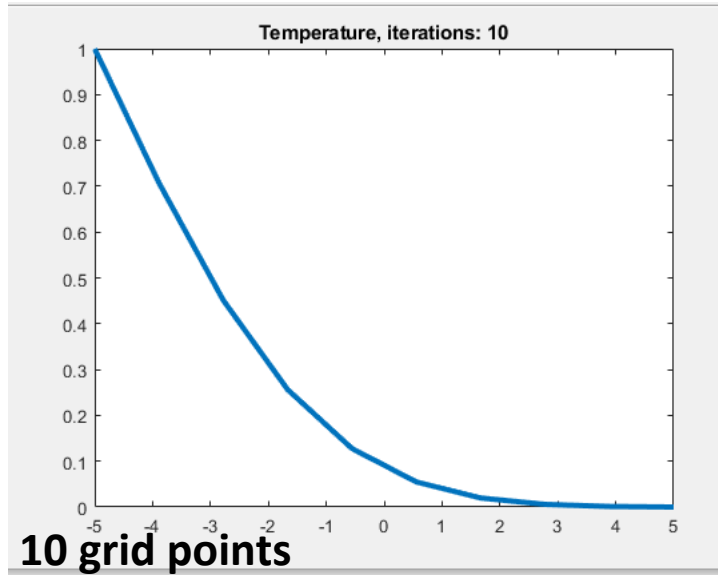
What is multigrid

- The essential multigrid principle is to approximate the smooth (long wavelength) part of the error on coarser grids.

