C# OOP Exam – 8 April 2023

RobotService



1. Overview

We are in the year 2100. Technology is so advanced that robots are all around us. They are autonomous and do whatever you tell them to do. They use fluidization instead of charging to provide the energy they need, so robots need to be fed.

You are working on a robot service and you need to create a RobotService project to monitor the actions of a robot. Each service has a robot that requires different care. Your job is to add, feed and take care of the robot, as well as upgrade it with various supplements.

2. Setup

- Upload only the RobotService project in every task except Unit Tests.
- Do not modify the interfaces or their packages.
- Use strong cohesion and loose coupling.
- Use inheritance and the provided interfaces wherever possible:
 - This includes constructors, method parameters, and return types.
- Do not violate your interface implementations by adding more public methods in the concrete class than the interface has defined.
- Make sure you have **no public fields** anywhere.
- **Exception messages** and **output messages** can be found in the "Utilities" folder.
- For solving this problem use Visual Studio 2019, Visual Studio 2022 and netcoreapp 3.1, netcoreapp 6.0

3. Task 1: Structure (50 points)

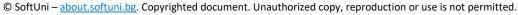
For this task's evaluation logic in the methods isn't included.

You are given some interfaces, and you have to implement their functionality in the correct classes.

There are **2** types of entities in the application: **Supplement** and **Robot**.

There should also be **SupplementRepository** and **RobotRepository**, both implementing the **IRepository** interface.



















Supplement

A Supplement is a base class of any type of supplement and it should not be able to be instantiated.

Data

- InterfaceStandard int
 - The compatibility standard that the Supplement supports.
- BatteryUsage int
 - The power that the Supplement will consume additionally when installed to a Robot.

Constructor

A **Supplement** should take the following values upon initialization:

int interfaceStandard, int batteryUsage

Child Classes

There are two concrete types of **Supplement**:

SpecializedArm

A SpecializedArm has an InterfaceStandard of 10045 and a BatteryUsage of 10 000 mAh.

Note: The Constructor should take no values upon initialization.

LaserRadar

A LaserRadar has an InterfaceStandard of 20082 and a BatteryUsage of 5 000 mAh.

Note: The Constructor should take no values upon initialization.

Robot

A Robot is a base class of any type of robot and it should not be able to be instantiated.

Data

- Model string
 - If the **Model** is **null or whitespace**, throw a new **ArgumentException** with the message:

"Model cannot be null or empty."

- BatteryCapacity int
 - o The maximum charging level of the **Robot** battery.
 - The BatteryCapacity cannot drop below zero. If it does, throw a new ArgumentException with the message:

"Battery capacity cannot drop below zero."

- BatteryLevel int
 - The current level of the battery. When creating a new Robot, set its initial value, equal to the BatteryCapacity.
- ConvertionCapacityIndex int
 - The ability of the **Robot** to convert food into energy.
- InterfaceStandards IReadOnlyCollection<int>
 - o A collection of all the supported connectivity standards by a specific **Robot**.

















Behavior

void Eating(int minutes)

The **Robot** will be in fluidization mode, so it will convert the food into electrical energy. For **every minute of eating**, it will produce energy equal to the ConvertionCapacityIndex multiplied by the given minutes.

- The **Eating()** method increases the **Robot's BatteryLevel**, with the produced energy.
- If the battery is fully charged (BatteryLevel = BatteryCapacity), the eating stops earlier.

void InstallSupplement(ISupplement supplement)

- The InstallSupplemet() method takes the given supplement's InterfaceStandard and adds it to the list of InterfaceStandards of the Robot.
- Decreases the BatteryCapacity of the robot by the BatteryUsage of the supplement.
- Decreases the **BatteryLevel** of the robot by the **BatteryUsage** of the supplement.

bool ExecuteService(int consumedEnergy)

The ExecuteService() method decreases the Robot's BatteryLevel, with the given amount of consumed energy.

- If the BatteryLevel is equal or greater than the given consumedEnergy, decrease the BatteryLevel with the given amount of consumedEnergy and return True.
- If the BatteryLevel is less than the given consumedEnergy, it means that it is NOT enough. Skip the execution and return False.