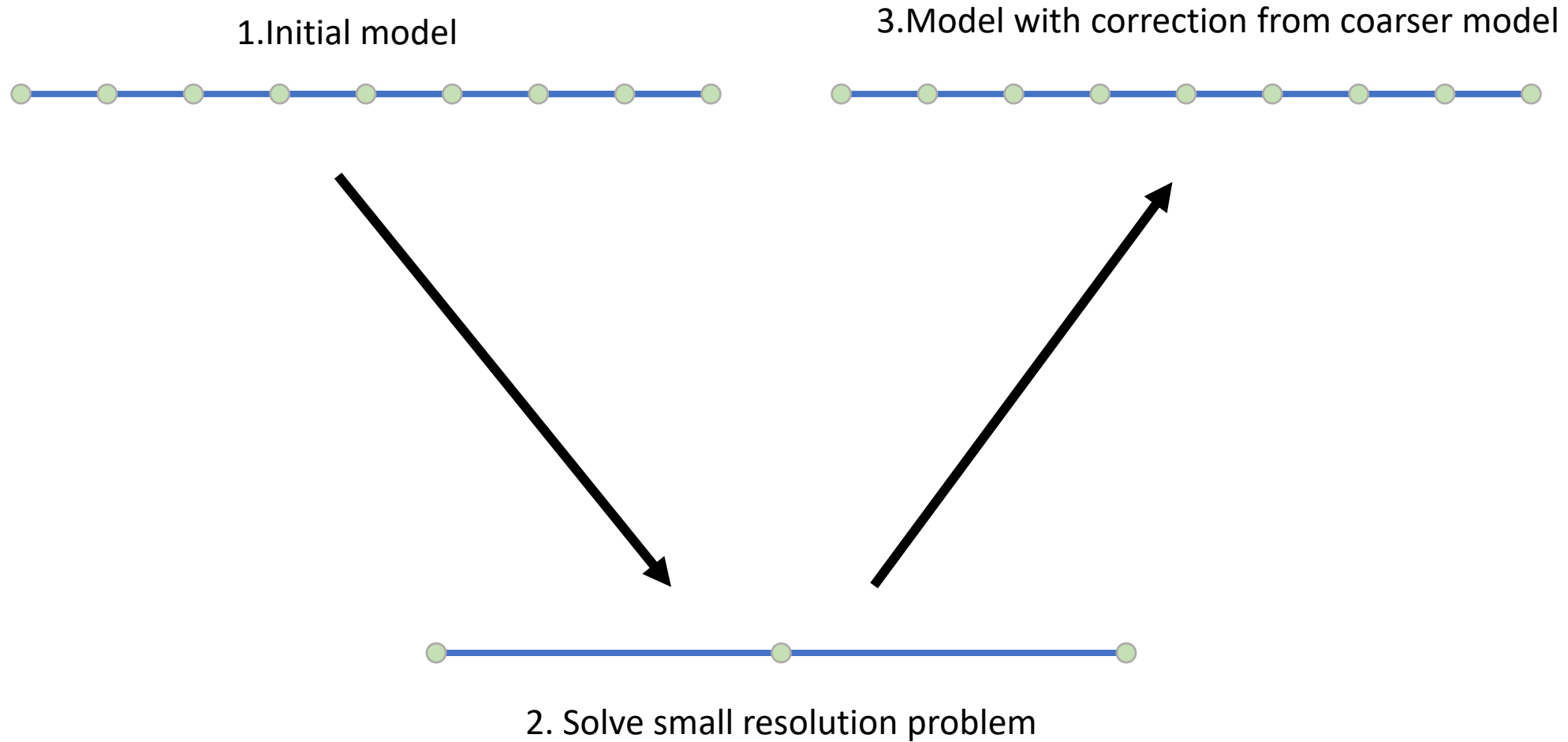


2-D multigrid
T. Gerya, 2008

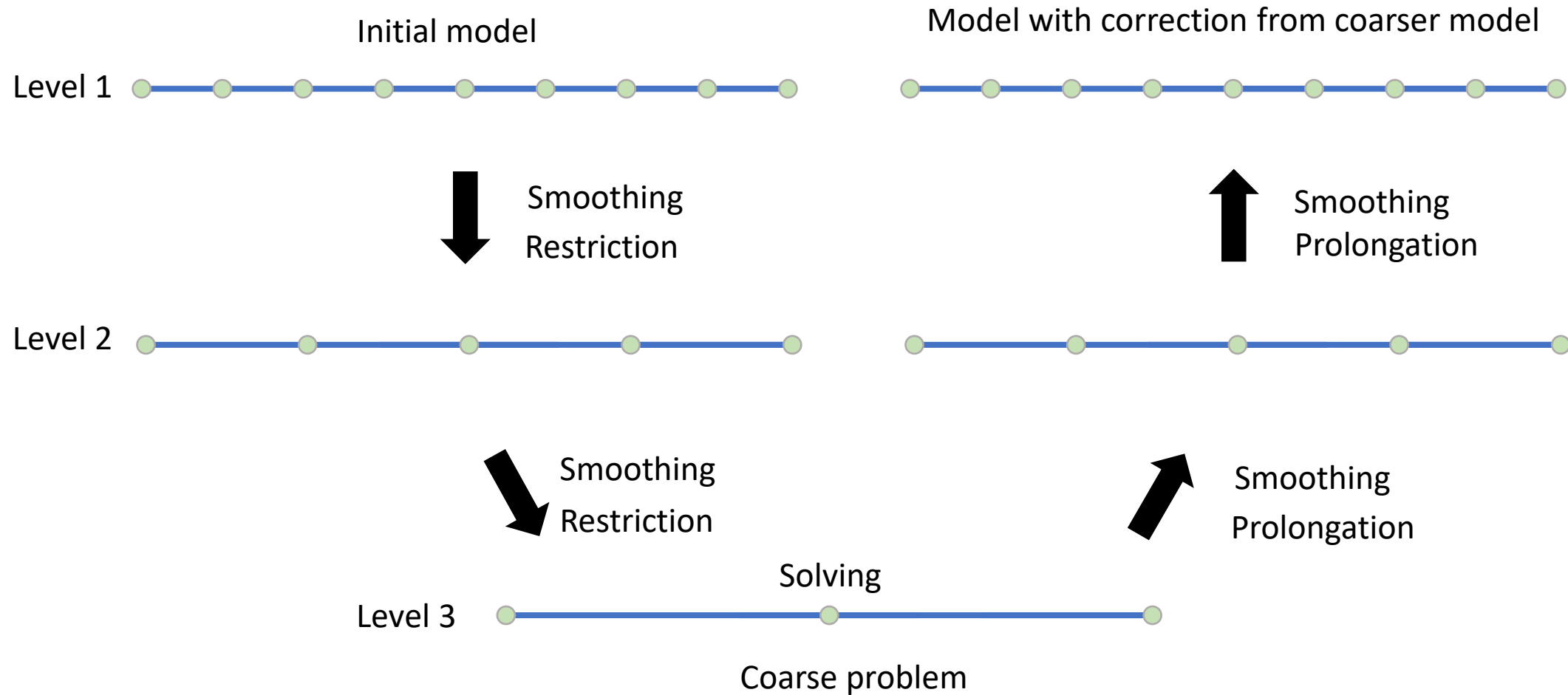