Override ToString() method:

Override the existing method **ToString()** and modify it, so the returned string must be in the following format:

```
"{robotTypeName} {Model}:
```

```
-- Maximum battery capacity: {BatteryCapacity}
```

```
--Current battery level: {BatteryLevel}
```

--Supplements installed: {standard₁} {standard₂}.../none"

Note: For best clarity see the output examples!

Constructor

A **Robot** should take the following values upon initialization:

string model, int batteryCapacity, int conversionCapacityIndex

Child Classes

There are several concrete types of **Robot**:

DomesticAssistant

Has BatteryCapacity of 20 000 mAh.

The DomesticAssistant will produce a capacity of 2000 mAh of energy for every minute of eating -(convertionCapacityIndex = 2 000).

















The Constructor of the **DomesticAssistant** should take the following parameters upon initialization:

string model

Industrial Assistant

Has BatteryCapacity of 40 000 mAh.

The IndustrialAssistant will produce a capacity of 5000 mAh of energy for every minute of eating -(convertionCapacityIndex = 5 000).

The Constructor of the **IndustrialAssistant** should take the following parameters upon initialization:

string model

SupplementRepository

The SupplementRepository is an IRepository<ISupplement>. Collection for the supplements that are created in the application.

Data

A private field would be useful to store the items added.

Behavior

IReadOnlyCollection<ISupplement> Models()

Returns all added items as a readonly collection.

void AddNew(ISupplement supplement)

• Adds a new ISupplement to the SupplementRepository.

bool RemoveByName(string typeName)

Removes the first **ISupplement** from the **collection**, which has the same typeName as the given **typeName**. **Returns true** if the removal was **successful**, **otherwise** returns **false**.

ISupplement FindByStandard(int interfaceStandard)

Returns the first ISupplement supporting the given interface, if there is any. Otherwise, returns null.

RobotRepository

The RobotRepository is an IRepository < IRobot >. Collection for the robots that are created in the application.

Data

A private field would be useful to store the items added.

Behavior

IReadOnlyCollection<IRobot> Models()

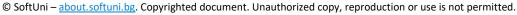
Returns all added items as a readonly collection.

void AddNew(IRobot robot)

Adds a new IRobot to the RobotRepository.

bool RemoveByName(string robotModel)



















Removes the first IRobot from the collection, which Model is the same as the given robotModel. Returns true if the deletion was successful, otherwise returns false.

IRobot FindByStandard(int interfaceStandard)

Returns the first IRobot supporting the given interface, if there is any. Otherwise, returns null.

Task 2: Business Logic (150 points)

The Controller Class

The business logic of the program should be concentrated around several commands, which you have to implement in the correct class.

The interface is IController. You must create a Controller class, which implements the interface and implements all of its methods. The constructor of the **Controller** does not take any arguments. The given methods should have the logic described for each in the Commands section. When you create the Controller class, go into the **Engine** class constructor and uncomment the "this.controller = new Controller();" line.

Data

You will need some private fields in your controller class:

- supplements SupplementRepository
- robots RobotRepository

Commands

There are several **commands**, which control the **business logic** of the **application**. They are **stated below**.

CreateRobot Command

Parameters

- model-string
- typeName string

Functionality

The method should create and add a new IRobot to the RobotRepository.

- If the given typeName is NOT presented as a valid Robot's child class (DomesticAssistant or IndustrialAssistant), return the following message: "Robot type {typeName} cannot be created."
- If the above case is NOT reached, create an IRobot from the valid child type and add it to the RobotRepository. Return the following message: "{typeName} {model} is created and added to the RobotRepository."

CreateSupplement Command

Parameters

typeName - string

Functionality

The method should create and add a new ISupplement to the SupplementRepository.

If the given typeName is NOT presented as a valid Supplement's child class (SpecializedArm or LaserRadar), return the following message: "{typeName} is not compatible with our robots."



















If the above case is NOT reached, create a new ISupplement and add it to the SupplementRepository. "{typeName} Return the following message: is created and added the SupplementRepository."