Correction propagation



V-cycle

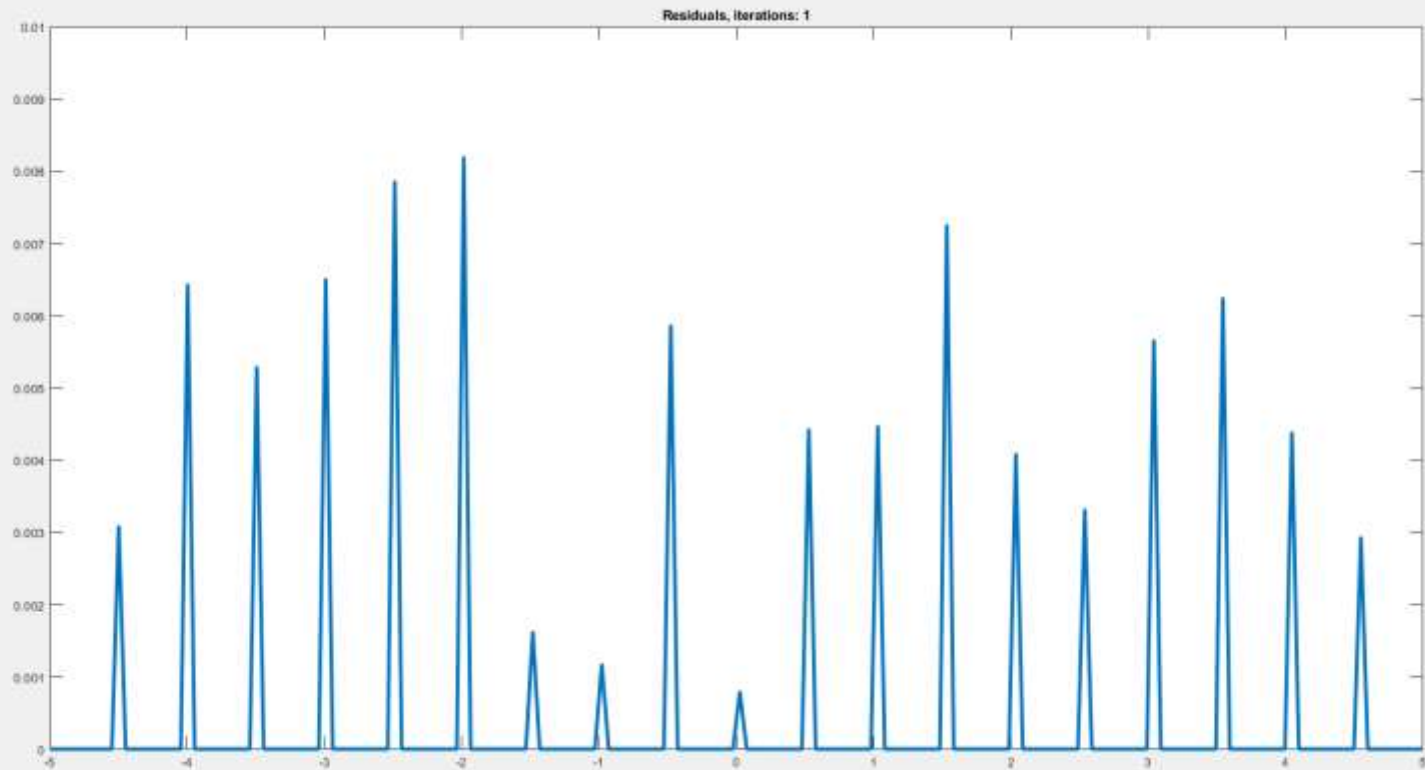


V-cycle 4 multigrid levels



Multigrid

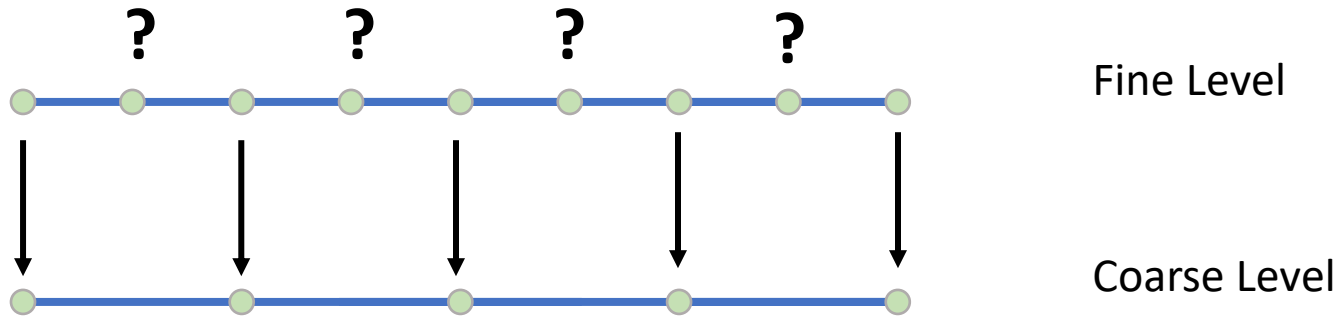
Smoothing



Residuals look spiky!