UpgradeRobot Command

Parameters

- model-string
- supplementTypeName string

Functionality

This method will upgrade a robot with a new supplement. There will always be at least one supplement from the correct type already added to the SupplementRepository. There will always be at least one robot from the given model already added to the RobotRepository:

- 1. Find the first ISupplement with the given supplementTypeName in the SupplementRepository and take its interface value.
- 2. From the RobotRepository, take only the robots, NOT supporting the interface value (check if every robot's InterfaceStandards collection NOT containing the interface value).
- 3. Select only the robots, from the given model (check if every robot's Model is equal to the given model).
- 4. If the collection is empty, that means all of the robots in the RobotRepository from the given model, are already upgraded with a **Supplement** from the given **supplementTypeName**,
 - return the following message: "All {model} are already upgraded!"
- 5. If there are still not upgraded robots, take the first **IRobot** from the previous selected robots and use the built-in **InstallSupplement()** method to upgrade the robot with the new supplement.
 - Remove the **ISupplement** from the **SupplementRepository**.
 - Return the following message: "{model} is upgraded with {supplementTypeName}."

PerformService Command

Parameters

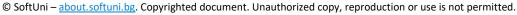
- serviceName string
- interfaceStandard int
- totalPowerNeeded int

Functionality

To perform a specific service, you will need **only** robots supporting the given **interfaceStandard**. You will have to check the InterfaceStandarts property of every single robot from the RobotRepository and take those which meet that requirement.

- 1. Select the robots, supporting the given interfaceStandard from the RobotRepository (check if every robot's InterfaceStandards collection contains the given interfaceStandard)
- 2. If NONE of the robots in the RobotRepository supports the given interfaceStandard, return the following message: "Unable to perform service, {intefaceStandard} not supported!"
- 3. Order the selected robots by BatteryLevel descending.
- 4. Find the sum of the BatteryLevel of the selected robots.



















- 5. If the sum of the BatteryLevel of the selected robots, is less than the totalPowerNeeded,
 - Return the following message:

"{serviceName} cannot be executed! {totalPowerNeeded - availablePower} more power needed."

- 6. Else if the totalPowerNeeded, is greater or equal to the BatteryLevel sum, each of the selected robots will work on the service until the service is performed successfully (totalPowerNeeded == 0):
 - Create a counter to calculate how many robots will take part in the service.
 - o If robot.BatteryLevel >= totalPowerNeeded
 - Extract energy from the battery, equal to the totalPowerNeeded (HINT: robot.ExecuteService(totalPowerNeeded))
 - Increase the counter by 1 and stop executing the service.
 - o If robot.BatteryLevel < totalPowerNeeded:</p>
 - Decrease the totalPowerNeeded with the value of robot.BatteryLevel
 - Extract all the energy from the battery (HINT: robot.ExecuteService(robot.BatteryLevel))
 - Increase the counter by 1 and proceed with the next robot.
- 7. When the service is performed successfully, return the following message: "{serviceName} is performed successfully with {usedRobotsCount} robots."

RobotRecovery Command

Parameters

- model string
- minutes int

Functionality

Feed all robots in the **RobotRepository** from the given **mode1** for the given count of **minutes**. Choose only those robots that have BatteryLevel under 50% from the total BatteryCapacity.

Remember that when feeding a robot, it will be in **fluidization mode** and it will **convert food into energy**. That means that after feeding, the robot's **BatteryLevel** should be **increased**. Use the built-in **Eating()** method of each robot.

Return a string with information about how many robots were successfully fed, in the following format:

"Robots fed: {fedCount}"

Report Command

Functionality

Returns information about each robot from the RobotRepository. Arrange the robots by BatteryLevel, descending, then by BatteryCapacity, ascending. In order to receive correct output, use the ToString() method of each robot:

```
"{robot₁}
{robot<sub>2</sub>}
{robot<sub>n</sub>}"
```

End Command

Ends the program.



















Input / Output

You are provided with one interface, which will help you with the correct execution process of your program. The interface is **Engine** and the class implementing this interface should read the input and when the program finishes, this class should print the output.

Input

Below, you can see the **format** in which **each command** will be given in the input:

- CreateRobot {model} {typeName}
- CreateSupplement {typeName}
- UpgardeRobot {model} {supplementTypeName}
- PerformService {serviceName} {interfaceStandard} {totalPowerNeeded}
- RobotRecovery {model} {minutes}
- Report
- Exit

Output

Print the output from each command when issued. If an exception is thrown during any of the commands' execution, print the exception message.