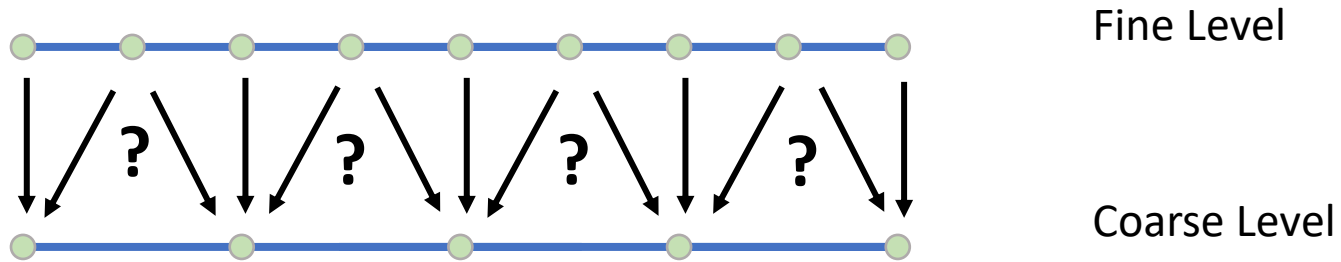
Geometric Multigrid

Restriction operation



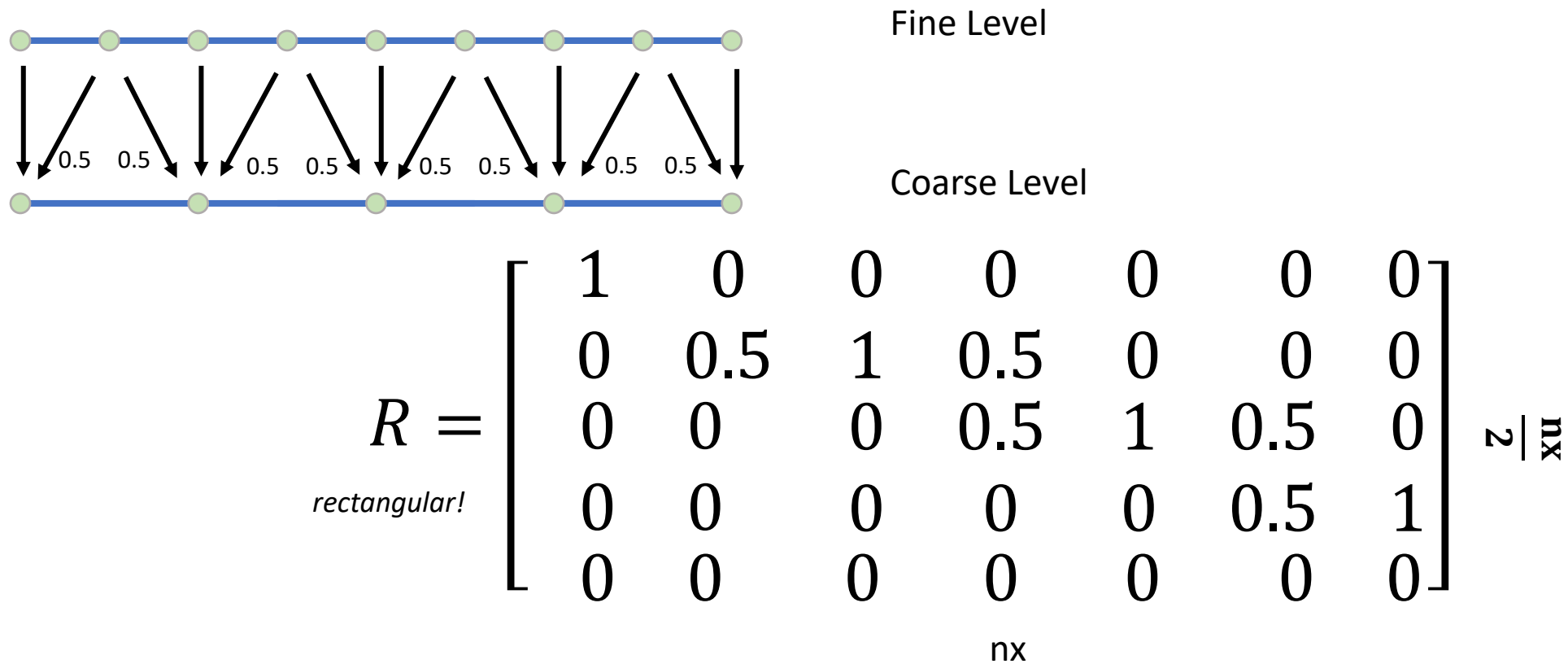
Geometric Multigrid

Restriction operation



Geometric Multigrid

Restriction operation



Geometric Multigrid