Examples

```
Input
CreateRobot K-2SO IndustrialAssistant
CreateRobot T-X IndustrialAssistant
CreateRobot AVA DomesticAssistant
CreateRobot KUSANAGI IndustrialAssistant
CreateRobot C-3PO DomesticAssistant
CreateRobot R2-D2 DomesticAssistant
CreateRobot C1-10P SocialAssistant
CreateRobot C-3PO DomesticAssistant
CreateSupplement FaceRecognitionCamera
CreateSupplement SpecializedArm
CreateSupplement SpecializedArm
CreateSupplement SpecializedArm
CreateSupplement SpecializedArm
CreateSupplement LaserRadar
CreateSupplement LaserRadar
CreateSupplement LaserRadar
CreateSupplement LaserRadar
PerformService Dishwashing 10045 1000
UpgradeRobot C-3PO SpecializedArm
UpgradeRobot C-3PO SpecializedArm
UpgradeRobot C-3PO SpecializedArm
UpgradeRobot C-3PO LaserRadar
UpgradeRobot R2-D2 SpecializedArm
UpgradeRobot KUSANAGI LaserRadar
UpgradeRobot KUSANAGI SpecializedArm
PerformService PaintRoad 20082 100000
PerformService DishWashing 10045 1000
PerformService AutomotiveAssembly 10045 25000
RobotRecovery C-3PO 3
RobotRecovery KUSANAGI 3
Report
```



















Output

```
IndustrialAssistant K-2SO is created and added to the RobotRepository.
IndustrialAssistant T-X is created and added to the RobotRepository.
DomesticAssistant AVA is created and added to the RobotRepository.
IndustrialAssistant KUSANAGI is created and added to the RobotRepository.
DomesticAssistant C-3PO is created and added to the RobotRepository.
DomesticAssistant R2-D2 is created and added to the RobotRepository.
Robot type SocialAssistant cannot be created.
DomesticAssistant C-3PO is created and added to the RobotRepository.
FaceRecognitionCamera is not compatible with our robots.
SpecializedArm is created and added to the SupplementRepository.
LaserRadar is created and added to the SupplementRepository.
Unable to perform service, 10045 not supported!
C-3PO is upgraded with SpecializedArm.
C-3PO is upgraded with SpecializedArm.
All C-3PO are already upgraded!
C-3PO is upgraded with LaserRadar.
R2-D2 is upgraded with SpecializedArm.
KUSANAGI is upgraded with LaserRadar.
KUSANAGI is upgraded with SpecializedArm.
PaintRoad cannot be executed! 70000 more power needed.
DishWashing is performed successfully with 1 robots.
AutomotiveAssembly is performed successfully with 2 robots.
Robots fed: 0
Robots fed: 1
IndustrialAssistant K-2SO:
-- Maximum battery capacity: 40000
-- Current battery level: 40000
--Supplements installed: none
IndustrialAssistant T-X:
-- Maximum battery capacity: 40000
--Current battery level: 40000
--Supplements installed: none
DomesticAssistant AVA:
-- Maximum battery capacity: 20000
--Current battery level: 20000
--Supplements installed: none
IndustrialAssistant KUSANAGI:
-- Maximum battery capacity: 25000
--Current battery level: 15000
--Supplements installed: 20082 10045
DomesticAssistant C-3PO:
-- Maximum battery capacity: 10000
--Current battery level: 10000
--Supplements installed: 10045
DomesticAssistant R2-D2:
--Maximum battery capacity: 10000
--Current battery level: 9000
--Supplements installed: 10045
DomesticAssistant C-3PO:
--Maximum battery capacity: 5000
--Current battery level: 5000
```



















--Supplements installed: 10045 20082

Task 3: Unit Tests (100 points)

You will receive a skeleton with three classes inside - Factory, Robot and Supplement. Factory class will have some methods, fields, and constructors. Cover the whole class with the unit test to make sure that the class is working as intended. If some of the methods in Factory change anything from the other classes, you should cover that functionality also. In Judge, you upload .zip (with RobotFactory.Tests inside) from the skeleton



