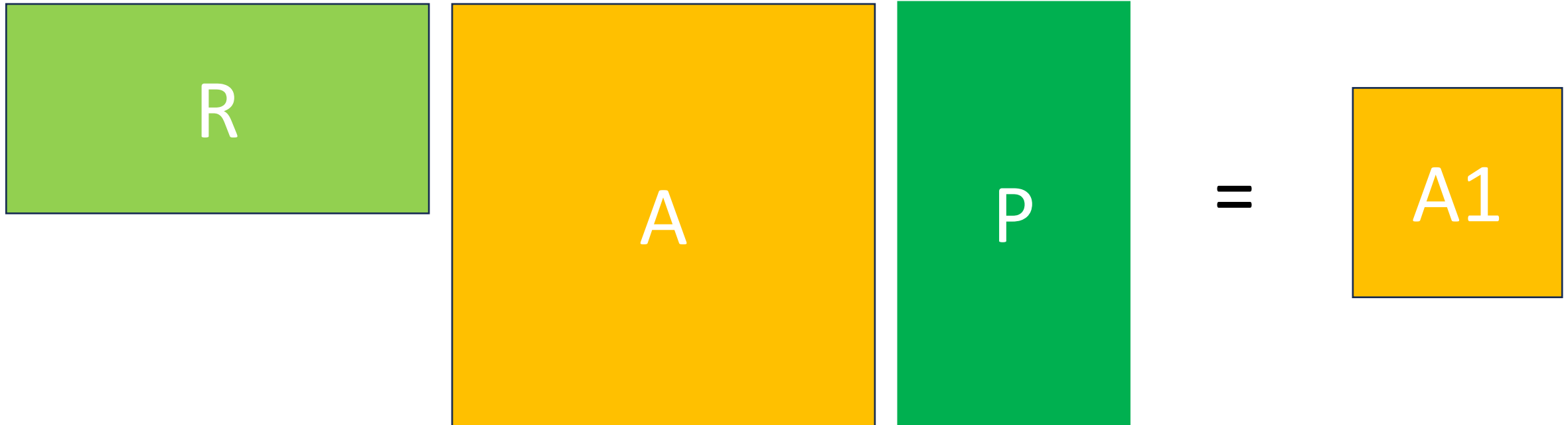
Prolongation operation

$$\mathbf{P} = \mathbf{R}$$

Geometric Multigrid

Galerkin Coarsening

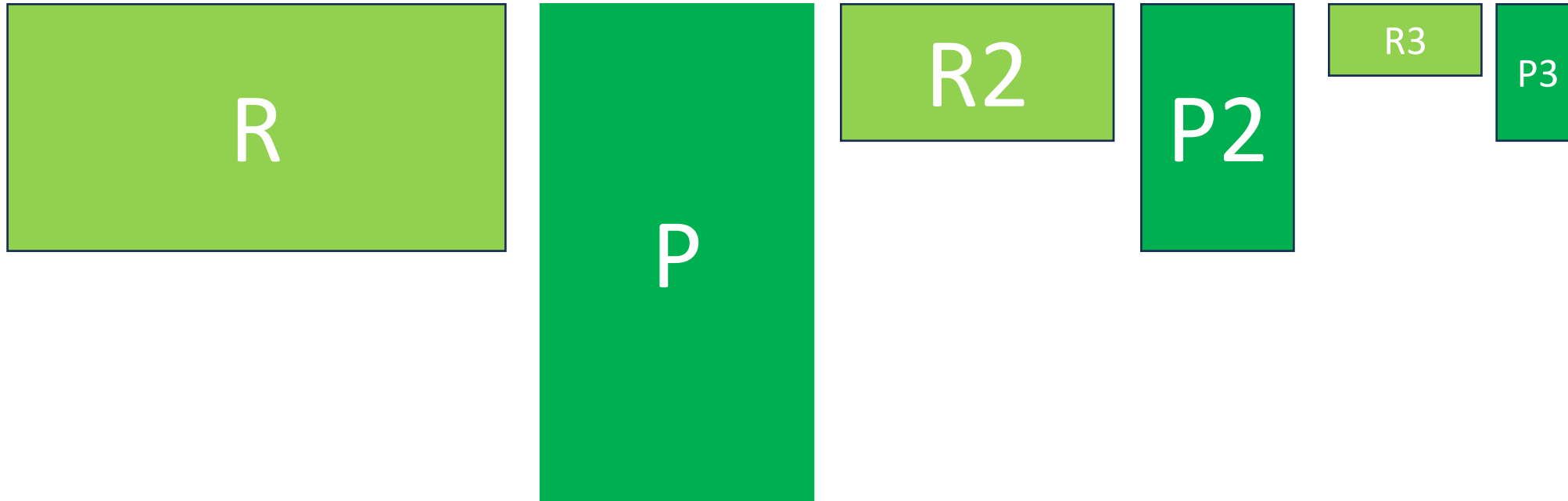
$$\begin{aligned} r_1 &= Rr \\ A_1 &= RAP \end{aligned}$$



Geometric Multigrid

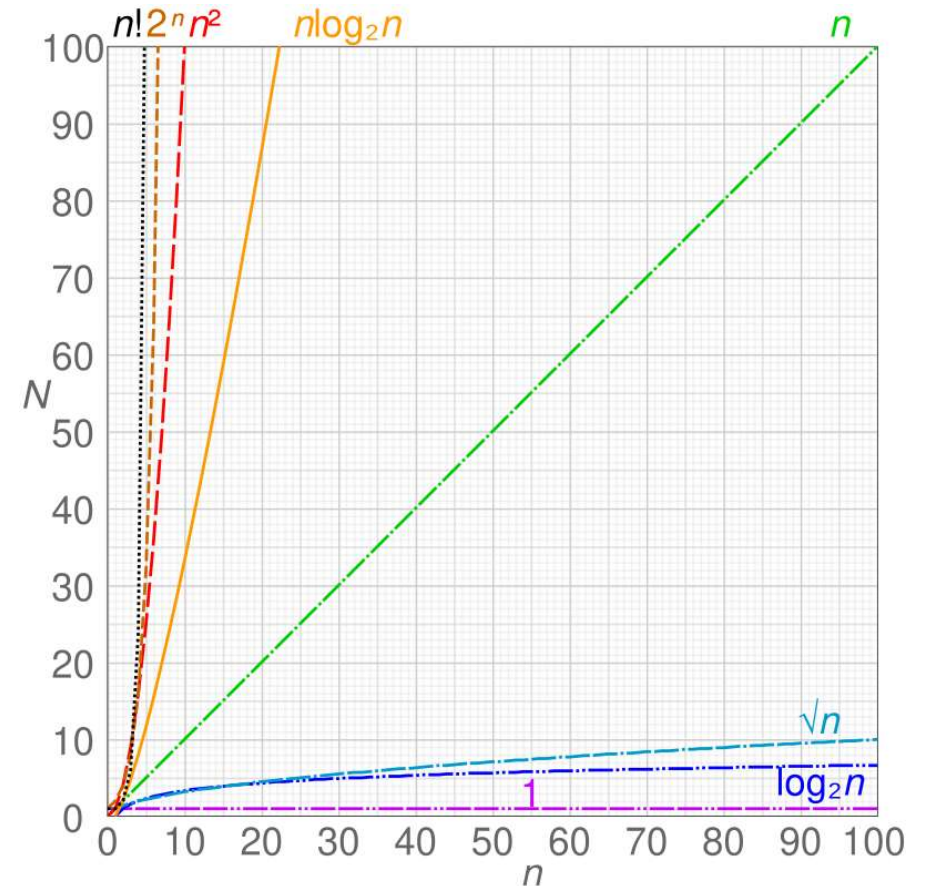
Galerkin Coarsening

You need to build all restriction operators in the beginning for geometric multigrid



What is an advantage of multigrid

- Good to parallelize
- Low memory usage
- Fast to converge
- Scalable
- No problem with sparse matrices
- Preconditioners
- Domain decomposition



Computational cost:

Direct solver: $O(n^3)$

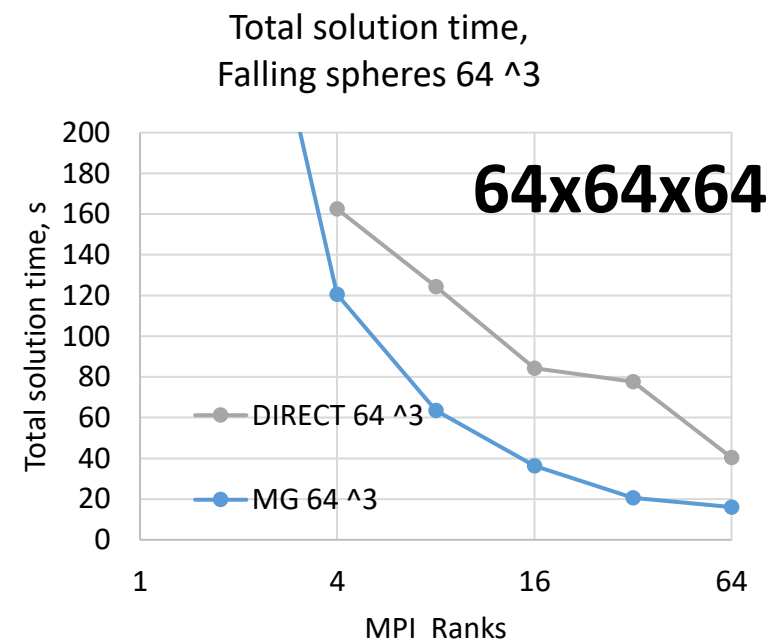
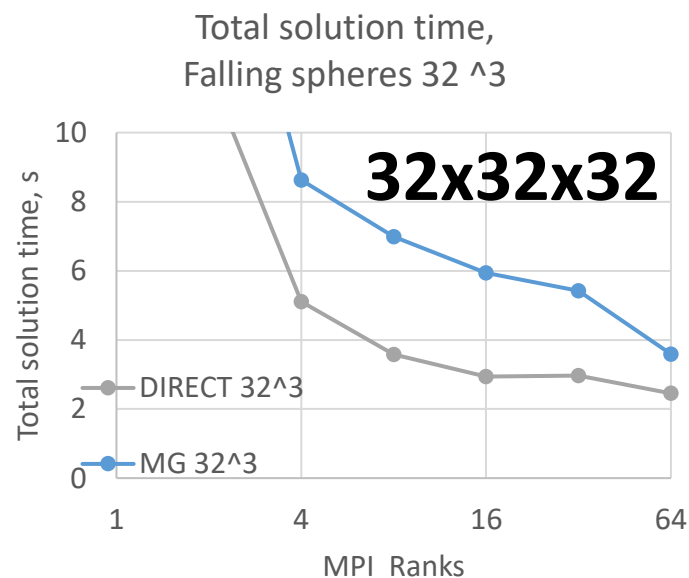
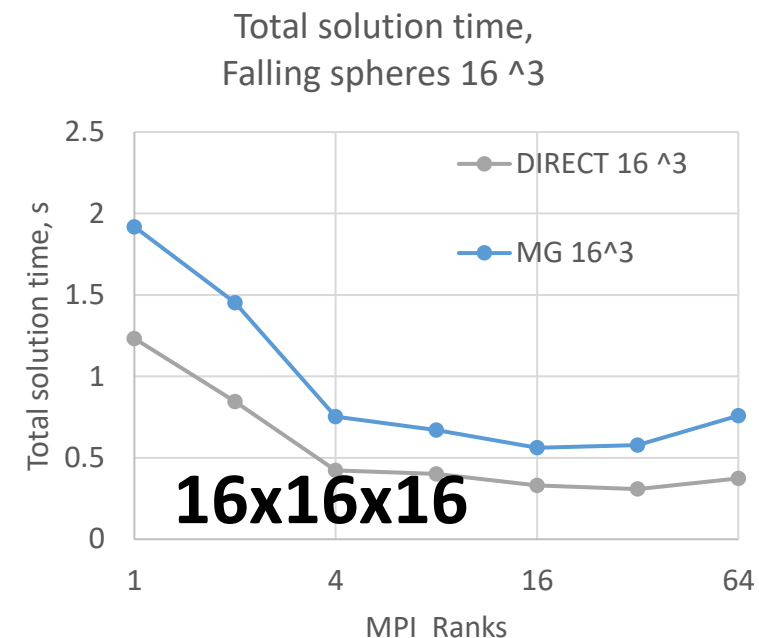
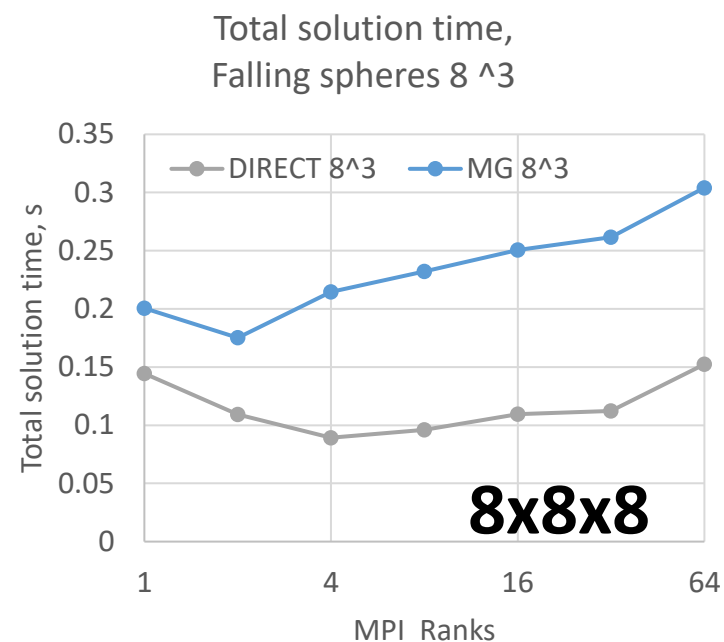
Iterative solvers (sparse): $O(\text{nnz}(A)) + O(n) \approx O(n^2)$

Multigrid: $O(n)$

LaMEM

Problem size:

Resolution	Cell Number
8x8x8	512
16x16x16	4096
32x32x32	32768
64x64x64	262144
128x128x128	2097152



Acknowledgments

Anton Popov (JGU Mainz) – With multigrid code
Evangelos Moulas (JGU Mainz) – Consultation